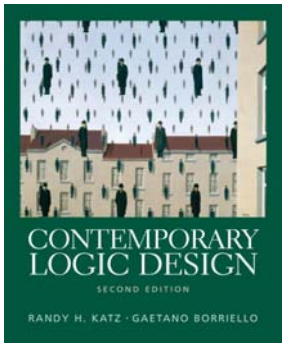
CSE 370 Spring 2006 Introduction to Digital Design

Lecture 13: Introduction to Sequential Logic



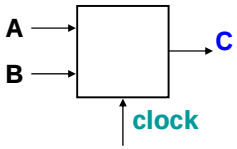
Last Lecture
- Adders

Today
- Sequential Logic

Administrivia

- Quiz #2

Sequential versus combinational



Apply fixed inputs A, B
Wait for clock edge
Observe C
Wait for another clock edge
Observe C again

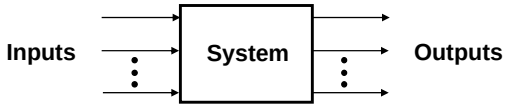
Combinational: C will stay the same
Sequential: C may be different

Sequential logic

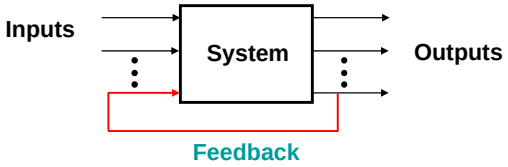
- Two types
  - Synchronous = clocked
  - Asynchronous = self-timed
- Has state
  - State = memory
- Employs feedback
- Assumes steady-state signals
  - Signals are valid after they have settled
  - State elements hold their settled output values

Sequential versus combinational (again)

- Combinational systems are memoryless
  - Outputs depend only on the present inputs

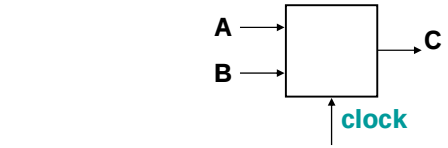


- Sequential systems have memory
  - Outputs depend on the present and the previous inputs

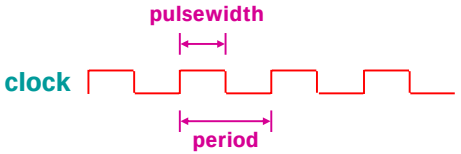


Synchronous sequential systems

- Memory holds a system's *state*
  - Changes in state occur at specific times
  - A periodic signal times or clocks the state changes
  - The clock period is the time between state changes



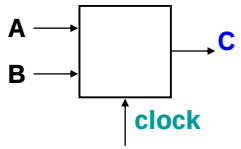
State changes occur at rising edge of clock



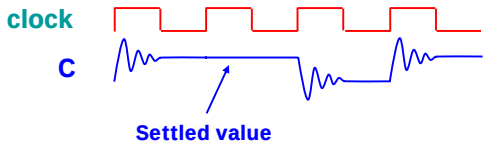
duty cycle = pulsewidth / period (here it is 50 %)

Steady-state abstraction

- Outputs retain their *settled values*
  - The clock period must be long enough for all voltages to settle to a steady state before the next state change



Clock hides transient behavior

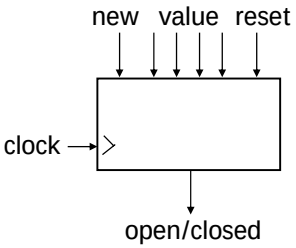


Example: A sequential system

- Door combination lock
  - Enter 3 numbers in sequence and the door opens
  - If there is an error the lock must be reset
  - After the door opens the lock must be reset
  - Inputs: Sequence of numbers, reset
  - Outputs: Door open/close
  - Memory: Must remember the combination

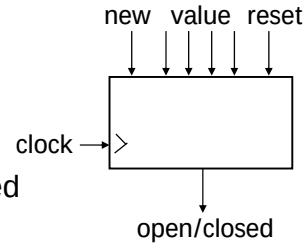
Understand the problem

- Consider I/O and unknowns
  - How many bits per input?
  - How many inputs in sequence?
  - How do we know a new input is entered?
  - How do we represent the system states?



Implement using sequential logic

- Behavior
  - Clock tells us when to look at inputs
    - After inputs have settled
  - Sequential: Enter sequence of numbers
  - Sequential: Remember if error occurred
- Need a finite-state diagram
  - Assume synchronous inputs
  - State sequence
    - Enter 3 numbers serially
    - Remember if error occurred
  - All states have outputs
    - Lock open or closed

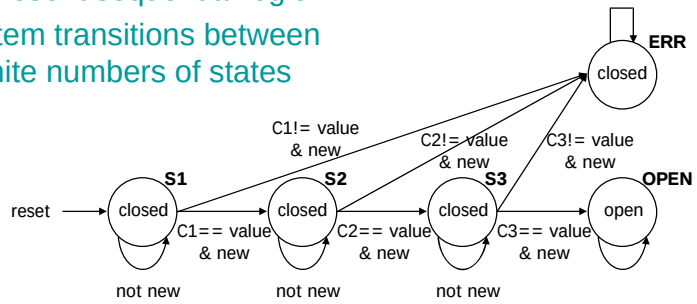


Finite-state diagram

- States: 5
  - Each state has outputs
- Outputs: open/closed
- Inputs: reset, new, results of comparisons
  - Assume synchronous inputs

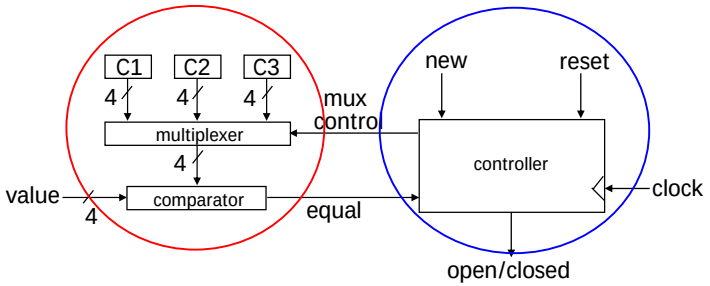
We use state diagrams to represent sequential logic

System transitions between finite numbers of states



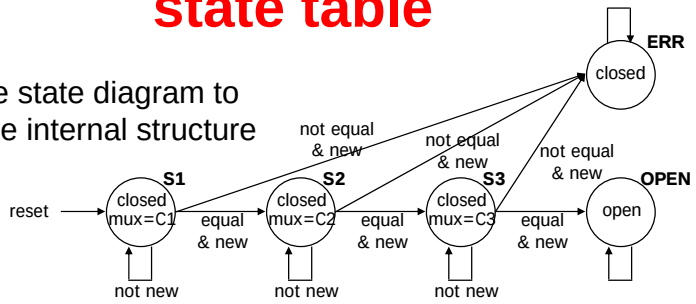
Separate data path and control

- Data path
  - Stores combination
  - Compares inputs with combination
- Control
  - Finite state-machine controller
  - Control for data path
  - State changes clocked



Refine diagram; generate state table

- Refine state diagram to include internal structure



- Generate state table

reset	new	equal	state	next state	mux	open/closed
1	–	–	–	S1	C1	closed
0	0	–	S1	S1	C1	closed
0	1	0	S1	ERR	–	closed
0	1	1	S1	S2	C2	closed
…						
0	1	1	S3	OPEN	–	open
…						

Encode state table

- State can be: S1, S2, S3, OPEN, or ERR
  - Need at least 3 bits to encode: 000, 001, 010, 011, 100
  - Can use 5 bits: 00001, 00010, 00100, 01000, 10000
  - Choose 4 bits: 0001, 0010, 0100, 1000, 0000
- Output to mux can be: C1, C2, or C3
  - Need 2 or 3 bits to encode
  - Choose 3 bits: 001, 010, 100
- Output open/closed can be: Open or closed
  - Need 1 or 2 bits to encode
  - Choose 1 bit: 1, 0

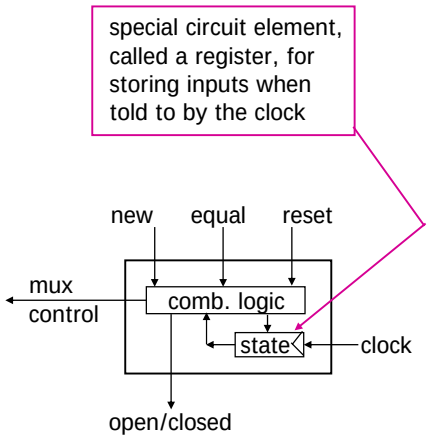
Encode state table (con't)

- Good encoding choice!
  - Mux control is identical to last 3 state bits
  - Open/closed is identical to first state bit
  - Output encoding ⇒ the outputs and state bits are the same

reset	new	equal	state	next state	mux	open/closed
1	–	–	–	0001	001	0
0	0	–	0001	0001	001	0
0	1	0	0001	0000	–	0
0	1	1	0001	0010	010	0
…						
0	1	1	0100	1000	–	1
…						

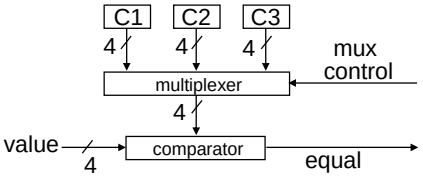
Implementing the controller

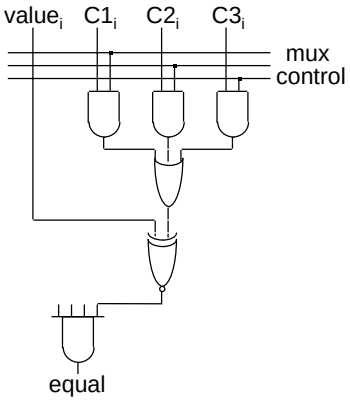
- We will learn how to design the controller given the encoded state-transition table



Designing the datapath

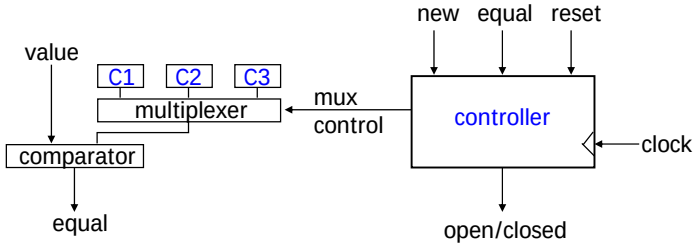
- Four 3:1 multiplexers
  - 2-input ANDs and 3-input OR
- Four single-bit comparators
  - 2-input XNORs
- 4-input AND





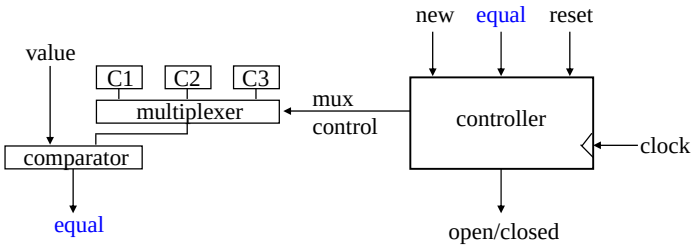
Where did we use memory?

- Memory: Stored combination, state (errors or successes in past inputs)



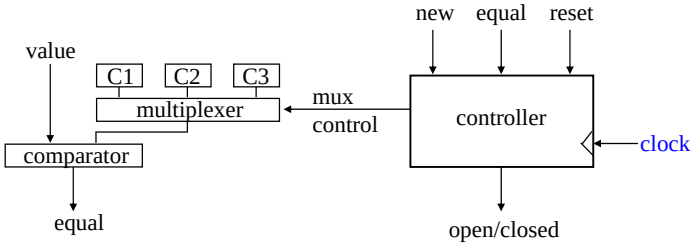
Where did we use feedback?

- Feedback: Comparator output ("equal" signal)



Where did we use clock?

- Clock synchronizes the inputs
  - Accept inputs when clock goes high
- Controller is clocked
  - Mux-control and open/closed signals change on the clock edge



Then next 5 weeks...

- We learn the details
  - Latches, flip-flops, registers
  - Shift registers, counters
  - State machines
  - Timing and timing diagrams
  - Synchronous and asynchronous inputs
    - Metastability
  - Clock skew
  - Moore and Mealy machines
  - One-hot encoding
  - More...