CSE 451: Operating Systems Autumn 2010

Module 4 Processes

Ed Lazowska lazowska@cs.washington.edu Allen Center 570

Process management

- This module begins a series of topics on processes, threads, and synchronization
 - this is the most important part of the class
 - there definitely will be several questions on these topics on the midterm (November 3)
- Today: processes and process management
 - What is a "process"?
 - What's the OS's process namespace?
 - How are processes represented inside the OS?
 - What are the executing states of a process?
 - How are they created?
 - How can this be made faster?
 - Shells
 - Signals

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What is a "process"?

- The process is the OS's abstraction for execution
 - A process is a program in execution
- Simplest (classic) case: a sequential process
 - An address space (an abstraction of memory)
 - A single thread of execution (an abstraction of the CPU)

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- A sequential process is:
 - The unit of execution
 - The unit of scheduling

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- The dynamic (active) execution context
 - vs. the program static, just a bunch of bytes



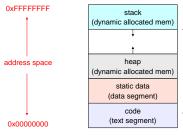
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What's "in" a process?

- A process consists of (at least):
 - An address space, containing
 - the code (instructions) for the running program
 - · the data for the running program
 - Thread state, consisting of
 - The program counter (PC), indicating the next instruction
 - The stack pointer register (implying the stack it points to)
 - Other general purpose register values
 - A set of OS resources
 - open files, network connections, sound channels, ...
- In other words, it's all the stuff you need to run the program
 - or to re-start it, if it's interrupted at some point

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A process's address space (idealized)



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The OS's process namespace

- (Like most things, the particulars depend on the specific OS, but the principles are general)
- The name for a process is called a process ID (PID)
 An integer
- The PID namespace is global to the system
 - Only one process at a time has a particular PID
- Operations that create processes return a PID
 - E.g., fork(), clone()
- · Operations on processes take PIDs as an argument
 - E.g., kill(), wait(), nice()

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Representation of processes by the OS

- The OS maintains a data structure to keep track of a process's state
 - Called the process control block (PCB)
 - Identified by the PID
- OS keeps all of a process's hardware execution state in the PCB when the process isn't running
 - PC, SP, registers, etc.
 - when a process is unscheduled, the state is transferred out of the hardware into the PCB
 - (when a process is running, its state is spread between the PCB and the CPU)
- Note: It's natural to think that there must be some esoteric techniques being used
 - fancy data structures that'd you'd never think of yourself

Wrong! It's pretty much just what you'd think of!

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The PCB

- The PCB is a data structure with many, many fields:
 - process ID (PID)
 - parent process ID
 - execution state
 - program counter, stack pointer, registers
 - address space info
 - UNIX user id, group id
 - scheduling priority
 - accounting info
 - pointers for state queues
- In Linux:
 - defined in task_struct (include/linux/sched.h)
 - over 95 fields!!!

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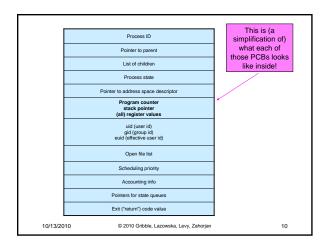
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PCBs and hardware state

- When a process is running, its hardware state is inside the CPU
 - PC, SP, registers
 - CPU contains current values
- When a process is transitioned to the waiting state, the OS saves its CPU state in the PCB
 - when the OS returns the process to the running state, it loads the hardware registers with values from that process's PCB
- The act of switching the CPU from one process to another is called a context switch
 - systems may do 100s or 1000s of switches/sec.
 - takes a few microseconds on today's hardware
- Choosing which process to run next is called scheduling

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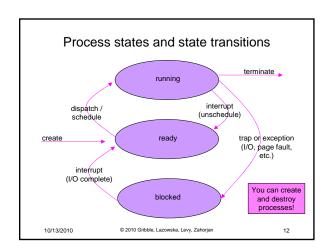
Process execution states

- Each process has an execution state, which indicates what it is currently doing
 - ready: waiting to be assigned to a CPU
 - could run, but another process has the CPU
 - running: executing on a CPU
 - · is the process that currently controls the CPU
 - pop quiz: how many processes can be running simultaneously?
 - waiting (aka "blocked"): waiting for an event, e.g., I/O completion
 - cannot make progress until event happens
- As a process executes, it moves from state to state
 - $-\,$ UNIX: run ${\tt ps},$ STAT column shows current state
 - which state is a process in most of the time?

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State queues

- The OS maintains a collection of queues that represent the state of all processes in the system
 - typically one queue for each state
 - . e.g., ready, waiting, ...
 - each PCB is queued onto a state queue according to the current state of the process it represents
 - as a process changes state, its PCB is unlinked from one queue, and linked onto another
- Once again, this is just as straightforward as it sounds! The PCBs are moved between queues, which are represented as linked lists. There is no magic!

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State queues

Ready queue header

head ptr
tail ptr

wait queue header

head ptr
tail ptr

- Cat (1468)

There may be many wait queues, one for each type of wait (particular device, timer, message, ...)

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PCBs and state queues

- PCBs are data structures
 - dynamically allocated inside OS memory
- When a process is created:
 - OS allocates a PCB for it
 - OS initializes PCB
 - OS puts PCB on the correct queue
- As a process computes:
 - OS moves its PCB from queue to queue
- When a process is terminated:
 - PCB may hang around for a while (exit code, etc.)
 - eventually, OS deallocates the PCB

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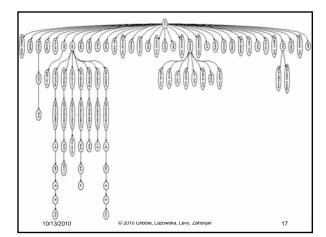
Process creation

- New processes are created by existing processes
 - creator is called the parent
 - created process is called the child
 - UNIX: do ps, look for PPID field
 - what creates the first process, and when?

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Process creation semantics

- (Depending on the OS) child processes inherit certain attributes of the parent
 - Examples:
 - Open file table: implies stdin/stdout/stderr
 - On some systems, resource allocation to parent may be divided among children
- (In Unix) when a child is created, the parent may either wait for the child to finish, or continue in parallel

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UNIX process creation details

- UNIX process creation through fork() system call
 - creates and initializes a new PCB
 - creates a new address space
 - initializes new address space with a copy of the entire contents of the address space of the parent
 - initializes kernel resources of new process with resources of parent (e.g., open files)
 - places new PCB on the ready queue
- the fork() system call "returns twice"
 - once into the parent, and once into the child
 - returns the child's PID to the parent
 - returns 0 to the child
- fork() = "clone me"

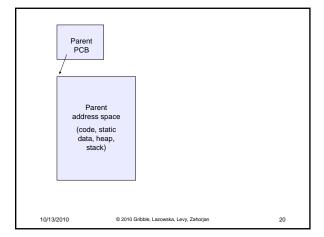
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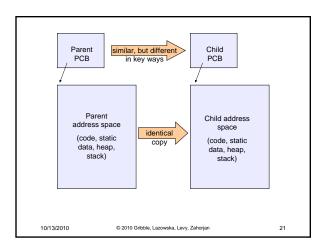
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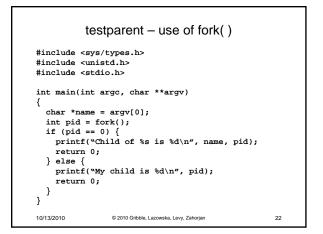
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testparent output

```
spinlock% gcc -o testparent testparent.c

spinlock% ./testparent

My child is 486

Child of testparent is 0

spinlock% ./testparent

Child of testparent is 0

My child is 571
```

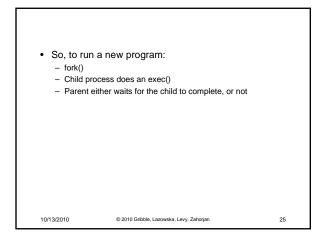
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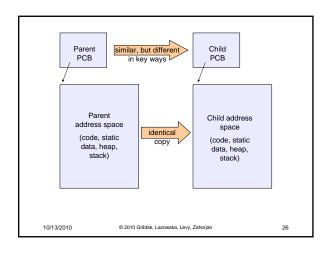
exec() vs. fork()

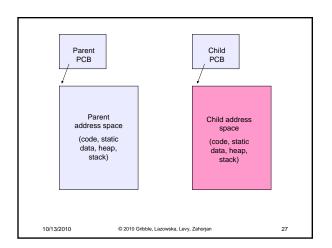
- Q: So how do we start a new program, instead of just forking the old program?
- A: First fork, then exec
 - int exec(char * prog, char * argv[])
- exec()
 - stops the current process
 - loads program 'prog' into the address space
 - i.e., over-writes the existing process image
 - initializes hardware context, args for new program
 - places PCB onto ready queue
 - note: <u>does not create a new process!</u>

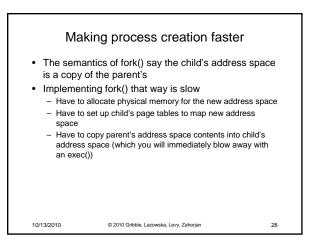
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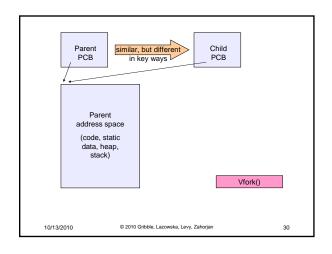


Method 1: vfork()

- vfork() is the older of the two approaches we'll talk about
- "Change the problem definition into something we can implement efficiently"
- Instead of "child's address space is a copy of the parent's," the semantics are "child's address space is the parent's"
 - With a "promise" that the child won't modify the address space before doing an exec()
 - Unenforced! You use vfork() at your own peril
 - When exec() is called, a new address space is created, new page tables set up for it, and it's loaded with the new executable
 - Saves wasted effort of duplicating parent's address space, just to blow it away

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Method 2: copy-on-write

- Retains the original semantics, but copies "only what is necessary" rather than the entire address space
- On fork():
 - Create a new address space
 - Initialize page tables with same mappings as the parent's (i.e., they both point to the same physical memory)
 - No copying of address space contents have occurred at this point
 - Set both parent and child page tables to make all pages read-only
 - If either parent or child writes to memory, an exception occurs
 - When exception occurs, OS copies the page, adjusts page tables, etc.

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```
UNIX shells
int main(int argc, char **argv)
{
   while (1) {
      printf ("$");
      char *cmd = get_next_command();
      int pid = fork();
      if (pid == 0) {
            exec(cmd);
            panic("exec failed!");
      } else {
            wait(pid);
      }
   }
}
```

Input/output redirection

- \$./myprog < input.txt > output.txt # UNIX
 - each process has an open file table
 - by (universal) convention:
 - 0: stdin
 - 1: stdout
 - 2: stderr
- A child process inherits the parent's open file table
- Redirection: the shell ...
 - copies its current stdin/stdout open file entries
 - opens input.txt as stdin and output.txt as stdout
 - fork ...
 - restore original stdin/stdout

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Inter-process communication via signals

- · Processes can register event handlers
 - Feels a lot like event handlers in Java, which ..
 - Feel sort of like catch blocks in Java programs
- When the event occurs, process jumps to event handler routine
- Used to catch exceptions
- Also used for inter-process (process-to-process) communication
 - A process can trigger an event in another process using signal

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Signals

Signal	Value	Action	Comment	
SIGHUP	1	Term	Hangup detected on controlling ter or death of controlling process	minal
SIGINT	2	Term	Interrupt from keyboard	
SIGQUIT	3	Core	Quit from keyboard	
SIGILL	4	Core	Illegal Instruction	
SIGABRT	6	Core	Abort signal from abort(3)	
SIGFPE	8	Core	Floating point exception	
SIGKILL	9	Term	Kill signal	
SIGSEGV	11	Core	Invalid memory reference	
SIGPIPE	13	Term	Broken pipe: write to pipe with no	read
SIGALRM	14	Term	Timer signal from alarm(2)	
SIGTERM	15	Term	Termination signal	
SIGUSR1	30,10,16	Term	User-defined signal 1	
SIGUSR2	31,12,17	Term	User-defined signal 2	
SIGCHLD	20,17,18	Ign	Child stopped or terminated	
SIGCONT	19,18,25		Continue if stopped	
SIGSTOP	17,19,23	Stop	Stop process	
SIGTSTP	18,20,24	Stop	Stop typed at tty	
SIGTTIN	21,21,26	Stop	tty input for background process	
SIGTTOU	22,22,27	Stop	tty output for background process	
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Example use

- You're implementing Apache, a web server
- Apache reads a configuration file when it is launched
 - Controls things like what the root directory of the web files is, what permissions there are on pieces of it, etc.
- Suppose you want to change the configuration while Apache is running
 - If you restart the currently running Apache, you drop some unknown number of user connections
- Solution: send the running Apache process a signal
 - It has registered a signal handler that gracefully re-reads the configuration file

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