Minimum Spanning Trees

CSE 373

Data Structures & Algorithms

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Spring 2013

Today's Outline

- Announcements:
 - > HW 5 due Friday, May 31.
- Today's Topics:
 - > Weiss 9.5, 9.6

6/3/13 Minimum Spanning Trees

Recall Spanning Tree

- Given (connected) graph G(V,E), a spanning tree T(V',E'):
 - Spans the graph (V' = V)
 - Forms a tree (no cycle);
 - › E' has |V| -1 edges

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Minimum Spanning Tree

- Edges are weighted: find minimum cost spanning tree
- Applications
 - › Find cheapest way to wire your house
 - Find minimum cost to send a message on the Internet

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Strategy for Minimum Spanning Tree

- For any spanning tree T, inserting an edge e_{new} not in T creates a cycle
- But
 - Removing any edge e_{old} from the cycle gives back a spanning tree
 - If e_{new} has a lower cost than e_{old} we have progressed!

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Minimum Spanning Trees

Strategy

- Strategy for construction:
 - Add an edge of minimum cost that does not create a cycle (greedy algorithm)
 - > Repeat |V| -1 times
 - Correct since if we could replace an edge with one of lower cost, the algorithm would have picked it up

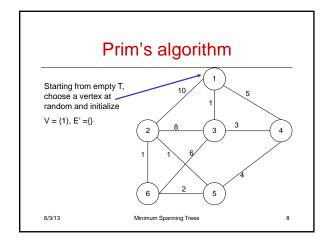
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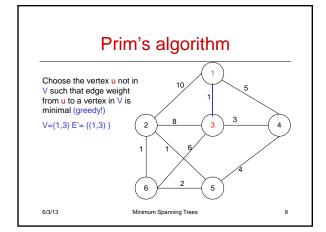
Minimum Spanning Trees

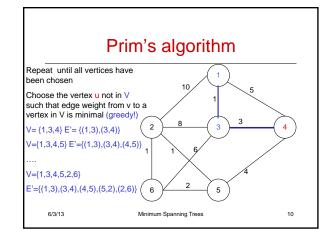
Two Algorithms

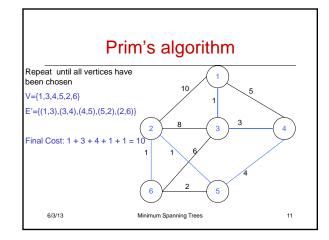
- Prim: (build tree incrementally)
 - Pick lower cost edge connected to known (incomplete) spanning tree that does not create a cycle and expand to include it in the tree
- Kruskal: (build forest that will finish as a tree)
 - Pick lower cost edge not yet in a tree that does not create a cycle and expand to include it somewhere in the forest

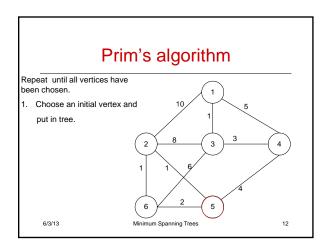
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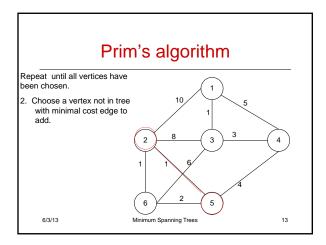


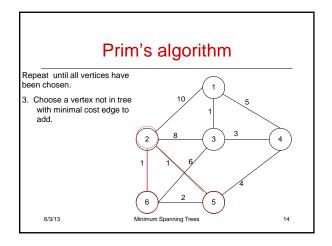


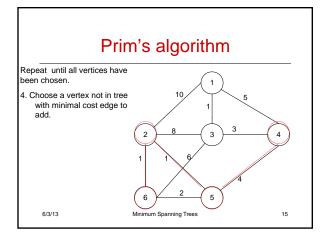


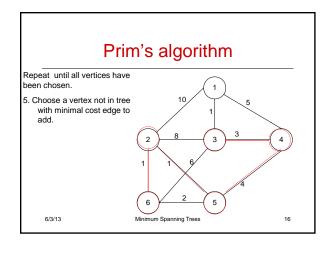


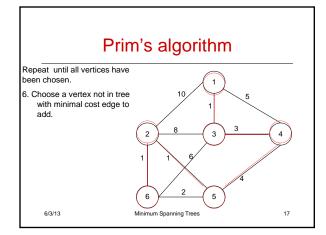




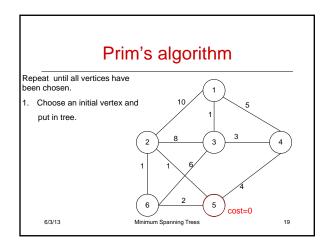


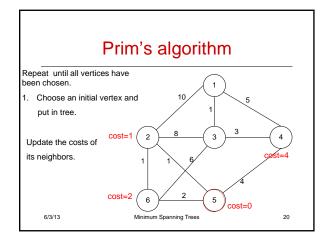


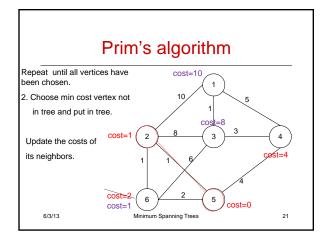


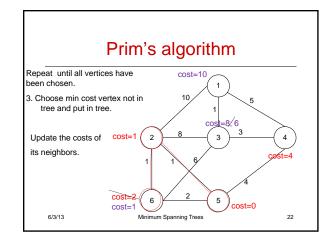


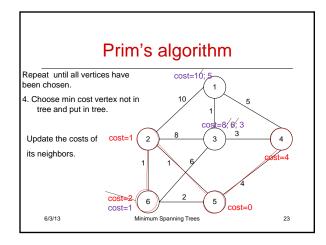
Prim's Algorithm Implementation • Assume adjacency list representation Initialize connection cost of each node to "inf" and "unmark" them Choose one node, say v and set cost[v] = 0 and prev[v] = 0 While there are unmarked nodes Select the unmarked node u with minimum cost; mark it For each unmarked node w adjacent to u if cost(u, w) < cost(w) then { cost(w) := cost (u, w) prev[w] = u} • Looks a lot like Dijkstra's algorithm! 6/3/13











Prim's algorithm Analysis • Like Dijkstra's algorithm • If the "Select the unmarked node u with minimum cost" is done with binary heap then O((n+m)logn)

Kruskal's Algorithm

- · Select edges in order of increasing cost
- Accept an edge to expand tree or forest only if it does not cause a cycle
- Implementation using adjacency list, priority queues and disjoint sets

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Kruskal's Algorithm

Initialize a forest of trees, each tree being a single node
Build a priority queue of edges with priority being lowest cost

Repeat until |V| -1 edges have been accepted {
 Deletemin edge from priority queue
 If it forms a cycle then discard it
 else accept the edge – It will join 2 existing trees yielding a larger tree
 and reducing the forest by one tree

The accepted edges form the minimum spanning tree

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Detecting Cycles

- If the edge to be added (u,v) is such that vertices u and v belong to the same tree, then by adding (u,v) you would form a cycle
 - Therefore to check, Find(u) and Find(v). If they are the same discard (u,v)
 - If they are different Union(Find(u),Find(v))

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Properties of trees in K's algorithm

- Vertices in different trees are disjoint
 - True at initialization and Union won't modify the fact for remaining trees
- Trees form equivalent classes under the relation "is connected to"
 - u connected to u (reflexivity)
 - u connected to v implies v connected to u (symmetry)
 - u connected to v and v connected to w implies a path from u to w so u connected to w (transitivity)

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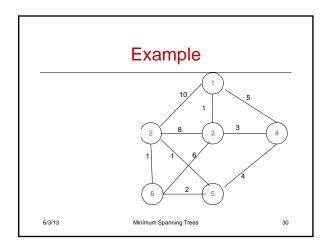
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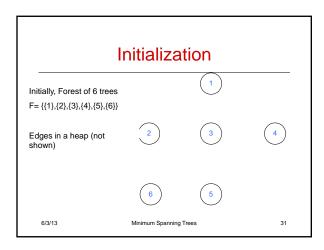
K's Algorithm Data Structures

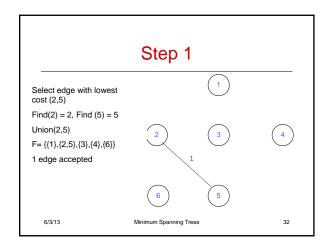
- · Adjacency list for the graph
 - To perform the initialization of the data structures below
- Disjoint Set ADT's for the trees (recall Up tree implementation of Union-Find)
- · Binary heap for edges

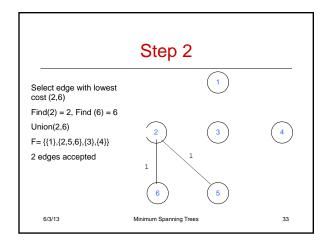
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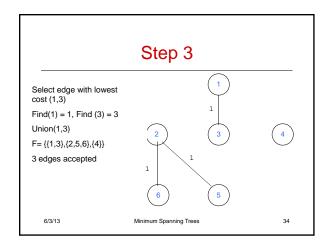
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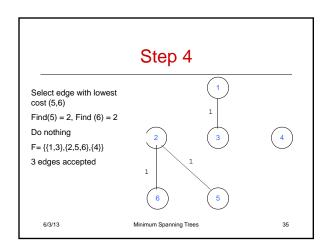


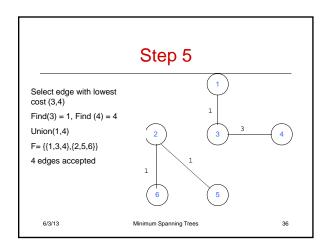


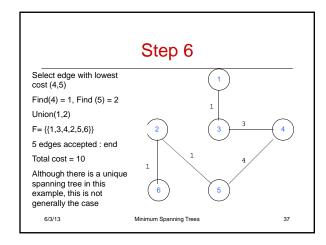












Kruskal's Algorithm Analysis

- Initialize forest O(n)
- Initialize heap O(m), m = |E|
- Loop performed m times
 - > In the loop one Deletemin O(logm)
 - Two Find, each O(logn)
 - One Union (at most) O(1)
- So worst case O(mlogm) = O(mlogn)

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Time Complexity Summary

- Recall that $m = |E| = O(V^2) = O(n^2)$
- Prim's runs in O((n+m) log n)
- Kruskal's runs in O(m log m)
- In practice, Kruskal has a tendency to run faster since graphs might not be dense and not all edges need to be looked at in the Deletemin operations

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