

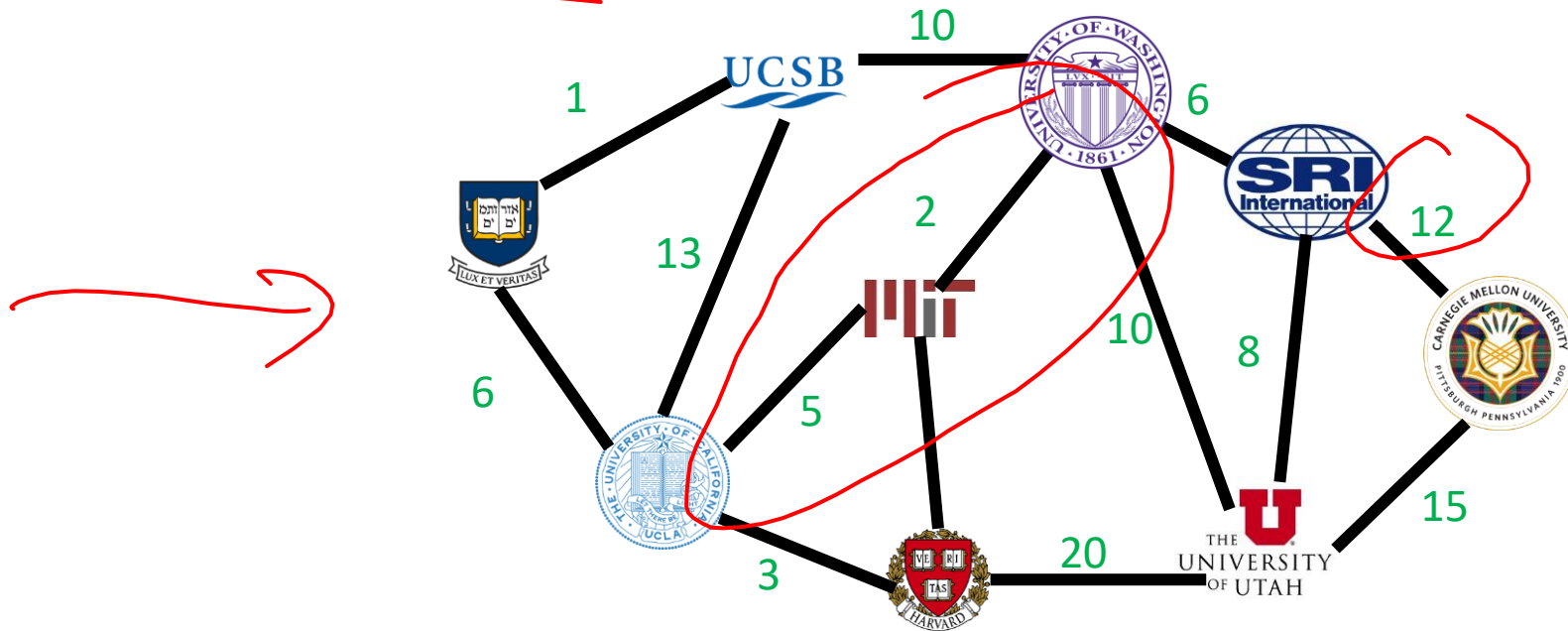
# CSE 332 Winter 2024

## Lecture 18: Dijkstra's, ForkJoin

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<http://www.cs.uw.edu/332>

# Single-Source Shortest Path



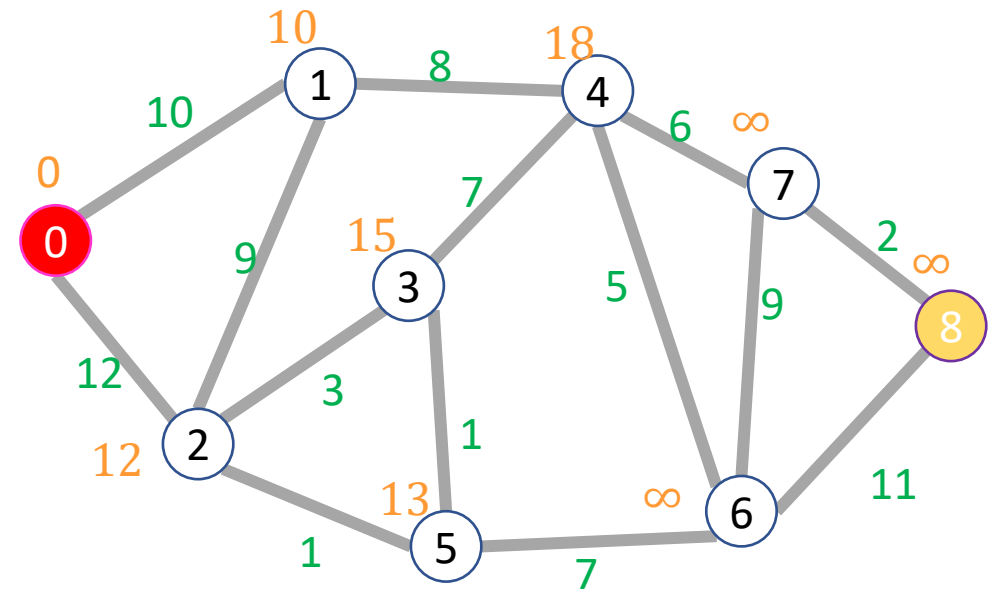
Find the quickest way to get from UVA to each of these other places

Given a graph  $G = (V, E)$  and a start node  $s \in V$ , for each  $v \in V$  find the least-weight path from  $s \rightarrow v$  (call this weight  $\delta(s, v)$ )

(assumption: all edge weights are positive)

# Dijkstra's Algorithm

- Input: graph with **no negative edge weights**, start node  $s$ , end node  $t$
- Behavior: Start with node  $s$ , repeatedly go to the incomplete node "nearest" to  $s$ , stop when
- Output:
  - Distance from start to end
  - Distance from start to every node



# Dijkstra's Algorithm

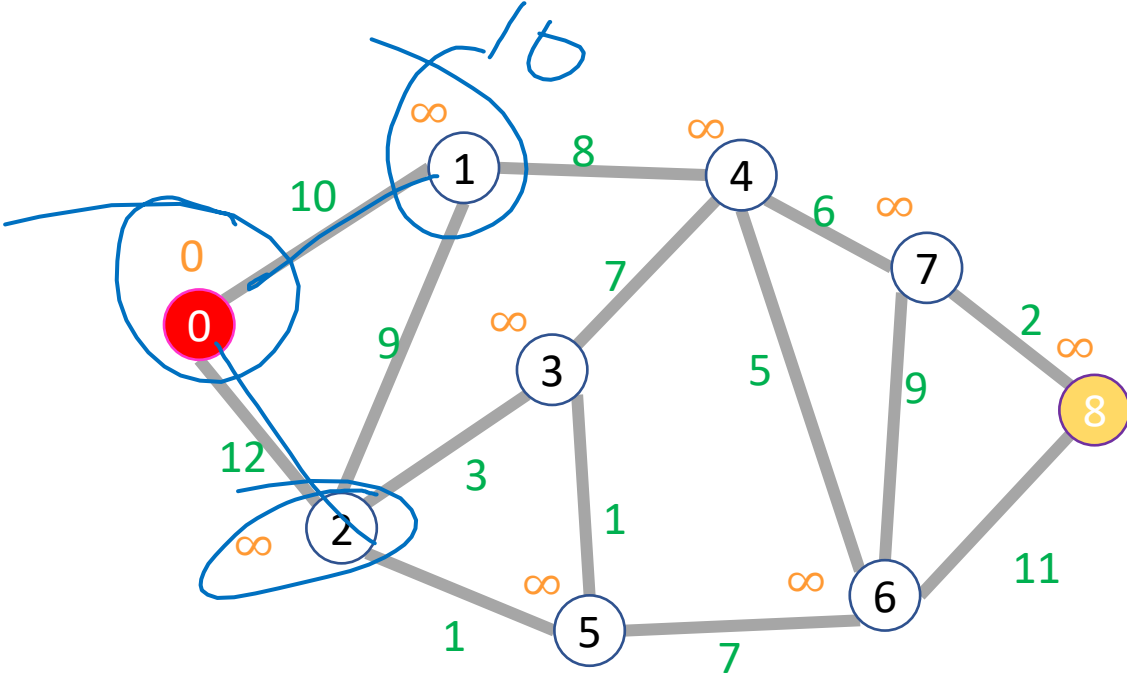
Start: 0

End: 8

Node	Done?
0	F
1	F
2	F
3	F
4	F
5	F
6	F
7	F
8	F

Node	Distance
0	0
1	$\infty$
2	$\infty$
3	$\infty$
4	$\infty$
5	$\infty$
6	$\infty$
7	$\infty$
8	$\infty$

Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path



# Dijkstra's Algorithm

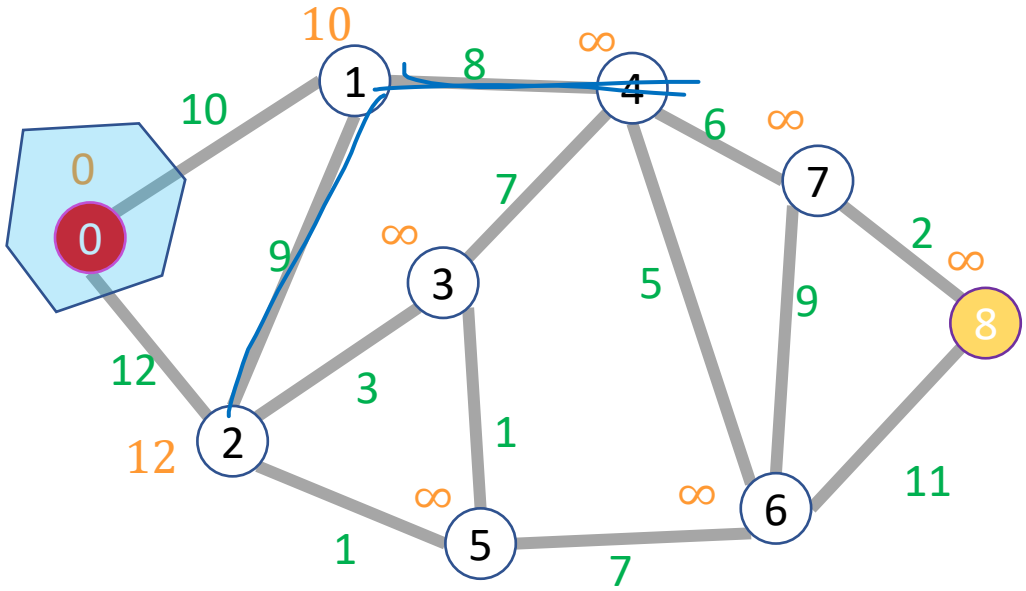
Start: 0

End: 8

Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path

Node	Done?
0	T
1	<del>F</del>
2	F
3	F
4	F
5	F
6	F
7	F
8	F

Node	Distance
0	0
1	10
2	12
3	$\infty$
4	<del><math>\infty</math></del> 18
5	$\infty$
6	$\infty$
7	$\infty$
8	$\infty$



# Dijkstra's Algorithm

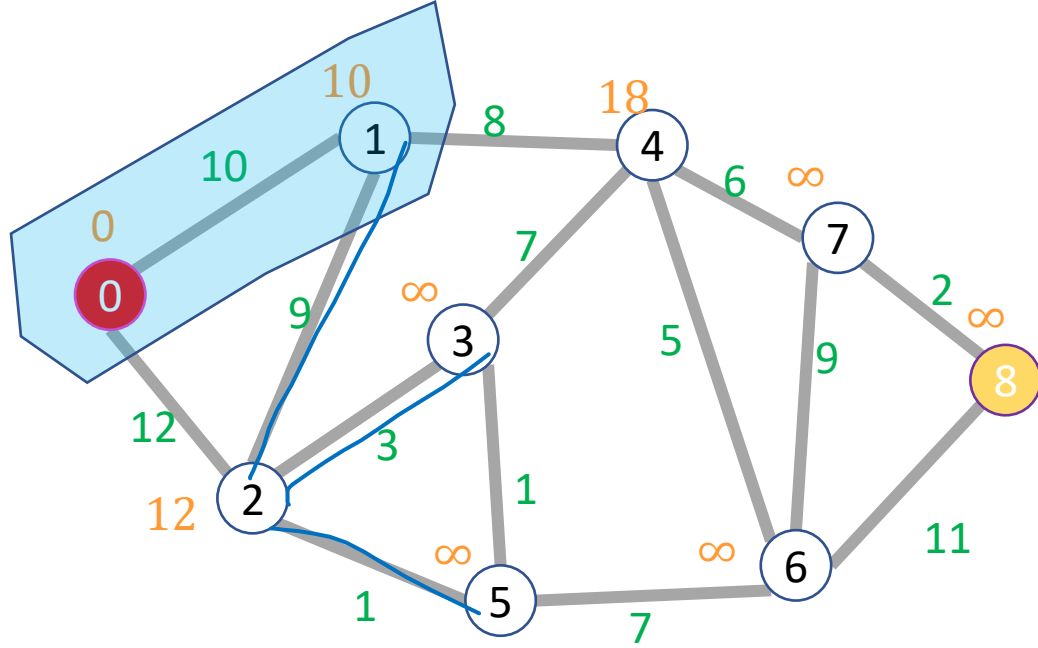
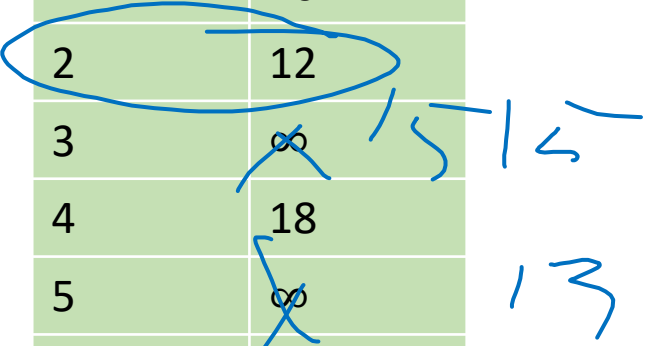
Start: 0

End: 8

Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path

Node	Done?
0	T
1	T
2	F
3	F
4	F
5	F
6	F
7	F
8	F

Node	Distance
0	0
1	10
2	12
3	<del>∞</del>
4	18
5	<del>∞</del>
6	∞
7	∞
8	∞



# Dijkstra's Algorithm

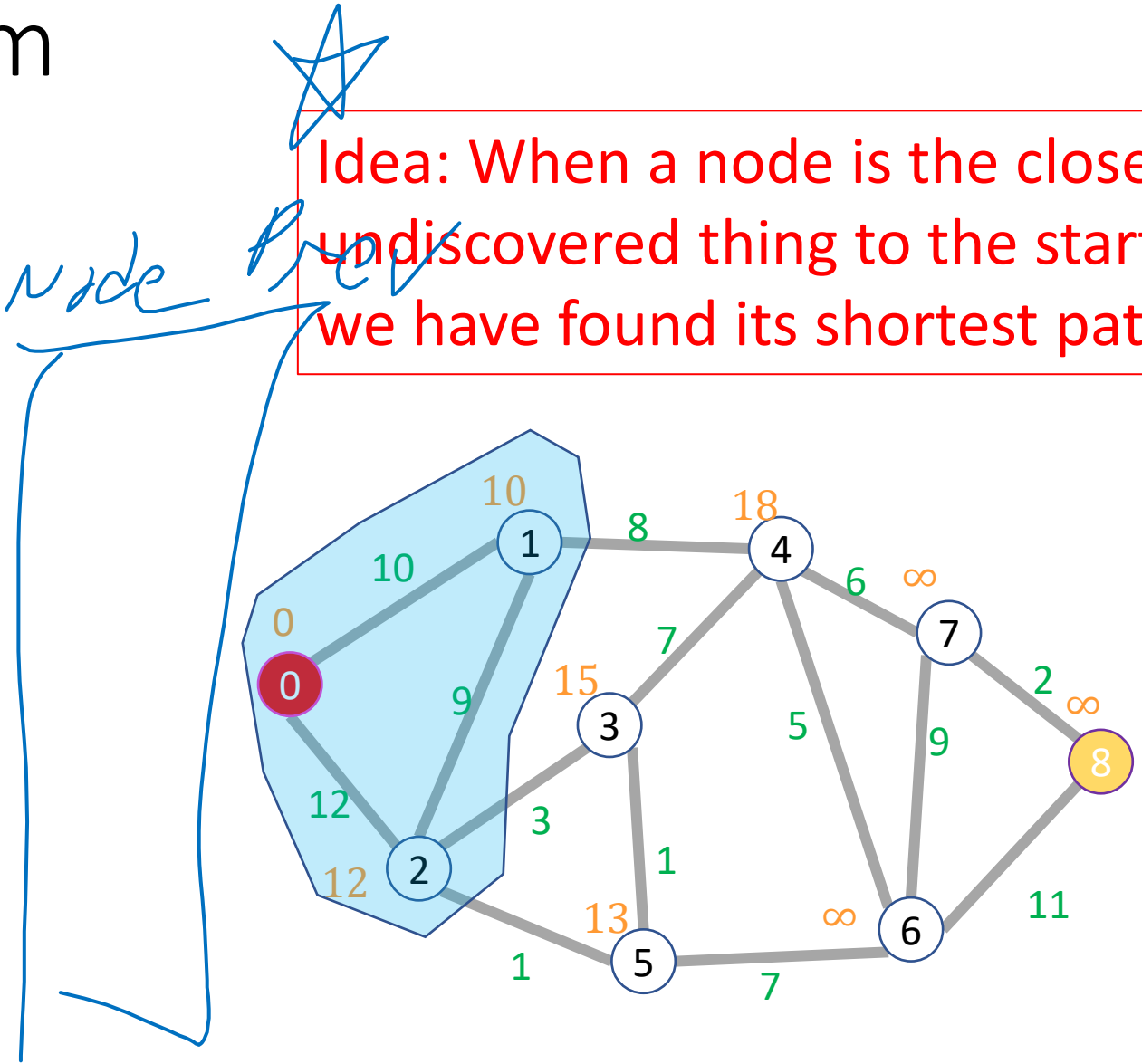
Start: 0

End: 8

Node	Done?
0	T
1	T
2	T
3	F
4	F
5	F
6	F
7	F
8	F

Node	Distance
0	0
1	10
2	12
3	15
4	18
5	13
6	$\infty$
7	$\infty$
8	$\infty$

Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path



# Dijkstra's Algorithm

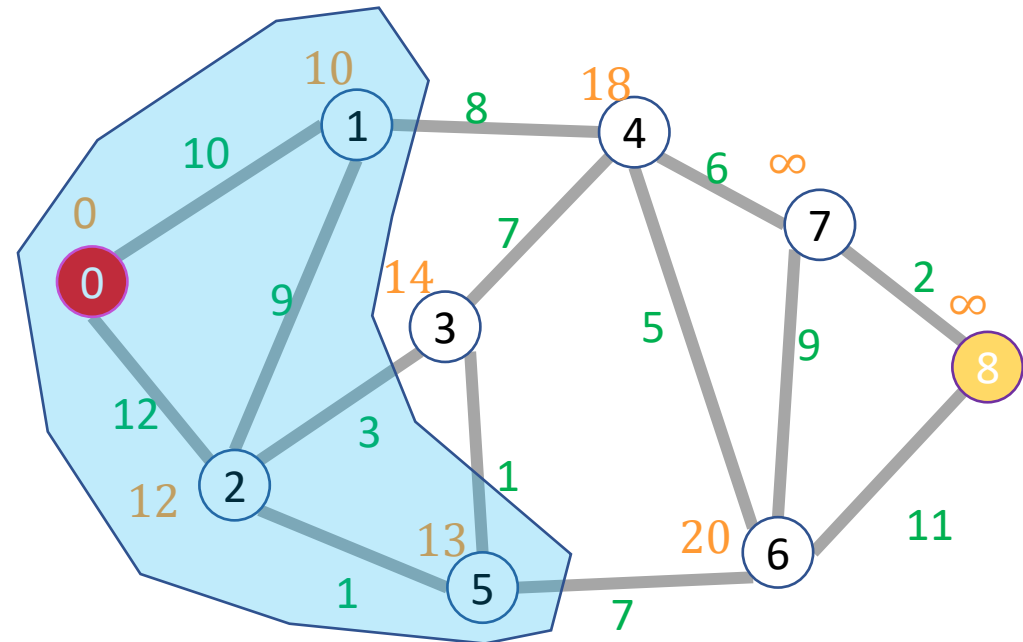
Start: 0

End: 8

Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path

Node	Done?
0	T
1	T
2	T
3	F
4	F
5	T
6	F
7	F
8	F

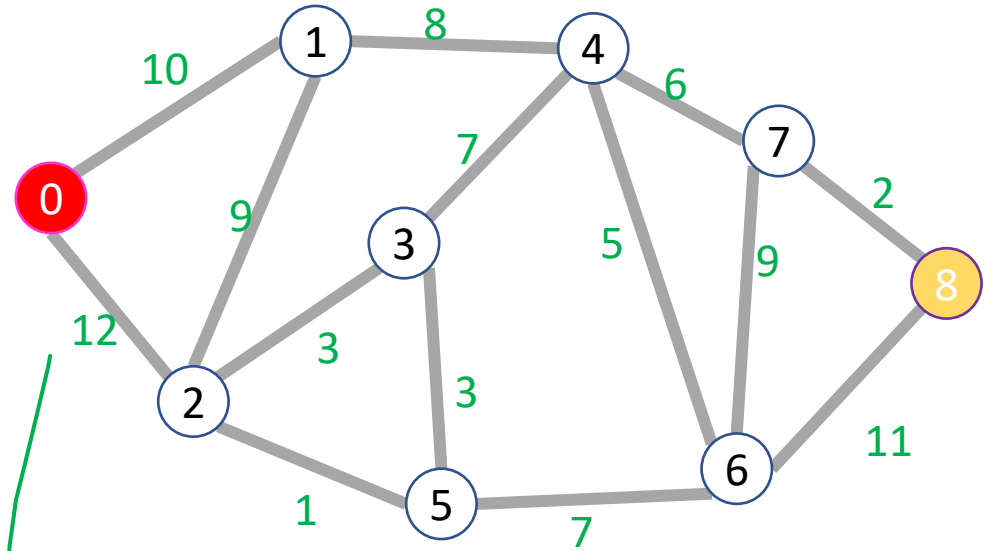
Node	Distance
0	0
1	10
2	12
3	14
4	18
5	13
6	$\infty$
7	20
8	$\infty$





# Dijkstra's Algorithm

```
int dijkstras(graph, start, end){  
    distances = [ $\infty$ ,  $\infty$ ,  $\infty$ , ...]; // one index per node  
    done = [False, False, False, ...]; // one index per node  
    PQ = new minheap();  
    PQ.insert(0, start); // priority=0, value=start  
    distances[start] = 0;  
    while (!PQ.isEmpty){  
        current = PQ.deleteMin();  
        done[current] = true;  
        for (neighbor : current.neighbors){  
            if (!done[neighbor]){  
                new_dist = distances[current]+weight(current,neighbor);  
                if (distances[neighbor] ==  $\infty$ ) {PQ.insert(neighbor, new_dist);}  
                if (new_dist < distances[neighbor]){  
                    distances[neighbor] = new_dist;  
                    PQ.decreaseKey(new_dist,neighbor); }  
            }  
        }  
    }  
    return distances[end]  
}
```

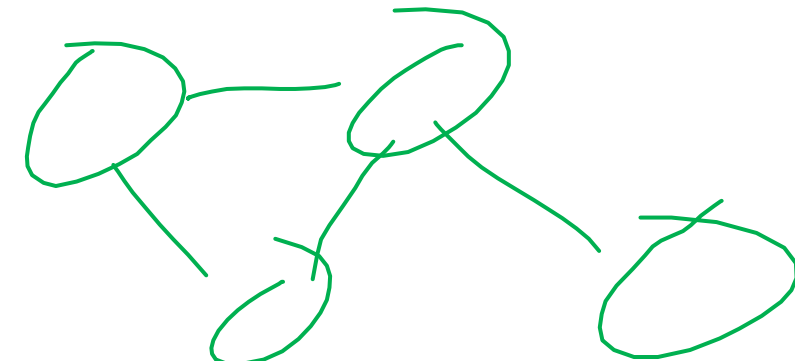


2/E/

# Dijkstra's Algorithm: Running Time

$$E \log V + V \log V$$

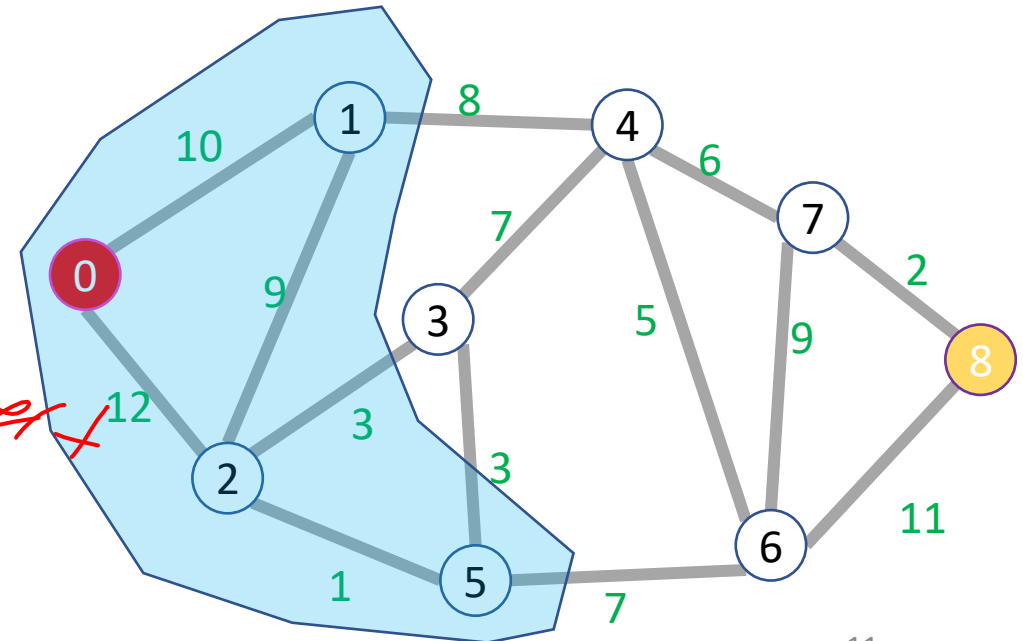
- How many total priority queue operations are necessary?
  - How many times is each node added to the priority queue?
  - How many times might a node's priority be changed?
- What's the running time of each priority queue operation?
  - $\log |V|$
- Overall running time:
  - $\Theta(|E| \log |V|)$



# Dijkstra's Algorithm: Correctness

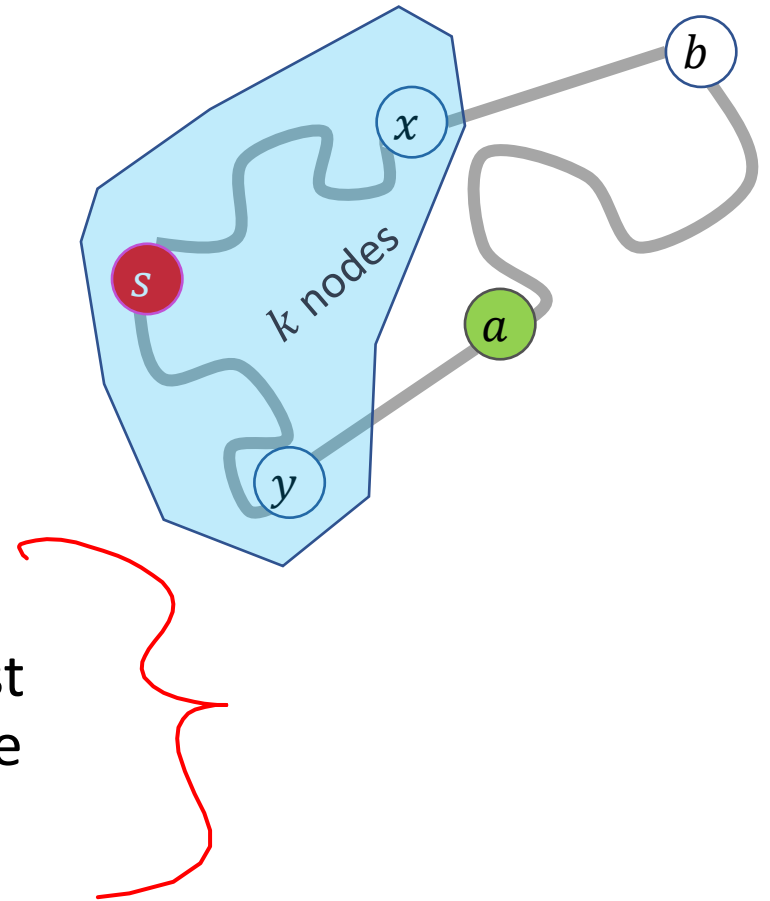
- Claim: when a node is removed from the priority queue, we have found its shortest path
- Induction over number of completed nodes
- Base Case: *start*
- Inductive Step:

*as assume all  $\uparrow$  nodes were correct*



# Dijkstra's Algorithm: Correctness

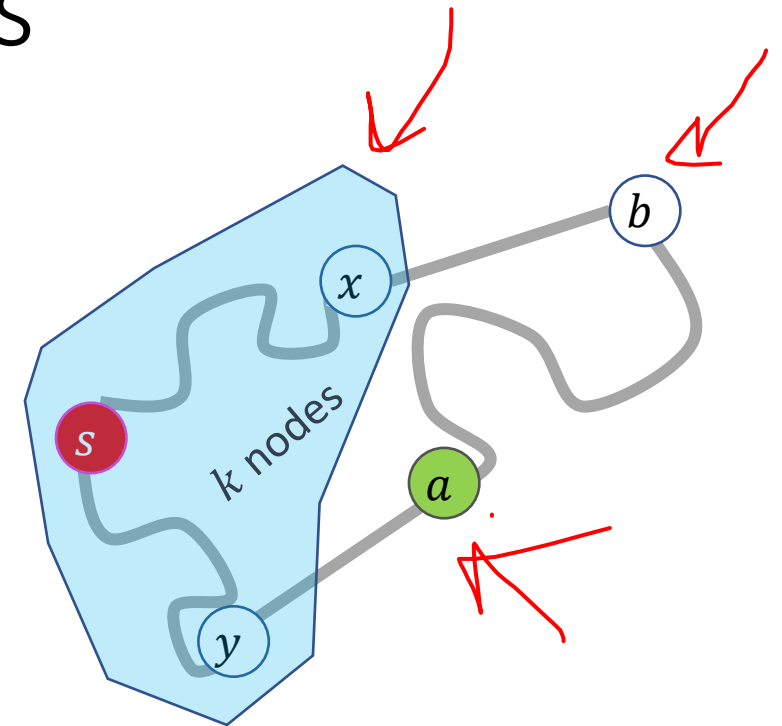
- Claim: when a node is removed from the priority queue, its distance is that of the shortest path
- Induction over number of completed nodes
- Base Case: Only the start node removed
  - It is indeed 0 away from itself
- Inductive Step:
  - If we have correctly found shortest paths for the first  $k$  nodes, then when we remove node  $k + 1$  we have found its shortest path



# Dijkstra's Algorithm: Correctness

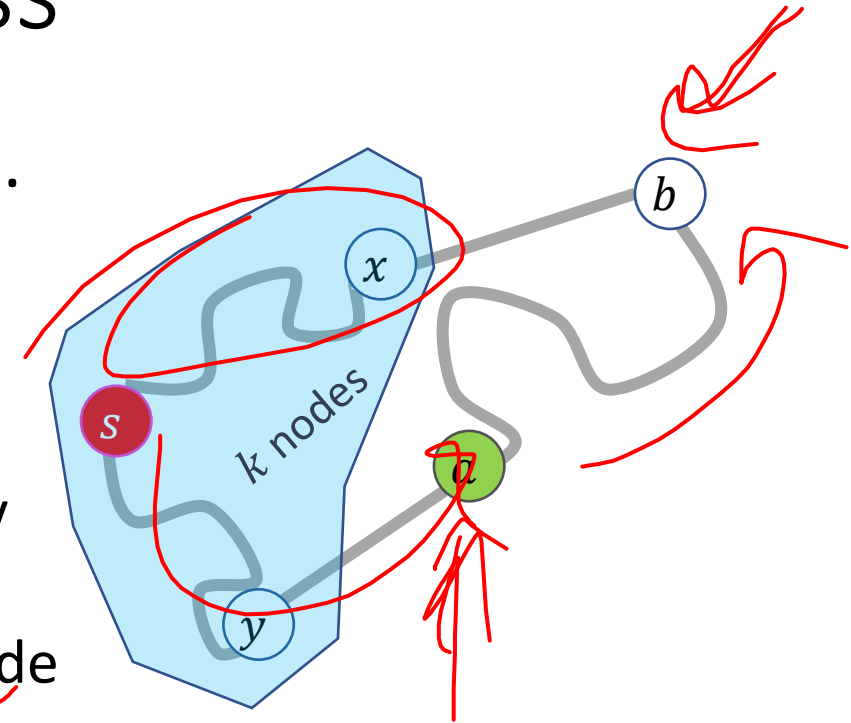
- Suppose  $a$  is the next node removed from the queue. What do we know about  $a$ ?

- $a$  has an edge to  $a$
- $a$  done node
- smallest priority
- $s \rightarrow a$  path is only known



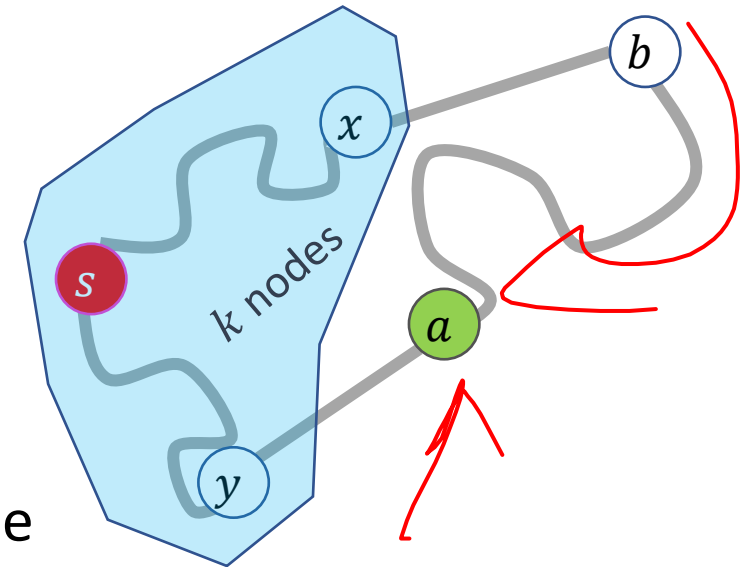
# Dijkstra's Algorithm: Correctness

- Suppose  $a$  is the next node removed from the queue.
  - No other ~~incomplete~~ node has a shorter path discovered so far
- Claim: no undiscovered path to  $a$  could be shorter
  - Consider any other incomplete node  $b$  that is 1 edge away from a complete node
  - $a$  is the closest node that is one away from a complete node
  - Thus no path that includes  $b$  can be a shorter path to  $a$
  - Therefore the shortest path to  $a$  must use only complete nodes, and therefore we have found it already!



# Dijkstra's Algorithm: Correctness

- Suppose  $a$  is the next node removed from the queue.
  - No other node incomplete node has a shorter path discovered so far
- Claim: no undiscovered path to  $a$  could be shorter
  - Consider any other incomplete node  $b$  that is 1 edge away from a complete node
  - $a$  is the closest node that is one away from a complete node
  - **No path from  $b$  to  $a$  can have negative weight**
  - Thus no path that includes  $b$  can be a shorter path to  $a$
  - Therefore the shortest path to  $a$  must use only complete nodes, and therefore we have found it already!



# A Programming Assumption Reconsidered

- So far:
  - Programs run by executing one line of code at a time in the order written
  - Called **Sequential Programming**
- Removing this assumptions creates challenges and opportunities
  - Programming: Divide computation across several **parallel threads**, then coordinate (synchronize) across them.
  - Algorithms: This parallel processing can speed up computation by increasing **throughput** (operations done per unit time)
  - Data Structures: May need to support **concurrent** access (multiple parallel processes attempting to use it at once)



# Why Parallelism?

- Pre 2005:

1960's

Moore

- Processors "naturally" got faster at an exponential rate (~2x faster every ~2 years)

- Since 2005:

- Some components cannot be improved in the same way due to limitations of physics
- Solution: increase computing speed by just adding more processors

# What to do with the extra processors?

- Time Slicing:
  - Your computer is always keeping track of multiple things at once
    - running the OS, rendering the display, running Powerpoint, autosaving a document, etc.
  - Multiple processors allow for the multiple tasks to be spread across them, so each processor dedicates more time to each one
- Parallelism (our focus):
  - Multiple processors collaborate on the same task.

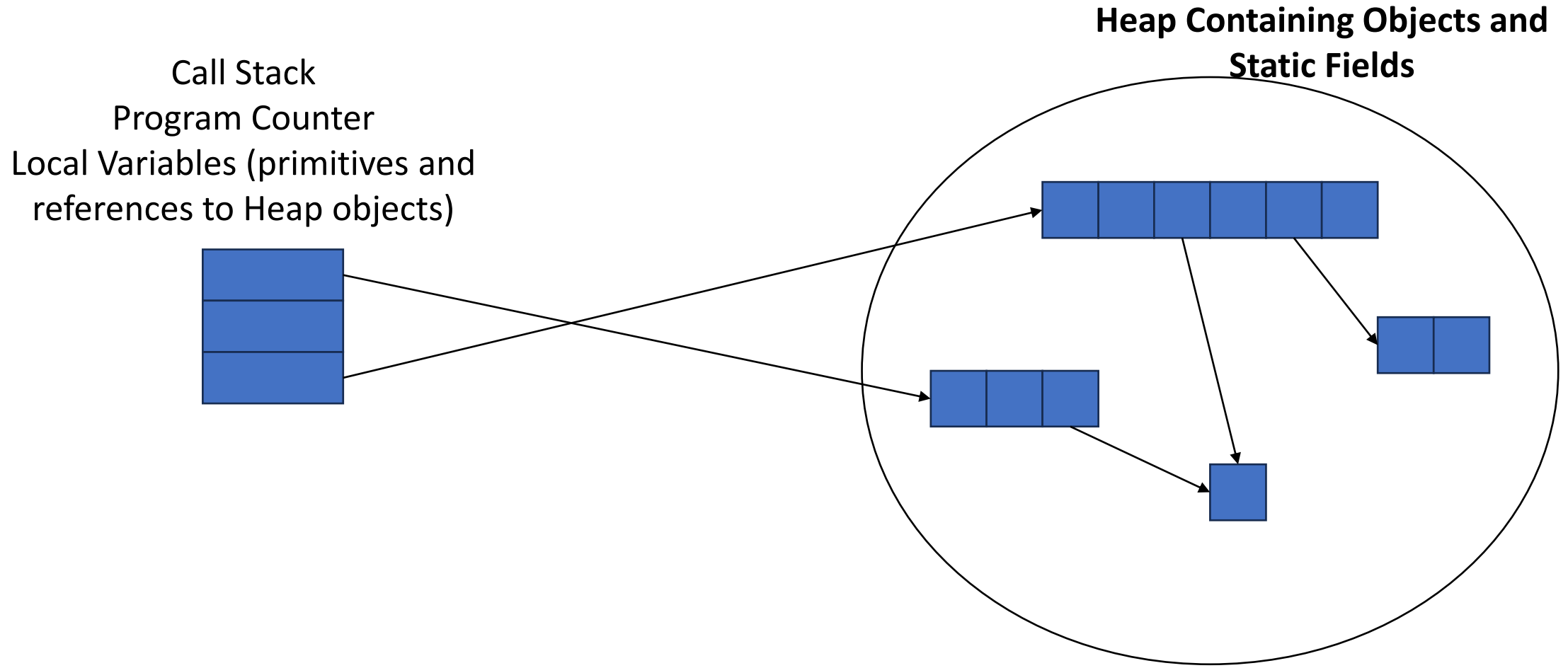
# Parallelism Vs. Concurrency (with Potatoes)

- Sequential:
  - The task is completed by just one processor doing one thing at a time
  - There is one cook who peels all the potatoes
- Parallelism:
  - One task being completed by many threads
  - Recruit several cooks to peel a lot of potatoes faster
- Concurrency:
  - Parallel tasks using a shared resource
  - Several cooks are making their own recipes, but there is only 1 oven

# New Story of Code Execution

- Old Story:
  - One program counter (current statement executing)
  - One call stack (with each stack frame holding local variables)
  - Objects in the heap created by memory allocation (i.e., new)
    - (nothing to do with data structure called a heap)
- New Story:
  - Collection of threads each with its own:
    - Program Counter
    - Call Stack
    - Local Variables
    - References to objects in a shared heap

# Old Story



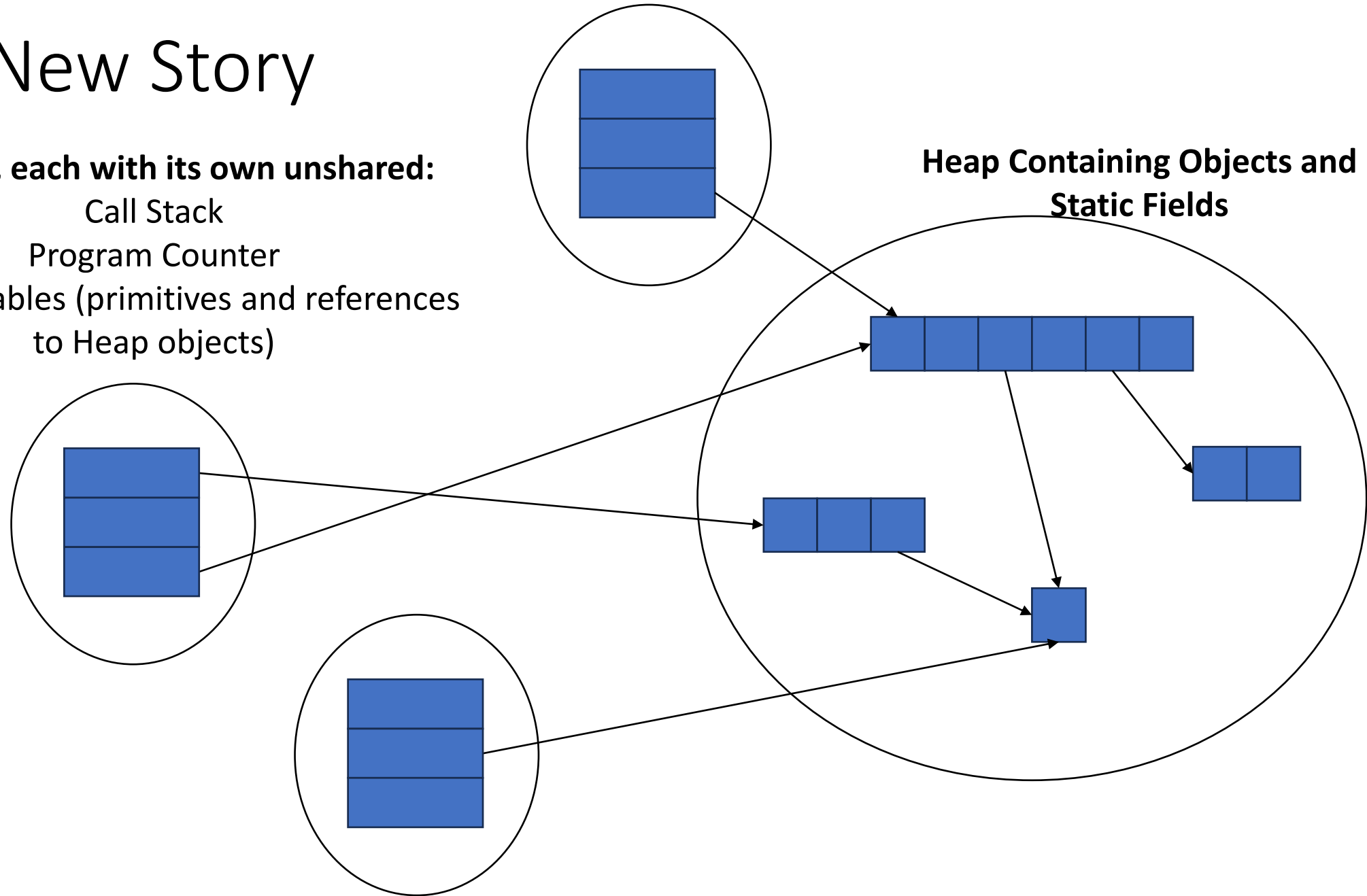
# New Story

**Threads, each with its own unshared:**

Call Stack

Program Counter

Local Variables (primitives and references to Heap objects)



**Heap Containing Objects and Static Fields**

# Needs from Our Programming Language

- A way to create multiple things running at once
  - Threads
- Ways to share memory
  - References to common objects
- Ways for threads to synchronize
  - For now, just wait for other threads to finish their work

# Parallelism Example (not real code)

- Goal: Find the sum of an array
- Idea: 4 processors will each find the sum of one quarter of the array, then we can add up those 4 results

Note: This FORALL construct does not exist, but it's similar to how we'll actually do it.

```
int sum(int[] arr){
    res = new int[4];
    len = arr.length;
    FORALL(i=0; i < 4; i++) { //parallel iterations
        res[i] = sumRange(arr,i*len/4,(i+1)*len/4); }
    return res[0]+res[1]+res[2]+res[3];
}

int sumRange(int[] arr, int lo, int hi) {
    result = 0;
    for(j=lo; j < hi; j++)
        result += arr[j]; return result;
}
```

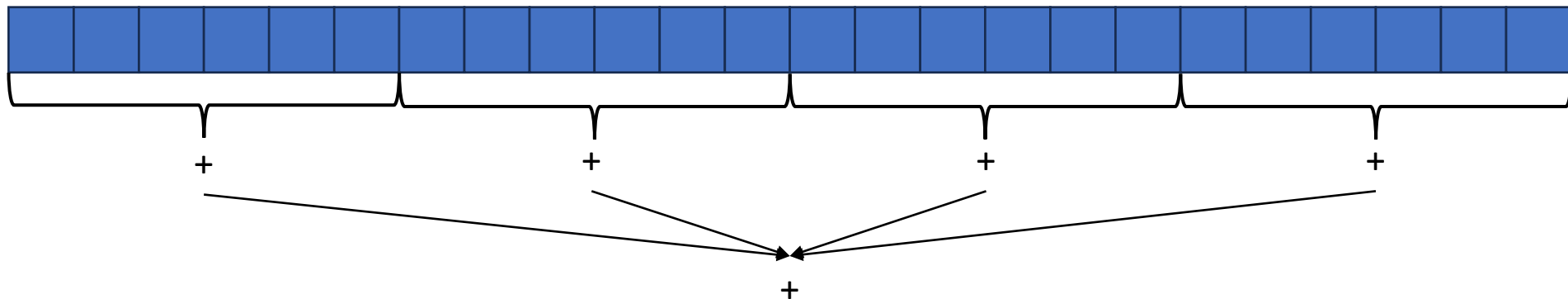


# Java.lang.Thread

- To run a new thread:
  1. Define a subclass **C** of java.lang.Thread, overriding **run**
  2. Create an object of class **C**
  3. Call that object's **start** method
    - **start** sets off a new thread, using **run** as its “main”
- Calling “**run**” directly causes the program to execute “**run**” sequentially

# Back to Summing an Array

- Goal: Find the sum of an array
- Idea: 4 threads each find the sum of one quarter of the array
- Process:
  - Create 4 thread objects, each given a portion of the work
  - Call `start()` on each thread object to run it in parallel
  - Wait for threads to finish using `join()`
  - Add together their 4 answers for the final result



# First Attempt (part 1, defining Thread Object)

```
class SumThread extends java.lang.Thread {
    int lo;    // fields, assigned in the constructor
    int hi;    // so threads know what to do.
    int[] arr;
    int ans = 0; // result

    SumThread(int[] a, int l, int h) {
        lo=l; hi=h; arr=a;
    }

    public void run() { //override must have this type
        for(int i=lo; i < hi; i++)
            ans += arr[i];
    }
}
```

# First Attempt (part 2, Creating Thread Objects)

```
class SumThread extends java.lang.Thread {
    int lo, int hi, int[] arr; // fields to know what to do
    int ans = 0; // result
    SumThread(int[] a, int l, int h) { ... }
    public void run(){ ... } // override }

int sum(int[] arr){ // can be a static method
    int len = arr.length;
    int ans = 0;
    SumThread[] ts = new SumThread[4];
    for(int i=0; i < 4; i++) // do parallel computations
        ts[i] = new SumThread(arr,i*len/4,(i+1)*len/4);
    for(int i=0; i < 4; i++) // combine results
        ans += ts[i].ans;
    return ans;
}
```

# First Attempt (part 3, Running Thread Objects)

```
class SumThread extends java.lang.Thread {
    int lo, int hi, int[] arr; // fields to know what to do
    int ans = 0; // result
    SumThread(int[] a, int l, int h) { ... }
    public void run(){ ... } // override }

int sum(int[] arr){ // can be a static method
    int len = arr.length;
    int ans = 0;
    SumThread[] ts = new SumThread[4];
    for(int i=0; i < 4; i++){ // do parallel computations
        ts[i] = new SumThread(arr,i*len/4,(i+1)*len/4);
        ts[i].start(); // start not run
    }
    for(int i=0; i < 4; i++) // combine results
        ans += ts[i].ans;
    return ans; }
```

# First Attempt (part 4, Synchronizing)

```
class SumThread extends java.lang.Thread {
    int lo, int hi, int[] arr; // fields to know what to do
    int ans = 0; // result
    SumThread(int[] a, int l, int h) { ... }
    public void run(){ ... } // override }
int sum(int[] arr){ // can be a static method
    int len = arr.length;
    int ans = 0;
    SumThread[] ts = new SumThread[4];
    for(int i=0; i < 4; i++){ // do parallel computations
        ts[i] = new SumThread(arr,i*len/4,(i+1)*len/4);
        ts[i].start(); // start not run}
    for(int i=0; i < 4; i++) // combine results
        ts[i].join(); // wait for thread to finish!
    ans += ts[i].ans;
    return ans; }
```

# Join

- Causes program to pause until the other thread completes its **run** method
- Avoids a **race condition**
  - Without join the other thread's **ans** field may not have its final answer yet

# Flaws With this Attempt

Different machines have different numbers of processors!

Making the thread count a parameter helps make your program more efficient and reusable across computers

```
int sum(int[] arr, int numTs){ // can be a static method
    int len = arr.length;
    int ans = 0;
    SumThread[] ts = new SumThread[numTs];
    for(int i=0; i < numTs; i++){ // do parallel computations
        ts[i] = new SumThread(arr,i*len/numTs,(i+1)*len/numTs);
        ts[i].start(); // start not run}
    for(int i=0; i < numTs; i++) // combine results
        ts[i].join(); // wait for thread to finish!
        ans += ts[i].ans;
    return ans; }
```



# Flaws With this Attempt

- Even If we make the number of threads equal the number of processors, the OS is doing time slicing, so we might not have all processors available right now
- For some problems, not all subproblems will take the same amount of time:
  - E.g. determining whether all integers in an array are prime.

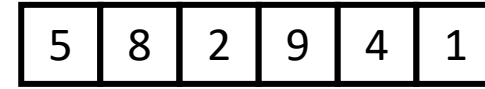
# One Potential Solution: More Threads!

- Identify an “optimal” workload per thread
  - E.g. maybe it’s not worth splitting the work if the array is shorter than 1000
- Split the array into chunks using this “sequential Cutoff”
  - $\text{numTs} = \text{len}/\text{SEQ\_CUTOFF};$
- Problem: One process is still responsible for summing all  $\text{len}/1000$  results
  - Process is still linear time

# A Better Solution: Divide and Conquer!

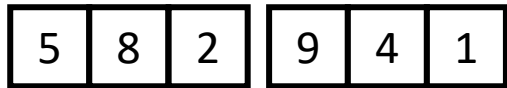
- Idea: Each thread checks its problem size. If its smaller than the sequential cutoff, it will sum everything sequentially. Otherwise it will split the problem in half across two separate threads.

# Merge Sort



- **Base Case:**

- If the list is of length 1 or 0, it's already sorted, so just return it



- **Divide:**

- Split the list into two "sublists" of (roughly) equal length



- **Conquer:**

- Sort both lists recursively

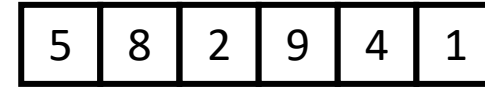


- **Combine:**

- **Merge** sorted sublists into one sorted list



# Parallel Sum



- **Base Case:**

- If the list's length is smaller than the Sequential Cutoff, find the sum sequentially

- **Divide:**

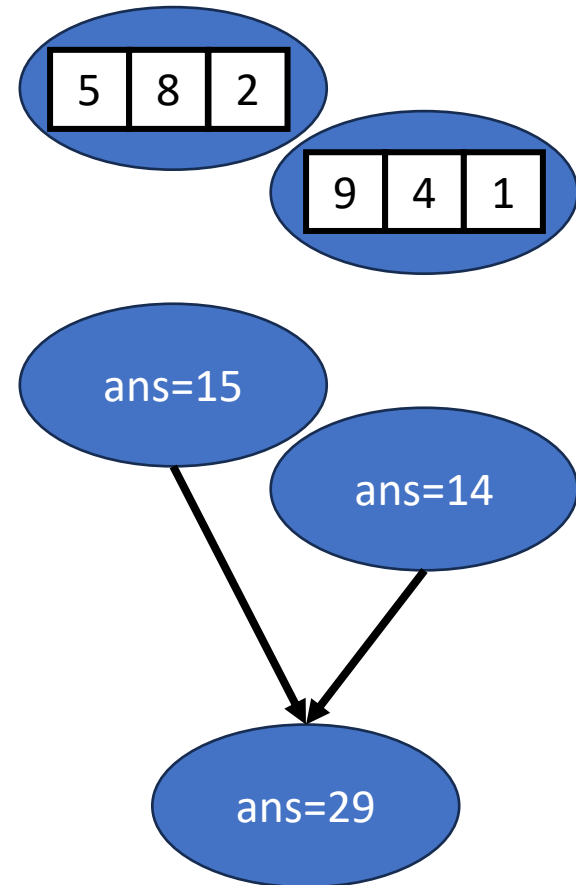
- Split the list into two "sublists" of (roughly) equal length, create a thread to sum each sublist.

- **Conquer:**

- Call **start()** for each thread

- **Combine:**

- Sum together the answers from each thread



# Divide and Conquer with Threads

```
class SumThread extends java.lang.Thread {
    public void run(){ // override
        if(hi - lo < SEQUENTIAL_CUTOFF) // "base case"
            for(int i=lo; i < hi; i++) ans += arr[i];
        else {
            SumThread left = new SumThread(arr,lo,(hi+lo)/2); // divide
            SumThread right= new SumThread(arr,(hi+lo)/2,hi); // divide
            left.start(); // conquer
            right.start(); // conquer
            left.join(); // don't move this up a line - why?
            right.join();
            ans = left.ans + right.ans; // combine
        }
    }
}

int sum(int[] arr){ // just make one thread!
    SumThread t = new SumThread(arr,0,arr.length);
    t.run();
    return t.ans; }
```

# Small optimization

- Instead of calling two separate threads for the two subproblems, create one parallel thread (using **start**) and one sequential thread (using **run**)

# Divide and Conquer with Threads (optimized)

```
class SumThread extends java.lang.Thread {
    public void run(){ // override
        if(hi - lo < SEQUENTIAL_CUTOFF) // "base case"
            for(int i=lo; i < hi; i++) ans += arr[i];
        else {
            SumThread left = new SumThread(arr,lo,(hi+lo)/2); // divide
            SumThread right= new SumThread(arr,(hi+lo)/2,hi); // divide
            left.start(); // conquer
            right.run(); // conquer
            left.join(); // don't move this up a line - why?
            //right.join();
            ans = left.ans + right.ans; // combine
        }
    }
}

int sum(int[] arr){ // just make one thread!
    SumThread t = new SumThread(arr,0,arr.length);
    t.run();
    return t.ans; }
```



# ForkJoin Framework

- This strategy is common enough that Java (and C++, and C#, and...) provides a library to do it for you!

What you would do in Threads	What to instead in ForkJoin
Subclass <b>Thread</b>	Subclass <b>RecursiveTask&lt;V&gt;</b>
Override <b>run</b>	Override <b>compute</b>
Store the answer in a field	Return a V from compute
Call <b>start</b>	Call <b>fork</b>
<b>join</b> synchronizes only	<b>join</b> synchronizes and returns the answer
Call <b>run</b> to execute sequentially	Call <b>compute</b> to execute sequentially
Have a topmost thread and call <b>run</b>	Create a pool and call <b>invoke</b>

# Divide and Conquer with ForkJoin

```
class SumTask extends RecursiveTask {
    int lo; int hi; int[] arr; // fields to know what to do
    SumTask(int[] a, int l, int h) { ... }
    protected Integer compute(){// return answer
        if(hi - lo < SEQUENTIAL_CUTOFF) { // base case
            int ans = 0; // local var, not a field
            for(int i=lo; i < hi; i++) {
                ans += arr[i]; return ans; }
        }
        else {
            SumTask left = new SumTask(arr,lo,(hi+lo)/2); // divide
            SumTask right= new SumTask(arr,(hi+lo)/2,hi); // divide
            left.fork(); // fork a thread and calls compute (conquer)
            int rightAns = right.compute(); //call compute directly (conquer)
            int leftAns = left.join(); // get result from left
            return leftAns + rightAns; // combine
        }
    }
}
```

# Divide and Conquer with ForkJoin (continued)

```
static final ForkJoinPool POOL = new ForkJoinPool();  
int sum(int[] arr){  
    SumTask task = new SumTask(arr,0,arr.length)  
    return POOL.invoke(task); // invoke returns the value compute returns  
}
```

# Section

- Working with examples of ForkJoin
- Make sure to bring your laptops!
  - And charge it!