

BucketSort (aka BinSort)

If all values to be sorted are *known* to be between 1 and K , create an array `count` of size K , **increment** counts while traversing the input, and finally output the result.

Example $K=5$. Input = (5,1,3,4,3,2,1,1,5,4,5)

count array	
1	
2	
3	
4	
5	



Running time to sort n items?

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BucketSort Complexity: $O(n+K)$

- Case 1: K is a constant
 - BinSort is linear time
- Case 2: K is variable
 - Not simply linear time
- Case 3: K is constant but large (e.g. 2^{32})
 - ???

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Fixing impracticality: RadixSort

- Radix = “The base of a number system”
 - We’ll use 10 for convenience, but could be anything
- Idea: BucketSort on each **digit**, least significant to most significant (lsd to msd)

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Radix Sort Example (1st pass)

Input data	Bucket sort by 1's digit	After 1 st pass
478		721
537		3
9		123
721		537
3		67
38		478
123		38
67		9

0	1	2	3	4	5	6	7	8	9
	721		3				537	478	9
			123				67	38	

This example uses $B=10$ and base 10 digits for simplicity of demonstration. Larger bucket counts should be used in an actual implementation.

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Radix Sort Example (2nd pass)

After 1 st pass	Bucket sort by 10's digit	After 2 nd pass
721		3
3		9
123		721
537		123
67		537
478		38
38		67
9		478

0	1	2	3	4	5	6	7	8	9
03	721	537				67	478		
09		123	38						

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Radix Sort Example (3rd pass)

After 2 nd pass	Bucket sort by 100's digit	After 3 rd pass
3		3
9		9
721		38
123		67
537		123
38		478
67		537
478		721

0	1	2	3	4	5	6	7	8	9
003	123			478	537		221		
009									
038									
067									

Invariant: after k passes the low order k digits are sorted.

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Radixsort: Complexity

- How many passes?
- How much work per pass?
- Total time?
- Conclusion?
- In practice
 - RadixSort only good for large number of elements with relatively small values
 - Hard on the cache compared to MergeSort/QuickSort

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Internal versus External Sorting

- Need sorting algorithms that minimize disk/tape access time
- **External sorting** – Basic Idea:
 - Load chunk of data into RAM, sort, store this “run” on disk/tape
 - Use the Merge routine from Mergesort to merge runs
 - Repeat until you have only one run (one sorted chunk)
 - Text gives some examples

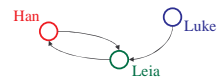
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Graphs

Chapter 9 in Weiss

Graph... ADT?

- Not quite an ADT... operations not clear
- A formalism for representing relationships between objects



Graph $G = (V, E)$

– Set of vertices:

$V = \{v_1, v_2, \dots, v_n\}$

– Set of edges:

$E = \{e_1, e_2, \dots, e_m\}$

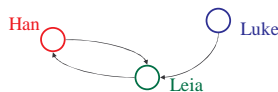
where each e_i connects two vertices (v_{i1}, v_{i2})

$V = \{\text{Han}, \text{Leia}, \text{Luke}\}$
 $E = \{(\text{Luke}, \text{Leia}), (\text{Han}, \text{Leia}), (\text{Leia}, \text{Han})\}$

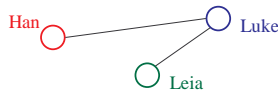
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Graph Definitions

In *directed* graphs, edges have a specific direction:



In *undirected* graphs, they don't (edges are two-way):



v is *adjacent* to u if $(u, v) \in E$

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More Definitions: Simple Paths and Cycles

A *simple path* repeats no vertices (except that the first can be the last):

$p = \{\text{Seattle}, \text{Salt Lake City}, \text{San Francisco}, \text{Dallas}\}$

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A *cycle* is a path that starts and ends at the same node:

$p = \{\text{Seattle}, \text{Salt Lake City}, \text{Dallas}, \text{San Francisco}, \text{Seattle}\}$

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A *simple cycle* is a cycle that repeats no vertices except that the first vertex is also the last (in undirected graphs, no edge can be repeated)

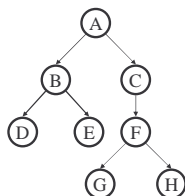
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Trees as Graphs

- Every tree is a graph!
- Not all graphs are trees!

A graph is a tree if

- There are *no cycles* (directed or undirected)
- There is a *path* from the root to *every node*

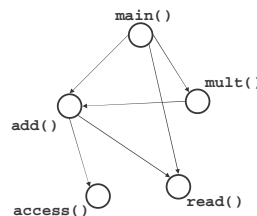


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Directed Acyclic Graphs (DAGs)

DAGs are directed graphs with no (directed) cycles.

Aside: If program call-graph is a DAG, then all procedure calls can be in-lined



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Graph Representations

0. List of vertices + list of edges
1. 2-D matrix of vertices (marking edges in the cells) "adjacency matrix"
2. List of vertices each with a list of adjacent vertices "adjacency list"



Things we might want to do:

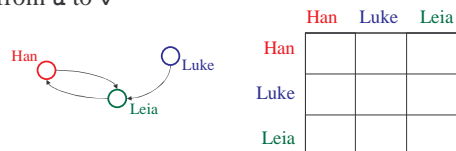
- iterate over vertices
- iterate over edges
- iterate over vertices adj. to a vertex
- check whether an edge exists

Vertices and edges may be labeled

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Representation 1: Adjacency Matrix

A $|V| \times |V|$ array in which an element (u, v) is true if and only if there is an edge from u to v



space requirements:

runtime:

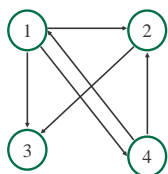
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Representation

- adjacency **matrix**:

$$A[u][v] = \begin{cases} \text{weight} & , \text{ if } (u, v) \in E \\ 0 & , \text{ if } (u, v) \notin E \end{cases}$$

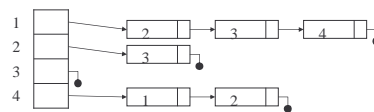
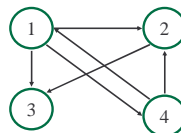
	1	2	3	4
1				
2				
3				
4				



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Representation

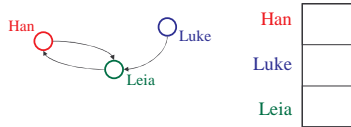
- adjacency **list**:



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Representation 2: Adjacency List

A $|\mathcal{V}|$ -ary list (array) in which each entry stores a list (linked list) of all adjacent vertices

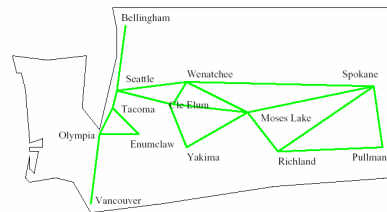


space requirements:

runtime:

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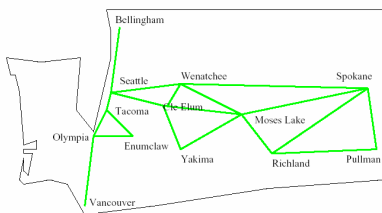
Some Applications: Moving Around Washington



What's the *shortest* way to get from Seattle to Pullman?
Edge labels:

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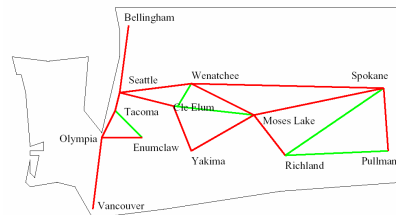
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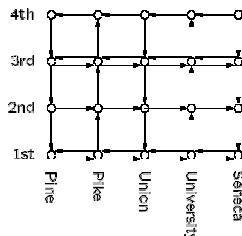
Some Applications: Reliability of Communication



If Wenatchee's phone exchange *goes down*,
can Seattle still talk to Pullman?

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Some Applications: Bus Routes in Downtown Seattle

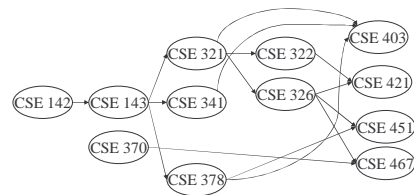


If we're at 3rd and Pine, how can we get to
1st and University using Metro?

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Application: Topological Sort

Given a directed graph, $G = (\mathcal{V}, \mathcal{E})$, output all the vertices in \mathcal{V} such that no vertex is output before any other vertex with an edge to it.



Is the output unique?

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Topological Sort: Take One

1. Label each vertex with its *in-degree* (# of inbound edges)
2. **While** there are vertices remaining:
 - a. Choose a vertex v of *in-degree zero*; output v
 - b. Reduce the in-degree of all vertices adjacent to v
 - c. Remove v from the list of vertices

Runtime:

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```
void Graph::topsort(){
    Vertex v, w;

    labelEachVertexWithItsIn-degree();

    for (int counter=0; counter < NUM_VERTICES;
         counter++){
        v = findNewVertexOfDegreeZero();

        v.topologicalNum = counter;
        for each w adjacent to v
            w.indegree--;
    }
}
```

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