Lecture 23

Polynomial-Time Reductions (cont.)

Why the notation?

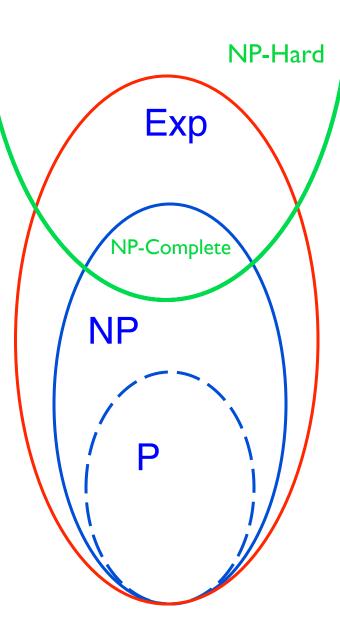
Define:
$$A \leq_p B$$
 "A is polynomial-time reducible to
B", iff there is a polynomial-time computable
function f such that: $x \in A \Leftrightarrow f(x) \in B$
"complexity of A" \leq "complexity of B" + "complexity of f"
(1) $A \leq_p B$ and $B \in P \Rightarrow A \in P$
(2) $A \leq_p B$ and $A \notin P \Rightarrow B \notin P$
(3) $A \leq_p B$ and $B \leq_p C \Rightarrow A \leq_p C$ (transitivity)

NP-Completeness

Definition: Problem B is *NP-hard* if every problem in NP is polynomially reducible to B.

Definition: Problem B is *NP-complete* if:

- (1) B belongs to NP, and
- (2) B is NP-hard.



"NP-completeness"

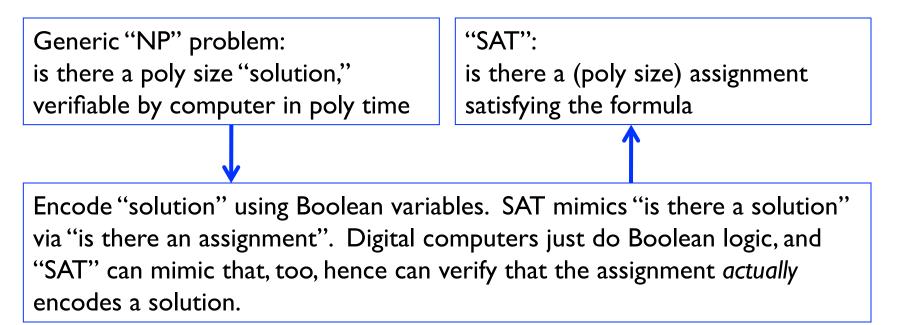
Cool concept, but are there any such problems?

Yes!

Cook's theorem: SAT is NP-complete

Why is SAT NP-complete?

Cook's proof is somewhat involved; details later. But its essence is not so hard to grasp:



Proving a problem is NP-complete

Technically, for condition (2) we have to show that every problem in NP is reducible to B. (Yikes! Sounds like a lot of work.)

For the very first NP-complete problem (SAT) this had to be proved directly.

However, once we have one NP-complete problem, then we don't have to do this every time.

Why? Transitivity.

Alt way to prove NP-completeness

Lemma: Problem B is NP-complete if:

- (I) B belongs to NP, and
- (2') A is polynomial-time reducible to B, for some problem A that is NP-complete.

That is, to show (2') given a new problem B, it is sufficient to show that SAT or any other NPcomplete problem is polynomial-time reducible to B.

Ex: VertexCover is NP-complete

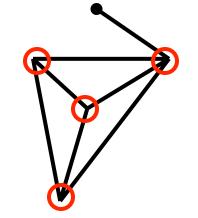
3-SAT is NP-complete (shown by S. Cook)
 3-SAT ≤_p VertexCover
 VertexCover is in NP (we showed this earlier)
 Therefore VertexCover is also NP-complete

So, poly-time algorithm for VertexCover would give poly-time algs for everything in NP

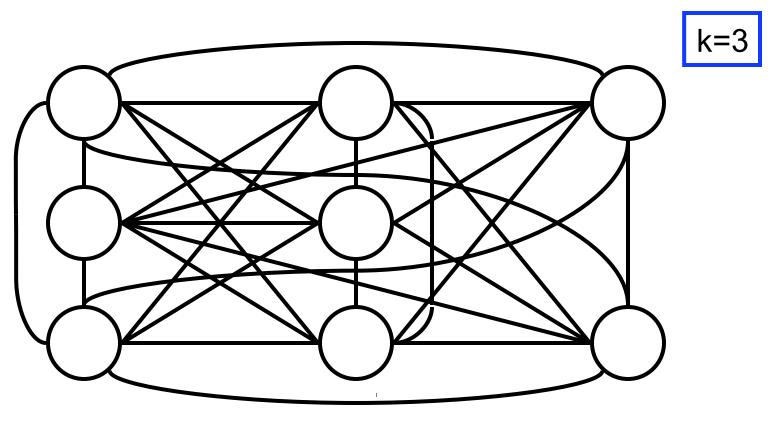
NP-complete problem: Clique

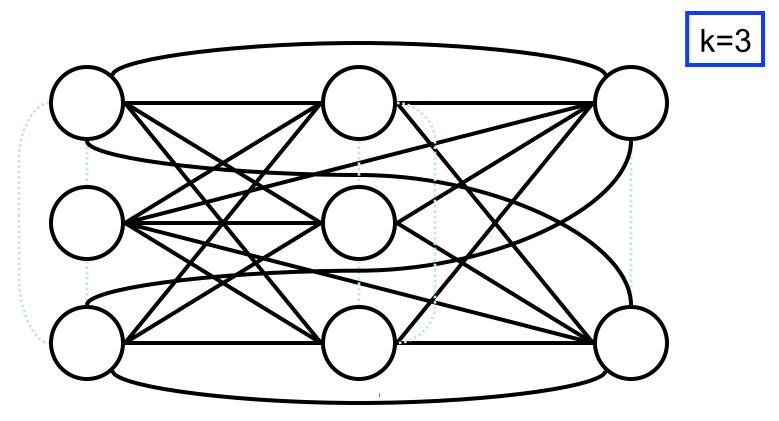
Input: Undirected graph G = (V, E), integer k. Output: True iff there is a subset C of V of size \geq k such that all vertices in C are connected to all other vertices in C.

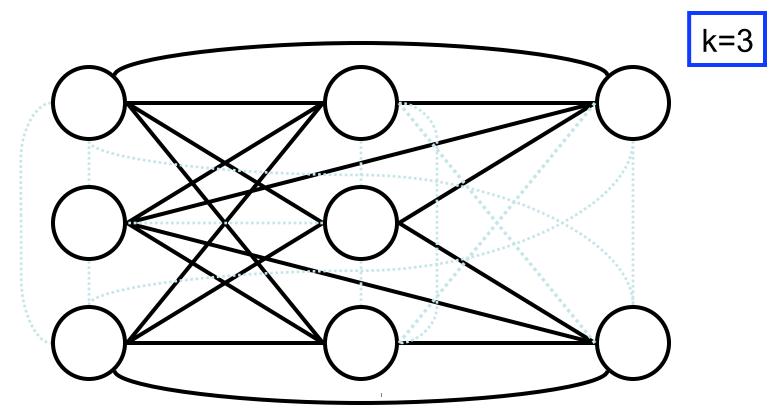
Example: Clique of size ≥ 4

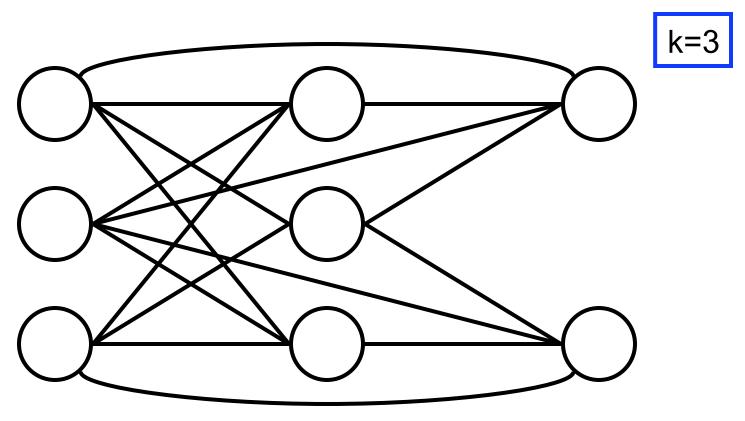


In NP? Exercise

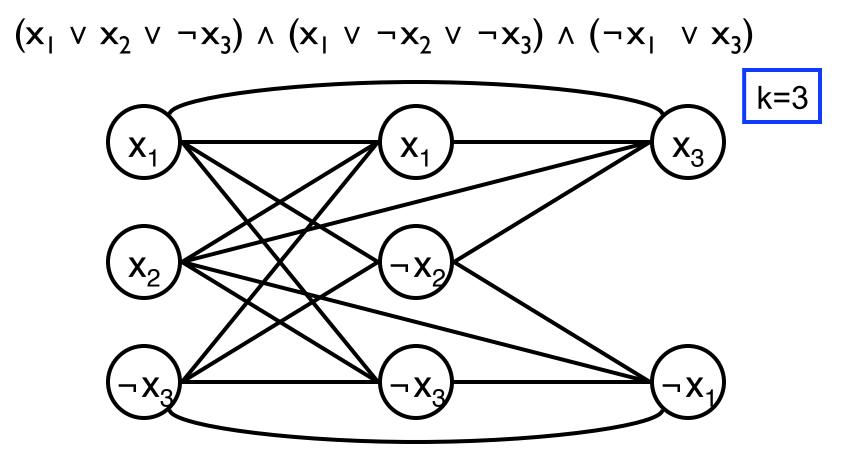


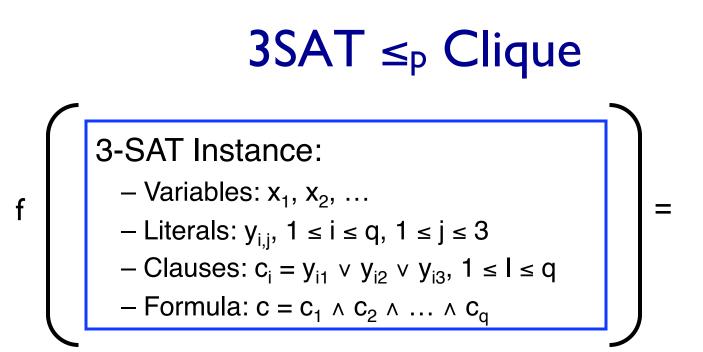












Clique Instance: - K = q - G = (V, E) - V = { [i,j] | 1 ≤ i ≤ q, 1 ≤ j ≤ 3 } - E = { ([i,j], [k,l]) | i ≠ k and $y_{ij} ≠ \neg y_{kl}$ }

Correctness of "3-SAT ≤_P Clique"

Summary of reduction function f:

Given formula, make graph G with column of nodes per clause, one node per literal. Connect each to all nodes in other columns, except complementary literals $(x, \neg x)$. Output graph G plus integer k = number of clauses. Note: f does not know whether formula is satisfiable or not; does not know if G has k-clique; does not try to find satisfying assignment or clique.

Correctness:

Show f poly time computable: A key point is that graph size is polynomial in formula size; mapping basically straightforward.

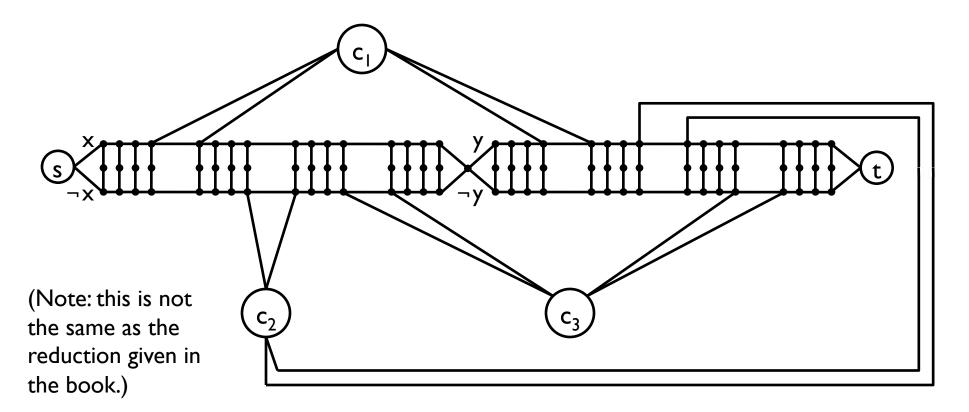
Show c in 3-SAT iff f(c)=(G,k) in Clique:

 (\Rightarrow) Given an assignment satisfying c, pick one true literal per clause. Show corresponding nodes in G are k-clique.

(\Leftarrow) Given a k-clique in G, clique labels define a truth assignment; show it satisfies c. Note: literals in a clique are a valid truth assignment [no "(x, \neg x)" edges] & k nodes must be 1 per column, [no edges within columns].

$3-SAT \leq_P UndirectedHamPath$

Example: $(x \lor y) \land (\neg x \lor y) \land (\neg x \lor \neg y)$





- Many copies of this 12-node gadget, each with one or more edges connecting each of the 4 corners to other nodes or gadgets (but no other edges to the 8 "internal" nodes).
- Claim: There are only 2 Ham paths one entering at I, exiting at I' (as shown); the other (by symmetry) $0 \rightarrow 0$ '
- Pf: Note *: at 1st visit to any column, must next go to *middle* node in column, else it will subsequently become an untraversable "dead end."
 WLOG, suppose enter at 1. By *, must then go down to 0. 2 cases:
- Case a: (top left) If next move is to right, then * forces path up, left is blocked, so right again, etc; out at 1'.
- Case b: (top rt) if exit at 0, then path must eventually reenter at 0' or 1'. * forces next move to be up/down to the other of 0'/1'. Must then go left to reach the 2 middle columns, but there's *no exit* from them. So case b is impossible.