

CSE 312

Foundations of Computing II


Lecture 16: Joint Continuous, Conditional Distributions, and Tail Bounds



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Slide Credit: Based on Stefano Tessaro's slides for 312 19au
incorporating ideas from Anna Karlin, Ryan O'Donnell, Alex Tsun, Rachel Lin, Hunter
Schafer & myself 😊

Agenda

- Joint Continuous Distributions 
- Conditional Expectation
 - Law of Total Expectation
- Tail Bounds
 - Markov's Inequality
 - Chebyshev's Inequality

	Discrete	Continuous
Joint PMF/PDF	$p_{X,Y}(x, y) = \mathbb{P}(X = x, Y = y)$	$f_{X,Y}(x, y) \neq \mathbb{P}(X = x, Y = y)$
Joint range/support $\Omega_{X,Y}$	$\{(x, y) \in \Omega_X \times \Omega_Y : p_{X,Y}(x, y) > 0\}$	$\{(x, y) \in \Omega_X \times \Omega_Y : f_{X,Y}(x, y) > 0\}$
Joint CDF	$F_{X,Y}(x, y) = \sum_{t \leq x, s \leq y} p_{X,Y}(t, s)$	$F_{X,Y}(x, y) = \int_{-\infty}^x \int_{-\infty}^y f_{X,Y}(t, s) ds dt$
Normalization	$\sum_{x,y} p_{X,Y}(x, y) = 1$	$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x, y) dx dy = 1$
Marginal PMF/PDF	$p_X(x) = \sum_y p_{X,Y}(x, y)$	$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy$
Expectation	$\mathbb{E}[g(X, Y)] = \sum_{x,y} g(x, y) p_{X,Y}(x, y)$	$\mathbb{E}[g(X, Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f_{X,Y}(x, y) dx dy$

Independence (continuous random variables)

Definition. Let X and Y be continuous random variables. The **joint pdf** of X and Y is

$$f_{X,Y}(a, b) \neq \Pr(X = a, Y = b)$$

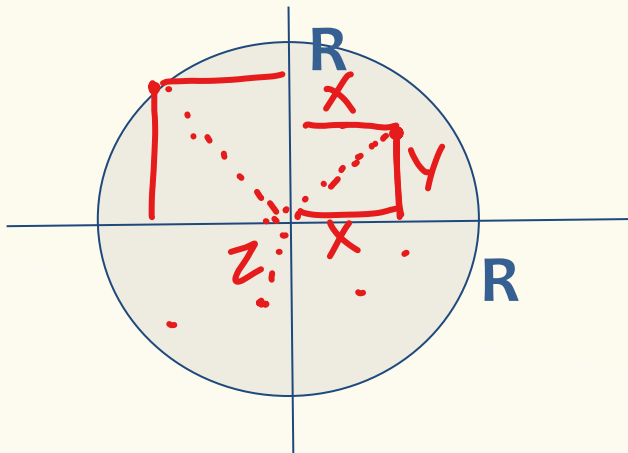
Definition. The **joint range** of $p_{X,Y}$ is

$$\Omega(X, Y) = \{(c, d) : p_{X,Y}(c, d) > 0\} \subseteq \Omega(X) \times \Omega(Y)$$

Definition. X and Y are **independent** iff for all a, b

$$f_{X,Y}(a, b) = f_X(a) \cdot f_Y(b)$$

- Suppose that the surface of a disk is a circle with ~~area~~ ^{radius} R centered at the origin and that there is a single point imperfection at a location which is uniformly distributed across the surface of the disk. Let X and Y be the x and y coordinates of the imperfection (random variables) and let Z be the distance of the imperfection from the origin.
 - What is their joint density $f(x,y)$?



$$f_{X,Y} = c \text{ for } x^2 + y^2 \leq R^2 \quad f_{X,Y} \left(\frac{R}{2}, \frac{R}{3} \right) = \frac{1}{\pi R^2}$$

$$\iint_{\pi R^2} c = 1 = c \pi R^2 = 1$$

$$c = \frac{1}{\pi R^2}$$

- Suppose that the surface of a disk is a circle with area R centered at the origin and that there is a single point imperfection at a location which is uniformly distributed across the surface of the disk. Let X and Y be the x and y coordinates of the imperfection (random variables) and let Z be the distance of the imperfection from the origin.

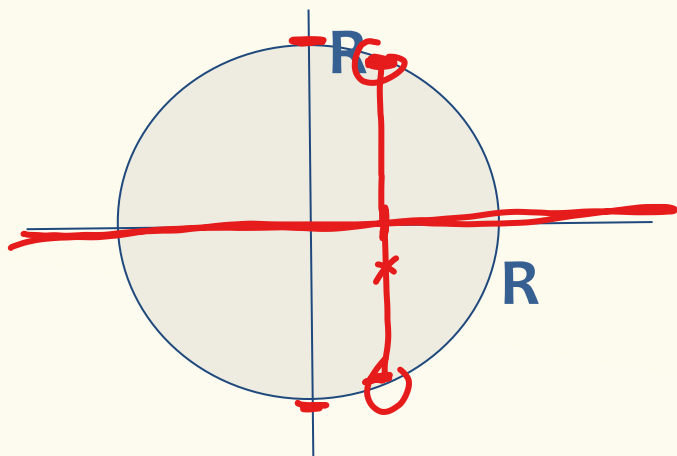
– What is the range of X & Y and the marginal density of X and of Y ?

$$\Omega_X: [-R, R]$$

$$\Omega_Y: [-R, R]$$

$$f_X(x) = \int_{-\sqrt{R^2-x^2}}^{\sqrt{R^2-x^2}} \frac{1}{\pi R^2} dy = \frac{2\sqrt{R^2-x^2}}{\pi R^2}$$

$$x^2 + y^2 = R^2$$



$$f_Y(y) = \dots$$



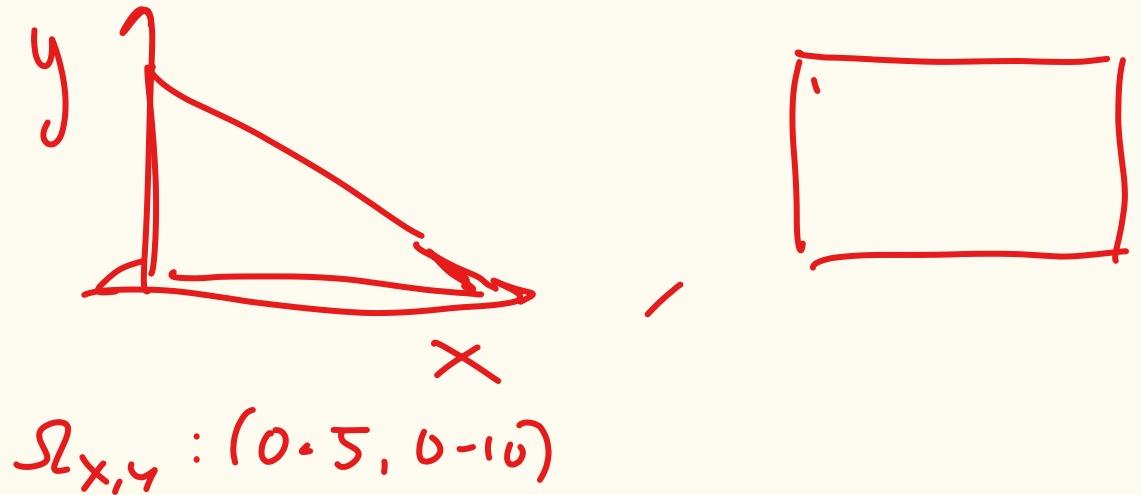
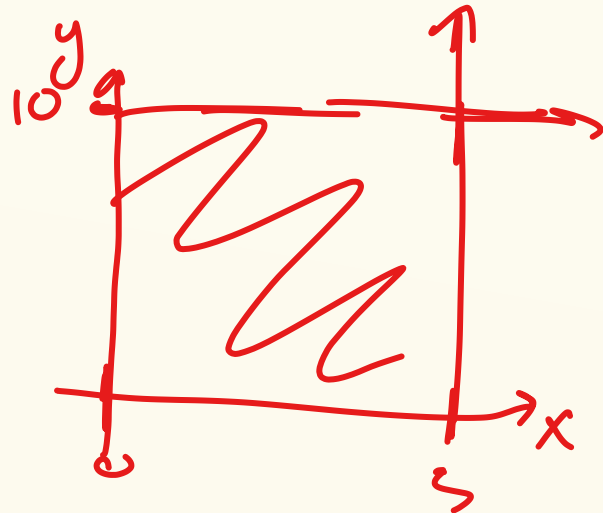
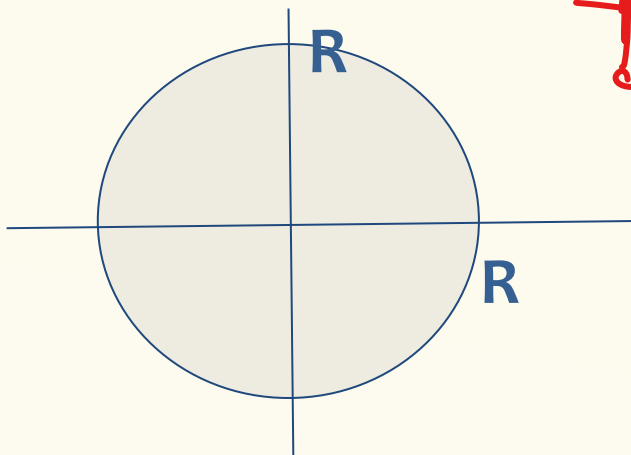
Poll:

What is Ω_X ?

- $[-\sqrt{R^2 - x^2}, \sqrt{R^2 - x^2}]$
- $[-R, R]$
- $[-\sqrt{R^2 - y^2}, \sqrt{R^2 - y^2}]$
- Not sure

- Suppose that the surface of a disk is a circle with area R centered at the origin and that there is a single point imperfection at a location which is uniformly distributed across the surface of the disk. Let X and Y be the x and y coordinates of the imperfection (random variables) and let Z be the distance of the imperfection from the origin.

– Are X and Y independent?



Poll:

Are X and Y independent?

a. yes

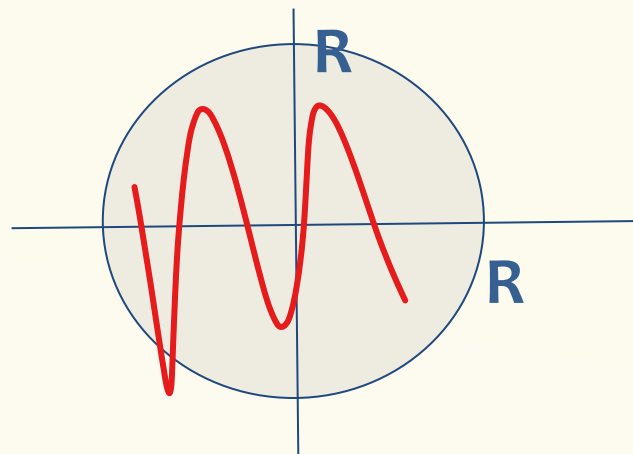
b. no

- Suppose that the surface of a disk is a circle with area R centered at the origin and that there is a single point imperfection at a location with is uniformly distributed across the surface of the disk. Let X and Y be the x and y coordinates of the imperfection (random variables) and let Z be the distance of the imperfection from the origin.

– What is $E(Z)$?

$$g(x, y) = \sqrt{x^2 + y^2}$$

$$E[\sqrt{x^2 + y^2}] = \iint_{x^2 + y^2 \leq R^2} \sqrt{x^2 + y^2} \frac{1}{\pi R^2} dx dy$$




$$E[g(X, Y)] = \iint g(x, y) f_{X, Y}(x, y) dx dy$$

All of this generalizes to more than 2 random variables

	Discrete	Continuous
Joint PMF/PDF	$p_{X,Y}(x, y) = \mathbb{P}(X = x, Y = y)$	$f_{X,Y}(x, y) \neq \mathbb{P}(X = x, Y = y)$
Joint range/support $\Omega_{X,Y}$	$\{(x, y) \in \Omega_X \times \Omega_Y : p_{X,Y}(x, y) > 0\}$	$\{(x, y) \in \Omega_X \times \Omega_Y : f_{X,Y}(x, y) > 0\}$
Joint CDF	$F_{X,Y}(x, y) = \sum_{t \leq x, s \leq y} p_{X,Y}(t, s)$	$F_{X,Y}(x, y) = \int_{-\infty}^x \int_{-\infty}^y f_{X,Y}(t, s) ds dt$
Normalization	$\sum_{x,y} p_{X,Y}(x, y) = 1$	$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x, y) dx dy = 1$
Marginal PMF/PDF	$p_X(x) = \sum_y p_{X,Y}(x, y)$	$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy$
Expectation	$\mathbb{E}[g(X, Y)] = \sum_{x,y} g(x, y) p_{X,Y}(x, y)$	$\mathbb{E}[g(X, Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f_{X,Y}(x, y) dx dy$

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- Joint Continuous Distributions
- **Conditional Expectation** 
 - Law of Total Expectation
- Tail Bounds
 - Markov's Inequality
 - Chebyshev's Inequality

Conditional Expectation

Definition. Let X be a discrete random variable then the **conditional expectation** of X given event A is

$$E[X | A] = \sum_{x \in \Omega(X)} x \Pr(X = x | A)$$

- Linearity of expectation still applies here

$$E[\underline{aX + bY + c} | A] = aE[X | A] + bE[Y | A] + c$$

Conditional Expectation


Definition. Let X be a discrete random variable then the **conditional expectation** of X given event $Y = y$ is

$$E[X | Y = y] = \sum_{x \in \Omega(X)} x \Pr(X = x | Y = y)$$

- Linearity of expectation still applies here

$$E[aX + bY + c | Y = y] = aE[X | Y = y] + bE[Y | Y = y] + c$$

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Law of Total Expectation

Law of Total Expectation (event version). Let X be a random variable and let events A_1, \dots, A_n partition the sample space. Then,

$$E[X] = \sum_{i=1}^n E[X|A_i] \Pr(A_i)$$

Proof of Law of Total Expectation

Follows from Law of Total Probability and manipulating sums

$$\begin{aligned} E[X] &= \sum_{x \in \Omega(X)} x \Pr(X = x) \\ &= \sum_{x \in \Omega(X)} x \sum_{i=1}^n \Pr(X = x | A_i) \Pr(A_i) && \text{(by LTP)} \\ &= \sum_{i=1}^n \Pr(A_i) \sum_{x \in \Omega(X)} x \Pr(X = x | A_i) && \text{(change order of sums)} \\ &= \sum_{i=1}^n \Pr(A_i) E[X | A_i] && \text{(def of cond. expect.)} \end{aligned}$$

Law of Total Expectation

Law of Total Expectation (random variable version). Let X be a random variable and Y be a discrete random variable. Then,

$$E[X] = \sum_{y \in \Omega(Y)} E[X|Y = y] \Pr(Y = y)$$

Example: Flipping Coins

Suppose wanted to analyze flipping a random number of coins. Suppose someone gave us $Y \sim Poi(5)$ fair coins and we wanted to compute the expected number of heads X from flipping those coins.

$$E[X] = \sum_{y=0}^{\infty} E[X|Y=y] P(Y=y)$$

$$= \sum_{y=0}^{\infty} y p \cdot e^{-\lambda} \frac{\lambda^y}{y!} = \left(p \cdot e^{-\lambda} \sum_{y=0}^{\infty} \frac{y \cdot \lambda^y}{y!} \right)$$

$$E[X|Y] \stackrel{?}{=} E[X] E[Y]$$

Elevator rides

The number of people who enter an elevator on the ground floor is a Poisson random variable with mean 10. If there are N floors above the ground floor, and if each person is equally likely to get off at any one of the N floors, independently of where others get off, compute the expected number of stops the elevator will make before discharging all the passengers.

$Y_i = 1$ if stops at floor i

$$E[Y] = \sum_{i=1}^N E[Y_i]$$

$P(Y_i = 1) = P(\text{at least one person gets off})$

$$E[Y | X = k] = N \left(1 - \left(1 - \frac{1}{N} \right)^k \right)$$

$= 1 - P(\text{Nobody gets off})$

$$E[Y] = \sum_{k=0}^{\infty} N \left(1 - \left(1 - \frac{1}{N} \right)^k \right) e^{-10} \frac{10^k}{k!}$$


$= 1 - P(\text{all choose another floor})$

$$= 1 - \left(1 - \frac{1}{N} \right)^k$$

Reference Sheet (with continuous RVs)

	Discrete	Continuous
Joint PMF/PDF	$p_{X,Y}(x, y) = P(X = x, Y = y)$	$f_{X,Y}(x, y) \neq P(X = x, Y = y)$
Joint CDF	$F_{X,Y}(x, y) = \sum_{t \leq x} \sum_{s \leq y} p_{X,Y}(t, s)$	$F_{X,Y}(x, y) = \int_{-\infty}^x \int_{-\infty}^y f_{X,Y}(t, s) ds dt$
Normalization	$\sum_x \sum_y p_{X,Y}(x, y) = 1$	$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x, y) dx dy = 1$
Marginal PMF/PDF	$p_X(x) = \sum_y p_{X,Y}(x, y)$	$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy$
Expectation	$E[g(X, Y)] = \sum_x \sum_y g(x, y) p_{X,Y}(x, y)$	$E[g(X, Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f_{X,Y}(x, y) dx dy$
Conditional PMF/PDF	$p_{X Y}(x y) = \frac{p_{X,Y}(x, y)}{p_Y(y)}$	$f_{X Y}(x y) = \frac{f_{X,Y}(x, y)}{f_Y(y)}$
Conditional Expectation	$E[X Y = y] = \sum_x x p_{X Y}(x y)$	$E[X Y = y] = \int_{-\infty}^{\infty} x f_{X Y}(x y) dx$
Independence	$\forall x, y, p_{X,Y}(x, y) = p_X(x) p_Y(y)$	$\forall x, y, f_{X,Y}(x, y) = f_X(x) f_Y(y)$

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Tail Bounds (Idea)


Bounding the probability a random variable is far from its mean. Usually statements of the form:

$$\Pr(X \geq a) \leq b$$
$$\Pr(|X - E[X]| \geq a) \leq b$$

Useful tool when

- An approximation that is easy to compute is sufficient
- The process is too complex to analyze exactly

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Markov's Inequality

Theorem. Let X be a random variable taking only non-negative values. Then, for any $t > 0$,

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}.$$

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}[X]}{t}$$

$$\mathbb{P}(X \geq t \cdot \mathbb{E}(X)) \leq \frac{1}{t}.$$

Incredibly simplistic – only requires that the random variable is non-negative and only needs you to know expectation. You don't need to know **anything else** about the distribution of X .

Markov's Inequality – Proof

Theorem. Let X be a (discrete) random variable taking only non-negative values. Then, for any $t > 0$,

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}.$$

$$\mathbb{E}(X) = \sum_x x \cdot \mathbb{P}(X = x)$$

$$= \sum_{x \geq t} x \cdot \mathbb{P}(X = x) + \sum_{x < t} x \cdot \mathbb{P}(X = x)$$

Markov's Inequality – Proof

Theorem. Let X be a (discrete) random variable taking only non-negative values. Then, for any $t > 0$,

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}.$$

$$\mathbb{E}(X) = \sum_x x \cdot \mathbb{P}(X = x)$$

$$= \sum_{x \geq t} x \cdot \mathbb{P}(X = x) + \sum_{x < t} x \cdot \mathbb{P}(X = x)$$

≥ 0 because $x \geq 0$
whenever $\mathbb{P}(X = x) \geq 0$
(takes only non-negative values)

$$\geq \sum_{x \geq t} x \cdot \mathbb{P}(X = x)$$

$$\mathbb{E}[X] \geq t \cdot \mathbb{P}(X \geq t)$$

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}$$

$$\geq \sum_{x \geq t} t \cdot \mathbb{P}(X = x) = t \cdot \mathbb{P}(X \geq t)$$

Follows by re-arranging terms
...

QED

Example – Binomial Random Variable

Markov's inequality

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}.$$

Let X be Binomial RV with parameters. n, p


$$\mathbb{E}(X) = \frac{n}{2}$$

What is the probability that $X \geq \frac{3n}{4}$?

Markov's inequality: $\mathbb{P}\left(X \geq \frac{3n}{4}\right) \leq \frac{4}{3n} \cdot \frac{n}{2} = \frac{2}{3}$

Can we do better?

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Using variance

- If we know more about the random variable, e.g. its variance, we can get a better bound!

Chebyshev's Inequality

Markov's inequality
 $\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}$.

Theorem. Let X be a random variable. Then, for any $t > 0$,

$$\mathbb{P}(|X - \mathbb{E}(X)| \geq t) \leq \frac{\text{Var}(X)}{t^2}.$$

Proof: Define $Z = X - \mathbb{E}(X)$

$$\mathbb{P}(|Z| \geq t) = \mathbb{P}(Z^2 \geq t^2) \leq \frac{\mathbb{E}(Z^2)}{t^2} = \frac{\text{Var}(X)}{t^2}$$

$|Z| \geq t$ iff $Z^2 \geq t^2$

Markov's inequality ($Z^2 \geq 0$)

Definition of Variance

Example – Binomial Random Variable

Chebychev's Inequality

$$\mathbb{P}(|X - \mathbb{E}(X)| \geq t) \leq \frac{\text{Var}(X)}{t^2}.$$

Let X be Binomial RV with parameters. $n, p = 0.5$

$$\mathbb{E}(X) = \frac{n}{2} \qquad \text{Var}(X) =$$

What is the probability that $X \geq \frac{3n}{4}$?

Chebychev's inequality: $\mathbb{P}\left(X \geq \frac{3n}{4}\right) \leq$

Markov's inequality: $\mathbb{P}\left(X \geq \frac{3n}{4}\right) \leq \frac{4}{3n} \cdot \frac{n}{2} = \frac{2}{3}$

Tail Bounds

Useful for approximations of complex systems. How good the approximation is depends on the actual distribution and the context you are using it in.

- Usually loose upper-bounds are okay when designing for worst-case

Generally, the more you know about your random variable the better tail bounds you can get.