

# Hashing

CSE 373  
Data Structures  
Lecture 10

## Readings and References

- Reading
  - › Chapter 5

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## The Need for Speed

- Data structures we have looked at so far
  - › Use comparison operations to find items
  - › Need  $O(\log N)$  time for Find and Insert
- In real world applications,  $N$  is typically between 100 and 100,000 (or more)
  - ›  $\log N$  is between 6.6 and 16.6
- Hash tables are an abstract data type designed for  $O(1)$  Find and Inserts

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## Fewer Functions Faster

- compare lists and stacks
  - › by reducing the flexibility of what we are allowed to do, we can increase the performance of the remaining operations
  - ›  $\text{insert}(L, X)$  into a list versus  $\text{push}(S, X)$  onto a stack
- compare trees and hash tables
  - › trees provide for known ordering of all elements
  - › hash tables just let you (quickly) find an element

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## Limited Set of Hash Operations

- For many applications, a limited set of operations is all that is needed
  - › Insert, Find, and Delete
  - › Note that no ordering of elements is implied
- For example, a compiler needs to maintain information about the symbols in a program
  - › user defined
  - › language keywords

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## Direct Address Tables

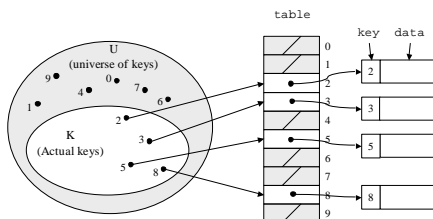
- Direct addressing using an array is very fast
- Assume
  - › keys are integers in the set  $U = \{0, 1, \dots, m-1\}$
  - ›  $m$  is small
  - › no two elements have the same key
- Then just store each element at the array location  $\text{array}[\text{key}]$ 
  - › search, insert, and delete are trivial

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## Direct Access Table



[Cormen, et al]

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## Direct Address Implementation

```
Delete(Table t, ElementType x)
    T[key[x]] = NULL
```

```
Insert(Table t, ElementType x)
    T[key[x]] = x
```

```
Find(Table t, Key k)
    return T[k]
```

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## An Issue

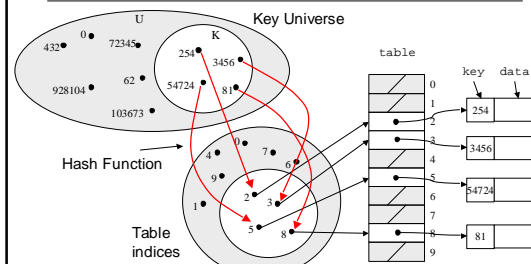
- The largest possible key in  $U$  may be much larger than the number of elements actually stored ( $|U|$  much greater than  $|K|$ )
  - › the table is very sparse and wastes space
  - › in worst case, table too large to have in memory
- If most keys in  $U$  are used
  - › direct addressing can work very well
- If most keys in  $U$  are not used
  - › need to map  $U$  to a smaller set closer in size to  $K$

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## Mapping the Keys



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## Hashing Schemes

- We want to store  $N$  items in a table of size  $M$ , at a location computed from the key  $K$
- **Hash function**
  - › Method for computing table index from key
- **Collision resolution strategy**
  - › How to handle two keys that hash to the same index

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## Looking for an Element

- Data records can be stored in arrays.
  - ›  $A[0] = \{\text{"CHEM 110", Size 89}\}$
  - ›  $A[3] = \{\text{"CSE 142", Size 251}\}$
  - ›  $A[17] = \{\text{"CSE 373", Size 85}\}$
- Class size for CSE 373?
  - › Linear search the array –  $O(N)$  worst case time
  - › Binary search –  $O(\log N)$  worst case

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## Go Directly to the Element

- What if we could directly index into the array using the key?
  - ›  $A[\text{"CSE 373"}] = \{\text{Size 85}\}$
- Main idea behind hash tables
  - › Use a key based on some aspect of the data element to index directly into an array
  - ›  $O(1)$  time to access records

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## Indexing into Hash Table

- Need a fast *hash function* to convert the element key (string or number) to an integer (the *hash value*) (ie, map from  $U$  to index)
  - › Then use this value to index into an array
  - ›  $\text{Hash}(\text{"CSE 373"}) = 157$ ,  $\text{Hash}(\text{"CSE 143"}) = 101$
- Output of the hash function
  - › must always be less than size of array
  - › should be as evenly distributed as possible

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## Choosing the Hash Function

- What properties do we want from a hash function?
  - › Want universe of hash values to be distributed randomly to minimize collisions
  - › Don't want systematic nonrandom pattern in selection of keys to lead to systematic collisions
  - › Want hash value to depend on all values in entire key and their positions

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## The Key Values are Important

- Notice that one issue with all the hash functions is that the actual content of the key set matters
- The elements in  $K$  (the keys that are used) are quite possibly a restricted subset of  $U$ , not just a random collection
  - › variable names, words in the English language, reserved keywords, telephone numbers, etc, etc

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## Simple Hashes

- It's possible to have very simple hash functions if you are certain of your keys
- For example,
  - › suppose we know that the keys  $s$  will be real numbers uniformly distributed over  $0 \leq s < 1$
  - › Then a very fast, very good hash function is
    - $\text{hash}(s) = \text{floor}(s \cdot m)$
    - where  $m$  is the size of the table

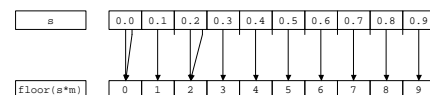
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## Very Simple Mapping

- $\text{hash}(s) = \text{floor}(s \cdot m)$  maps from  $0 \leq s < 1$  to  $0..m-1$ 
  - ›  $m = 10$



Note the even distribution. There are collisions, but we will deal with them later.

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## Perfect Hashing

- In some cases it's possible to map a known set of keys uniquely to a set of index values
- You must know every single key beforehand and be able to derive a function that works *one-to-one* (not necessarily *onto*)



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## Mod Hash Function

- One solution for a less constrained key set
  - › modular arithmetic
- $a \bmod \text{size}$ 
  - › remainder when "a" is divided by "size"
  - › in C or Java this is written as `r = a % size;`
  - › If TableSize = 251
    - $408 \bmod 251 = 157$
    - $352 \bmod 251 = 101$

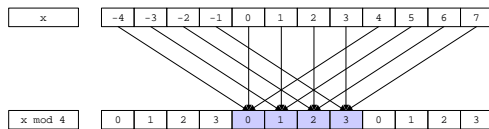
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## Modulo Mapping

- $a \bmod m$  maps from integers to  $0..m-1$ 
  - › one to one? no
  - › onto? yes



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## Hashing Integers

- If keys are integers, we can use the hash function:
  - ›  $\text{Hash}(\text{key}) = \text{key} \bmod \text{TableSize}$
- Problem 1: What if TableSize is 11 and all keys are 2 repeated digits? (eg, 22, 33, ...)
- › all keys map to the same index
- › Need to pick TableSize carefully: often, a prime number

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## Nonnumerical Keys

- Many hash functions assume that the universe of keys is the natural numbers  $\mathbf{N}=\{0,1,\dots\}$
- Need to find a function to convert the actual key to a natural number quickly and effectively before or during the hash calculation
- Generally work with the ASCII character codes when converting strings to numbers

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## Characters to Integers

- If keys are strings can get an integer by adding up ASCII values of characters in *key*
- We are converting a very large string  $c_0c_1c_2\dots c_n$  to a relatively small number  $c_0+c_1+c_2+\dots+c_n \bmod \text{size}$ .

character	C	S	E		3	7	3	<0>
ASCII value	67	83	69	32	51	55	51	0

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## Hash Must be Onto Table

- Problem 2: What if *TableSize* is 10,000 and all keys are 8 or less characters long?
  - › chars have values between 0 and 127
  - › Keys will hash only to positions 0 through  $8 \times 127 = 1016$
- Need to distribute keys over the entire table or the extra space is wasted

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## Problems with Adding Characters

- Problems with adding up character values for string keys
  - › If string keys are short, will not hash evenly to all of the hash table
  - › Different character combinations hash to same value
    - "abc", "bca", and "cab" all add up to the same value

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## Characters as Integers

- An character string can be thought of as a base 256 number. The string  $c_1c_2 \dots c_n$  can be thought of as the number  $c_n + 256c_{n-1} + 256^2c_{n-2} + \dots + 256^{n-1}c_1$
- Use Horner's Rule to Hash!

```

r = 0;
for i = 1 to n do
    r := (c[i] + 256*r) mod TableSize
    
```

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## Collisions

- A **collision** occurs when two different keys hash to the same value
  - › E.g. For *TableSize* = 17, the keys 18 and 35 hash to the same value
  - ›  $18 \bmod 17 = 1$  and  $35 \bmod 17 = 1$
- Cannot store both data records in the same slot in array!

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## Collision Resolution

- Separate Chaining
  - › Use data structure (such as a linked list) to store multiple items that hash to the same slot
- Open addressing (or probing)
  - › search for empty slots using a second function and store item in first empty slot that is found

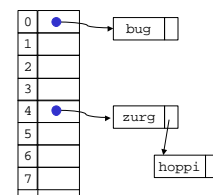
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## Resolution by Chaining

- Each hash table cell holds pointer to linked list of records with same hash value
- Collision: Insert item into linked list
- To Find an item: compute hash value, then do Find on linked list
- Note that there are potentially as many as *TableSize* lists



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## Why Lists?

- Can use List ADT for Find/Insert/Delete in linked list
  - ›  $O(N)$  runtime where  $N$  is the number of elements in the particular chain
- Can also use Binary Search Trees
  - ›  $O(\log N)$  time instead of  $O(N)$
  - › But the number of elements to search through should be small
  - › generally not worth the overhead of BSTs

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## Load Factor of a Hash Table

- Let  $N$  = number of items to be stored
- Load factor  $\lambda = N/\text{TableSize}$ 
  - ›  $\text{TableSize} = 101$  and  $N = 505$ , then  $\lambda = 5$
  - ›  $\text{TableSize} = 101$  and  $N = 10$ , then  $\lambda = 0.1$
- Average length of chained list =  $\lambda$  and so average time for accessing an item =  $O(1) + O(\lambda)$ 
  - › Want  $\lambda$  to be close to 1 (i.e.  $\text{TableSize} \approx N$ )
  - › But chaining continues to work for  $\lambda > 1$

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## Resolution by Open Addressing

- No links, all keys are in the table
  - › reduced overhead saves space
- When searching for  $x$ , check locations  $h_1(x)$ ,  $h_2(x)$ ,  $h_3(x)$ , ... until either
  - ›  $x$  is found; or
  - › we find an empty location ( $x$  not present)
- Various flavors of open addressing differ in which probe sequence they use

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## Cell Full? Keep Looking.

- $h_i(x) = (\text{Hash}(x) + F(i)) \bmod \text{TableSize}$ 
  - › Define  $F(0) = 0$
- $F$  is the collision resolution function. Some possibilities:
  - › **Linear**:  $F(i) = i$
  - › **Quadratic**:  $F(i) = i^2$
  - › **Double Hashing**:  $F(i) = i - \text{Hash}_2(x)$

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## Linear Probing

- When searching for  $x$ , check locations  $h(x)$ ,  $h(x)+1$ ,  $h(x)+2$ , ...  $\bmod \text{TableSize}$  until either
  - ›  $x$  is found; or
  - › we find an empty location ( $x$  not present)
- If table is very sparse, almost like separate chaining.
- When table starts filling, we get clustering but still constant average search time.
- Full table  $\Rightarrow$  infinite loop.

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## Primary Clustering Problem

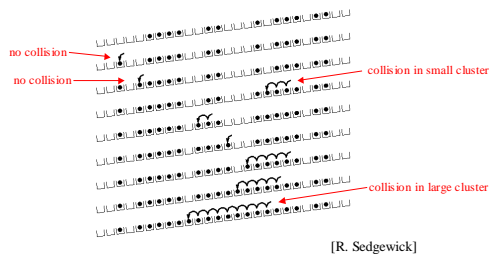
- Once a block of a few contiguous occupied positions emerges in table, it becomes a "target" for subsequent collisions
- As clusters grow, they also merge to form larger clusters.
- Primary clustering: elements that hash to different cells probe same alternative cells

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## Linear Probing – Clustering



[R. Sedgewick]

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## Quadratic Probing

- When searching for  $x$ , check locations  $h_1(x), h_1(x) + i^2, h_1(x) + i^3, \dots \text{mod TableSize}$  until either
  - $x$  is found; or
  - we find an empty location ( $x$  not present)
- No primary clustering but secondary clustering possible

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## Double Hashing

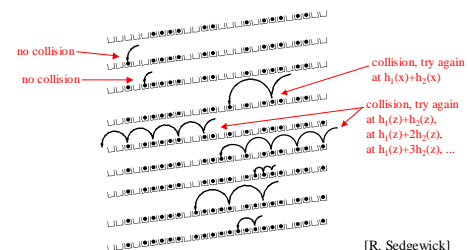
- When searching for  $x$ , check locations  $h_1(x), h_1(x) + h_2(x), h_1(x) + 2 \cdot h_2(x), \dots \text{mod TableSize}$  until either
  - $x$  is found; or
  - we find an empty location ( $x$  not present)
- Must be careful about  $h_2(x)$ 
  - Not 0 and not a divisor of  $M$
  - eg,  $h_1(k) = k \text{ mod } m_1, h_2(k) = 1 + (k \text{ mod } m_2)$
  - where  $m_2$  is slightly less than  $m_1$

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## Double Hashing



[R. Sedgewick]

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## Rules of Thumb

- Separate chaining is simple but wastes space...
- Linear probing uses space better, is fast when tables are sparse, interacts well with paging and caching
- Double hashing is space efficient, fast (get initial hash and increment at the same time), needs careful implementation
- For average cost about  $t + O(1)$ 
  - Max load for Linear Probing is  $1 - 1/\sqrt{t}$
  - Max load for Double Hashing is  $1 - 1/t$

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## Rehashing – Rebuild the Table

- Need to use lazy deletion if we use probing (why?)
  - Need to mark array slots as deleted after Delete
  - consequently, deleting doesn't make the table any less full than it was before the delete
- If table gets too full ( $\lambda \approx 1$ ) or if many deletions have occurred, running time gets too long and Inserts may fail

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## Rehashing

- Build a bigger hash table of approximately twice the size when  $\lambda$  exceeds a particular value
  - › Go through old hash table, ignoring items marked deleted
  - › Recompute hash value for each non-deleted key and put the item in new position in new table
  - › Cannot just copy data from old table because the bigger table has a new hash function
- Running time is  $O(N)$  but happens very infrequently
  - › Not good for real-time safety critical applications

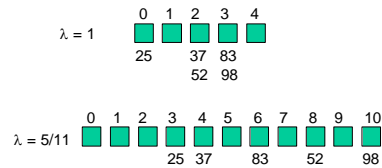
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## Rehashing Example

- Open hashing –  $h_1(x) = x \bmod 5$  rehashes to  $h_2(x) = x \bmod 11$ .



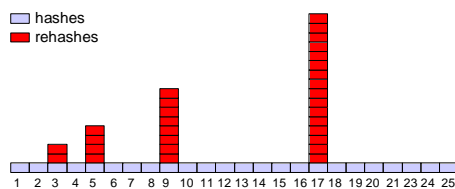
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## Rehashing Picture

- Starting with table of size 2, double when load factor  $> 1$ .



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## Amortized Analysis of Rehashing

- Cost of inserting  $n$  keys is  $< 3n$
- $2^k + 1 \leq n \leq 2^{k+1}$ 
  - › Hashes =  $n$
  - › Rehashes =  $2 + 2^2 + \dots + 2^k = 2^{k+1} - 2$
  - › Total =  $n + 2^{k+1} - 2 < 3n$
- Example
  - ›  $n = 33$ , Total =  $33 + 64 - 2 = 95 < 99$

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## Caveats

- Hash functions are very often the cause of performance bugs.
- Hash functions often make the code not portable.
- Sometime a poor HF distribution-wise is faster overall.
- Always check where the time goes

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