Minimum Spanning Trees

CSE 373

Data Structures

Recall Spanning Tree

```
• Given (connected) graph G(V,E),
```

```
a spanning tree T(V',E'):
```

- Spans the graph (V' = V)
- > Forms a tree (no cycle);
- > E' has |V| -1 edges

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Minimum Spanning Tree

- Edges are weighted: find minimum cost spanning tree
- Applications
 - > Find cheapest way to wire your house
 - Find minimum cost to send a message on the Internet

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3

Strategy for Minimum Spanning Tree

- For any spanning tree T, inserting an edge e_{new} not in T creates a cycle
- But
 - Removing any edge e_{old} from the cycle gives back a spanning tree
 - If e_{new} has a lower cost than e_{old} we have progressed!

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Strategy

- Strategy for construction:
 - Add an edge of minimum cost that does not create a cycle (greedy algorithm)
 - > Repeat |V| -1 times
 - Correct since if we could replace an edge with one of lower cost, the algorithm would have picked it up

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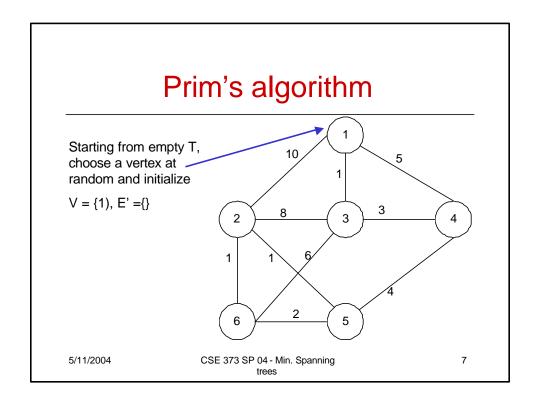
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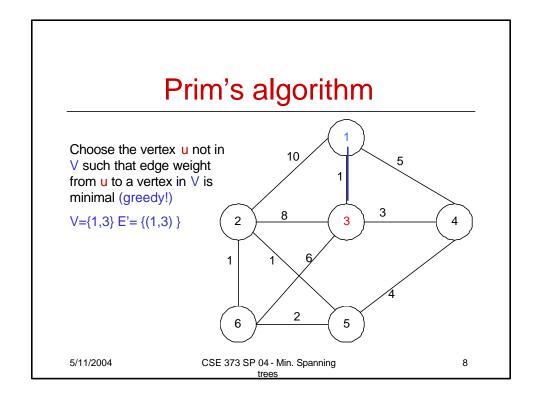
Two Algorithms

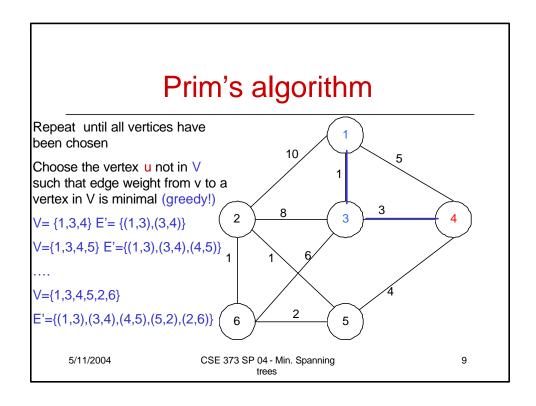
- Prim: (build tree incrementally)
 - Pick lower cost edge connected to known (incomplete) spanning tree that does not create a cycle and expand to include it in the tree
- Kruskal: (build forest that will finish as a tree)
 - Pick lower cost edge not yet in a tree that does not create a cycle and expand to include it somewhere in the forest

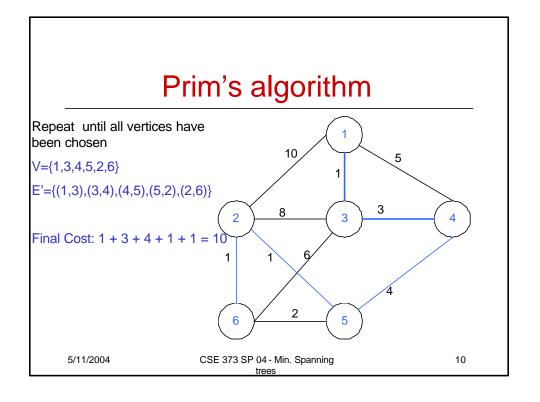
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Prim's Algorithm Implementation

Assume adjacency list representation

Initialize connection cost of each node to "inf" and "unmark" them Choose one node, say v and set cost[v]=0 and prev[v]=0 While they are unmarked nodes

Select the unmarked node \mathbf{u} with minimum cost; mark it For each unmarked node \mathbf{w} adjacent to \mathbf{u} if $cost(\mathbf{u}, \mathbf{w}) < cost(\mathbf{w})$ then $cost(\mathbf{w}) := cost(\mathbf{u}, \mathbf{w})$ prev[w] = u

· Looks a lot like Dijkstra's algorithm!

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11

Prim's algorithm Analysis

- Like Dijkstra's algorithm
- If the "Select the unmarked node u with minimum cost" is done with binary heap then O((n+m)logn)

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Kruskal's Algorithm

- Select edges in order of increasing cost
- Accept an edge to expand tree or forest only if it does not cause a cycle
- Implementation using adjacency list, priority queues and disjoint sets

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13

Kruskal's Algorithm

```
Initialize a forest of trees, each tree being a single node
Build a priority queue of edges with priority being lowest cost
Repeat until |V| -1 edges have been accepted {
    Deletemin edge from priority queue
    If it forms a cycle then discard it
    else accept the edge – It will join 2 existing trees yielding a larger tree
        and reducing the forest by one tree
}
```

The accepted edges form the minimum spanning tree

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trees

Detecting Cycles

- If the edge to be added (u,v) is such that vertices u and v belong to the same tree, then by adding (u,v) you would form a cycle
 - Therefore to check, Find(u) and Find(v). If they are the same discard (u,v)
 - If they are different Union(Find(u),Find(v))

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15

Properties of trees in K's algorithm

- · Vertices in different trees are disjoint
 - True at initialization and Union won't modify the fact for remaining trees
- Trees form equivalent classes under the relation "is connected to"
 - u connected to u (reflexivity)
 - u connected to v implies v connected to u (symmetry)
 - u connected to v and v connected to w implies a path from u to w so u connected to w (transitivity)

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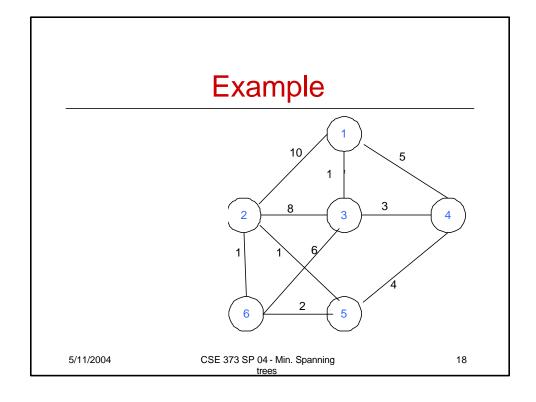
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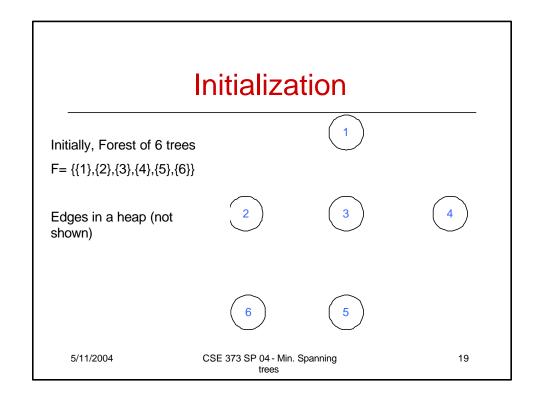
K's Algorithm Data Structures

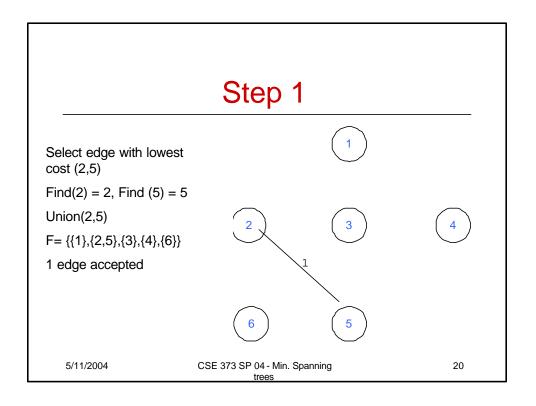
- · Adjacency list for the graph
 - To perform the initialization of the data structures below
- Disjoint Set ADT's for the trees (recall Up tree implementation of Union-Find)
- Binary heap for edges

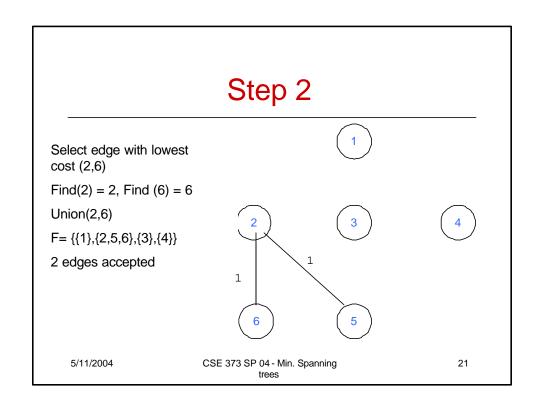
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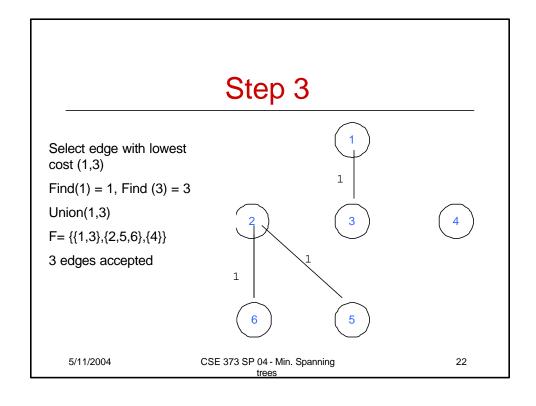
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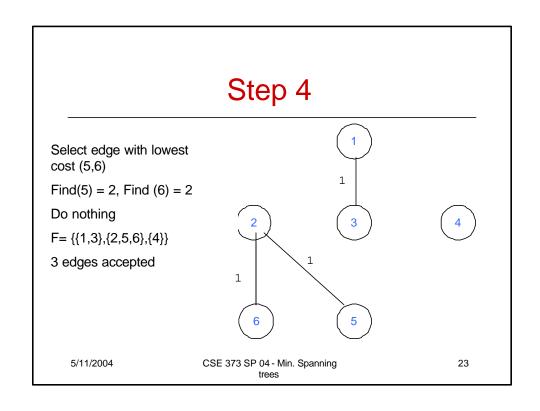


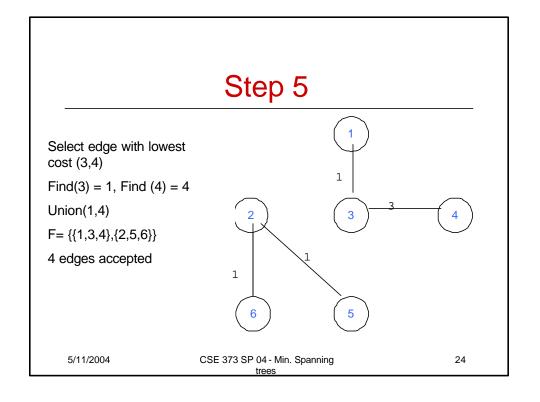


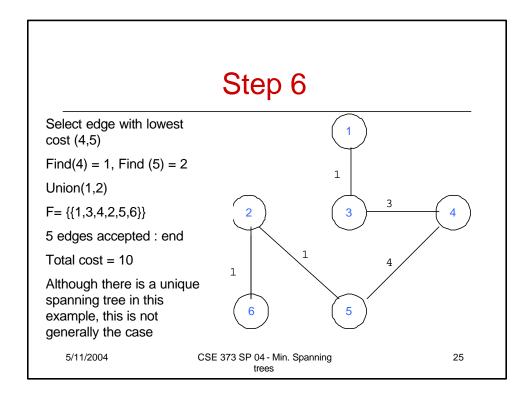












Kruskal's Algorithm Analysis

- Initialize forest O(n)
- Initialize heap O(m), m = |E|
- Loop performed m times
 - > In the loop one Deletemin O(logm)
 - > Two Find, each O(logn)
 - One Union (at most) O(1)
- So worst case O(mlogm) = O(mlogn)

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Time Complexity Summary

- Recall that m = |E| = O(V²) = O(n²)
- Prim's runs in O((n+m) log n)
- Kruskal's runs in O(mlogm) = O(mlogn)
- In practice, Kruskal has a tendency to run faster since graphs might not be dense and not all edges need to be looked at in the Deletemin operations

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