

# Heap Sort

CSE 373 - Data Structures

May 10, 2002

# Readings and References

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- Reading
  - › Sections 7.5, *Data Structures and Algorithm Analysis in C*, Weiss
- Other References

# Binary Search Trees for Sorting?

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- Shell sort with Hibbard's increments got us to  $O(N^{1.5})$
- Can we beat  $O(N^{1.5})$  using a BST to sort  $N$  elements?
  - › Insert each element into an initially empty BST
  - › Do an In-Order traversal to get sorted output
- Running time:
  - ›  $N$  Inserts at  $O(\log N)$  apiece =  $O(N \log N)$
  - › plus  $O(N)$  for In-Order traversal
  - ›  **$O(N \log N)$**  total which is  $o(N^{1.5})$

# Binary Search Tree sort issue

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- Extra Space
  - › Need to allocate space for tree nodes and pointers
  - ›  $O(N)$  extra space, not *in place* sorting
- What if the tree is complete, and we use an array representation – can we sort in place?
  - › Recall your favorite data structure with the initials B. H.

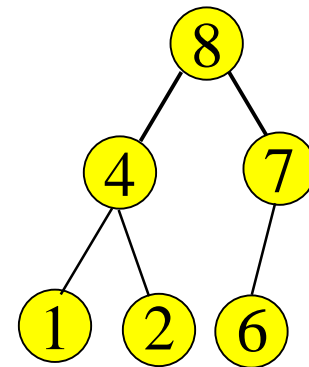
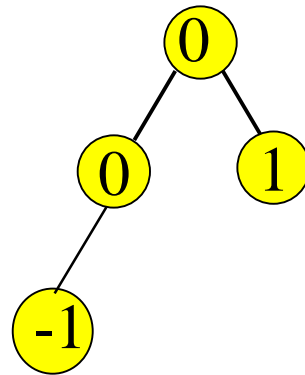
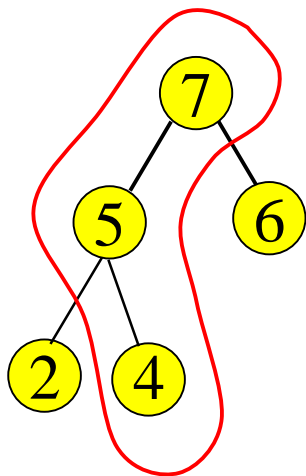
# Binary Heaps

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- A binary heap is a binary tree that is:
  - › Complete: the tree is completely filled except possibly the bottom level, which is filled from left to right
  - › Satisfies the heap order property
    - every node is less than or equal to its children
    - or every node is greater than or equal to its children
- The root node is always the smallest node
  - › or the largest, depending on the heap order

# Heap order property

- A heap provides limited ordering information
- Each *path* is sorted, but the subtrees are not sorted relative to each other
  - › A binary heap is NOT a binary search tree



These are all valid binary heaps (maximum)

# Structure property

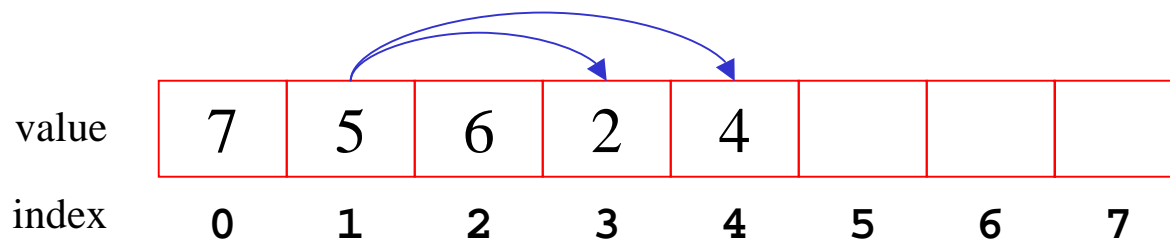
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- A binary heap is a complete tree
  - › All nodes are in use except for possibly the right end of the bottom row
- Array implementation is compact because we know how many children there are and we know that they are all present
  - › no pointers are needed, we can directly calculate subscript offsets to the nodes of the tree

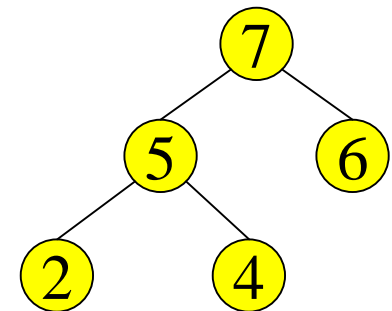
# Heap Sort using an array

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- Root node =  $A[0]$
- Children of  $A[i] = A[2i+1], A[2i+2]$
- Keep track of current size  $N$  (number of nodes)



$N = 5$

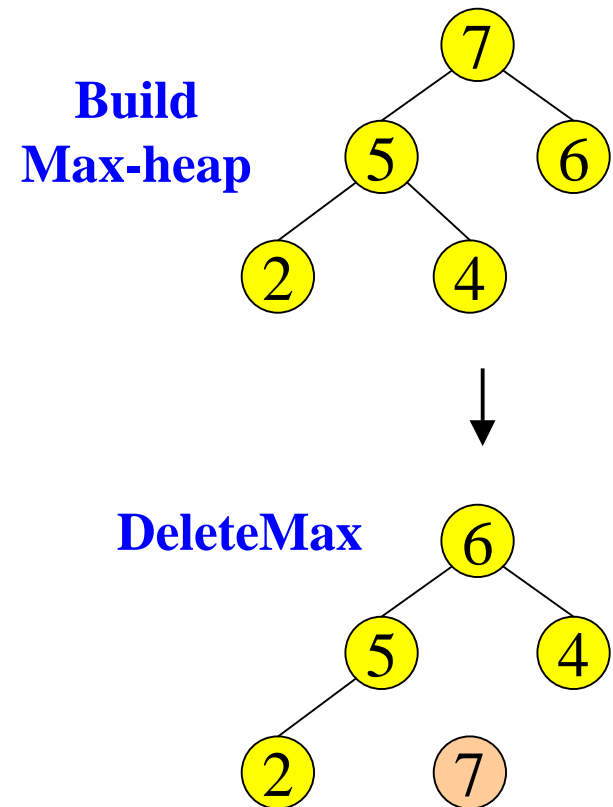




# Using Binary Heaps for Sorting

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- Build a max-heap
- Do N DeleteMax operations and store each Max element as it comes out of the heap
- Data comes out in largest to smallest order
- Where can we put the elements as they are removed from the heap?

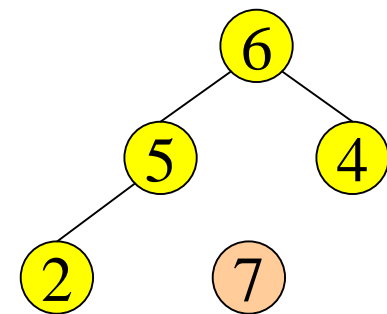


# 1 Removal = 1 Addition

- Every time we do a DeleteMin, the heap gets smaller by one node, and we have one more node to store
  - › Store the data at the end of the heap array
  - › Not "in the heap" but it is in the heap array

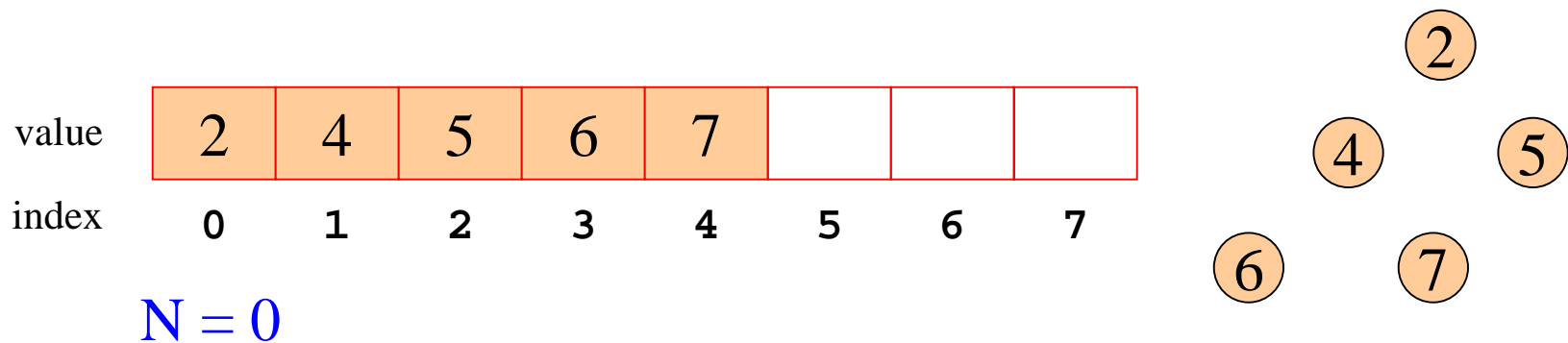
|       |   |   |   |   |   |   |   |   |
|-------|---|---|---|---|---|---|---|---|
| value | 6 | 5 | 4 | 2 | 7 |   |   |   |
| index | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |

$$N = 4$$



# Heap Sort is In-place

- After all the DeleteMins, the heap is gone but the array is full and is in sorted order
- Note that this heap implementation uses index 0 for data and has no sentinel value



# Heapsort: Analysis

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- Running time
  - › time to build max-heap is  $O(N)$
  - › time for  $N$  DeleteMax operations is  $N O(\log N)$
  - › total time is  **$O(N \log N)$**
- Can also show that running time is  $\Omega(N \log N)$  for some inputs,
  - › so *worst case* is  **$\Theta(N \log N)$**
  - › *Average case* running time is also  $O(N \log N)$