CSE 373: B-Trees

Pete Morcos University of Washington 4/14/00

http://www.cs.washington.edu/education/courses/cse373/00sp

A new style of tree

- B-trees are unlike the other trees we've seen
 Data only stored in leaves; interior nodes just for searching
 - Each node has many children (often hundreds)Thus, tree is extremely shallow
- · Very important in database systems
- Designed for high performance when managing enormous amounts of data

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Disks

- Many databases hold many gigabytes or terabytes (10¹²) of info
- Too much to fit in memory

- Disk access time is measured in ms, memory time in ns—about a million times slower
- When disk data is accessed, you read a whole page (512 bytes to a few K), not just one byte
 We'll assume 1000 byte pages for simplicity
- The all-important goal is to reduce the number of disk accesses!

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Why not just use binary trees?

- Recall that in binary search trees, each node visited reduces search space by about one-half
 Thus, log₂ N node accesses needed per search
- log₂ 1,000,000,000,000 is about 40
 40 disk accesses for each piece of data is unacceptable
- Since we are going to get a whole page of data per disk read anyway, make nodes as big as possible
 - Each node has M children
 - Suppose search keys are strings up to 36 bytes
 - M = 1000 / (36 + 4 [for a child pointer]) = 250
 - $-\log_{250} 1,000,000,000,000 = 5$ (as opposed to 40)
- Often, top 2 levels fit in memory, so medium size B-trees only have to hit the disk once (for the actual data node) UW, Spring 2000 CSE 37: Data Structures and Algorithms Per Macros

Our simplifying assumptions

- Databases can't use pointers in B-trees since some
- nodes will be in memory, some on disk
- We'll assume everything fits in memory
- Some of our written problems will ask you about 1000 byte disk pages, as on previous slide
- But most examples and homework will use what I'll call a mini B-tree, with M = 4

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Example B-tree

<u>□→□→□→□→□→□→□→□→□→□→□→□→□→□→□→□→</u>□→

· B-tree rules:

...→...→...→...→...→...-

- All leaves at same depth, and hold sorted array of data
- Root has 2 to M children (labeled P₀ to P_{M-1})
- Other non-leaf nodes have $\lceil M/2 \rceil$ to M children
- Each non-leaf has up to M-1 values (k₁ to k_{M-1}); child P_i holds values ≥ k_i; P0 holds stuff ≤ k₁
- Note that values in non-leaves are not actual data!



Find

______ +...+..+..+..+..+..+..+..+..+..+..+..

- · Similar to binary search trees, but now have M possible choices at each node-O(M) work to pick one, or O(log M) if we binary search the node
- Overall search time is O(log M * log_M N)



Insert

- Do a Find to pick the right leaf, then add to leaf
- · If leaf overflows, split it into two and add new child
 - to parent (e.g. inserting 45 in example) - This might overflow parent, so repeat recursively to root
- Splitting root is only way that tree gets taller
- More sophisticated implementation would try to • overflow into sibling leaves before making new leaf



Remove

- · Remove item from leaf
- If leaf becomes empty, remove it
- optionally try stealing data from sibling leaf first
- This might cause parent to have $< \lceil M/2 \rceil$ children - Try stealing a value from sibling if possible

 - Else, merge with a sibling-might cause next node up to be too small, so do this recursively - If root drops below 2 children, delete it (tree gets shorter)
- · Deletion might cause interior nodes to contain values that are
- no longer in the database (e.g. deleting 41 in example)
- Not a problem since interior nodes still valid for navigation

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- Analysis of Insert/Remove
- ×□→□→□→□→□→□→□→□→□→□→□→□→□→□→□→□→□→□→
- O(log_M N) steps taken (height of tree)
- Unlike Find, each step might require a rearrangement of a node, which is O(M) work
- Total time complexity is, then, $O(M \log_M N)$ - Can rewrite as O([M/log M] log N)
- · For large M, worse than binary search trees if everything is in memory, but far better if lower nodes would require disk accesses

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Next Week

- Sorting
- · An important topic, so we'll spend some time on it
- Read 7-7.3 and 7.5-7.6 (either book)