Trees

CSE 373

Data Structures

Lecture 7

Readings and References

Reading

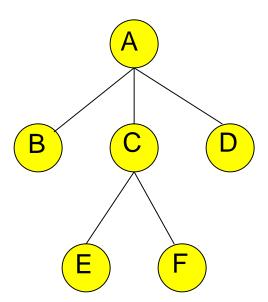
> Chapter 4.1-4.3,

Why Do We Need Trees?

- Lists, Stacks, and Queues are linear relationships
- Information often contains hierarchical relationships
 - File directories or folders on your computer
 - Moves in a game
 - Employee hierarchies in organizations
- Can build a tree to support fast searching

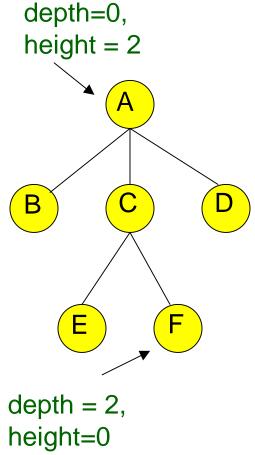
Tree Jargon

- root
- nodes and edges
- leaves
- parent, children, siblings
- ancestors, descendants
- subtrees
- path, path length
- height, depth



More Tree Jargon

- Length of a path = number of edges
- Depth of a node N = length of path from root to N
- Height of node N = length of longest path from N to a leaf
- Depth of tree = depth of deepest node
- Height of tree = height of root



Definition and Tree Trivia

- A tree is a set of nodes
 - that is an empty set of nodes, or
 - has one node called the root from which zero or more trees (subtrees) descend
- A tree with N nodes always has N-1 edges
- Two nodes in a tree have at most one path between them

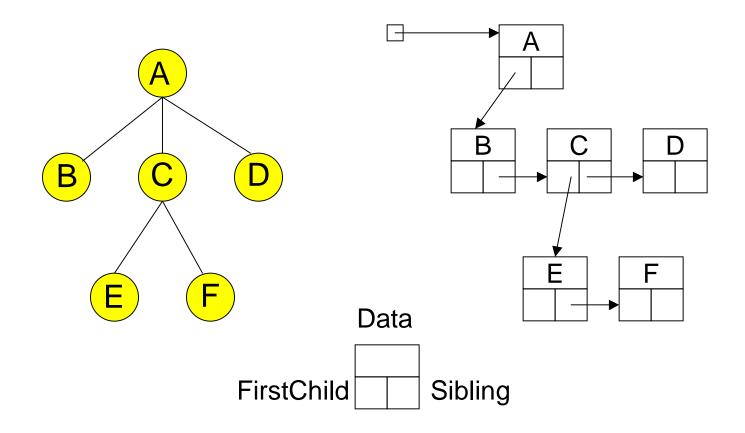
Paths

- Can a non-zero path from node N reach node N again?
 - No. Trees can never have cycles (loops)
- Does depth of nodes in a non-zero path increase or decrease?
 - Depth always increases in a non-zero path

Implementation of Trees

- One possible pointer-based Implementation
 - tree nodes with value and a pointer to each child
 - but how many pointers should we allocate space for?
- A more flexible pointer-based implementation
 - 1st Child / Next Sibling List Representation
 - Each node has 2 pointers: one to its first child and one to next sibling
 - Can handle arbitrary number of children

Arbitrary Branching



Application: Arithmetic Expression Trees

Example Arithmetic Expression:

$$A + (B * (C / D))$$

How would you express this as a tree?

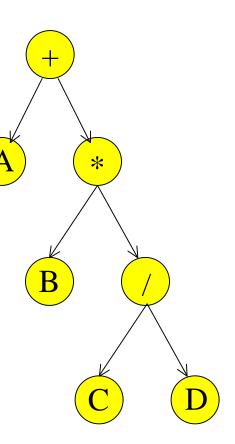
Application: Arithmetic Expression Trees

Example Arithmetic Expression:

$$A + (B * (C / D))$$

Tree for the above expression:

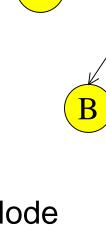
- Used in most compilers
- No parenthesis need use tree structure
- Can speed up calculations e.g. replace
 / node with C/D if C and D are known
- Calculate by traversing tree (how?)



Traversing Trees

Preorder: Node, then Children recursively

 Inorder: Left child recursively, Node, Right child recursively (Binary Trees)
 A + B * C / D



Postorder: Children recursively, then Node
 A B C D / * +

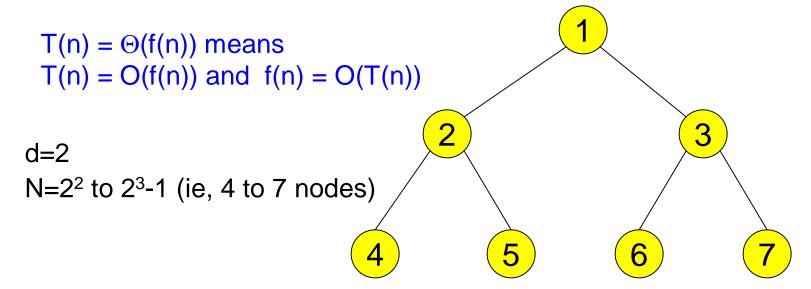
Binary Trees

- Every node has at most two children
 - Most popular tree in computer science
 - Easy to implement, fast in operation
- Given N nodes, what is the minimum depth of a binary tree?
 - At depth d, you can have $N = 2^d$ to 2^{d+1} -1 nodes

$$2^{d} \le N \le 2^{d+1} - 1$$
 implies $d = |log_2N|$

Minimum depth vs node count

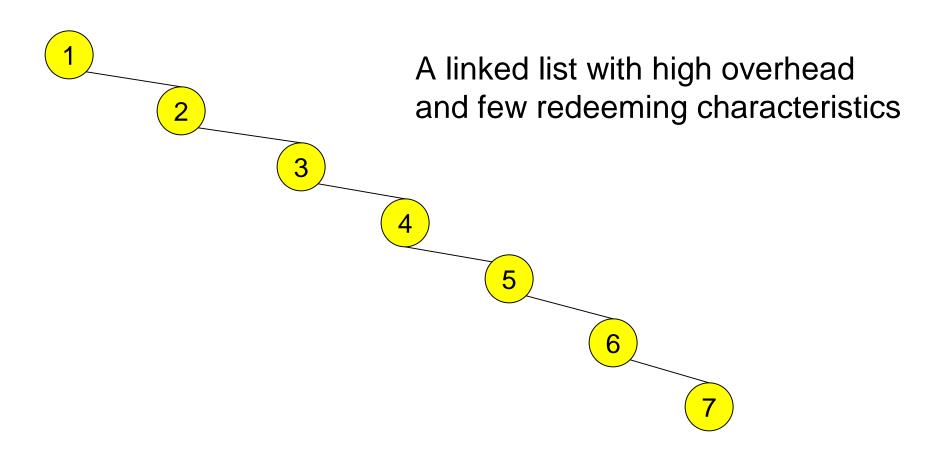
- At depth d, you can have N = 2^d to 2^{d+1}-1 nodes
- minimum depth d is ⊕(log N)*



Maximum depth vs node count

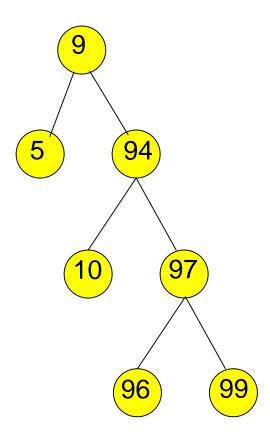
- What is the maximum depth of a binary tree?
 - Degenerate case: Tree is a linked list!
 - Maximum depth = N-1
- Goal: Would like to keep depth at around log N to get better performance than linked list for operations like Find

A degenerate tree



Binary Search Trees

- Binary search trees are binary trees in which
 - all values in the node's left subtree are less than node value
 - all values in the node's right subtree are greater than node value
- Operations:
 - Find, FindMin, FindMax, Insert, Delete



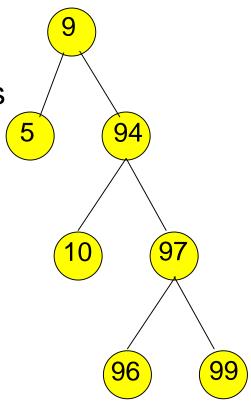
Operations on Binary Search Trees

How would you implement these?

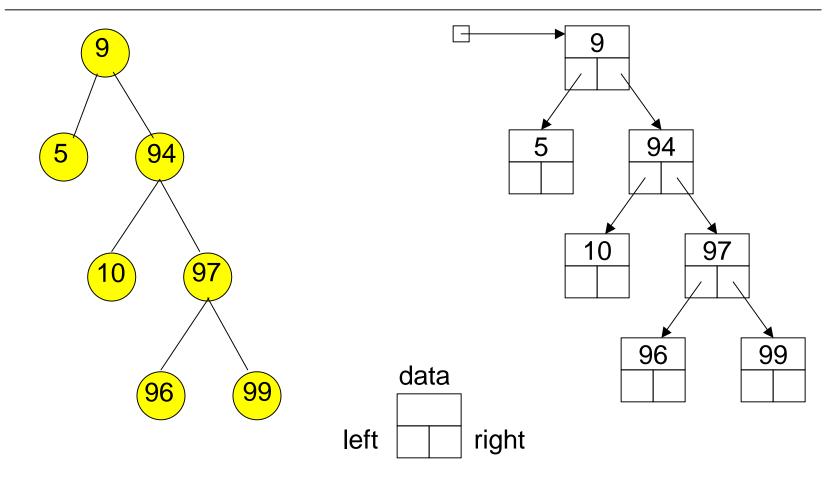
 Recursive definition of binary search trees allows recursive routines

Call by reference helps too

- FindMin
- FindMax
- Find
- Insert
- Delete



Binary SearchTree



10/14/02

Trees - Lecture 7

Find

```
Find(T : tree pointer, x : element): tree pointer {
  case {
    T = null : return null;
    T.data = x : return T;
    T.data > x : return Find(T.left,x);
    T.data < x : return Find(T.right,x)
}
</pre>
```

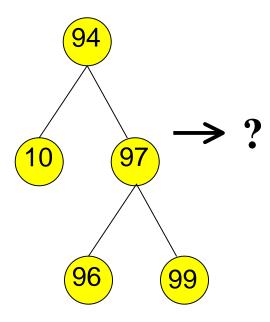
FindMin

- Class Participation
- Design recursive FindMin operation that returns the smallest element in a binary search tree.

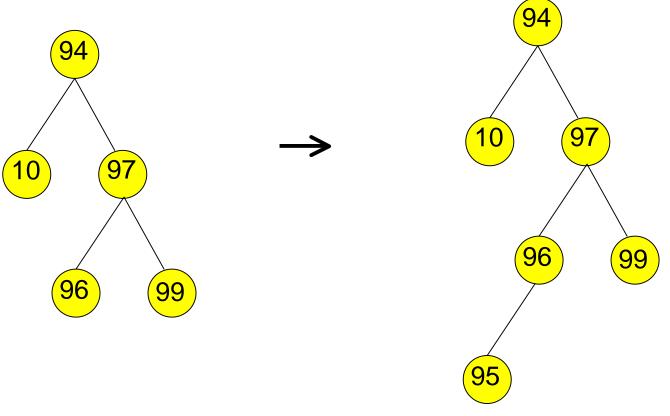
```
> FindMin(T : tree pointer) : tree pointer {
  // precondition: T is not null //
  ???
}
```

Insert Operation

- Insert(T: tree, X: element)
 - Do a "Find" operation for X
 - If X is found à update duplicates counter
 - Else, "Find" stops at a NULL pointer
 - Insert Node with X there
- Example: Insert 95



Insert 95



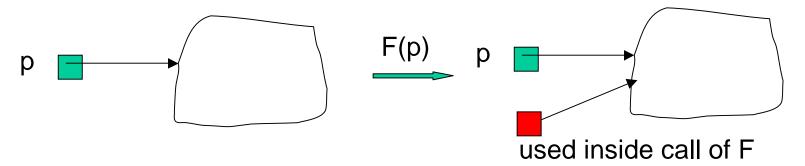
Insert Done Very Elegantly

```
Insert(T : reference tree pointer, x : element) : integer {
  if T = null then
    T := new tree; T.data := x; return 1
  case {
    T.data = x : return 0;
    T.data > x : return Insert(T.left, x);
    T.data < x : return Insert(T.right, x);
}</pre>
```

Advantage of reference parameter is that the call has the original pointer not a copy.

Call by Value vs Call by Reference

- Call by value
 - Copy of parameter is used



- Call by reference
 - Actual parameter is used

Delete Operation

Delete is a bit trickier...Why?

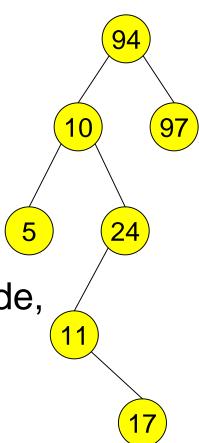
Suppose you want to delete 10

Strategy:

> Find 10

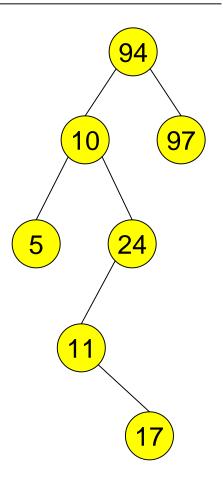
Delete the node containing 10

 Problem: When you delete a node, what do you replace it by?

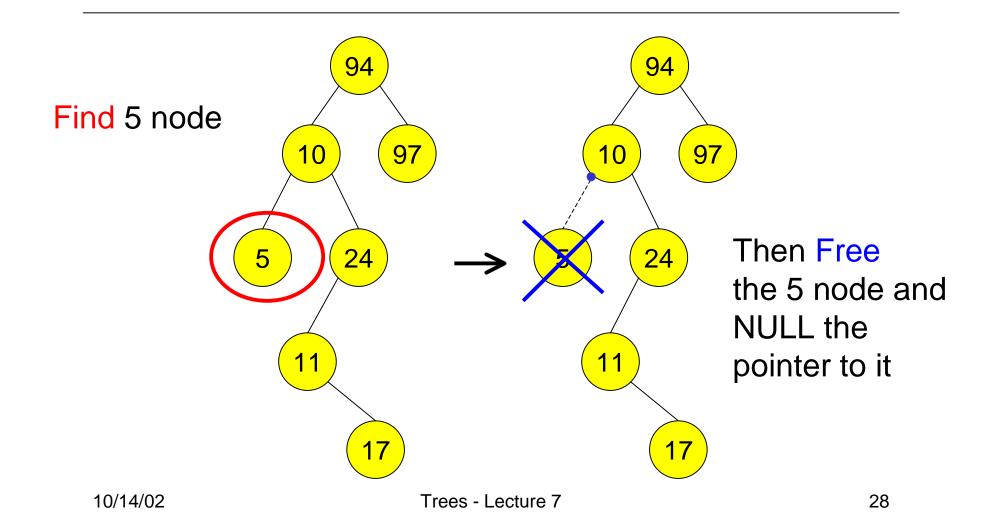


Delete Operation

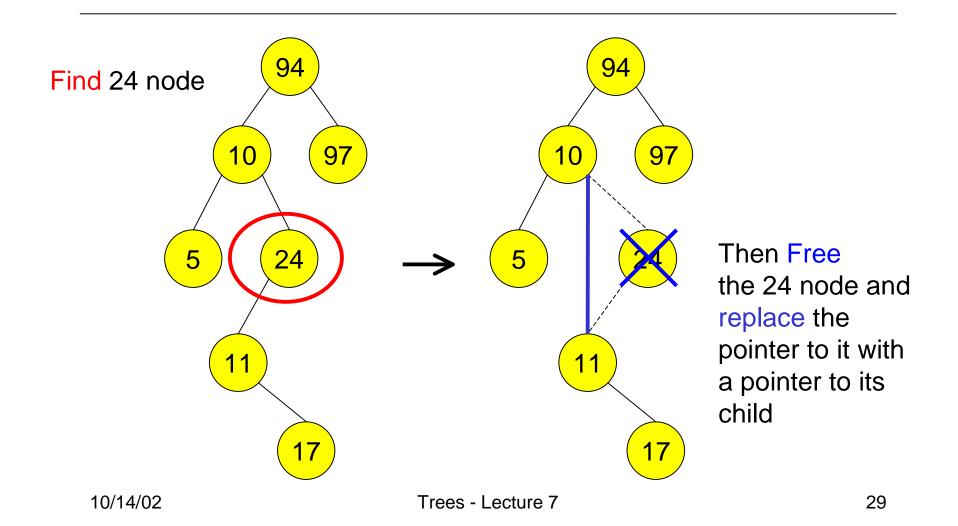
- Problem: When you delete a node, what do you replace it by?
- Solution:
 - If it has no children, by NULL
 - If it has 1 child, by that child
 - If it has 2 children, by the node with the smallest value in its right subtree (the successor of the node)



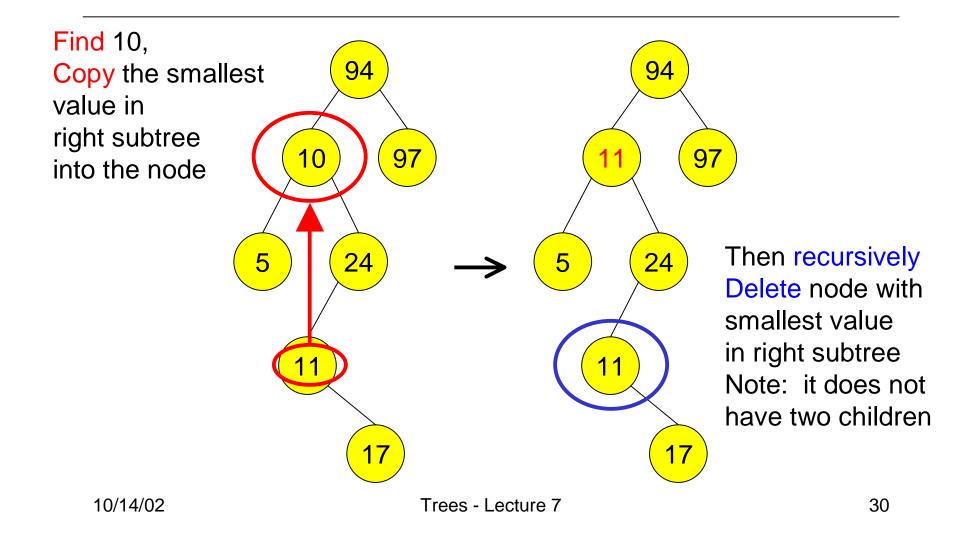
Delete "5" - No children



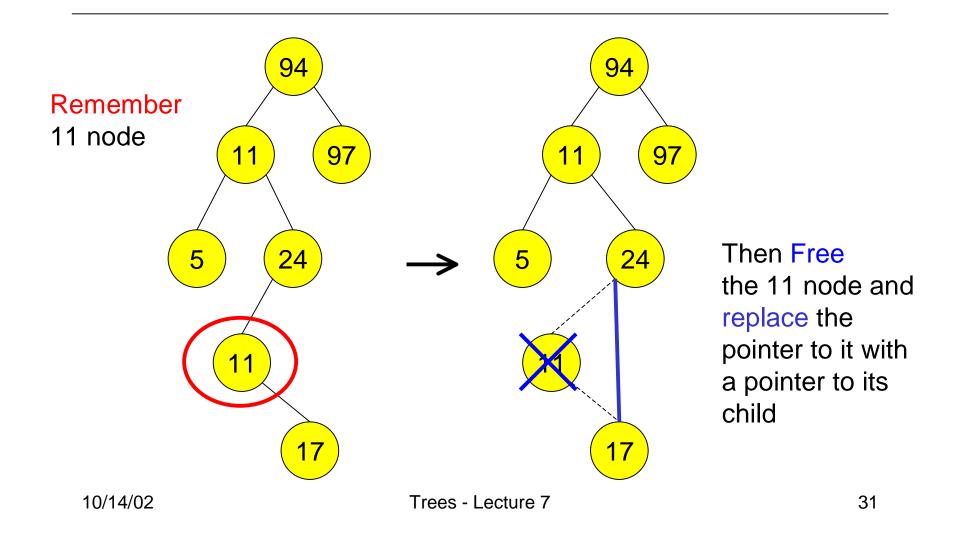
Delete "24" - One child



Delete "10" - two children



Delete "11" - One child



FindMin Solution

```
FindMin(T : tree pointer) : tree pointer {
  // precondition: T is not null //
  if T.left = null return T
  else return FindMin(T.left)
}
```