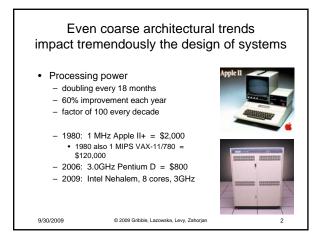
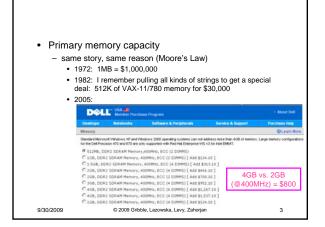
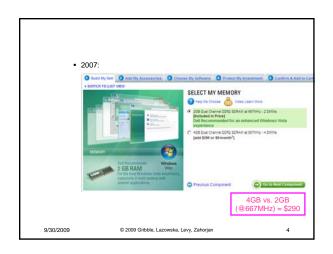
CSE 451: Operating Systems Autumn 2009

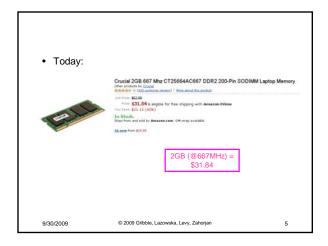
Module 2
Architectural Support for Operating Systems

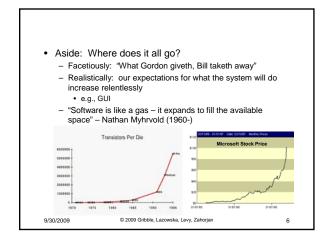
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- doubled every 3+ years
- 25% improvement each year
- factor of 10 every decade
- Still exponential, but far less rapid than processor performance
- Disk capacity since 1990
 - doubling every 12 months
 - 100% improvement each year
 - factor of 1000 every decade
 - 10x as fast as processor performance!

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- Only a few years ago, we purchased disks by the megabyte (and it hurt!)
- Today, 1 GB (a billion bytes) costs \$1 \$0.50 \$0.25 from Dell (except you have to buy in increments of 40 80 250 GB)
 - => 1 TB costs \$1K \$500 \$250, 1 PB costs \$1M \$500K \$250K

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Newly arrived, and coming soon...

- Solid state storage (SSD)
 - promises 10,000 100,000 random IOs per second
 - 700 MB/s transfer rates
 - still costly, but quickly riding Moore's law
 - \$5-10 per GB, compared to hard drives \$0.10 per GB
- Phase-change memory (PRAM)
 - promises speed of DRAM, but non-volatile
 - still experimental, though early product shipping

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· Optical bandwidth today

- Doubling every 9 months
- 150% improvement each year
- Factor of 10,000 every decade
- 10x as fast as disk capacity!
- 100x as fast as processor performance!!

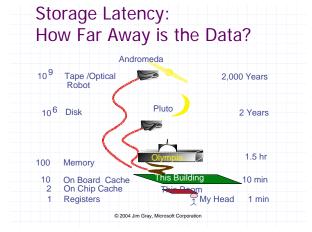
What are some of the implications of these trends?

 Just one example: We have always designed systems so that they "spend" processing power in order to save "scarce" storage and bandwidth!

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9

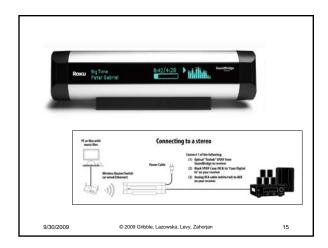
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Lower-level architecture affects the OS even more dramatically

- The operating system supports sharing and protection
 - multiple applications can run concurrently, sharing resources
 - a buggy or malicious application can't nail other applications or the system
- There are many approaches to achieving this
- The architecture determines which approaches are viable (reasonably efficient, or even possible)
 - includes instruction set (synchronization, I/O, ...)
 - also hardware components like MMU or DMA controllers

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- Architectural support can vastly simplify (or complicate!) OS tasks
 - e.g.: early PC operating systems (DOS, MacOS) lacked support for virtual memory, in part because at that time PCs lacked necessary hardware support
 - Apollo workstation used two CPUs as a bandaid for nonrestartable instructions!
 - Until very recently, Intel-based PCs still lacked support for 64-bit addressing (which has been available for a decade on other platforms: MIPS, Alpha, IBM, etc...)
 - changing rapidly due to AMD's 64-bit architecture

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Architectural features affecting OS's

- These features were built primarily to support OS's:
 - timer (clock) operation
 - synchronization instructions (e.g., atomic test-and-set)
 - memory protection
 - I/O control operations
 - interrupts and exceptions
 - protected modes of execution (kernel vs. user)
 - privileged instructions
 - system calls (and software interrupts)

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Privileged/Protected instructions

- · some instructions are restricted to the OS
 - known as protected or privileged instructions
- . e.g., only the OS can:
 - directly access I/O devices (disks, network cards)
 - why?
 - manipulate memory state management
 - page table pointers, TLB loads, etc.
 - why?
 - manipulate special 'mode bits'
 - · interrupt priority level
 - why?
 - halt instruction
 - · why?

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19

21

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20

22

24

OS protection

- So how does the processor know if a privileged instruction should be executed?
 - the architecture must support at least two modes of operation; kernel mode and user mode
 - mode is set by status bit in a protected processor register
 - user programs execute in user mode
 - OS executes in kernel mode (OS == kernel)
- Privileged instructions can only be executed in kernel mode
 - what happens if user mode attempts to execute a privileged instruction?

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Crossing protection boundaries

- So how do user programs do something privileged?
 - e.g., how can you write to a disk if you can't execute I/O instructions?
- User programs must call an OS procedure
 - OS defines a sequence of system calls
 - how does the user-mode to kernel-mode transition happen?
- There must be a system call instruction, which:
 - causes an exception (throws a software interrupt), which vectors to a kernel handler
 - passes a parameter indicating which system call to invoke
 - saves caller's state (registers, mode bit) so they can be restored
 - OS must verify caller's parameters (e.g., pointers)
 - must be a way to return to user mode once done

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A kernel crossing illustrated Firefox: read(int fileDescriptor, void *buffer, int numBytes) package arguments trap to kernel mode user mode kernel mode restore app state, return to trap handler user mode. save registers resume find sys_read() handler in vector table sys_read() kernel routine 9/30/2009 © 2009 Gribble, Lazowska, Levy, Zahorjan 23

System call issues

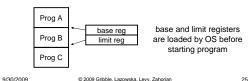
- What would happen if kernel didn't save state?
- Why must the kernel verify arguments?
- How can you reference kernel objects as arguments or results to/from system calls?

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Memory protection

- OS must protect user programs from each other
 maliciousness, ineptitude
- · OS must also protect itself from user programs
 - integrity and security
 - what about protecting user programs from OS?
- Simplest scheme: base and limit registers
 - are these protected?



More sophisticated memory protection

- · coming later in the course
- · paging, segmentation, virtual memory
 - page tables, page table pointers
 - translation lookaside buffers (TLBs)
 - page fault handling

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OS control flow

- After the OS has booted, all entry to the kernel happens as the result of an event
 - event immediately stops current execution
 - changes mode to kernel mode, event handler is called
- · Kernel defines handlers for each event type
 - specific types are defined by the architecture
 - e.g.: timer event, I/O interrupt, system call trap
 - when the processor receives an event of a given type, it
 - transfers control to handler within the OS
 - handler saves program state (PC, regs, etc.)
 - handler functionality is invoked
 - handler restores program state, returns to program

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Interrupts and exceptions

- Two main types of events: interrupts and exceptions
 - exceptions are caused by software executing instructions
 - e.g., the x86 'int' instruction
 - e.g., a page fault, or an attempted write to a read-only page
 - an expected exception is a "trap", unexpected is a "fault"
 - interrupts are caused by hardware devices
 - e.g., device finishes I/O
 - e.g., timer fires

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27

29

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28

30

I/O control

- · Issues:
 - how does the kernel start an I/O?
 - special I/O instructions
 - memory-mapped I/O
 - how does the kernel notice an I/O has finished?
 - polling
 - Interrupts
 - how does the kernel exchange data with an I/O device?
 - Programmed I/O (PIO)
 - Direct Memory Access (DMA)

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Asynchronous I/O

- Interrupts are the basis for asynchronous I/O
 - device performs an operation asynchronously to CPU
 - device sends an interrupt signal on bus when done
 - in memory, a vector table contains list of addresses of kernel routines to handle various interrupt types
 - who populates the vector table, and when?
 - CPU switches to address indicated by vector index specified by interrupt signal
- What's the advantage of asynchronous I/O?

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Timers

- How can the OS prevent runaway user programs from hogging the CPU (infinite loops?)
 - use a hardware timer that generates a periodic interrupt
 - before it transfers to a user program, the OS loads the timer with a time to interrupt
 - "quantum" how big should it be set?
 - when timer fires, an interrupt transfers control back to OS
 - · at which point OS must decide which program to schedule next
 - · very interesting policy question: we'll dedicate a class to it
- Should the timer be privileged?
 - for reading or for writing?

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31

33

Synchronization

- · Interrupts cause a wrinkle:
 - may occur any time, causing code to execute that interferes with code that was interrupted
 - OS must be able to synchronize concurrent processes
- · Synchronization:
 - guarantee that short instruction sequences (e.g., readmodify-write) execute atomically
 - one method: turn off interrupts before the sequence, execute it, then re-enable interrupts
 - · architecture must support disabling interrupts
 - another method: have special complex atomic instructions
 - · read-modify-write
 - · test-and-set
 - · load-linked store-conditional

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32

34

"Concurrent programming"

- Management of concurrency and asynchronous events is biggest difference between "systems programming" and "traditional application programming"
 - modern "event-oriented" application programming is a middle ground
- Arises from the architecture
 - Can be sugar-coated, but cannot be totally abstracted away
- Huge intellectual challenge
 - Unlike vulnerabilities due to buffer overruns, which are just sloppy programming

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Architectures are still evolving

- New features are still being introduced to meet modern demands
 - Support for virtual machine monitors
 - Hardware transaction support (to simplify parallel programming)
 - Support for security (encryption, trusted modes)
 Increasingly sophisticated video / graphics

 - Other stuff that hasn't been invented yet...
- In current technology transistors are free CPU makers are looking for new ways to use transistors to make their chips more desirable
- Intel's big challenge: finding applications that require new hardware support, so that you will want to upgrade to a new computer to run them

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Some questions

- Why wouldn't you want a user program to be able to access an I/O device (e.g., the disk) directly?
- OK, so what keeps this from happening? What prevents user programs from directly accessing the
- So, how does a user program cause disk I/O to
- What prevents a user program from scribbling on the memory of another user program?
- What prevents a user program from scribbling on the memory of the operating system?
- What prevents a user program from running away with the CPU?

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35