

CSE 326: Data Structures Don't Sweat It - Splay It

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AVL Trees: Are They Worth It?

Advantages

- Rotations are cool!

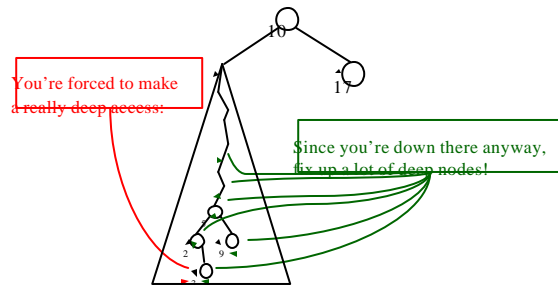
Disadvantages

- Wouldn't want to meet one in a dark alley at night

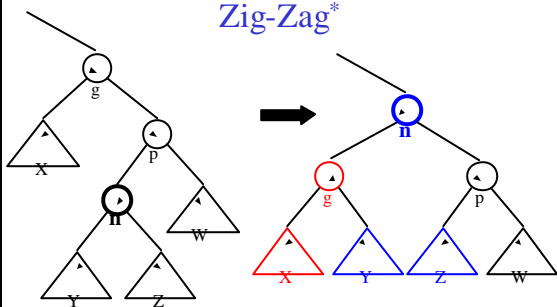
Splay What?

- Blind adjusting version of AVL trees
 - Why worry about balances? Just rotate anyway!
- *Amortized* time for all operations is $O(\log n)$
- Worst case time is $O(n)$
- Insert/Find always rotates node *to the root!*

Idea

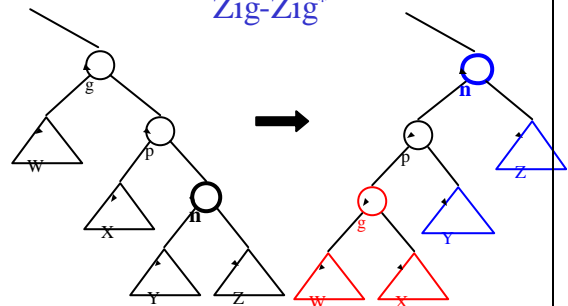


Zig-Zag*

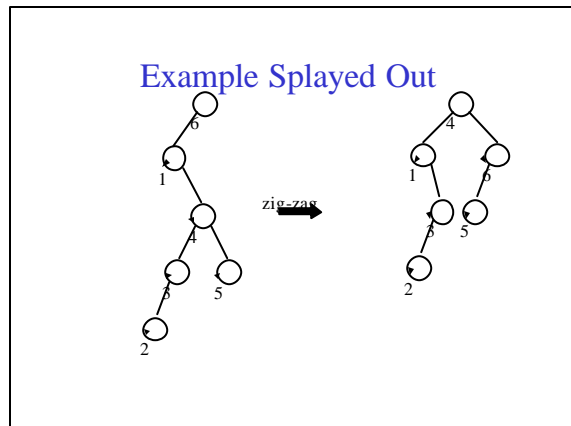
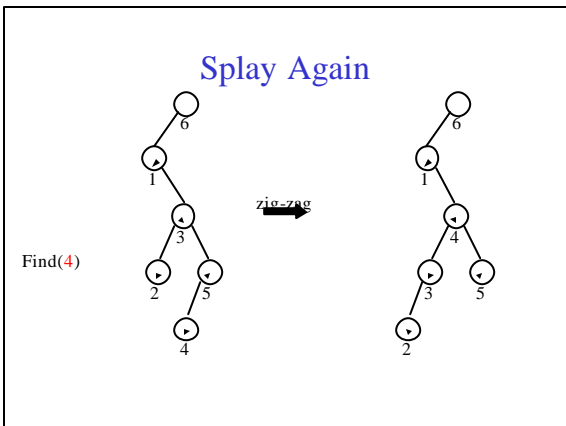
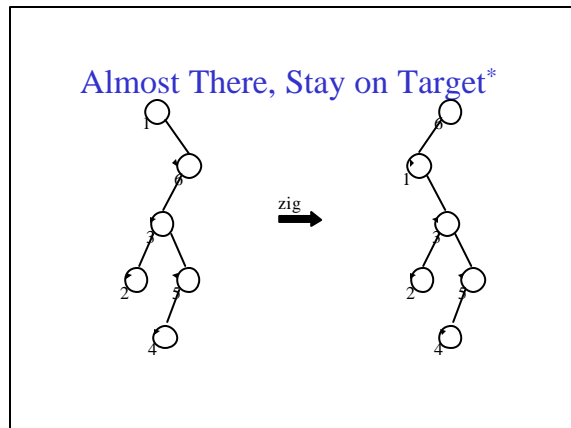
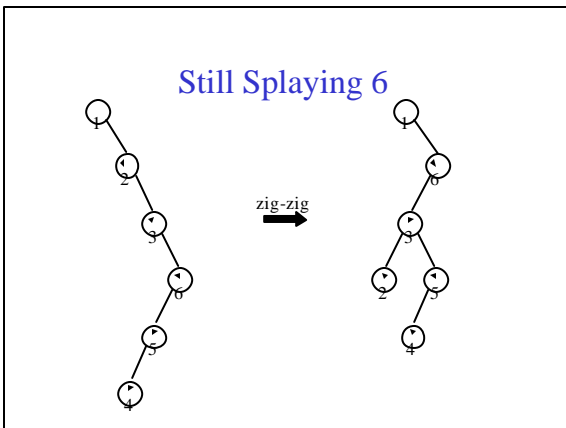
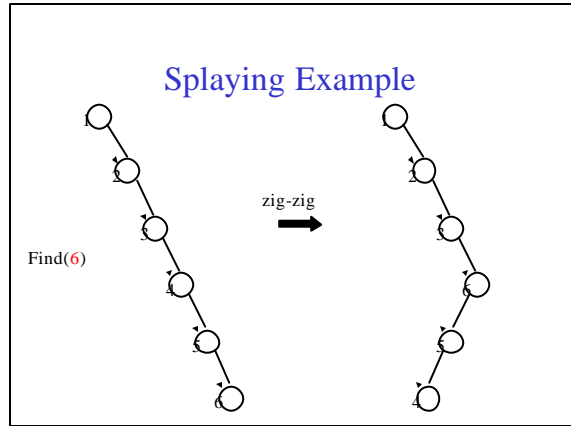
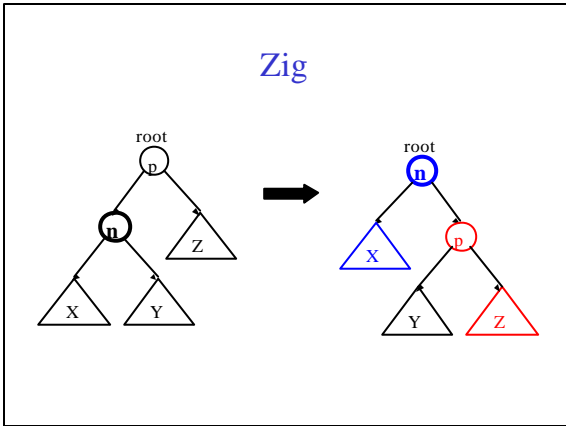


*This is just an AVL double rotation

Zig-Zig*



*Yes, the original 1985 paper actually uses this terminology!



Why Splaying Helps

- If a node n on the access path is at depth d before the splay, it's at about depth $d/2$ after the splay
 - Exceptions are the root, the child of the root, and the node splayed
- Overall, nodes which are below nodes on the access path tend to move closer to the root
- Splaying gets amortized $O(\log n)$ performance.

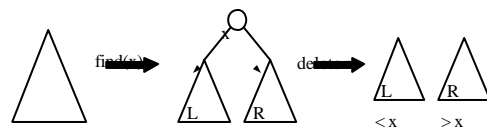
Splay Operations: Find

- Find the node in normal BST manner
- Splay the node to the root

Splay Operations: Insert

- Insert the node in normal BST manner
- Splay the node to the root

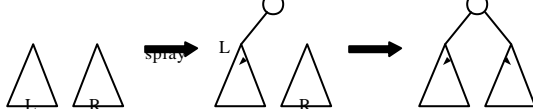
Splay Operations: Remove



Now what?

Join

- Join(L, R): given two trees such that $L < R$, merge them

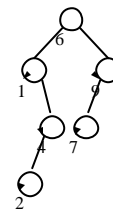


- Splay on the maximum element in L then attach R

Proof by analogy is not a valid proof technique!

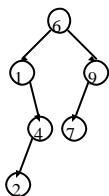
Insert Example

Insert(5)



Delete Example

Delete(4)



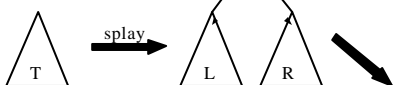
Nifty Splay Operation: Splitting

- Split(T, x) creates two BSTs L and R :
 - all elements of T are in either L or R ($T = L \dot{\cup} R$)
 - all elements in L are $\leq x$
 - all elements in R are $\geq x$
 - L and R share no elements ($L \cap R = \emptyset$)

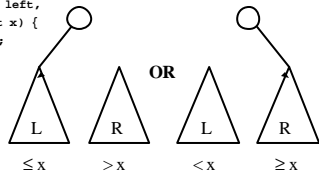
How do we split a splay tree?

Splitting Splays

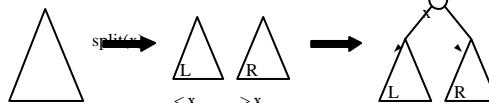
split(x)



```
void split(Node * root, Node *& left,
          Node *& right, Object x) {
    Node * target = root->find(x);
    splay(target);
    if (target < x) {
        left = target->left;
        target->left = NULL;
        right = target;
    }
    ...
}
```



Pssst: Another Way to Insert



```
void insert(Node *& root, Object x) {
    Node * left, * right;
    split(root, left, right, x);
    root = new Node(x, left, right);
}
```

Interesting note: split-and-insert was the original algorithm. But insert-and-splay has better constants

Splay Tree Summary

- All operations are in amortized $O(\log n)$ time
- Splaying can be done top-down; better because:
 - only one pass
 - no recursion or parent pointers necessary
- Splay trees are *very* effective search trees
 - Relatively simple
 - No extra fields required
 - **Excellent locality properties:** frequently accessed keys are cheap to find

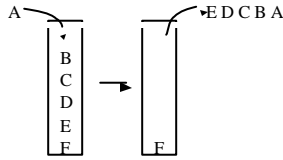
Interlude: Amortized Analysis

- Consider *any* sequence of operations applied to a data structure
 - *Your worst enemy could choose the sequence!*
- Some operations may be fast, others slow
- **Goal:**
 - Show that the average time per operation is still good

$$\frac{\text{total time for } n \text{ operations}}{n}$$

Stack ADT

- Stack operations
 - push
 - pop
 - isEmpty
- Stack property: if x is on the stack before y is pushed, then x will be popped after y is popped



What is biggest problem with an array implementation?

Stretchy Stack Implementation

```
int * data;           Best case Push ∈ O( )
int maxsize;        Worst case Push ∈ O( )
int top;

Push(e){
    if (top == maxsize){
        temp = new int[2*maxsize];
        for (i=0;i<maxsize;i++) temp[i]=data[i];
        delete data;
        data = temp;
        maxsize = 2*maxsize;
    } else { data[++top] = e; }
```

Stretchy Stack Amortized Analysis

- Consider sequence of n operations
push(3); push(19); push(2); ...
- What is the max number of stretches?
- What is the total time?
 - let's say a regular push takes time a , and stretching an array contain k elements takes time bk .

• Amortized time =

Series

• Arithmetic series: $\sum_{i=1}^N i = \frac{N(N+1)}{2}$

• Geometric series: $\sum_{i=0}^N A^i = \frac{A^{N+1}-1}{A-1}$

$$\sum_{i=0}^n 2^i = \frac{2^{n+1}-1}{2-1} = 2^{n+1}-1$$

$$\sum_{i=0}^{\log n} 2^i = \frac{2^{\log n+1}-1}{2-1} = (2^{\log n})2^1 - 1 = 2n-1$$

Moral of the Story

- For more complicated analyses, this procedure is formalized with the idea of *credit*
- We said that a splay was $O(\log n)$
 - Always *invest* $\log n$ per splay
 - For an easy splay, *bank* the leftover money
 - For a hard splay, *use* money from the bank
 - Prove there's *always* enough money in the bank for any operation



Bug Brian or Hannah for more references on amortized analysis!