### Lecture 26

# Coping with NP-Completeness

Is your real problem a special subcase?

E.g. 3-SAT is NP-complete, but 2-SAT is not; ditto 3- vs 2- coloring

E.g. you only need planar graphs, or degree 3 graphs, ...?

Guaranteed approximation good enough?

E.g. Euclidean TSP within 2 \* Opt in poly time

Fast enough in practice (esp. if n is small),

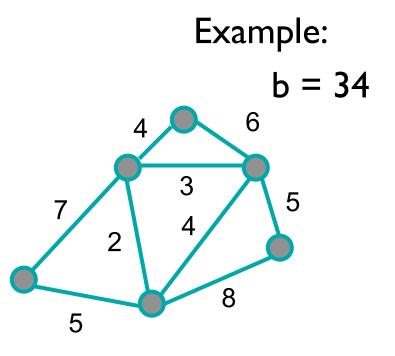
E.g. clever exhaustive search like backtrack, branch & bound, pruning

Heuristics – usually a good approximation and/or usually fast

### NP-complete problem: TSP

Input: An undirected graph G=(V,E) with integer edge weights, and an integer b.

Output: YES iff there is a simple cycle in G passing through all vertices (once), with total cost  $\leq$  b.



### **TSP - Nearest Neighbor Heuristic**

#### NN Heuristic –go to nearest unvisited vertex

Fact: NN tour can be about (log n) x opt, i.e.

$$\lim_{n \to \infty} \frac{NN}{OPT} \to \infty$$

(above example is not that bad)

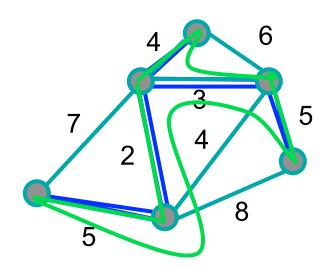
## 2x Approximation to EuclideanTSP

A TSP tour visits all vertices, so contains a spanning tree, so TSP cost is > cost of min spanning tree.

Find MST

Find "DFS" Tour

Shortcut



 $TSP \leq shortcut < DFST = 2 * MST < 2 * TSP$ 

## Summary

Big-O – good

P – good

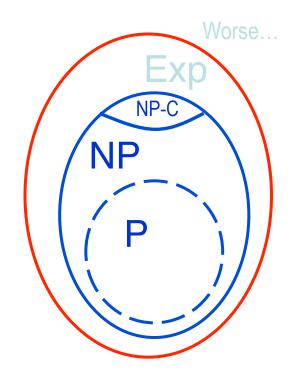
Exp – bad

Exp, but hints help? NP

NP-hard, NP-complete – bad (I bet)

To show NP-complete – reductions

NP-complete = hopeless? – no, but you need to lower your expectations: heuristics & approximations.



## Beyond NP

Many complexity classes are worse, e.g. time 2<sup>2<sup>n</sup></sup>, 2<sup>2<sup>n</sup></sup>, ...

Others seem to be "worse" in a different sense, e.g., not in NP, but still exponential time. E.g., let

Lp = "assignment y satisfies formula x",  $\in P$ 

Then :

$$\begin{split} &\mathsf{SAT} = \big\{ \ \mathbf{x} \ \big| \ \exists \mathbf{y} \ \langle \mathbf{x}, \mathbf{y} \rangle \in \mathsf{L}_{\mathsf{P}} \ \big\} \\ &\mathsf{UNSAT} = \big\{ \ \mathbf{x} \ \big| \ \forall \mathbf{y} \ \langle \mathbf{x}, \mathbf{y} \rangle \in \mathsf{L}_{\mathsf{P}} \ \big\} \\ &\mathsf{QBF}_{\mathsf{k}} = \big\{ \ \mathbf{x} \ \big| \ \exists \mathbf{y}_{1} \ \forall \mathbf{y}_{2} \exists \mathbf{y}_{3} \dots & \bigcirc_{\mathsf{k}} \ \langle \mathbf{x}, \mathbf{y}_{1} \dots \mathbf{y}_{\mathsf{k}} \rangle \in \mathsf{L}_{\mathsf{P}} \ \big\} \\ &\mathsf{QBF}_{\infty} = \big\{ \ \mathbf{x} \ \big| \ \exists \mathbf{y}_{1} \ \forall \mathbf{y}_{2} \exists \mathbf{y}_{3} \dots & \langle \mathbf{x}, \mathbf{y}_{1} \dots & \rangle \in \mathsf{L}_{\mathsf{P}} \ \big\} \end{split}$$