## Introduction to Database Systems CSE 444

Lecture 19: Operator Algorithms

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# Why Learn About Op Algos?

- Implemented in commercial DBMSs
  - DBMSs implement different subsets of known algorithms
- Good algorithms can greatly improve performance
- Need to know about physical operators to understand query optimization

#### **Cost Parameters**

- In database systems the data is on disk
- Cost = total number of I/Os
- Parameters:
  - B(R) = # of blocks (i.e., pages) for relation R
  - T(R) = # of tuples in relation R
  - V(R, a) = # of distinct values of attribute a
    - When a is a key, V(R,a) = T(R)
    - When a is not a key, V(R,a) can be anything < T(R)

## Cost

- Cost of an operation = number of disk I/Os to
  - Read the operands
  - Compute the result
- Cost of writing the result to disk is *not included* Need to count it separately when applicable

# Cost of Scanning a Table

- Result may be unsorted: B(R)
- Result needs to be sorted: 3B(R)
  - We will discuss sorting later

# Outline for Today

#### Join operator algorithms

- One-pass algorithms (Sec. 15.2 and 15.3)
- Index-based algorithms (Sec 15.6)
- Two-pass algorithms (Sec 15.4 and 15.5)
- Note about readings:
  - In class, we will discuss only algorithms for join operator (because other operators are easier)
  - Read the book to get more details about these algos
  - Read the book to learn about algos for other operators

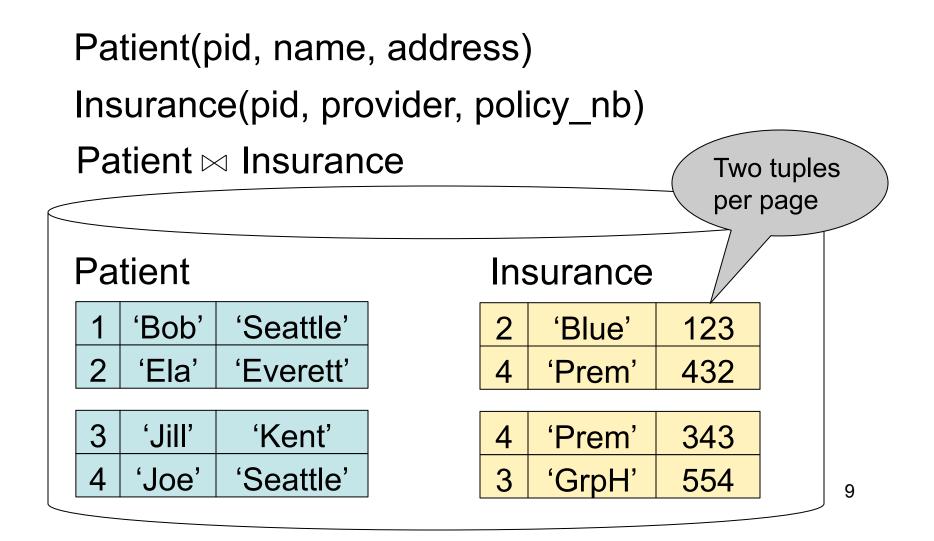
## **Basic Join Algorithms**

- Logical operator:
  - Product(pname, cname) 
     Kompany(cname, city)
- Propose three physical operators for the join, assuming the tables are in main memory:
  - Hash join
  - Nested loop join
  - Sort-merge join

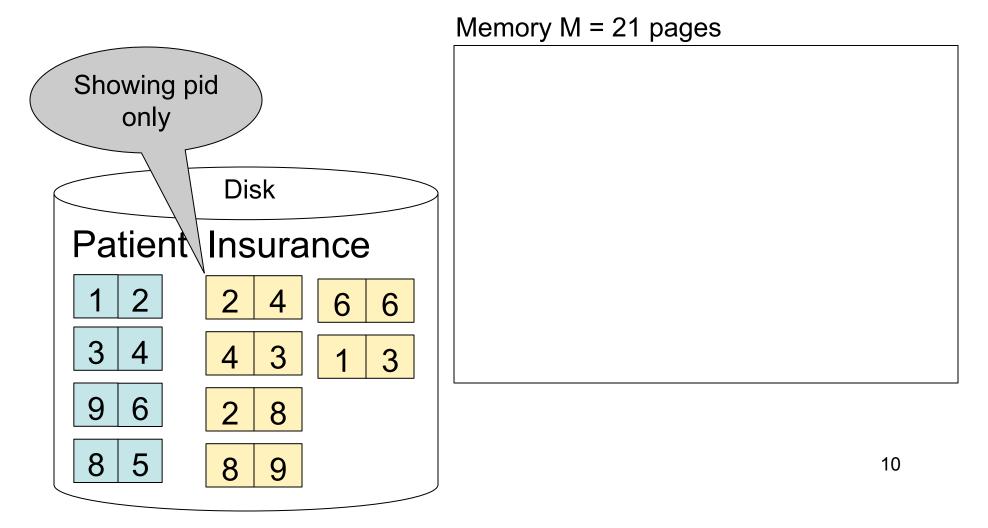
# Hash Join

Hash join:  $R \bowtie S$ 

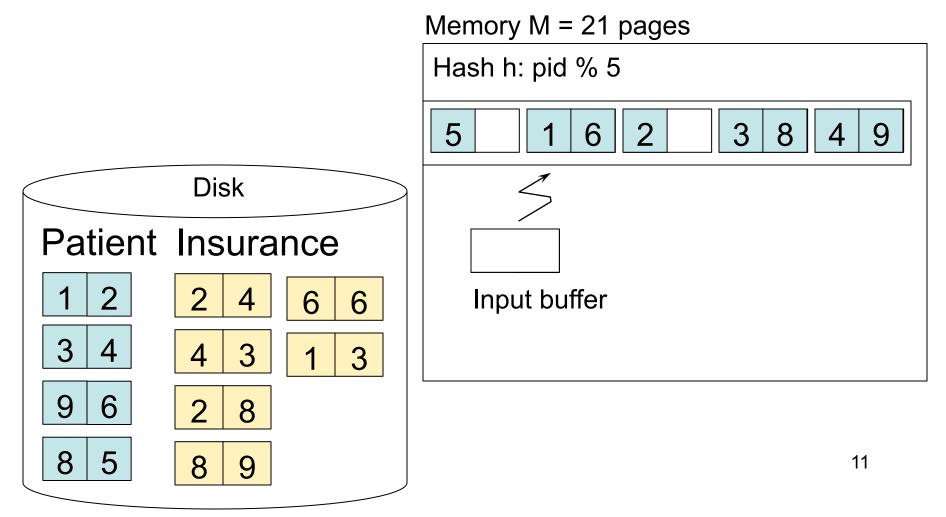
- Scan R, build buckets in main memory
- Then scan S and join
- Cost: B(R) + B(S)
- One-pass algorithm when B(R) <= M</li>
  - By "one pass", we mean that the operator reads its operands only once. It does not write intermediate results back to disk.



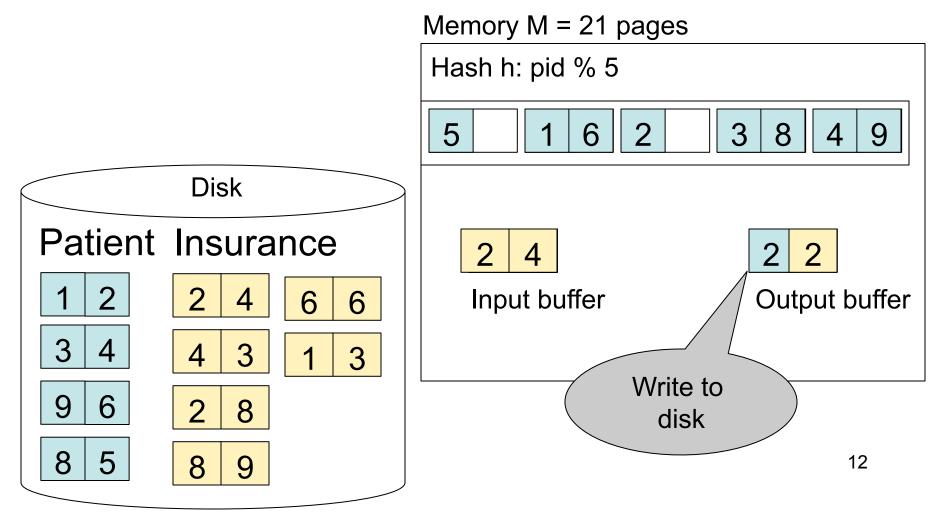
#### Patient ⋈ Insurance



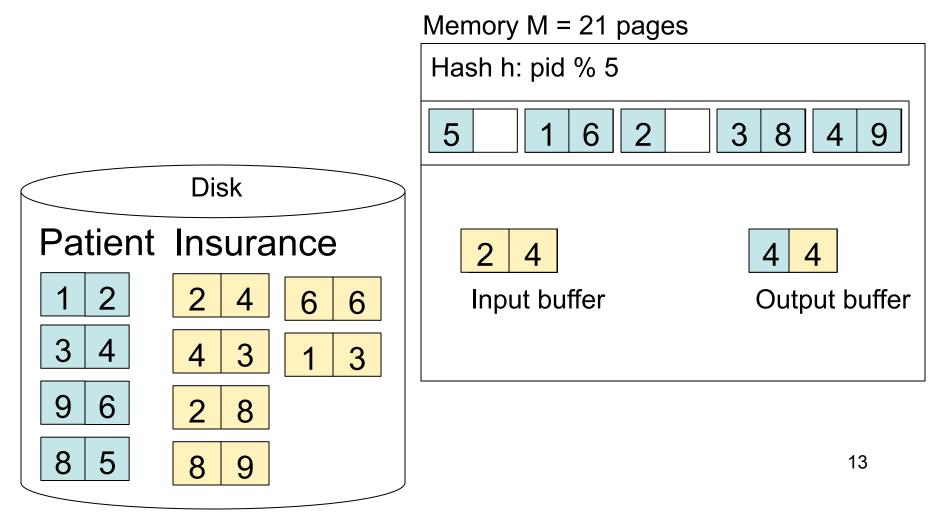
#### Step 1: Scan Patient and create hash table in memory



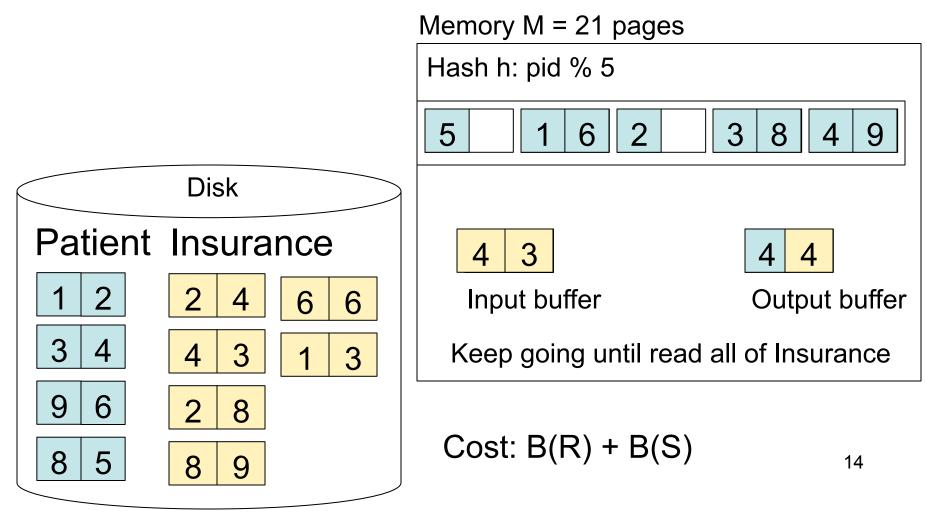
#### Step 2: Scan Insurance and probe into hash table



#### Step 2: Scan Insurance and probe into hash table



#### Step 2: Scan Insurance and probe into hash table



#### Hash Join Details

```
Open() {
H = newHashTable();
S.Open();
x = S.GetNext();
while (x != null) {
     H.insert(x); x = S.GetNext();
 }
S.Close();
R.Open();
buffer = [];
```

#### Hash Join Details

```
GetNext() {
while (buffer == []) {
     x = R.GetNext();
     if (x==Null) return NULL;
     buffer = H.find(x);
}
z = buffer.first();
buffer = buffer.rest( );
return z;
```

### Hash Join Details

Close() {
 release memory (H, buffer, etc.);
 R.Close()
 }

## **Nested Loop Joins**

- Tuple-based nested loop  $\mathsf{R} \bowtie \mathsf{S}$
- R is the outer relation, S is the inner relation

for each tuple r in R do

for each tuple s in S do

if r and s join then output (r,s)

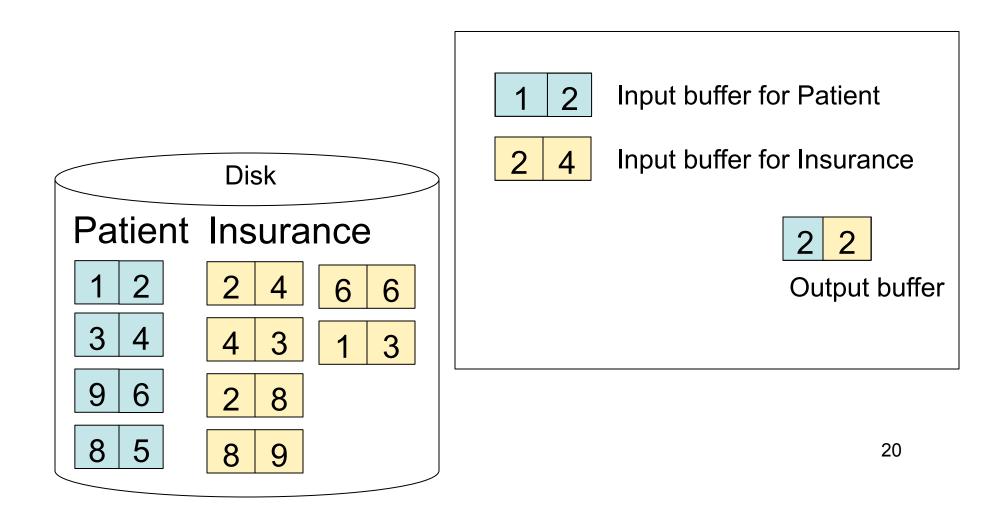
- Cost: B(R) + T(R) B(S)
- Not quite one-pass since S is read many times

## Page-at-a-time Refinement

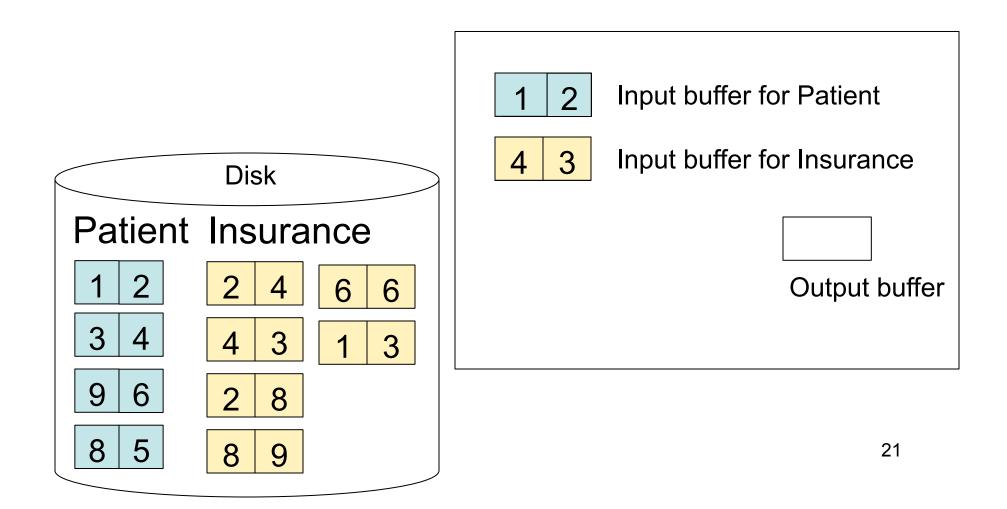
for each page of tuples r in R do for each page of tuples s in S do for all pairs of tuples if r and s join then output (r,s)

• Cost: B(R) + B(R)B(S)

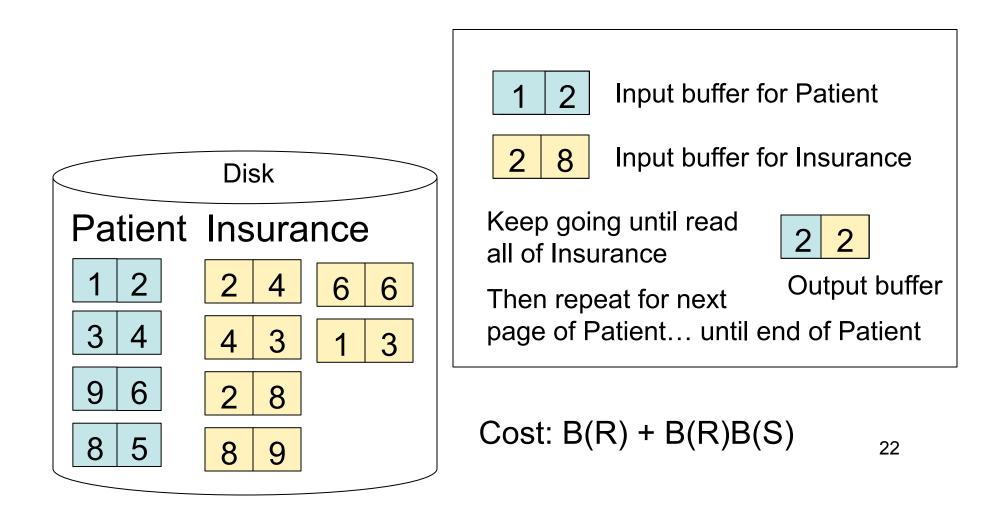
## Nested Loop Example



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## Nested Loop Example

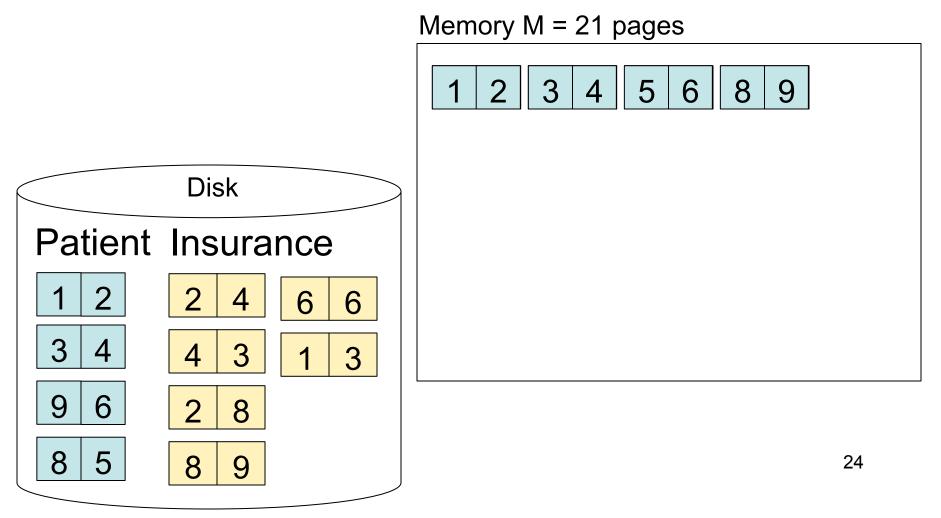


# Sort-Merge Join

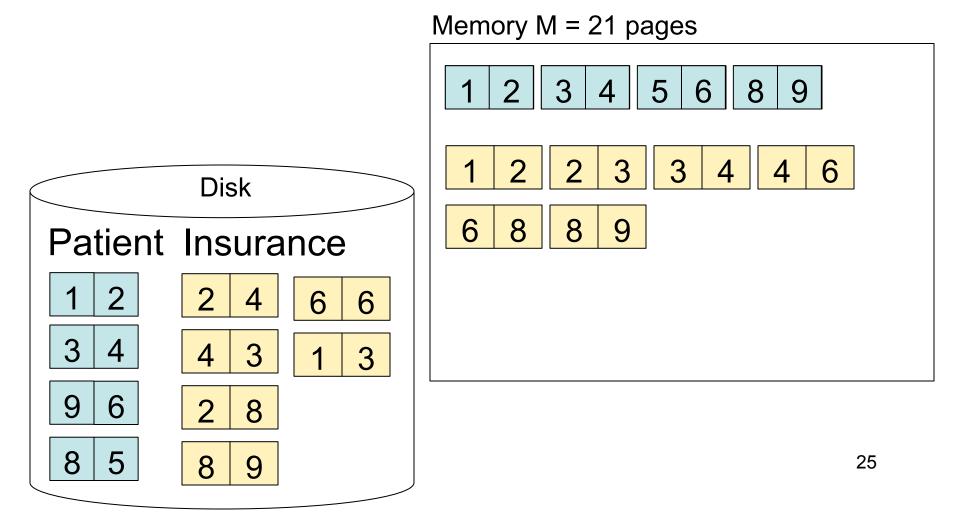
Sort-merge join:  $R \bowtie S$ 

- Scan R and sort in main memory
- Scan S and sort in main memory
- Merge R and S
- Cost: B(R) + B(S)
- One pass algorithm when B(S) + B(R) <= M
- Typically, this is NOT a one pass algorithm

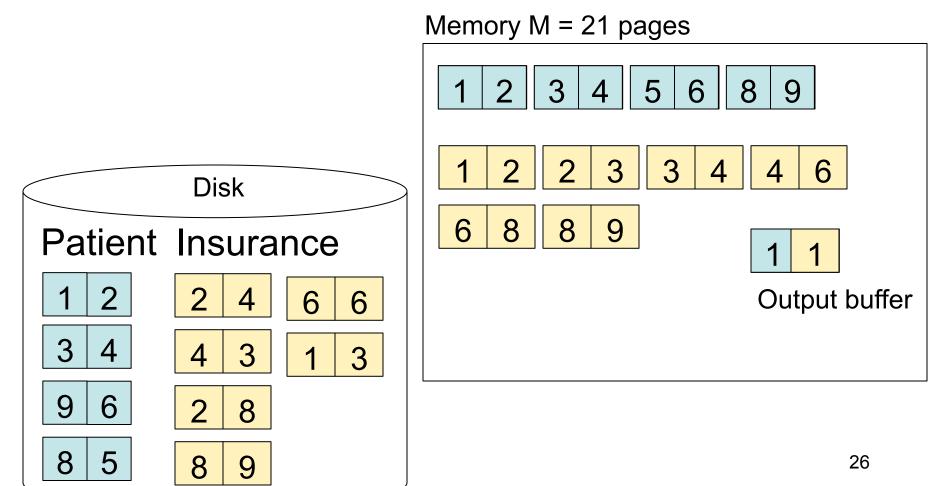
#### Step 1: Scan Patient and sort in memory



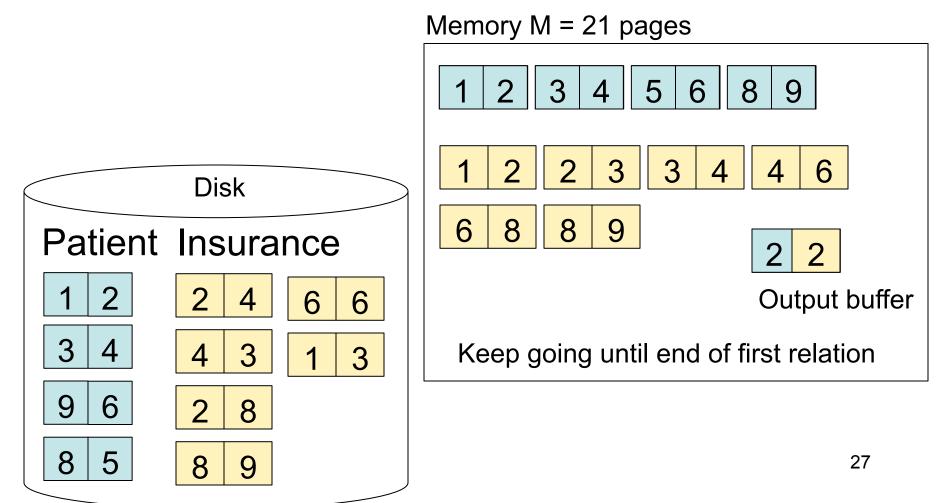
#### Step 2: Scan Insurance and sort in memory



#### Step 3: Merge Patient and Insurance



#### Step 3: Merge Patient and Insurance



## Outline for Today

#### Join operator algorithms

- One-pass algorithms (Sec. 15.2 and 15.3)
- Index-based algorithms (Sec 15.6)
- Two-pass algorithms (Sec 15.4 and 15.5)

## **Review: Access Methods**

#### Heap file

- Scan tuples one at the time
- Hash-based index
  - Efficient selection on equality predicates
  - Can also scan data entries in index
- Tree-based index
  - Efficient selection on equality or range predicates
  - Can also scan data entries in index

## Index Based Selection

- Selection on equality:  $\sigma_{a=v}(R)$
- V(R, a) = # of distinct values of attribute a
- Clustered index on a: cost B(R)/V(R,a)
- Unclustered index on a: cost T(R)/V(R,a)
- Note: we ignored I/O cost for index pages

# Index Based Selection

• Example:

cost of 
$$\sigma_{a=v}(R) = ?$$

- Table scan: B(R) = 2,000 I/Os
- Index based selection
  - If index is clustered: B(R)/V(R,a) = 100 I/Os
  - If index is unclustered: T(R)/V(R,a) = 5,000 I/Os
- Lesson
  - Don't build unclustered indexes when V(R,a) is small !

## Index Nested Loop Join

 $\mathsf{R} \bowtie \mathsf{S}$ 

- Assume S has an index on the join attribute
- Iterate over R, for each tuple fetch corresponding tuple(s) from S
- Cost:
  - If index on S is clustered: B(R) + T(R)B(S)/V(S,a)
  - If index on S is unclustered: B(R) + T(R)T(S)/V(S,a)

## Outline for Today

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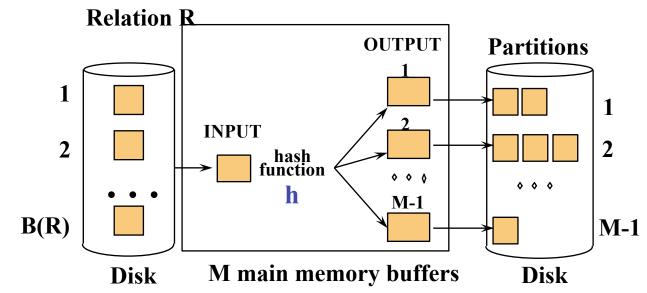
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- Two-pass algorithms (Sec 15.4 and 15.5)

## **Two-Pass Algorithms**

- What if data does not fit in memory?
- Need to process it in multiple passes
- Two key techniques
  - Hashing
  - Sorting

# Two Pass Algorithms Based on Hashing

- Idea: partition a relation R into buckets, on disk
- Each bucket has size approx. B(R)/M



Does each bucket fit in main memory ?

-Yes if  $B(R)/M \le M$ , i.e.  $B(R) \le M^2$ 

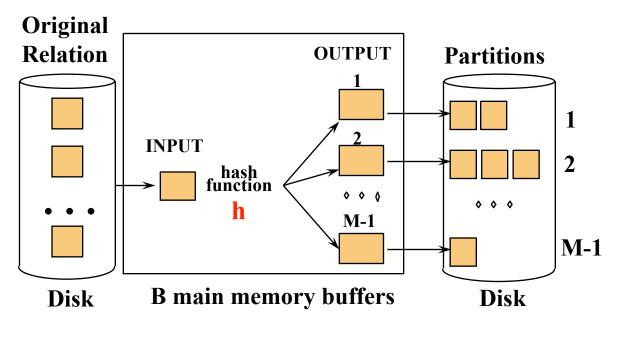
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# Partitioned (Grace) Hash Join

 $\mathsf{R} \bowtie \mathsf{S}$ 

- Step 1:
  - Hash S into M-1 buckets
  - Send all buckets to disk
- Step 2
  - Hash R into M-1 buckets
  - Send all buckets to disk
- Step 3
  - Join every pair of buckets

- Partition both relations using hash fn h
- R tuples in partition i will only match S tuples in partition i.



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- Read in partition of R, hash it using h2 (≠ h)
   Build phase
- Scan matching partition of S, search for matches
  - Probe phase **Partitions** Join Result of R & S Hash table for partition Si ( < M-1 pages) hash fn 000 h2 h2 **• • •** 000 **Input buffer** Output for Ri buffer Disk **B** main memory buffers Disk

- Cost: 3B(R) + 3B(S)
- Assumption: min(B(R), B(S)) <= M<sup>2</sup>

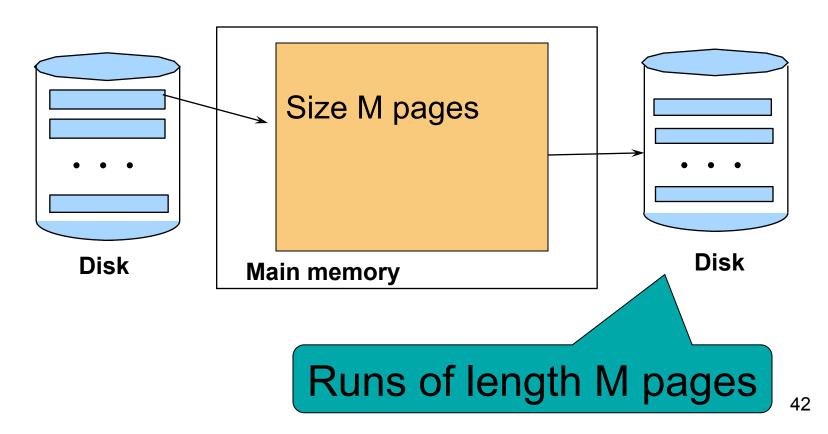
• See detailed example on the board

# **External Sorting**

- Problem: Sort a file of size B with memory M
- Where we need this:
  - ORDER BY in SQL queries
  - Several physical operators
  - Bulk loading of B+-tree indexes.
- Sorting is two-pass when  $B < M^2$

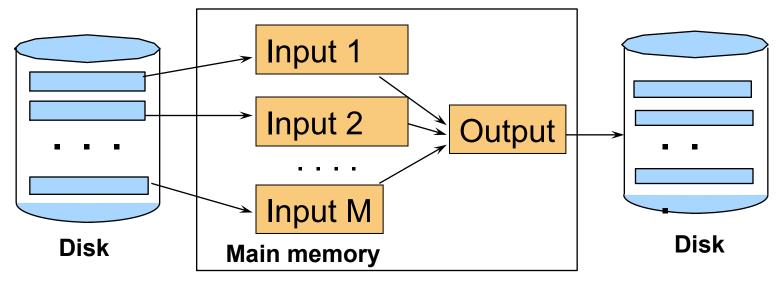
#### External Merge-Sort: Step 1

• Phase one: load M pages in memory, sort



#### External Merge-Sort: Step 2

- Merge M 1 runs into a new run
- Result: runs of length M (M 1) $\approx$  M2



If  $B \le M^2$  then we are done

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# External Merge-Sort

- Cost:
  - Read+write+read = 3B(R)
  - Assumption:  $B(R) \le M^2$
- Other considerations
  - In general, a lot of optimizations are possible

## **External Merge-Sort**

• See detailed example on the board

# Two-Pass Join Algorithm Based on Sorting

 $\mathsf{Join}\ \mathsf{R}\bowtie\mathsf{S}$ 

- Step 1: sort both R and S on the join attribute:
   Cost: 4B(R)+4B(S) (because need to write to disk)
- Step 2: Read both relations in sorted order, match tuples
  - Cost: B(R)+B(S)
- Total cost: 5B(R)+5B(S)
- Assumption:  $B(R) \le M^2$ ,  $B(S) \le M^2$

# Two-Pass Join Algorithm Based on Sorting

 $\mathsf{Join} \ \mathsf{R} \bowtie \mathsf{S}$ 

- If B(R) + B(S) <= M<sup>2</sup>
   Or if use a priority queue to create runs of length 2|M|
- If the number of tuples in R matching those in S is small (or vice versa)
- We can compute the join during the merge phase
- Total cost: 3B(R)+3B(S)

# Two-Pass Join Algorithm Based on Sorting

• See detailed example on the board

### Summary of Join Algorithms

Nested Loop Join: B(R) + B(R)B(S)

Assuming page-at-a-time refinement

- Hash Join: 3B(R) + 3B(S)
  - Assuming:  $min(B(R), B(S)) \le M2$
- Sort-Merge Join: 3B(R)+3B(S)

- Assuming  $B(R)+B(S) \le M2$ 

- Index Nested Loop Join: B(R) + T(R)B(S)/V(S,a)
  - Assuming S has clustered index on a

# Summary of Query Execution

- For each logical query plan
  - There exist many physical query plans
  - Each plan has a different cost
  - Cost depends on the data
- Additionally, for each query
  - There exist several logical plans
- Next lecture: query optimization
  - How to compute the cost of a complete plan?
  - How to pick a good query plan for a query?