



CSE373: Data Structures & Algorithms Lecture 12: Hash Collisions

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Hash Tables: Review

Aim for constant-time (i.e., O(1)) find, insert, and delete
 "On average" under some reasonable assumptions



Collision resolution

Collision:

When two keys map to the same location in the hash table

We try to avoid it, but number-of-keys exceeds table size

So hash tables should support collision resolution

- Ideas?



Chaining:

All keys that map to the same table location are kept in a list (a.k.a. a "chain" or "bucket")

As easy as it sounds



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Thoughts on chaining

- Worst-case time for **find**?
 - Linear
 - But only with really bad luck or bad hash function
 - So not worth avoiding (e.g., with balanced trees at each bucket)
- Beyond asymptotic complexity, some "data-structure engineering" may be warranted
 - Linked list vs. array vs. chunked list (lists should be short!)
 - Move-to-front
 - Maybe leave room for 1 element (or 2?) in the table itself, to optimize constant factors for the common case
 - A time-space trade-off...

Time vs. space (constant factors only here)



More rigorous chaining analysis

Definition: The load factor, λ , of a hash table is

$$\lambda = \frac{N}{TableSize} \quad \leftarrow number of elements$$

Under chaining, the average number of elements per bucket is _____

So if some inserts are followed by *random* finds, then on average:

- Each unsuccessful find compares against _____ items
- Each successful **find** compares against _____ items

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Under chaining, the average number of elements per bucket is λ

So if some inserts are followed by *random* finds, then on average:

- Each unsuccessful **find** compares against *λ* items
- Each successful **find** compares against $\lambda/2$ items

So we like to keep λ fairly low (e.g., 1 or 1.5 or 2) for chaining

- Another simple idea: If h (key) is already full,
 - try (h(key) + 1) % TableSize. If full,
 - try (h(key) + 2) % TableSize. If full,
 - try (h(key) + 3) % TableSize. If full...
- Example: insert 38, 19, 8, 109, 10



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Open addressing

This is one example of open addressing

In general, open addressing means resolving collisions by trying a sequence of other positions in the table

Trying the next spot is called probing

- We just did linear probing
 - ith probe was (h(key) + i) % TableSize
- In general have some probe function f and use h(key) + f(i) % TableSize

Open addressing does poorly with high load factor λ

- So want larger tables
- Too many probes means no more O(1)

Terminology

We and the book use the terms

- "chaining" or "separate chaining"
- "open addressing"

Very confusingly,

- "open hashing" is a synonym for "chaining"
- "closed hashing" is a synonym for "open addressing"

(If it makes you feel any better, most trees in CS grow upside-down ^(C)) 20

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Other operations

insert finds an open table position using a probe function

What about **find**?

- Must use same probe function to "retrace the trail" for the data
- Unsuccessful search when reach empty position

What about **delete**?

- *Must* use "lazy" deletion. Why?
 - Marker indicates "no data here, but don't stop probing"
- Note: delete with chaining is plain-old list-remove

(Primary) Clustering

It turns out linear probing is a *bad idea*, even though the probe function is quick to compute (which is a good thing)

Tends to produce *clusters*, which lead to long probing sequences

- Called primary clustering
- Saw this starting in our example



Analysis of Linear Probing

- Trivial fact: For any λ < 1, linear probing will find an empty slot
 It is "safe" in this sense: no infinite loop unless table is full
- Non-trivial facts we won't prove:
 Average # of probes given λ (in the limit as TableSize →∞)

- Unsuccessful search:
$$\frac{1}{2} \left(1 + \frac{1}{(1-\lambda)^2} \right)$$

- Successful search:
$$\frac{1}{2} \left(1 + \frac{1}{(1-\lambda)} \right)$$

• This is pretty bad: need to leave sufficient empty space in the table to get decent performance (see chart)

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In a chart

- Linear-probing performance degrades rapidly as table gets full
 - (Formula assumes "large table" but point remains)



By comparison, chaining performance is linear in λ and has no trouble with λ>1

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Quadratic probing

- We can avoid primary clustering by changing the probe function (h(key) + f(i)) % TableSize
- A common technique is quadratic probing:

 $f(i) = i^2$

- So probe sequence is:
 - Oth probe: h(key) % TableSize
 - 1st probe: (h(key) + 1) % TableSize
 - 2nd probe: (h(key) + 4) % TableSize
 - 3rd probe: (h(key) + 9) % TableSize
 - ...
 - ith probe: (h(key) + i²) % TableSize
- Intuition: Probes quickly "leave the neighborhood"

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TableSize = 7

Insert:

76

40

48

5

55

(76	5 % 7	7 = 6)
(40) % 7	7 = 5)
(48	8 % 7	7 = 6)
(5	5 % 7	7 = 5)
(55	5 % 7	7 = 6)
(47	/ % 7	7 = 5)



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Doh!: For all *n*, ((n*n) +5) % 7 is 0, 2, 5, or 6

- Excel shows takes "at least" 50 probes and a pattern
- Proof uses induction and $(n^2+5) \approx 7 = ((n-7)^2+5) \approx 7$
 - In fact, for all c and k, (n^2+c) % $k = ((n-k)^2+c)$ % k

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From Bad News to Good News

- Bad news:
 - Quadratic probing can cycle through the same full indices, never terminating despite table not being full
- Good news:
 - If TableSize is prime and λ < ½, then quadratic probing will find an empty slot in at most TableSize/2 probes
 - So: If you keep λ < ½ and TableSize is prime, no need to detect cycles
 - Optional: Proof is posted in lecture12.txt
 - Also, slightly less detailed proof in textbook
 - Key fact: For prime T and 0 < i, j < T/2 where i ≠ j,
 (k + i²) % T ≠ (k + j²) % T (i.e., no index repeat)

Clustering reconsidered

- Quadratic probing does not suffer from primary clustering: no problem with keys initially hashing to the same neighborhood
- But it's no help if keys initially hash to the same index
 - Called secondary clustering
- Can avoid secondary clustering with a probe function that depends on the key: double hashing...

Double hashing

Idea:

- Given two good hash functions h and g, it is very unlikely that for some key, h(key) == g(key)
- So make the probe function f(i) = i*g(key)

Probe sequence:

- Oth probe: h(key) % TableSize
- 1st probe: (h(key) + g(key)) % TableSize
- 2nd probe: (h(key) + 2*g(key)) % TableSize
- 3rd probe: (h(key) + 3*g(key)) % TableSize
-
- ith probe: (h(key) + i*g(key)) % TableSize

Detail: Make sure g(key) cannot be 0

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Double-hashing analysis

- Intuition: Because each probe is "jumping" by g(key) each time, we "leave the neighborhood" and "go different places from other initial collisions"
- But we could still have a problem like in quadratic probing where we are not "safe" (infinite loop despite room in table)
 - It is known that this cannot happen in at least one case:
 - h(key) = key % p
 - g(key) = q (key % q)
 - 2 < q < p
 - **p** and **q** are prime

More double-hashing facts

- Assume "uniform hashing"
 - Means probability of g(key1) % p == g(key2) % p is 1/p
- Non-trivial facts we won't prove:
 Average # of probes given λ (in the limit as TableSize →∞)
 - Unsuccessful search (intuitive):

$$\overline{1-\lambda}$$

- Successful search (less intuitive):

$$\frac{1}{\lambda} \log_{e} \left(\frac{1}{1 - \lambda} \right)$$

 Bottom line: unsuccessful bad (but not as bad as linear probing), but successful is not nearly as bad

Charts



Rehashing

- As with array-based stacks/queues/lists, if table gets too full, create a bigger table and copy everything
- With chaining, we get to decide what "too full" means
 - Keep load factor reasonable (e.g., < 1)?</p>
 - Consider average or max size of non-empty chains?
- For open addressing, half-full is a good rule of thumb
- New table size
 - Twice-as-big is a good idea, except, uhm, that won't be prime!
 - So go *about* twice-as-big
 - Can have a list of prime numbers in your code since you won't grow more than 20-30 times