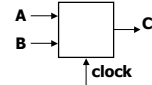


Overview

- ◆ Last lecture
 - Adders
 - ✦ Ripple-carry
 - ✦ Carry-lookahead
 - ✦ Carry-select
 - The conclusion of combinational logic!!!
- ◆ Today
 - Introduction to sequential logic and systems
 - ✦ The basic concepts
 - ✦ A simple example

Sequential versus combinational



Apply fixed inputs A, B
 Wait for clock edge
 Observe C
 Wait for another clock edge
 Observe C again

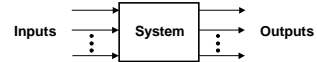
Combinational: C will stay the same
 Sequential: C may be different

Sequential logic

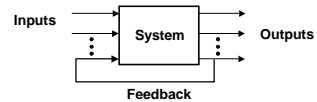
- ◆ Two types
 - Synchronous = clocked
 - Asynchronous = self-timed
- ◆ Has state
 - State = memory
- ◆ Employs feedback
- ◆ Assumes steady-state signals
 - Signals are valid after they have settled
 - State elements hold their settled output values

Sequential versus combinational (again)

- ◆ Combinational systems are memoryless
 - Outputs depend only on the present inputs

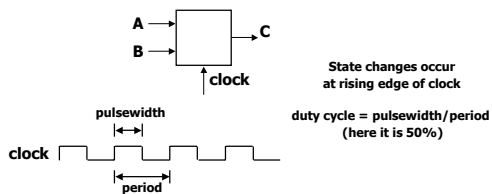


- ◆ Sequential systems have memory
 - Outputs depend on the present and the previous inputs



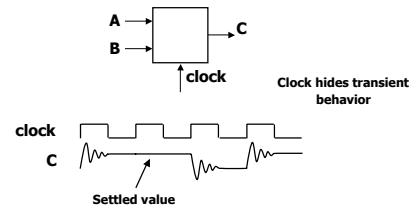
Synchronous sequential systems

- ◆ Memory holds a system's *state*
 - Changes in state occur at specific times
 - A periodic signal times or clocks the state changes
 - The clock period is the time between state changes



Steady-state abstraction

- ◆ Outputs retain their *settled values*
 - The clock period must be long enough for all voltages to settle to a steady state before the next state change

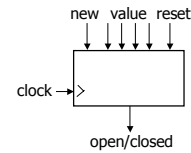


Example: A sequential system

- ◆ Door combination lock
 - Enter 3 numbers in sequence and the door opens
 - If there is an error the lock must be reset
 - After the door opens the lock must be reset
 - Inputs: Sequence of numbers, reset
 - Outputs: Door open/close
 - Memory: Must remember the combination

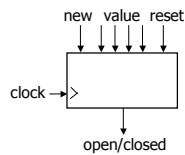
Understand the problem

- ◆ Consider I/O and unknowns
 - How many bits per input?
 - How many inputs in sequence?
 - How do we know a new input is entered?
 - How do we represent the system states?



Implement using sequential logic

- ◆ Behavior
 - Clock tells us when to look at inputs
 - ☑ After inputs have settled
 - Sequential: Enter sequence of numbers
 - Sequential: Remember if error occurred
- ◆ Need a finite-state diagram
 - Assume synchronous inputs
 - State sequence
 - ☑ Enter 3 numbers serially
 - ☑ Remember if error occurred
 - All states have outputs
 - ☑ Lock open or closed

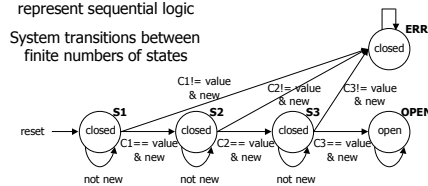


Finite-state diagram

- ◆ States: 5
 - Each state has outputs
- ◆ Inputs: reset, new, results of comparisons
 - Assume synchronous inputs
- ◆ Outputs: open/closed

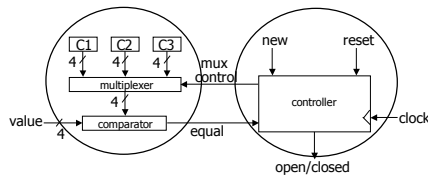
We use state diagrams to represent sequential logic

System transitions between finite numbers of states



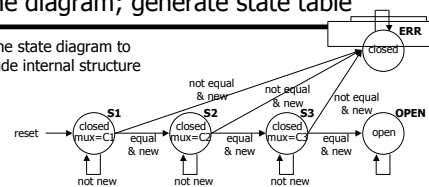
Separate data path and control

- ◆ Data path
 - Stores combination
 - Compares inputs with combination
- ◆ Control
 - Finite state-machine controller
 - Control for data path
 - State changes clocked



Refine diagram; generate state table

- ◆ Refine state diagram to include internal structure



- ◆ Generate state table

reset	new	equal	state	next state	mux	open/closed
1	-	-	-	S1	C1	closed
0	0	-	S1	S1	C1	closed
0	1	0	S1	ERR	-	closed
0	1	1	S1	S2	C2	closed
...
0	1	1	S3	OPEN	-	open
...

Encode state table

- ◆ State can be: S1, S2, S3, OPEN, or ERR
 - Need at least 3 bits to encode: 000, 001, 010, 011, 100
 - Can use 5 bits: 00001, 00010, 00100, 01000, 10000
 - Choose 4 bits: 0001, 0010, 0100, 1000, 0000
- ◆ Output to mux can be: C1, C2, or C3
 - Need 2 or 3 bits to encode
 - Choose 3 bits: 001, 010, 100
- ◆ Output open/closed can be: Open or closed
 - Need 1 or 2 bits to encode
 - Choose 1 bit: 1, 0

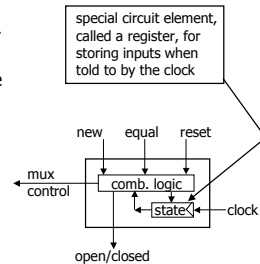
Encode state table (con't)

- ◆ Good encoding choice!
 - Mux control is identical to last 3 state bits
 - Open/closed is identical to first state bit
 - Output encoding \Rightarrow the outputs and state bits are the same

reset	new	equal	state	next state	mux	open/closed
1	-	-	-	0001	001	0
0	0	-	0001	0001	001	0
0	1	0	0001	0000	-	0
0	1	1	0001	0010	010	0
...						
0	1	1	0100	1000	-	1
...						

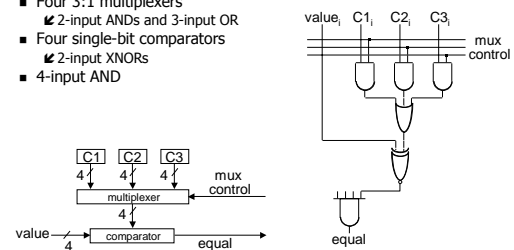
Implementing the controller

- ◆ We will learn how to design the controller given the encoded state-transition table



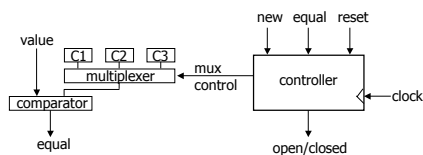
Designing the datapath

- Four 3:1 multiplexers
 - ↳ 2-input ANDs and 3-input OR
- Four single-bit comparators
 - ↳ 2-input XNORs
- 4-input AND



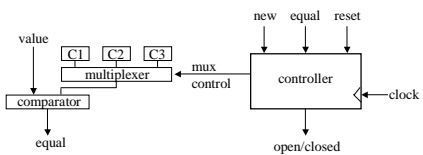
Where did we use memory?

- ◆ Memory: Stored combination, state (errors or successes in past inputs)



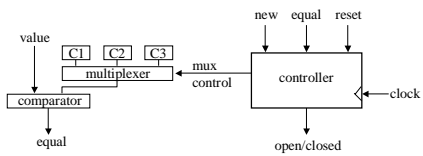
Where did we use feedback?

- ◆ Feedback: Comparator output ("equal" signal)



Where did we use clock?

- ◆ Clock synchronizes the inputs
 - Accept inputs when clock goes high
- ◆ Controller is clocked
 - Mux-control and open/closed signals change on the clock edge



Then next 5 weeks...

- ◆ We learn the details
 - Latches, flip-flops, registers
 - Shift registers, counters
 - State machines
 - Timing and timing diagrams
 - Synchronous and asynchronous inputs
 - Metastability
 - Clock skew
 - Moore and Mealy machines
 - One-hot encoding
 - More...