

Lecture 27: The Grand Finale

- ◆ Agenda for the final class:
 - ⇒ P, NP, and NP-completeness
 - ⇒ The NP =? P problem
 - ◆ Major extra-credit problem
 - ⇒ Final Review
 - ◆ Summary of what you've learned in this course
 - ⇒ End-of-quarter M.o.M. party
 - ◆ Munch on munchies as you leave...

The “complexity” class NP

- ◆ Definition: NP is the set of all problems for which a given *candidate solution* can be *tested* in polynomial time
 - ⇒ Suppose someone gives you a solution – can it be tested in polynomial time? (testing is easier than solving it)
- ◆ Example of a problem in NP:
 - ⇒ Our new friend, the Hamiltonian circuit problem: Why is it in NP?
 - ◆ Given a candidate path, can test in linear time if it is a Hamiltonian circuit – just check if all vertices are visited exactly once in the candidate path (except start/finish vertex)

From Last Time: The “complexity” class P

- ◆ The set P is defined as the set of all problems that can be solved in polynomial worst case time
 - ⇒ Also known as the polynomial time complexity class – contains problems whose time complexity is $O(N^k)$ for some k
- ◆ Examples of problems in P: searching, sorting, topological sort, single-source shortest path, Euler circuit, etc.

Why NP?

- ◆ NP stands for Nondeterministic Polynomial time
 - ⇒ Why “nondeterministic”? Corresponds to algorithms that can search all possible solutions in parallel and pick the correct one → each solution can be checked in polynomial time
 - ⇒ Nondeterministic algorithms don't exist – purely theoretical idea invented to understand how hard a problem could be
- ◆ Examples of problems in NP:
 - ⇒ Hamiltonian circuit: Given a candidate path, can test in linear time if it is a Hamiltonian circuit
 - ⇒ Sorting: Can test in linear time if a candidate ordering is sorted
 - ⇒ Sorting is also in P. Are any other problems in P also in NP?

More revelations about NP

- ◆ Sorting is in P. Are any other problems in P also in NP?
 - ⇒ YES! All problems in P are also in NP $\rightarrow P \subseteq NP$
 - ◆ If you can solve a problem in polynomial time, can definitely verify a solution in polynomial time
- ◆ Question: Are all problems in NP also in P?
 - ⇒ Is $NP \subseteq P$?

NP-complete problems

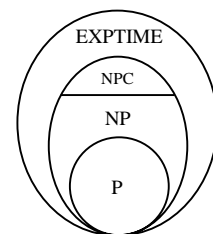
- ◆ The “hardest” problems in NP are called NP-complete (NPC) problems
- ◆ Why “hardest”? A problem X is NP-complete if:
 1. X is in NP and
 2. *any* problem Y in NP can be *converted to* X in polynomial time, such that *solving X also provides a solution for Y* \rightarrow Can use algorithm for X as a *subroutine* to solve Y
- ◆ Thus, if you find a poly time algorithm for just one NPC problem, all problems in NP can be solved in poly time
- ◆ Example: The Hamiltonian circuit problem can be shown to be NP-complete (not so easy to prove!)

Your chance to win a Turing award: $P = NP$?

- ◆ Nobody knows whether $NP \subseteq P$
 - ⇒ Proving or disproving this will bring you instant fame!
- ◆ It is generally believed that $P \neq NP$ i.e. there are problems in NP that are not in P
 - ⇒ But no one has been able to show even one such problem
- ◆ A very large number of problems are in NP (such as the Hamiltonian circuit problem)
 - ⇒ No one has found fast (polynomial time) algorithms for these problems
 - ⇒ On the other hand, no one has been able to prove such algorithms don't exist (i.e. that these problems are not in P)!

P, NP, and Exponential Time Problems

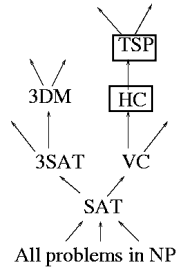
- ◆ All algorithms for NP-complete problems so far have tended to run in nearly exponential worst case time
 - ⇒ But this doesn't mean fast sub-exponential time algorithms don't exist! Not proven yet...
- ◆ Diagram depicts relationship between P, NP, and EXPTIME (class of problems that require exponential time to solve)



It is believed that $P \neq NP \neq EXPTIME$

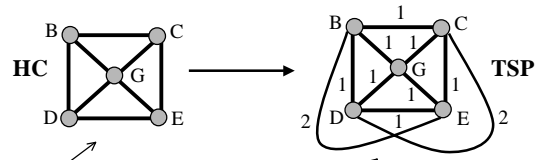
The “graph” of NP-completeness

- ◆ Cook first showed (in 1971) that satisfiability of Boolean formulas (SAT) is NP-complete
- ◆ Hundreds of other problems (from scheduling and databases to optimization theory) have since been shown to be NPC
- ◆ How? By showing an algorithm that converts a known NPC problem to your pet problem in poly time → then, your problem is also NPC!



TSP is NP-complete!

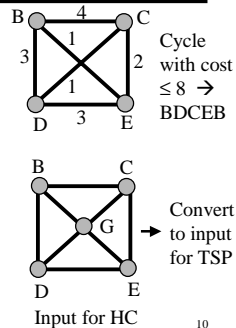
- ◆ We can show TSP is also NPC if we can convert any input for HC to an input for TSP in poly time. Here's one way:



This graph has a Hamiltonian circuit iff this fully-connected graph has a TSP cycle of total cost $\leq K$, where $K = |V|$ (here, $K = 5$)

Showing NP-completeness: An example

- ◆ Consider the **Traveling Salesperson (TSP) Problem**: Given a fully connected, weighted graph $G = (V, E)$, is there a cycle that visits all vertices exactly once and has total cost $\leq K$?
- ◆ TSP is in NP (why?)
- ◆ Can we show TSP is NP-complete?
 - ⇒ Hamiltonian Circuit (HC) is NPC
 - ⇒ Can show TSP is also NPC if we can convert any input for HC to an input for TSP in poly time



Coping with NP-completeness

- ◆ Given that it is difficult to find fast algorithms for NPC problems, what do we do?
- ◆ Alternatives:
 1. **Dynamic programming**: Avoid repeatedly solving the same subproblem – use table to store results (see Chap. 10)
 2. **Settle for algorithms that are fast on average**: Worst case still takes exponential time, but doesn't occur very often
 3. **Settle for fast algorithms that give near-optimal solutions**: In TSP, may not give the cheapest tour, but maybe good enough
 4. **Try to get a “wimpy exponential” time algorithm**: It's okay if running time is $O(1.00001^N)$ – bad only for $N > 1,000,000$

Yawn... What does all this have to do with data structures and programming?

- ◆ Top 5 reasons to know and understand NP-completeness:
- 5. What if there's an NP-completeness question in the final?
- 4. When you are having a tough time programming a fast algorithm for a problem, you could show it is NP-complete
- 3. When you are having a tough time programming a fast algorithm for a problem, you could just say it is NPC (and many will believe you (yes, it's a sad state of affairs))
- 2. When you are at a cocktail party, you can impress your friends with your profound knowledge of NP-completeness
- 1. Make money with new T-shirt slogan: "And God said: P=NP"

Final Review: What you need to know

- ◆ Basic Math
 - ⇒ Logs, exponents, summation of series
 - ⇒ Proof by induction
- ◆ Asymptotic Analysis
 - ⇒ Big-oh, little-oh, Theta and Omega
 - ⇒ Know the definitions and how to show f(N) is big-oh/little-oh/Theta/Omega of (g(N))
 - ⇒ How to estimate Running Time of code fragments
 - ◆ E.g. nested "for" loops
- ◆ Recurrence Relations
 - ⇒ Deriving recurrence relation for run time of a recursive function
 - ⇒ Solving recurrence relations by expansion to get run time

$$\sum_{i=1}^N i = \frac{N(N+1)}{2}$$

$$\sum_{i=0}^N A^i = \frac{A^{N+1}-1}{A-1}$$

Final Review

("We've covered way too much in this course...
What do I really need to know?")

Final Review: What you need to know

- ◆ Lists, Stacks, Queues
 - ⇒ Brush up on ADT operations – Insert/Delete, Push/Pop etc.
 - ⇒ Array versus pointer implementations of each data structure
 - ⇒ Header nodes, circular, doubly linked lists
- ◆ Trees
 - ⇒ Definitions/Terminology: root, parent, child, height, depth etc.
 - ⇒ Relationship between depth and size of tree
 - ◆ Depth can be between O(log N) and O(N) for N nodes

Final Review: What you need to know

- ◆ Binary Search Trees
 - ⇒ How to do Find, Insert, Delete
 - ◆ Bad worst case performance – could take up to $O(N)$ time
 - ⇒ AVL trees
 - ◆ Balance factor is +1, 0, -1
 - ◆ Know single and double rotations to keep tree balanced
 - ◆ All operations are $O(\log N)$ worst case time
 - ⇒ Splay trees – good amortized performance
 - ◆ A single operation may take $O(N)$ time but in a sequence of operations, average time per operation is $O(\log N)$
 - ◆ Every Find, Insert, Delete causes accessed node to be moved to the root
 - ◆ Know how to zig-zig, zig-zag, etc. to “bubble” node to top
 - ⇒ B-trees: Know basic idea behind Insert/Delete

Final Review: What you need to know

- ◆ Sorting Algorithms: Know run times and how they work
 - ⇒ Elementary sorting algorithms and their run time
 - ◆ Bubble sort, Selection sort, Insertion sort
 - ⇒ Shellsort – based on several passes of Insertion sort
 - ◆ Increment Sequence
 - ⇒ Heapsort – based on binary heaps (max-heaps)
 - ◆ BuildHeap and repeated DeleteMax's
 - ⇒ Mergesort – recursive divide-and-conquer, uses extra array
 - ⇒ Quicksort – recursive divide-and-conquer, Partition in-place
 - ◆ fastest in practice, but $O(N^2)$ worst case time
 - ◆ Pivot selection – median-of-three works best
 - ⇒ Know which of these are stable and in-place
 - ⇒ Lower bound on sorting, bucket sort, and radix sort

Final Review: What you need to know

- ◆ Priority Queues
 - ⇒ Binary Heaps: Insert/DeleteMin, Percolate up/down
 - ◆ Array implementation
 - ◆ BuildHeap takes only $O(N)$ time (used in heapsort)
 - ⇒ Binomial Queues: Forest of binomial trees with heap order
 - ◆ Merge is fast – $O(\log N)$ time
 - ◆ Insert and DeleteMin based on Merge
- ◆ Hashing
 - ⇒ Hash functions based on the mod function
 - ⇒ Collision resolution strategies
 - ◆ Chaining, Linear and Quadratic probing, Double Hashing
 - ⇒ Load factor of a hash table

Final Review: What you need to know

- ◆ Disjoint Sets and Union-Find
 - ⇒ Up-trees and their array-based implementation
 - ⇒ Know how Union-by-size and Path compression work
 - ⇒ No need to know run time analysis – just know the result:
 - ◆ Sequence of M operations with Union-by-size and P.C. is $\Theta(M \alpha(M,N))$ – basically $\Theta(1)$ amortized time per op
- ◆ Graph Algorithms
 - ⇒ Adjacency matrix versus adjacency list representation of graphs
 - ⇒ Know how to Topological sort in $O(|V| + |E|)$ time using a queue
 - ⇒ Breadth First Search (BFS) for unweighted shortest path

Final Review: What you need to know

◆ Graph Algorithms (cont.)

- ⇒ Dijkstra's shortest path algorithm – greed works!
 - ◆ Know how a priority queue can speed up the algorithm
- ⇒ Depth First Search (DFS)
- ⇒ Minimum Spanning trees: Know the 2 greedy algorithms
 - ◆ Prim's algorithm – similar to Dijkstra's algorithm
 - ◆ Kruskal's algorithm
 - Know how it uses a priority queue and Union/Find
 - ◆ Euler versus Hamiltonian circuits – difference in run times
 - ◆ Know what P, NP, and NP-completeness mean
 - How one problem can be "reduced" to another (e.g. input to HC can be transformed into input for TSP)

Final Exam:

Where: This room

When: Wednesday, June 6, 2:30-4:20pm

To Do:

Go over sample final exam on web site

Prepare, prepare, prepare (for the final)

Have a great summer!