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# CSE 421

## Polynomial Time Reductions NP Completeness

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# Decision Problems

A decision problem is a computational problem where the answer is just **yes/no**

Here, we study computational complexity of decision Problems.

## Why?

- much simpler to deal with
- Decision version is not harder than Search version, so it is easier to lower bound Decision version
- Less important, usually, you can use decider multiple times to find an answer .

# Polynomial Time

Define  $P$  (polynomial-time) to be the set of all **decision problems** solvable by algorithms whose worst-case running time is bounded by some polynomial in the input size.

Do we well understand  $P$ ?

- We can prove that a problem is in  $P$  by exhibiting a polynomial time algorithm
- It is in most cases very hard to prove a problem is not in  $P$ .

# Beyond P?

We have seen many problems that seem hard

- Independent Set
- 3-coloring
- Min Vertex Cover
- 3-SAT

The independent set S

The 3-coloring

The vertex cover S

The T/F assignment

Given a 3-CNF  $(x_1 \vee \overline{x_2} \vee x_9) \wedge (\overline{x_2} \vee x_3 \vee x_7) \wedge \dots$  is there a satisfying assignment?

**Common Property:** If the answer is yes, there is a “short” proof (a.k.a., certificate), that allows you to verify (in polynomial-time) that the answer is yes.

- The proof may be hard to find

# NP

**Certifier:** algorithm  $C(x, t)$  is a **certifier** for problem  $A$  if for every string  $x$ , the answer is “yes” iff there exists a string  $t$  such that  $C(x, t) = \text{yes}$ .

**Intuition:** Certifier doesn't determine whether answer is “yes” on its own; rather, it checks a proposed proof that answer is “yes”.

**NP:** Decision problems for which there exists a poly-time certifier.

Remark. NP stands for nondeterministic polynomial-time.

# Example: 3SAT is in NP

Given a 3-CNF formula, is there a satisfying assignment?

**Certificate:** An assignment of truth values to the  $n$  boolean variables.

**Verifier:** Check that each clause has at least one true literal.

**Ex:**  $(x_1 \vee \overline{x_3} \vee x_4) \wedge (x_2 \vee \overline{x_4} \vee x_3) \wedge (x_2 \vee \overline{x_1} \vee x_3)$

**Certificate:**  $x_1 = T, x_2 = F, x_3 = T, x_4 = F$

**Conclusion:** 3-SAT is in NP

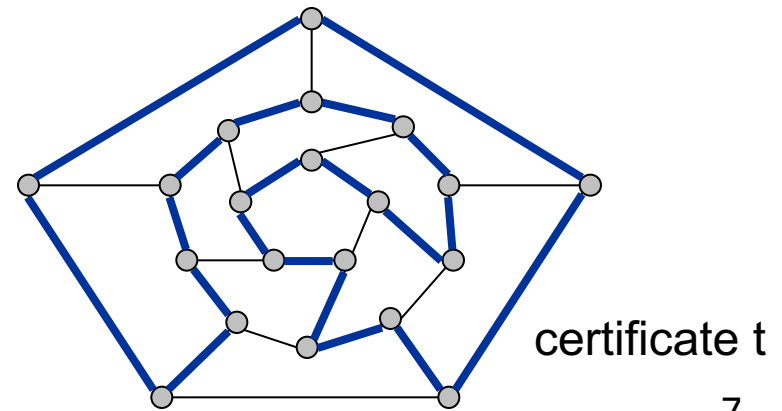
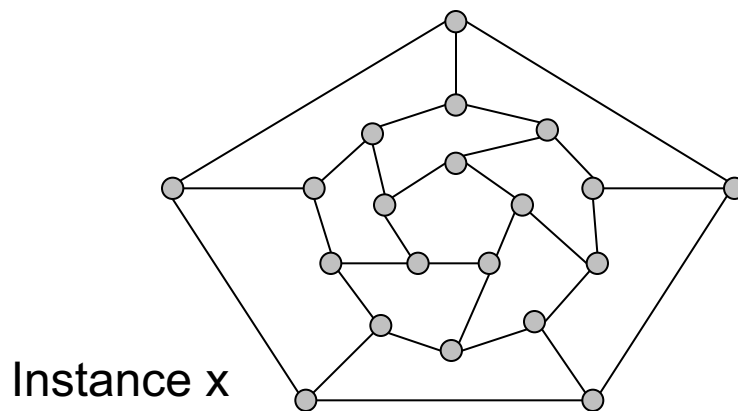
# Example: Hamil-Cycle is in NP

**HAM-CYCLE.** Given an undirected graph  $G = (V, E)$ , does there exist a simple cycle  $C$  that visits every node?

**Certificate.** A permutation of the  $n$  nodes.

**Certifier.** Check that the permutation contains each node in  $V$  exactly once, and that there is an edge between each pair of adjacent nodes in the permutation.

**Conclusion.** HAM-CYCLE is in NP.



# Example: Min s,t-cut in in NP

**MIN-CUT.** Given a flow network, and a number  $k$ , does there exist a min-cut of capacity at most  $k$ ?

**Certificate.** A s-t min-cut  $(A,B)$ .

**Certifier.** Check that the capacity of the min-cut is at most  $k$ .

**Conclusion.** MIN-CUT is in NP.



# P, NP, EXP

**P.** Decision problems for which there is a **poly-time algorithm**.

**EXP.** Decision problems for which there is an **exponential-time algorithm**.

**NP.** Decision problems for which there is a **poly-time certifier**.

**Claim.**  $P \subseteq NP$ .

**Pf.** Consider any problem  $X$  in  $P$ .

By definition, there exists a poly-time algorithm  $A(x)$  that solves  $X$ .

Certificate:  $t = \text{empty string}$ , certifier  $C(x, \emptyset) = A(x)$ . ■

**Claim.**  $NP \subseteq EXP$ .

**Pf.** Consider any problem  $X$  in  $NP$ .

By definition, there exists a poly-time certifier  $C(x, t)$  for  $X$ .

To solve input  $x$ , run  $C(x, t)$  on all strings  $t$  with length  $\text{polyn}$  in  $|x|$

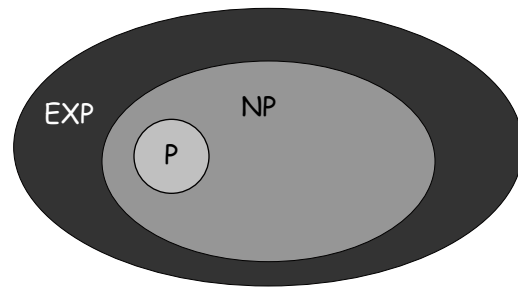
Return  $\text{yes}$ , if  $C(x, t)$  returns  $\text{yes}$  for any of these.

# The main question: P vs NP

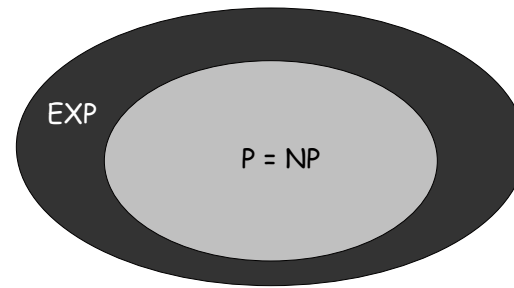
Does  $P = NP$ ? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]

Is the decision problem as easy as the certification problem?

Clay \$1 million prize.



If  $P \neq NP$



If  $P = NP$

If yes: Efficient algorithms for 3-COLOR, TSP, FACTOR, SAT, ...

If no: No efficient algorithms possible for 3-COLOR, TSP, SAT, ...

# What do we know about NP?

- Nobody knows if all problems in NP can be done in polynomial time, i.e. does  $P=NP$ ?
  - one of the most important open questions in all of science.
  - Huge practical implications specially if answer is yes
- To show Hamil-cycle  $\notin P$  we have to prove that there is no poly-time algorithm for it even using all mathematical theorem that will be discovered in **future!**

# NP Completeness

**Complexity Theorists Approach:** We don't know how to prove any problem in NP is hard. So, let's find **hardest** problems in NP.

**NP-hard:** A problem B is NP-hard iff for any problem  $A \in NP$ , we have  $A \leq_p B$

**NP-Completeness:** A problem B is NP-complete iff B is NP-hard and  $B \in NP$ .

## Motivations:

- If  $P \neq NP$ , then every NP-Complete problems is not in P. So, we shouldn't try to design Polytime algorithms
- To show  $P = NP$ , it is enough to design a polynomial time algorithm for just one NP-complete problem.

# Cook-Levin Theorem

**Theorem (Cook 71, Levin 73):** 3-SAT is NP-complete, i.e., for all problems  $A \in NP$ ,  $A \leq_p$  3-SAT.

- So, 3-SAT is the hardest problem in NP.

What does this say about other problems of interest? Like Independent set, Vertex Cover, ...

**Fact:** If  $A \leq_p B$  and  $B \leq_p C$  then,  $A \leq_p C$

**Pf idea:** Just compose the reductions from A to B and B to C

So, if we prove  $3\text{-SAT} \leq_p$  Independent set, then Independent Set, Clique, Vertex cover, Set cover are all NP-complete

$3\text{-SAT} \leq_p$  Independent Set  $\leq_p$  Vertex Cover  $\leq_p$  Set Cover

# Summary

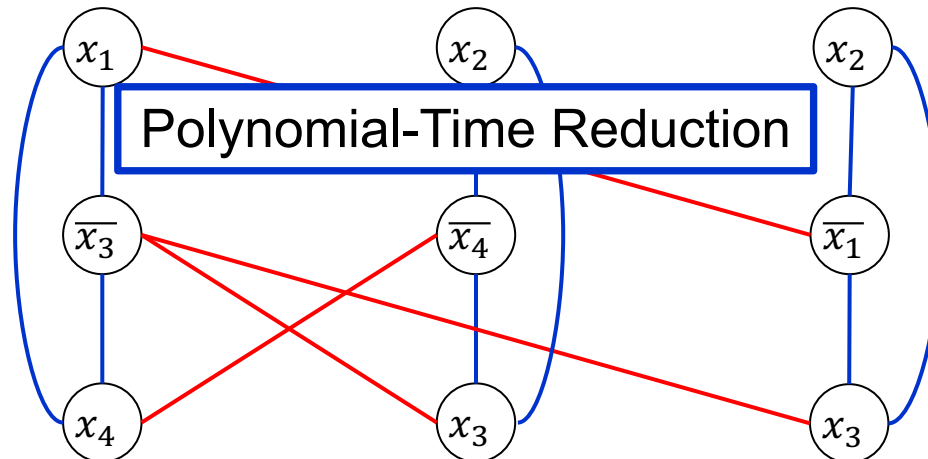
- If a problem is NP-hard it does not mean that all instances are hard, e.g., Vertex-cover has a polynomial-time algorithm on trees or bipartite graphs
- We learned the crucial idea of polynomial-time reduction. This can be even used in algorithm design, e.g., we know how to solve max-flow so we reduce image segmentation to max-flow
- NP-Complete problems are the hardest problem in NP
- NP-hard problems may not necessarily belong to NP.
- Polynomial-time reductions are transitive relations

# 3-SAT $\leq_p$ Independent Set

Map a 3-CNF to  $(G,k)$ . Say  $m$  is number of clauses

- Create a vertex for each literal
- Join two literals if
  - They belong to the same clause (blue edges)
  - The literals are negations, e.g.,  $x_i, \bar{x}_i$  (red edges)
- Set  $k=m$

$$(x_1 \vee \bar{x}_3 \vee x_4) \wedge (x_2 \vee \bar{x}_4 \vee x_3) \wedge (x_2 \vee \bar{x}_1 \vee x_3)$$



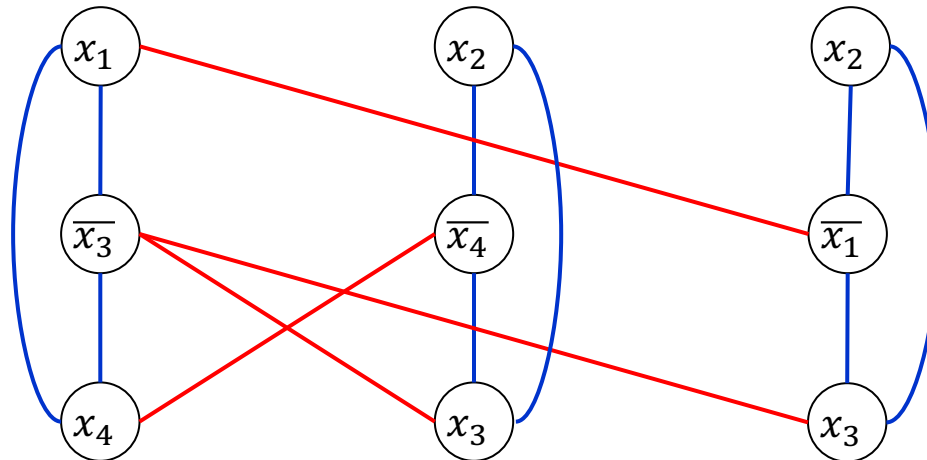
# Correctness of $3\text{-SAT} \leq_p \text{Indep Set}$

F satisfiable  $\Rightarrow$  An independent of size m

Given a satisfying assignment, Choose one node from each clause where the literal is satisfied

$$(x_1 \vee \bar{x}_3 \vee x_4) \wedge (x_2 \vee \bar{x}_4 \vee x_3) \wedge (x_2 \vee \bar{x}_1 \vee x_3)$$

Satisfying assignment:  $x_1 = T, x_2 = F, x_3 = T, x_4 = F$



- S has exactly one node per clause  $\Rightarrow$  No blue edges between S
- S follows a truth-assignment  $\Rightarrow$  No red edges between S
- S has one node per clause  $\Rightarrow |S|=m$



# Correctness of $3\text{-SAT} \leq_p \text{Indep Set}$

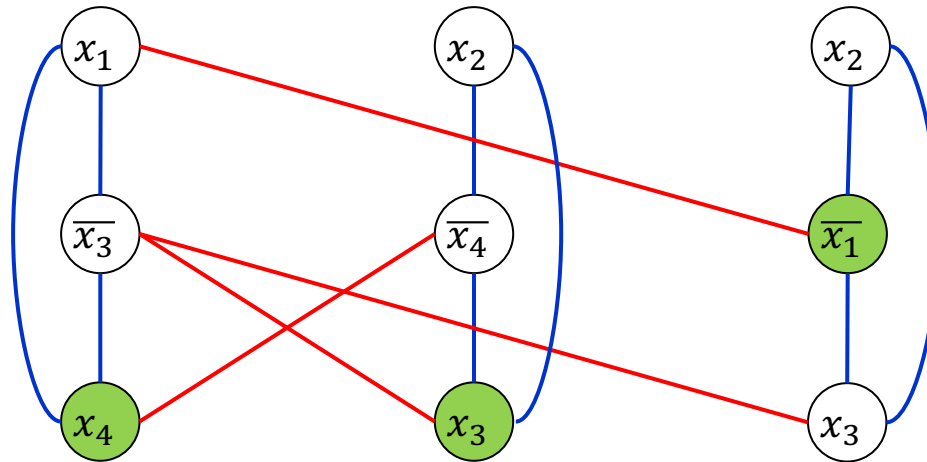
An independent set of size  $m \Rightarrow$  A satisfying assignment

Given an independent set  $S$  of size  $m$ .

$S$  has exactly one vertex per clause (because of blue edges)

$S$  does not have  $x_i, \bar{x}_i$  (because of red edges)

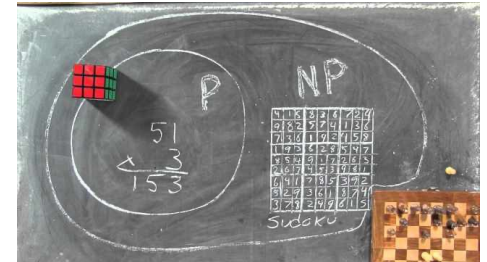
So,  $S$  gives a satisfying assignment



Satisfying assignment:  $x_1 = F, x_2 = ?, x_3 = T, x_4 = T$   
 $(x_1 \vee \bar{x}_3 \vee x_4) \wedge (x_2 \vee \bar{x}_4 \vee x_3) \wedge (x_2 \vee \bar{x}_1 \vee x_3)$

# What is next?

- CSE 431 (Complexity Course)
  - How to prove lower bounds on algorithms?
- CSE 422 (Advanced Toolkit for Modern Alg)
  - SVD, Data structures, many programming tasks

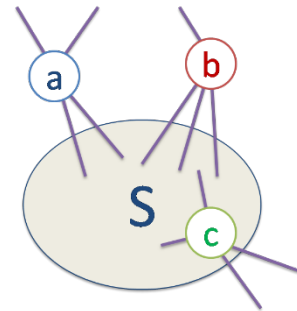


- CSE 521 (Graduate Algorithms Course)

Prereq: 312, Math 308

- How to design streaming algorithms?
- How to design algorithms for high dimensional data?
- How to use matrices/eigenvalues/eigenvectors to design algorithms
- How to use LPs to design algorithms?

$$p(a,S) = 2/8$$
$$p(b,S) = 3/8$$
$$p(c,S) = 6/8$$



- CSE 525 (Graduate Randomized Algorithms Course)

Prereq: CSE 521

- How to use randomization to design algorithms?
- How to use Markov Chains to design algorithms?



# Course Evaluations

- How can we improve this course?
- Did you like topics related to linear programming? Did you like to see more of that?
- Which topic was most/least interesting to you?
- Which problem sets did you like more?