







 Defn: The load factor, λ, of a hash table is the ratio: <sup>N</sup> ← no. of elements
 <sup>M</sup> ← table size

For separate chaining,  $\lambda$  = average # of elements in a bucket

- Unsuccessful find cost:
- · Successful find cost:

How big should the hash table be?

• For Separate Chaining:

### Closed Hashing (Open Addressing)

- No chaining, every key fits in the hash table.
- Probe sequence
  - > h(k)
  - (h(k) + f(1)) mod HSize
     (h(k) + f(2)) mod HSize , ...
- Insertion: Find the first probe with an empty slot.
- Find: Find the first probe that equals the query or is empty. Stop at HSize probe, in any case.
- Deletion: lazy deletion is needed. That is, mark locations as deleted, if a deleted key resides there.









Write pseudocode for find(k) for Open Addressing with linear probing
Find(k) returns i where T(i) = k



Student Activity







Quadratic Probing Example				
$\frac{1}{76\%7} = 6$	insert(40) 40%7 = 5	insert(48) 48%7 = 6	insert(5) 5%7 = 5	insert(55) 55%7 = 6
1			But.	insert(47) 47%7 = 5
3				
5				
<sup>6</sup> 76				







### **Double Hashing**

f(i) = i \* g(k)where g is a second hash function

#### • Probe sequence:

 $\begin{array}{l} 0^{th} \mbox{ probe } = \mbox{ h}(k) \mbox{ mod TableSize} \\ 1^{th} \mbox{ probe } = \mbox{ (h}(k) + \mbox{ g}(k)) \mbox{ mod TableSize} \\ 2^{th} \mbox{ probe } = \mbox{ (h}(k) + \mbox{ 2*g}(k)) \mbox{ mod TableSize} \\ 3^{th} \mbox{ probe } = \mbox{ (h}(k) + \mbox{ 3*g}(k)) \mbox{ mod TableSize} \\ & \cdots \\ i^{th} \mbox{ probe } = \mbox{ (h}(k) + \mbox{ i*g}(k)) \mbox{ mod TableSize} \end{array}$ 









### Rehashing

- Idea: When the table gets too full, create a bigger table (usually 2x as large) and hash all the items from the original table into the new table.
- When to rehash?
  - $\rightarrow$  half full ( $\lambda$  = 0.5)
  - > when an insertion fails
  - > some other threshold
- · Cost of rehashing?





## Amortized Analysis of Rehashing

- Cost of inserting n keys is < 3n
- 2<sup>k</sup> + 1 < n < 2<sup>k+1</sup>
- Hashes = n
- > Rehashes =  $2 + 2^2 + ... + 2^k = 2^{k+1} 2$
- > Total = n +  $2^{k+1} 2 < 3n$
- Example > n = 33, Total = 33 + 64 -2 = 95 < 99





#### Analysis • Binary Search Storage = N pointers + words = 360,000 bytes Time = $\log_2 N \le 15$ probes in worst case Open hashing

- Storage =  $2N + N/\lambda$  pointers + words
- $\lambda = 1$  implies 600,000 bytes
- > Time = 1 +  $\lambda/2$  probes per access  $\lambda$  = 1 implies 1.5 probes per access

#### Closed hashing

- > Storage = N/ $\lambda$  pointers + words  $\lambda$  = 1/2 implies 480,000 bytes
- Time =  $(1/2)(1+1/(1-\lambda))$  probes  $\lambda = 1/2$  implies 1.5 probes per access

#### Extendible Hashing Extendible hashing is a technique for storing large data sets that do not fit in memory. • An alternative to B-trees 3 bits of hash value used 000 001 010 011 100 101 110 111 In memory (2) 00001 00011 (2) 01001 01011 (2) 11001 11011 (3) Pages 10001 10011 10101 10110 11100 11110 00100 01100 10111 00110





# **Fingerprints**

- · Given a string x we want a fingerprint x' with the properties.
  - > x' is short, say 128 bits
  - > Given  $x \neq y$  the probability that x' = y' is infinitesimal (almost zero)
  - > Computing x' is very fast
- MD5 Message Digest Algorithm 5 is a recognized standard
- · Applications in databases and cryptography

# **Fingerprint Math**

Given 128 bits and N strings what is the probability that the fingerprints of two strings coincide?

$$1 - \frac{2^{128}(2^{128} - 1)L(2^{128} - N + 1)}{(2^{128})^{N}}$$

This is essentially zero for  $N < 2^{40}$ .

# Hashing Summary

- Hashing is one of the most important data structures.
- Hashing has many applications where operations are limited to find, insert, and delete.
- Dynamic hash tables have good amortized complexity.