

# CSE 326: Data Structures

## Mind Your Priority Queues

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Winter Quarter 2003

## Today's Outline

- Finish Asymptotic Analysis
- Questions
- Trees Review
- Priority Queues
- Heaps
- d-Heaps

## Simplifying Recurrences

1. Given some equation for the running time:  
e.g.  $T(n) = \log \lfloor \text{floor}(n/2) \rfloor$
2. Solve the recursive equation
  - For an **upper-bound** analysis, you can optionally simplify the equation to something **larger**  
e.g.  $T(n) = T(\text{floor}(n/2)) + 1 \preceq T(n) < T(n/2) + 1$
  - For a **lower-bound** analysis, you can optionally simplify the equation to something **smaller**  
e.g.  $T(n) = 2T(N/2 + 1) + 1 \preceq T(n) > 2T(N/2) + 1$

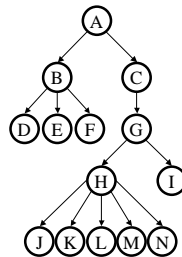
## The One Page Cheat Sheet

- **Calculating series:**  
e.g.  $\sum_{i=1}^n i ? \frac{n(n+1)}{2}$
- **Solving recurrences:**  
e.g.  $T(n) = T(N/2) + 1$ 
  1. Brute force (Section 1.2.3)
  1. Expansion (example in class)
  2. Induction (Section 1.2.5)
  2. Induction (Section 1.2.5, slides)
  3. Memorize simple ones!
  3. Telescoping (later...)
- **General proofs (Section 1.2.5)**  
e.g. How many edges in a binary tree?
  1. Counterexample
  2. Induction
  3. Contradiction

(we'll see more examples coming up)

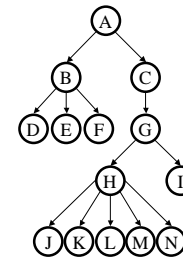
## Tree Review

root:  
leaf:  
child:  
parent:  
sibling:  
ancestor:  
descendent:  
subtree:



## More Tree Terminology

depth:  
height:  
degree:  
branching factor:

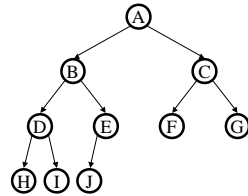


## One More Tree Terminology Slide

binary:

n-ary:

complete:



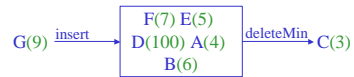
## Back to Queues

- Some applications
  - ordering CPU jobs
  - simulating events
  - picking the next search site
- Problems?
  - short jobs **should go first**
  - earliest (simulated time) events **should go first**
  - most promising sites **should be searched first**

**Remember ADTs?**

## Priority Queue ADT

- Priority Queue operations
  - create
  - destroy
  - insert
  - deleteMin
  - is\_empty
- Priority Queue property: for two elements in the queue,  $x$  and  $y$ , if  $x$  has a lower priority value than  $y$ ,  $x$  will be deleted before  $y$



## Applications of the Priority Q

- Hold jobs for a printer in order of length
- Store packets on network routers in order of urgency
- Simulate events
- Select symbols for compression
- Sort numbers
- Anything *greedy*

## Naïve Priority Q Data Structures

- Unsorted array:
  - insert:
  - deleteMin:
- Sorted array:
  - insert:
  - deleteMin:

## Binary Search Tree Priority Q Data Structure (that's a mouthful)

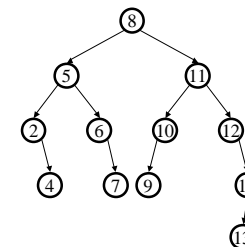
Average performance  
insert:

deleteMin:

Problems

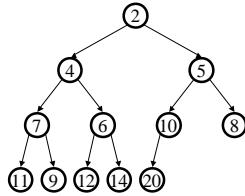
1.

2.



## Binary Heap Priority Q Data Structure

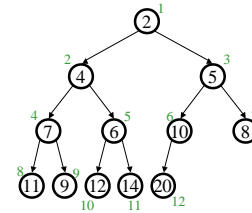
- Heap-order property
  - parent's key is less than children's keys
  - result: minimum is always at the top
- Structure property
  - complete tree with fringe nodes packed to the left
  - result: depth is always  $O(\log n)$ ; next open location always known



How do we find the minimum?

## Nifty Storage Trick

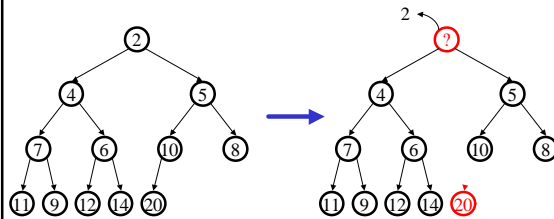
- Calculations:
  - child:
  - parent:
  - root:
  - next free:



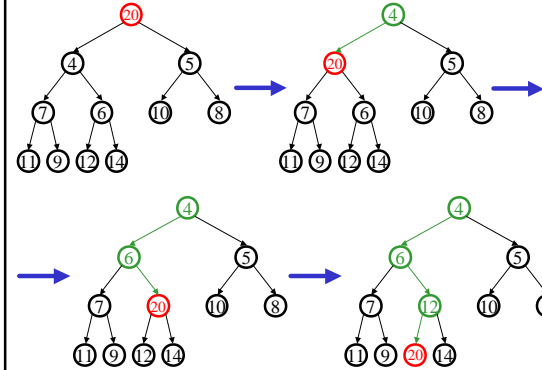
0	1	2	3	4	5	6	7	8	9	10	11	12
12	2	4	5	7	6	10	8	11	9	12	14	20

## DeleteMin

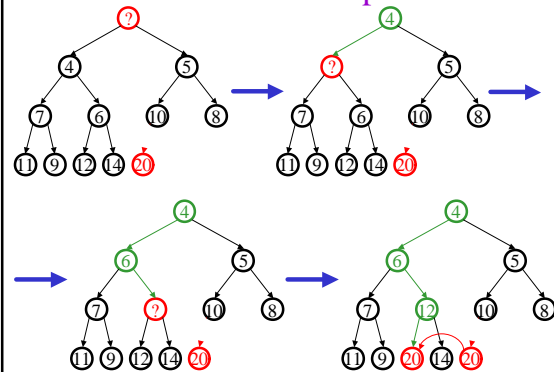
pqueue.deleteMin()



## Percolate Down – Basic



## Percolate Down – Optimized



## DeleteMin Code (Optimized)

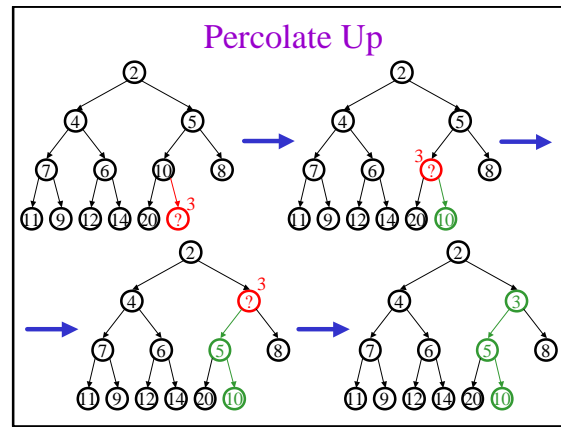
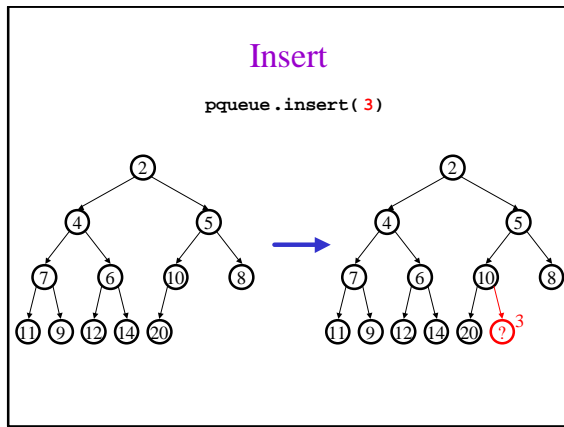
```

Object deleteMin() {
    assert(!isEmpty());
    returnVal = Heap[1];
    size--;
    newPos =
        percolateDown(1,
            Heap[size+1]);
    Heap[newPos] =
        Heap[size + 1];
    return returnVal;
}

int percolateDown(int hole,
    object val) {
    while (2*hole <= size) {
        left = 2*hole;
        right = left + 1;
        if (right <= size &&
            Heap[right] < Heap[left])
            target = right;
        else
            target = left;

        if (Heap[target] < val) {
            Heap[hole] = Heap[target];
            hole = target;
        }
        else
            break;
    }
    return hole;
}
    
```

runtime:



### Insert Code

```

void insert(Object o) {
    assert(!isFull());
    size++;
    newPos =
        percolateUp(size,o);
    Heap[newPos] = o;
}

int percolateUp(int hole,
                Object val) {
    while (hole > 1 &&
           val < Heap[hole/2])
        Heap[hole] = Heap[hole/2];
        hole /= 2;
    return hole;
}
    
```

*runtime:*

### Other Priority Queue Operations

- **decreaseKey**
  - given a pointer to an object in the queue, reduce its priority value

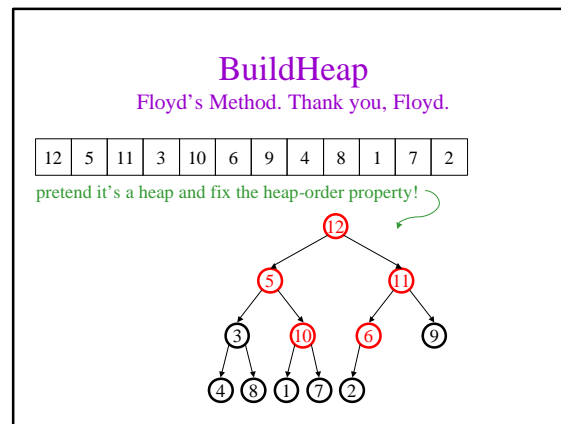
Solution: change priority and \_\_\_\_\_
- **increaseKey**
  - given a pointer to an object in the queue, increase its priority value

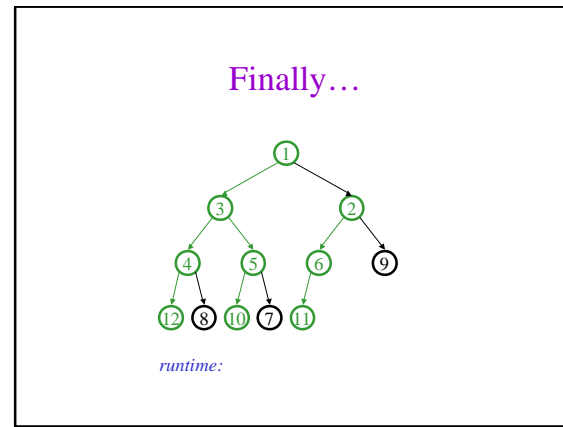
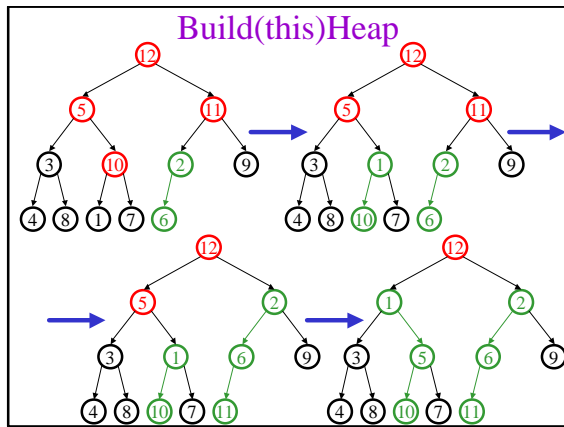
Solution: change priority and \_\_\_\_\_

### Still More Priority Queue Operations

- **remove**
  - given a pointer to an object in the queue, remove it

Solution: set priority to negative infinity, percolate up to root and deleteMin
- **buildHeap**
  - Naïve solution:
  - Running time:
  - Can we do better?





- ### Thinking about Heaps
- Observations
    - finding a child/parent index is a multiply/divide by two
    - operations jump widely through the heap
    - each operation looks at only two new nodes
    - inserts are at least as common as deleteMins
  - Realities
    - division and multiplication by powers of two are **fast**
    - looking at one new piece of data sucks in a cache line
    - with **huge** data sets, disk accesses dominate

- ### Solution: d-Heaps
- Each node has  $d$  children
  - Still representable by array
  - Good choices for  $d$ :
    - optimize performance based on # of inserts/removes
    - choose a power of two for efficiency
    - fit one set of children in a cache line
    - fit one set of children on a memory page/disk block
- 12 1 3 7 2 4 8 5 12 11 10 6 9
- Does this help **insert** or **deleteMin** more?

- ### One More Operation
- Merge two heaps. Ideas?

- ### To Do
- Finish Homework #1
    - Start Homework #2 if you've already finished
  - Read chapter 6 in the book

## Coming Up

- Mergable Priority Q's
- Leftist heaps
- Skew heaps
  
- No class on July 4!!!

