Content-Based Image Retrieval
Readings: Chapter 8: 8.1-8.4

- Queries
- Commercial Systems
- Retrieval Features
- Indexing in the FIDS System
- Lead-in to Object Recognition

Content-based Image Retrieval (CBIR)

Searching a large database for images that *match* a query:

- What kinds of databases?
- What kinds of queries?
- What constitutes a match?
- How do we make such searches efficient?

Applications

- Art Collections

  e.g. Fine Arts Museum of San Francisco
- Medical Image Databases

  CT, MRI, Ultrasound, The Visible Human
- Scientific Databases

  e.g. Earth Sciences
- General Image Collections for Licensing

  Corbis, Getty Images
- The World Wide Web

  Google, Microsoft, etc

What is a query?

- an image you already have
- a rough sketch you draw
- a symbolic description of what you want
  e.g. an image of a man and a woman on a beach

Some Systems You Can Try

Corbis Stock Photography and Pictures

http://pro.corbis.com/

- Corbis sells high-quality images for use in advertising, marketing, illustrating, etc.
- Search is entirely by keywords.
- Human indexers look at each new image and enter keywords.
- A thesaurus constructed from user queries is used.

Google Image

- Google Similar Images
http://similar-images.googlelabs.com/

- Google Image Swirl
http://image-swirl.googlelabs.com/

Microsoft Bing

- http://www.bing.com/
- first use keywords, then mouse over an image and click on show similar images

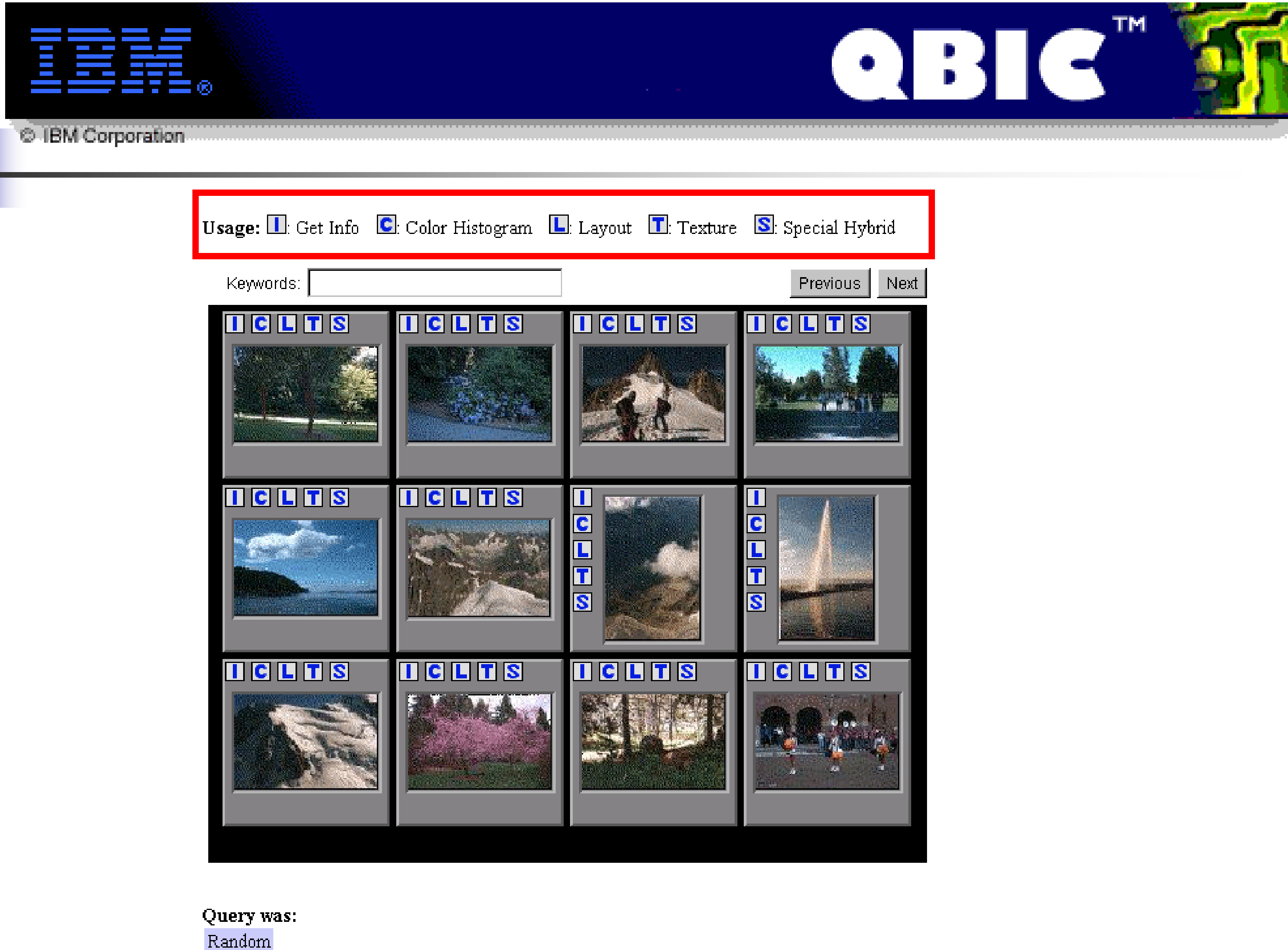
QBIC

IBM's QBIC (Query by Image Content)

http://wwwqbic.almaden.ibm.com

- The first commercial system.
- Uses or has-used color percentages, color layout, texture, shape, location, and keywords.

Original QBIC system looked like this



Like

- Shopping search engine
- http://www.like.com/

Problem with Text-Based Search

- Retrieval for pigs for the color chapter of my book
- Small company (was called Ditto)
- Allows you to search for pictures from web pages

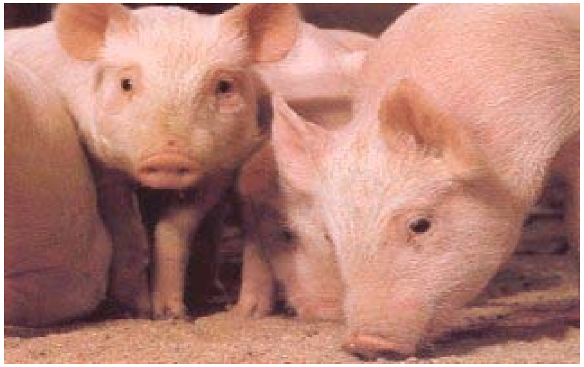
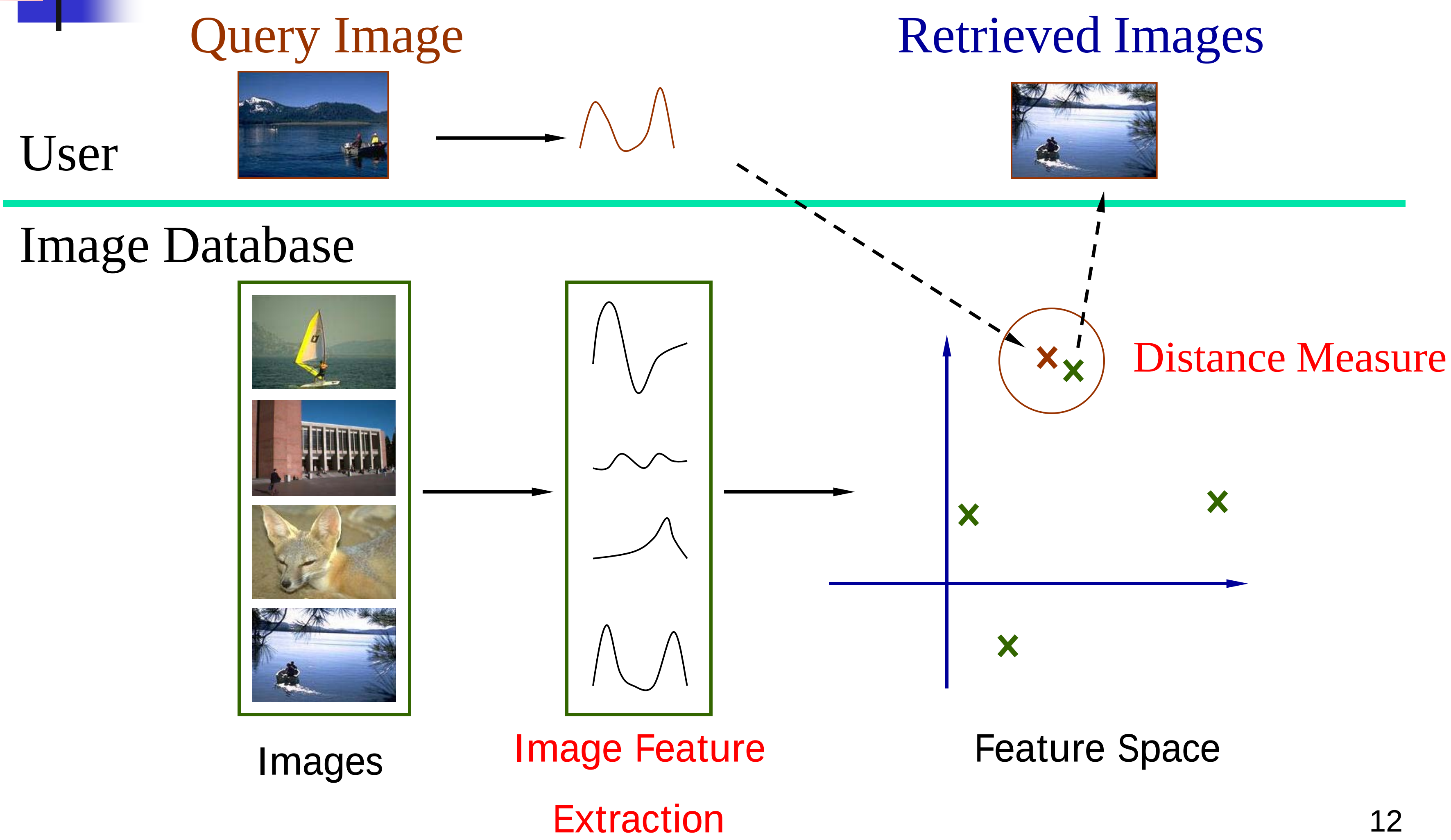


Image Features / Distance Measures

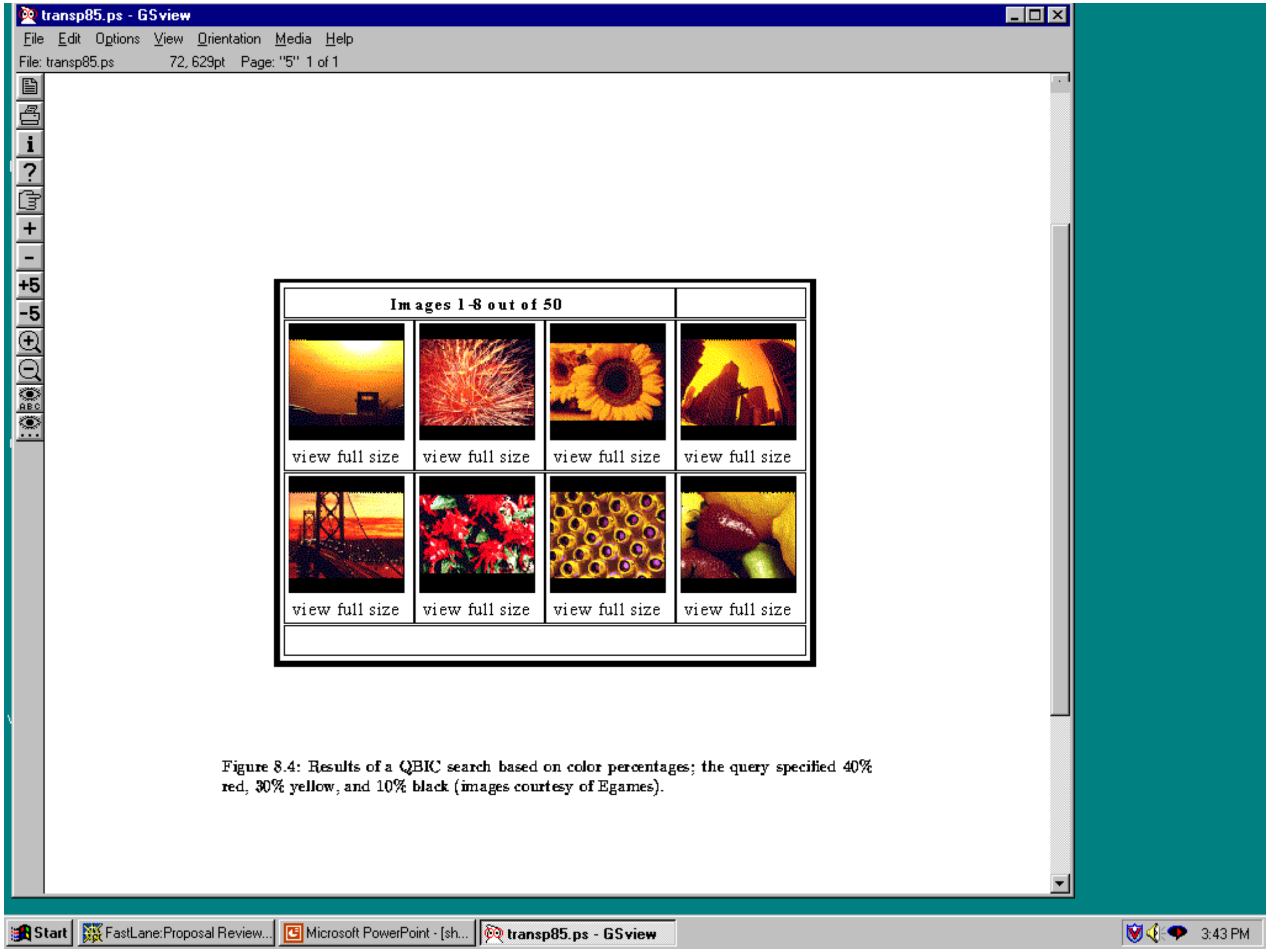


Features

- Color (histograms, gridded layout, wavelets)
- Texture (Laws, Gabor filters, local binary pattern)
- Shape (first segment the image, then use statistical or structural shape similarity measures)
- Objects and their Relationships

This is the most powerful, but you have to be able to recognize the objects!

Color Histograms



QBIC's Histogram Similarity

The QBIC color histogram distance is:

$$d_{hist}(I,Q) = (h(I) - h(Q))^T \mathbf{A} \, (h(I) - h(Q))$$

- h(I) is a K-bin histogram of a database image
- h(Q) is a K-bin histogram of the query image
- A is a K x K similarity matrix

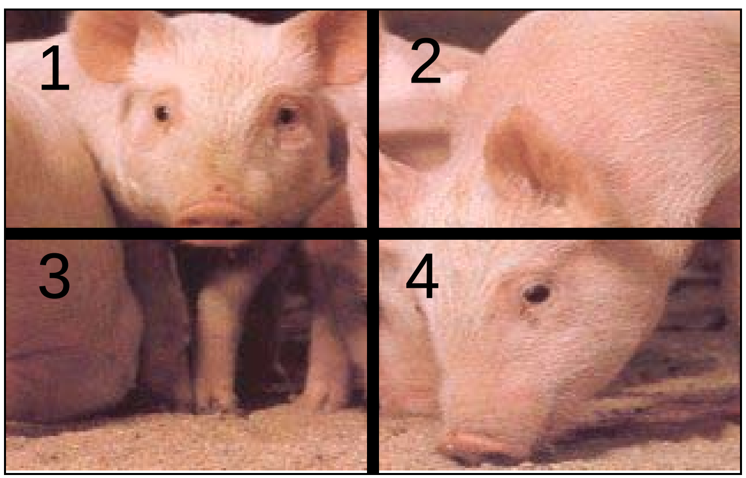
Similarity Matrix

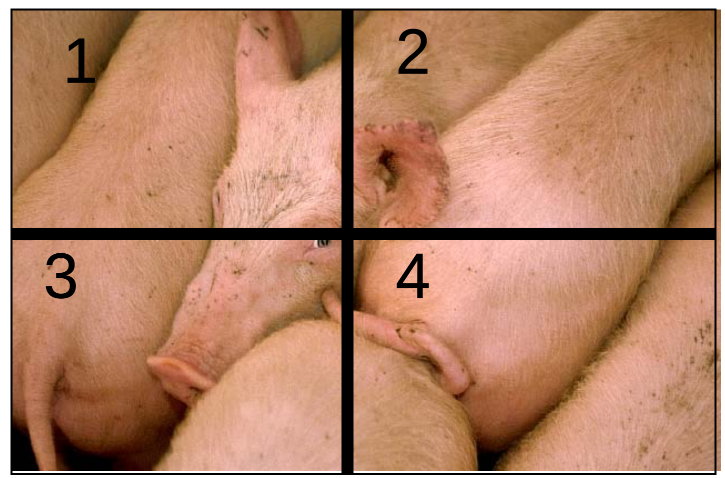
	R	G	B	Y	C	V
R	1	0	0	.5	0	.5
G	0	1	0	.5	.5	0
B	0	0	1		?	
Y				1		
C		?			1	
V						1

How similar is blue to cyan?

Gridded Color

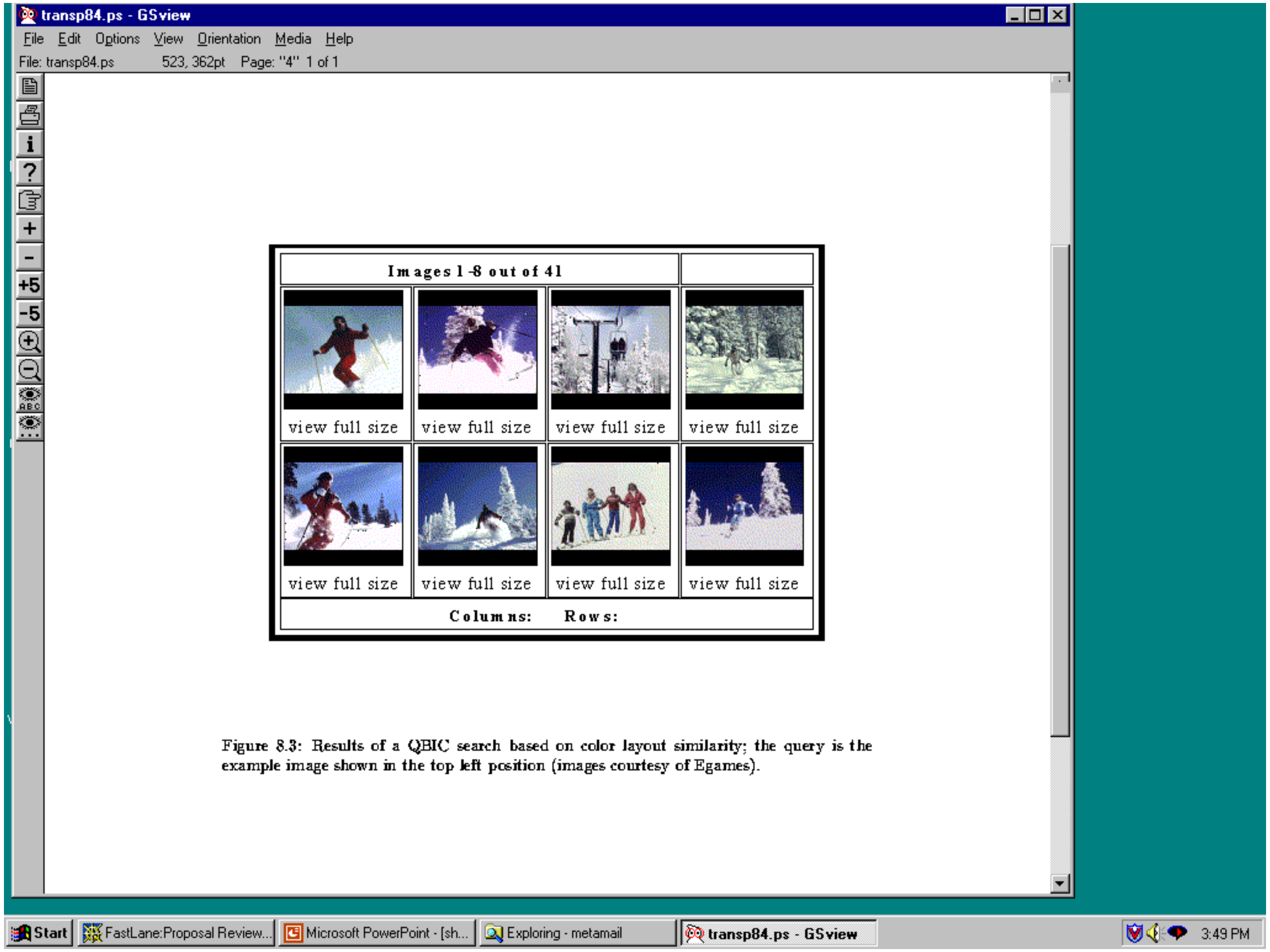
Gridded color distance is the sum of the color distances in each of the corresponding grid squares.





What color distance would you use for a pair of grid squares?

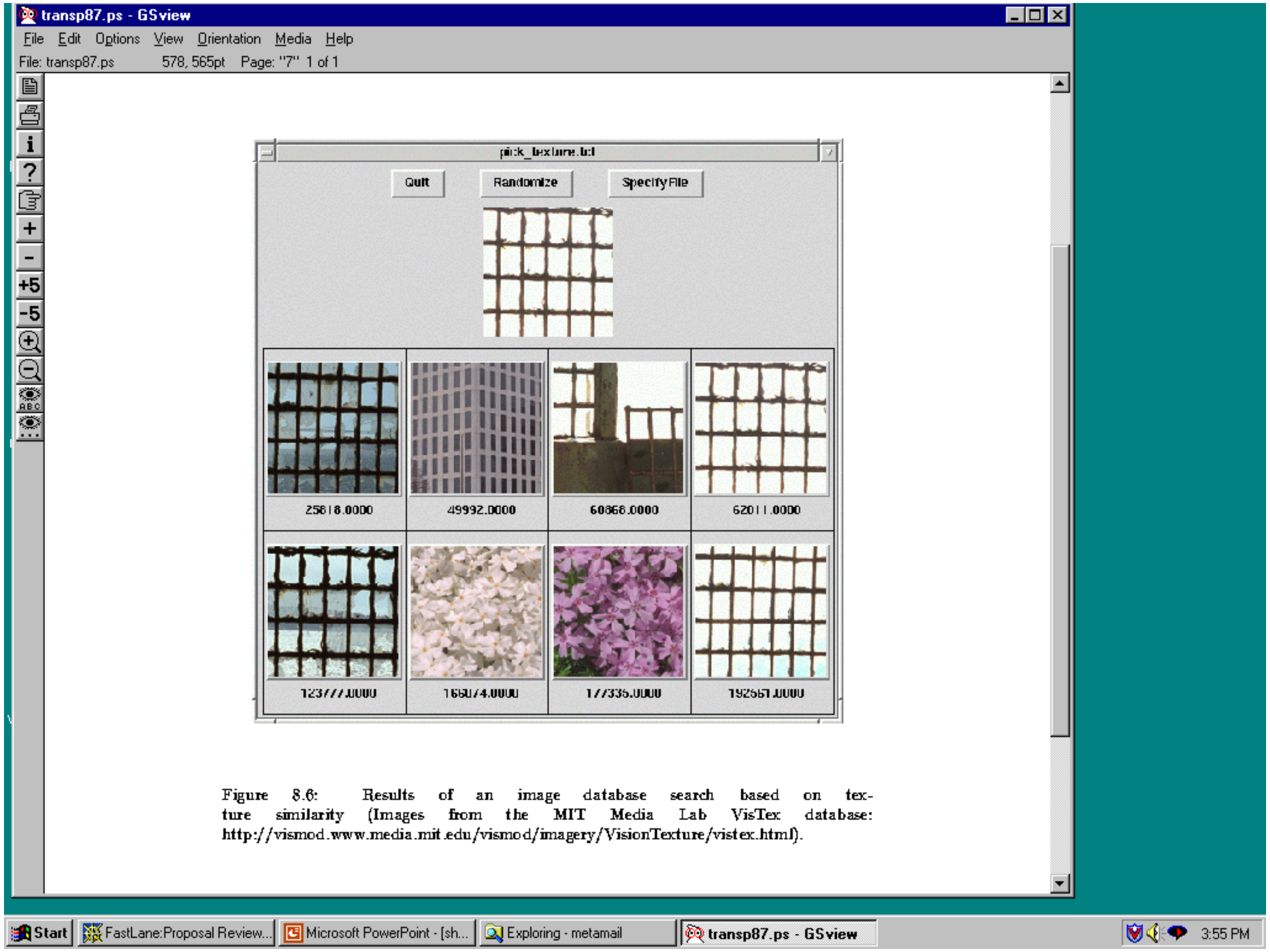
Color Layout (IBM's Gridded Color)



Texture Distances

- Pick and Click (user clicks on a pixel and system retrieves images that have in them a region with similar texture to the region surrounding it.
- Gridded (just like gridded color, but use texture).
- Histogram-based (e.g. compare the LBP histograms).

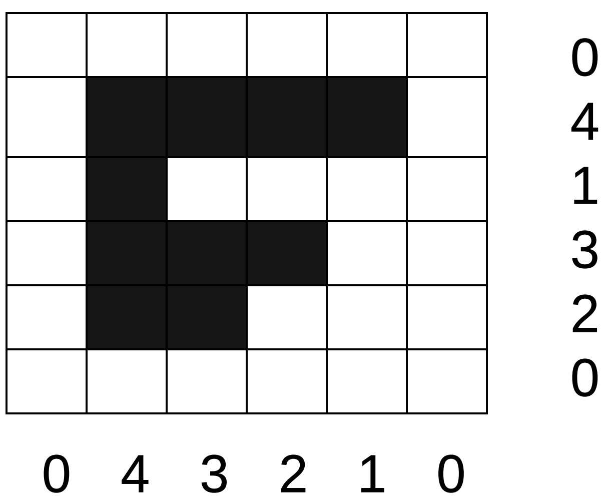
Laws Texture



Shape Distances

- Shape goes one step further than color and texture.
- It requires identification of regions to compare.
- There have been many shape similarity measures suggested for pattern recognition that can be used to construct shape distance measures.

Global Shape Properties: Projection Matching

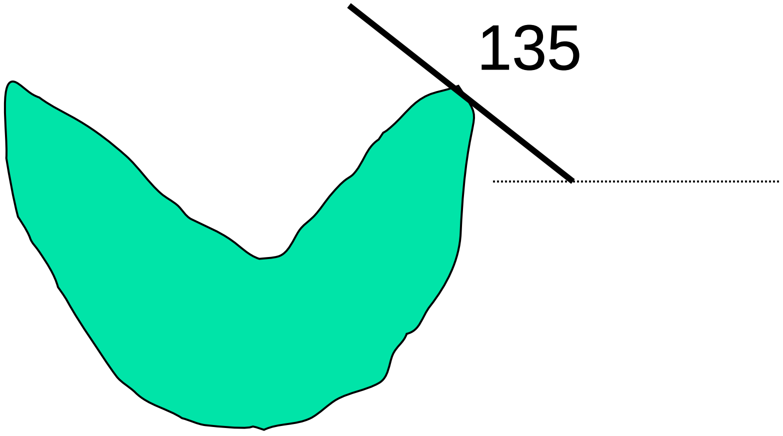


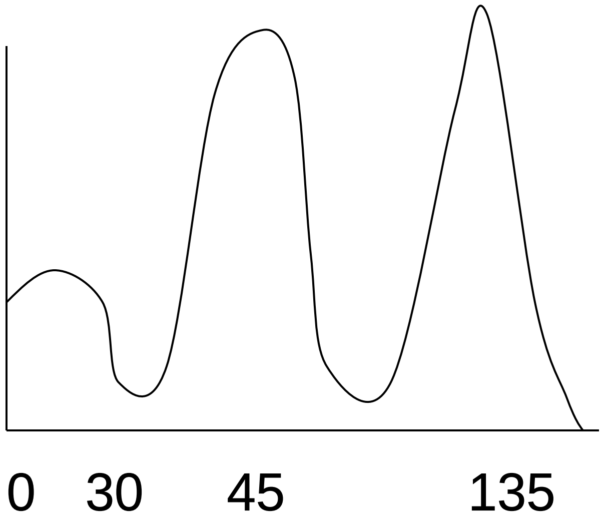
Feature Vector
(0,4,1,3,2,0,0,4,3,2,1,0)

In projection matching, the horizontal and vertical projections form a histogram.

What are the weaknesses of this method? strengths?

Global Shape Properties: Tangent-Angle Histograms





Is this feature invariant to starting point?
Is it invariant to size, translation, rotation?

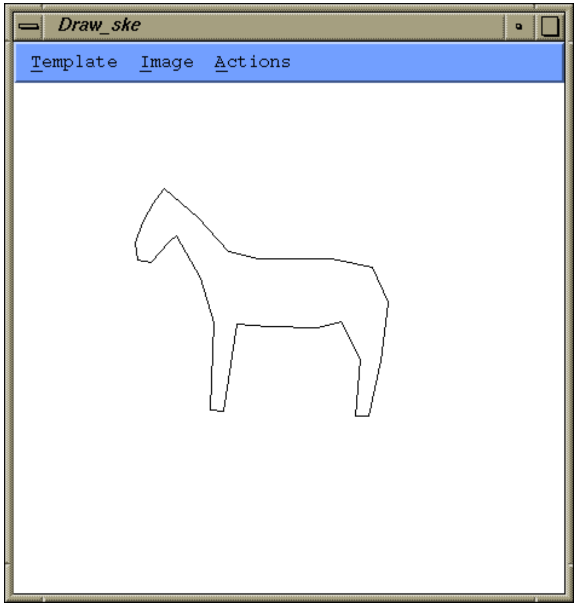
Boundary Matching

- Fourier Descriptors
- Sides and Angles
- Elastic Matching

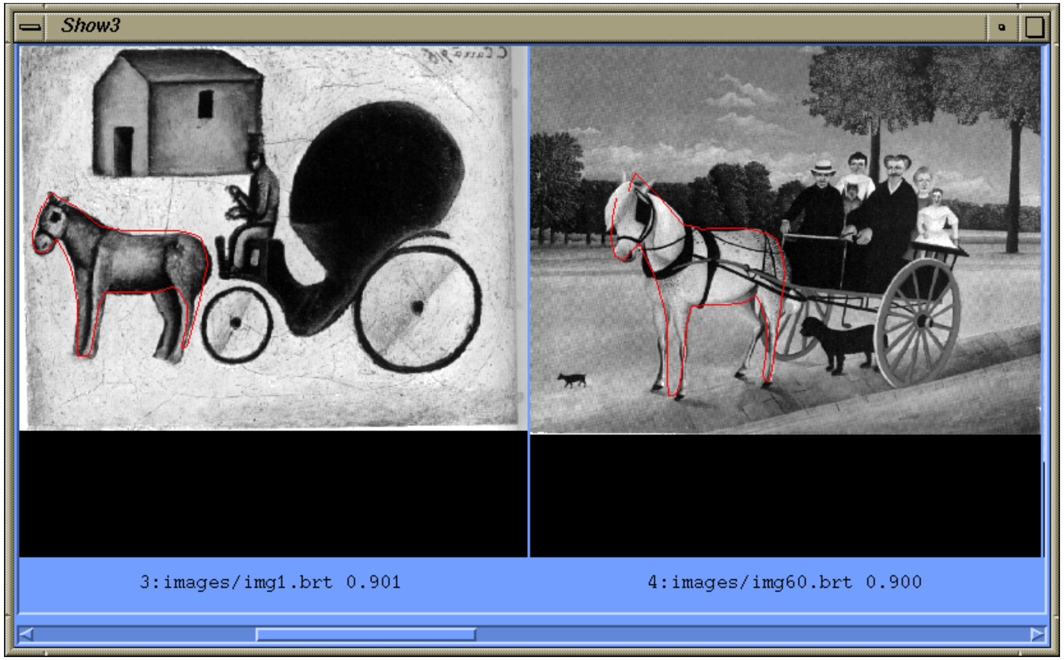
  The distance between query shape and image shape has two components:

  1. energy required to deform the query shape into one that best matches the image shape
  2. a measure of how well the deformed query matches the image

Del Bimbo Elastic Shape Matching



query



retrieved images

Regions and Relationships

- Segment the image into regions
- Find their properties and interrelationships
- Construct a graph representation with nodes for regions and edges for spatial relationships
- Use graph matching to compare images

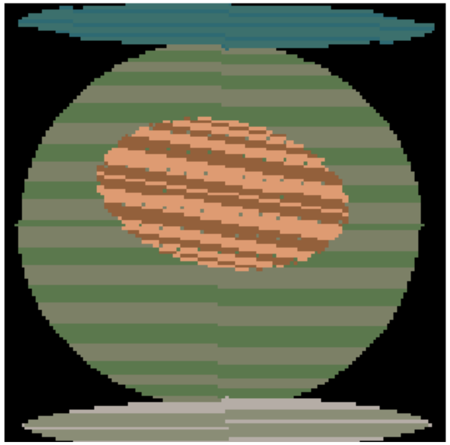
Like what?

Blobworld (Carson et al, 1999)

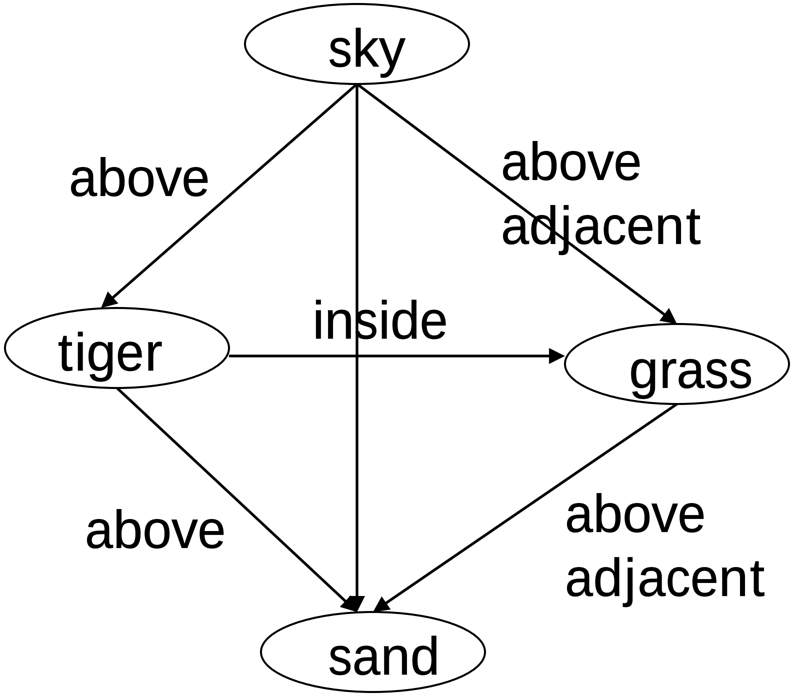
- Segmented the query (and all database images) using EM on color+texture
- Allowed users to select the most important region and what characteristics of it (color, texture, location)
- Asked users if the background was also important

Tiger Image as a Graph (motivated by Blobworld)

image

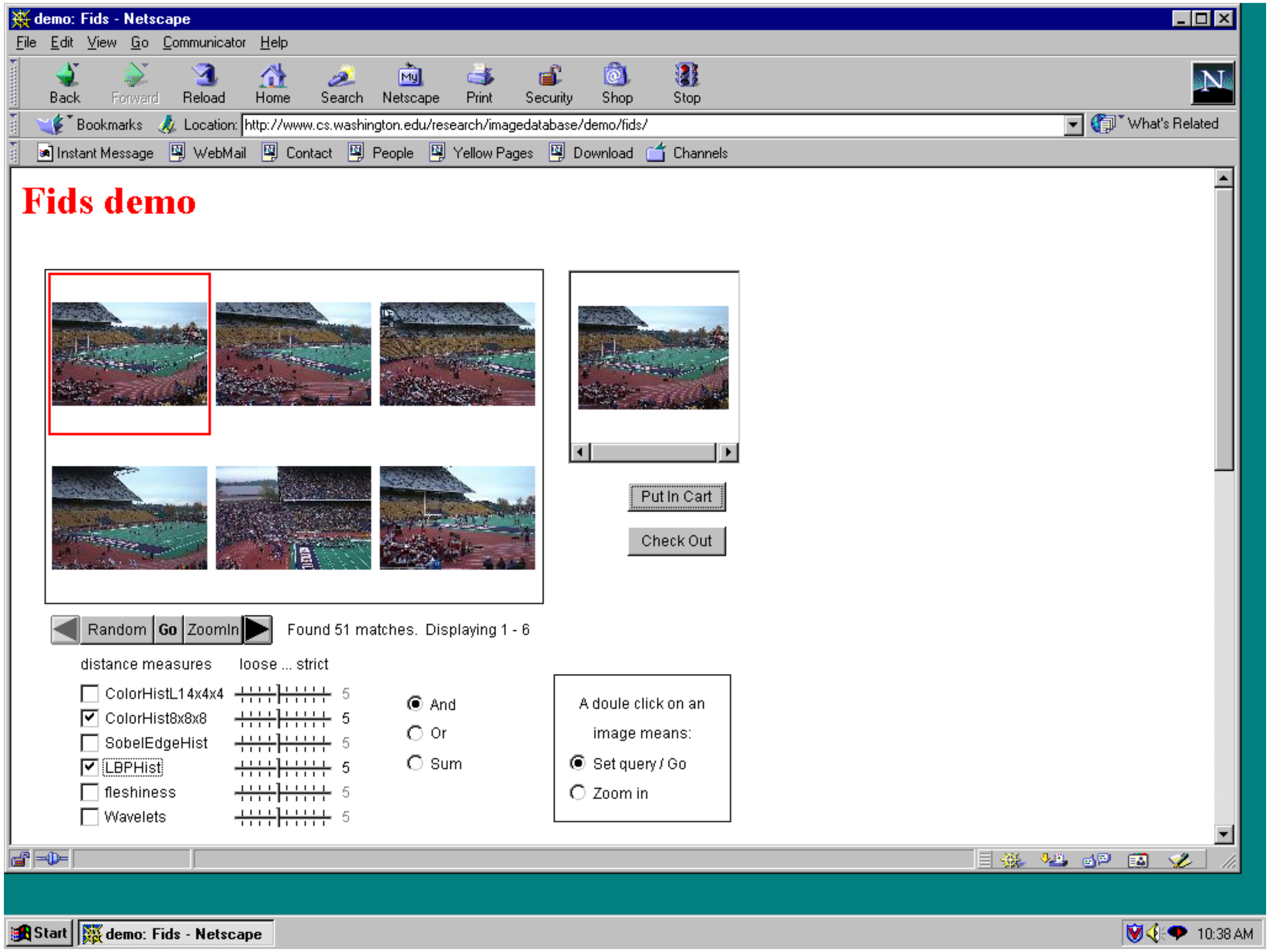


abstract regions



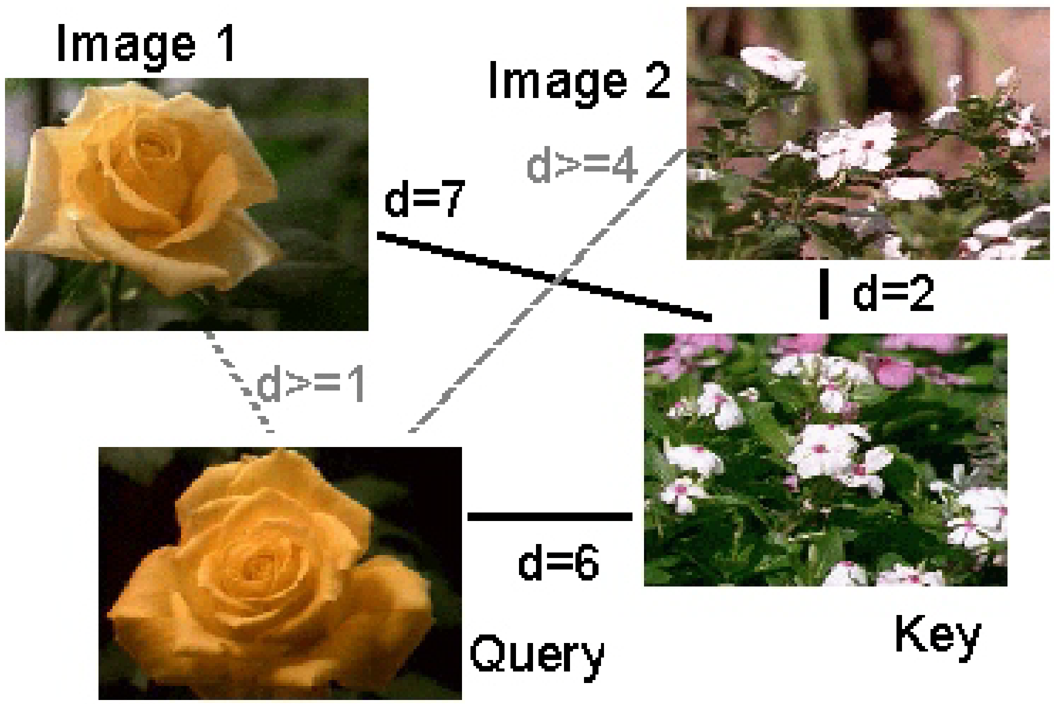
Andy Berman’s FIDS System

multiple distance measures
Boolean and linear combinations
efficient indexing using images as keys



Andy Berman's FIDS System:

Use of key images and the triangle inequality for efficient retrieval.



Andy Berman's FIDS System:

Bare-Bones Triangle Inequality Algorithm

Offline

1. Choose a small set of key images
2. Store distances from database images to keys

Online (given query Q)

1. Compute the distance from Q to each key
2. Obtain lower bounds on distances to database images
3. Threshold or return all images in order of lower bounds

Andy Berman’s FIDS System:

Flexible Image Database System: Example

An example from our system using a simple color measure.
images in system: 37,748
threshold: 100 out of 1000
images eliminated: 37,729

Andy Berman's FIDS System:

Bare-Bones Algorithm with Multiple Distance Measures

Offline

1. Choose key images for each measure
2. Store distances from database images to keys for all measures

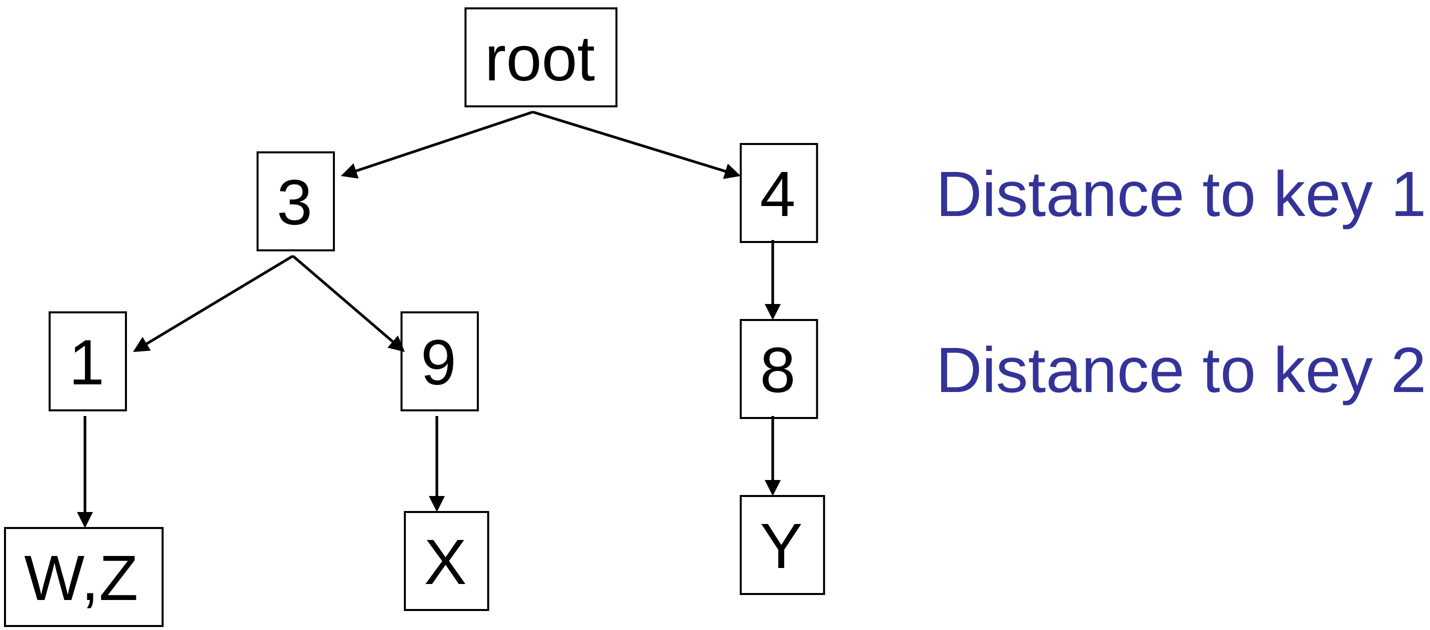
Online (given query Q)

1. Calculate lower bounds for each measure
2. Combine to form lower bounds for composite measures
3. Continue as in single measure algorithm

Andy Berman's FIDS System:

Triangle Tries

A triangle trie is a tree structure that stores the distances from database images to each of the keys, one key per tree level.



Andy Berman's FIDS System:

Triangle Tries and Two-Stage Pruning

- First Stage: Use a short triangle trie.

- Second Stage: Bare-bones algorithm on the images returned from the triangle-trie stage.

The quality of the output is the same as with the bare-bones algorithm itself, but execution is faster.

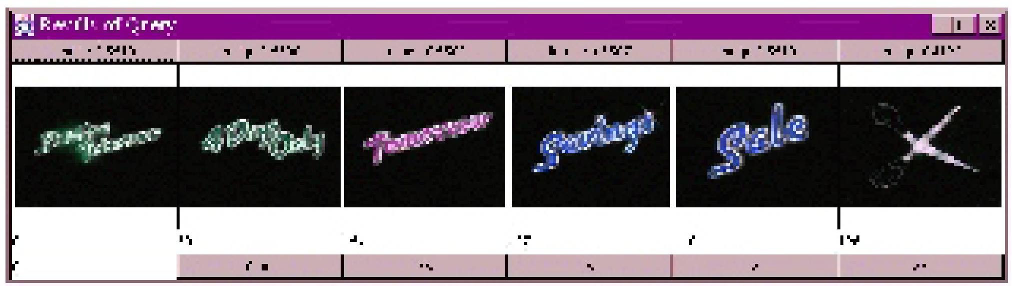
Andy Berman's FIDS System:

Flexible Image Database System: Example

# of images in system: 37,748
Depth of triangle trie: 6
# of images eliminated by trie: 30,300
images eliminated by second-stage: 7429
19 images remaining, as before

Andy Berman’s FIDS System:

Flexible Image Database System: Example



Example from our system using a combination color+texture measure
images in system: 37,748
images from color trie: 3,676
images from texture trie: 497
images in merged set: 3,785
images eliminated: 33,963

Andy Berman's FIDS System:

Performance on a Pentium Pro 200-mHz

Step 1. Extract features from query image. (.02s $\leq$ t $\leq$ .25s)

Step 2. Calculate distance from query to key images. (1μs $\leq$ t $\leq$ .8ms)

Step 3. Calculate lower bound distances. (t $\approx$ 4ms per 1000 images using 35 keys, which is about 250,000 images per second.)

Step 4. Return the images with smallest lower bound distances.

Demo of FIDS

- http://www.cs.washington.edu/research/imagedatabase/demo/

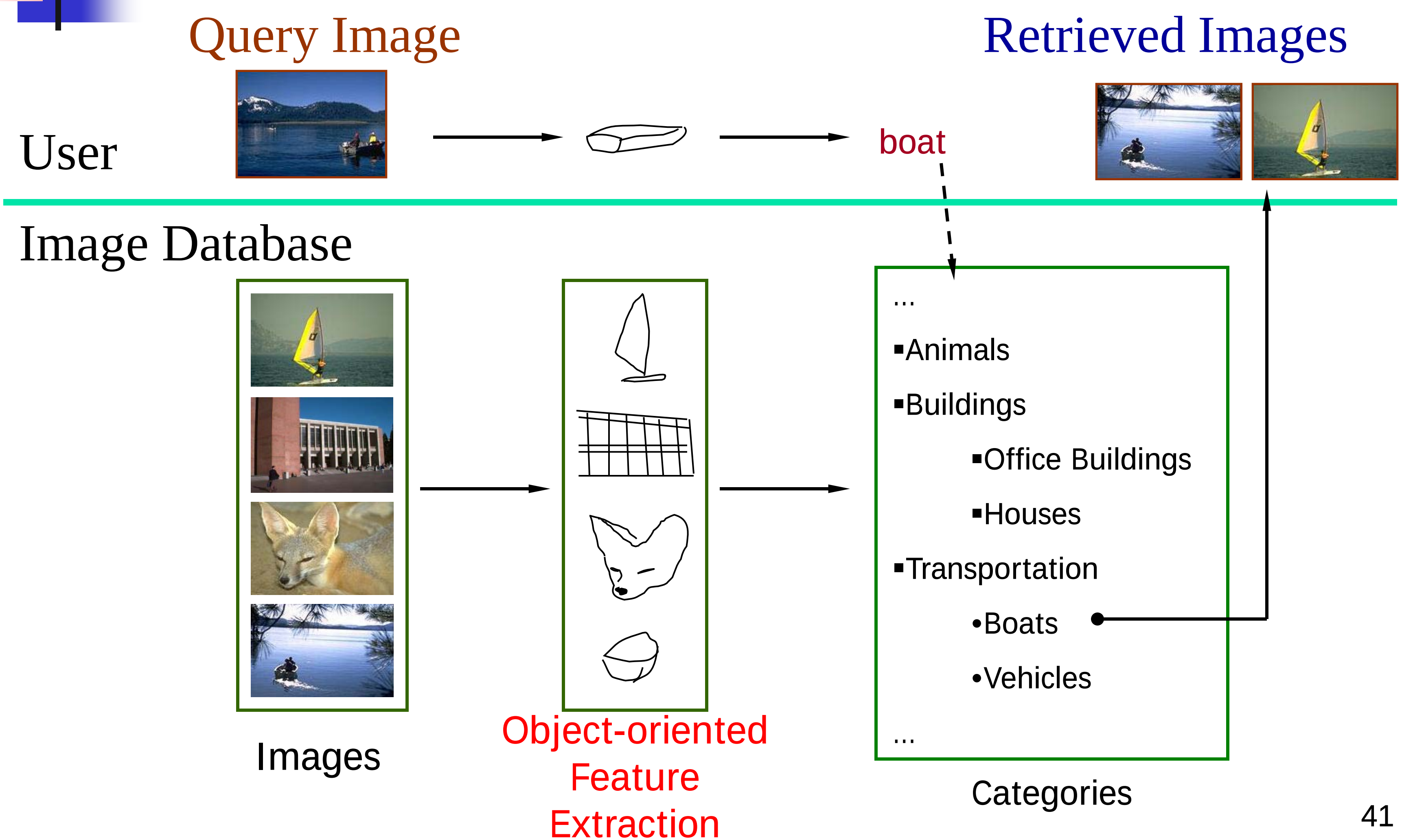
- Try this and the other demos on the same page.

Weakness of Low-level Features

- Can’t capture the high-level concepts

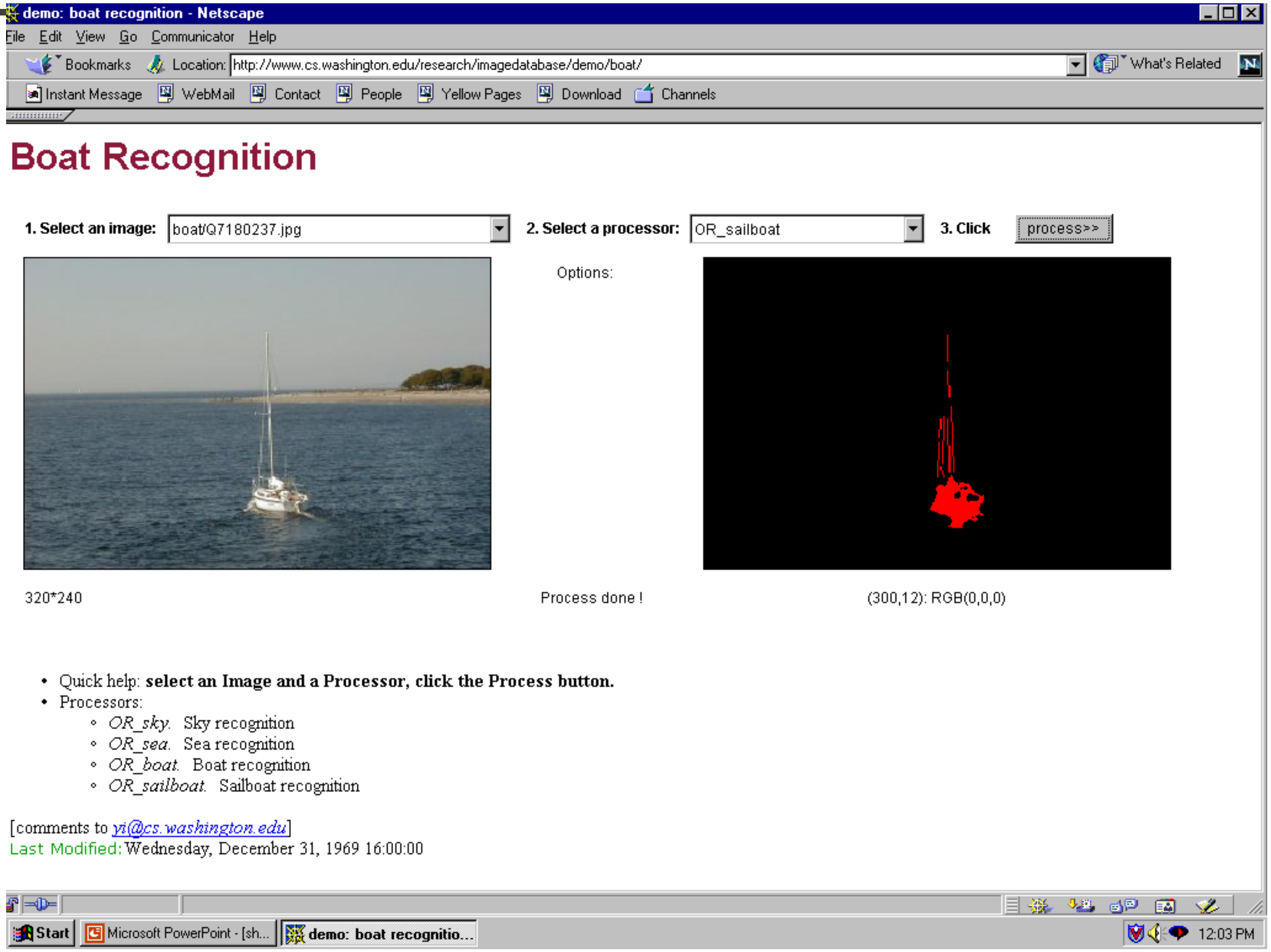
Current Research Objective



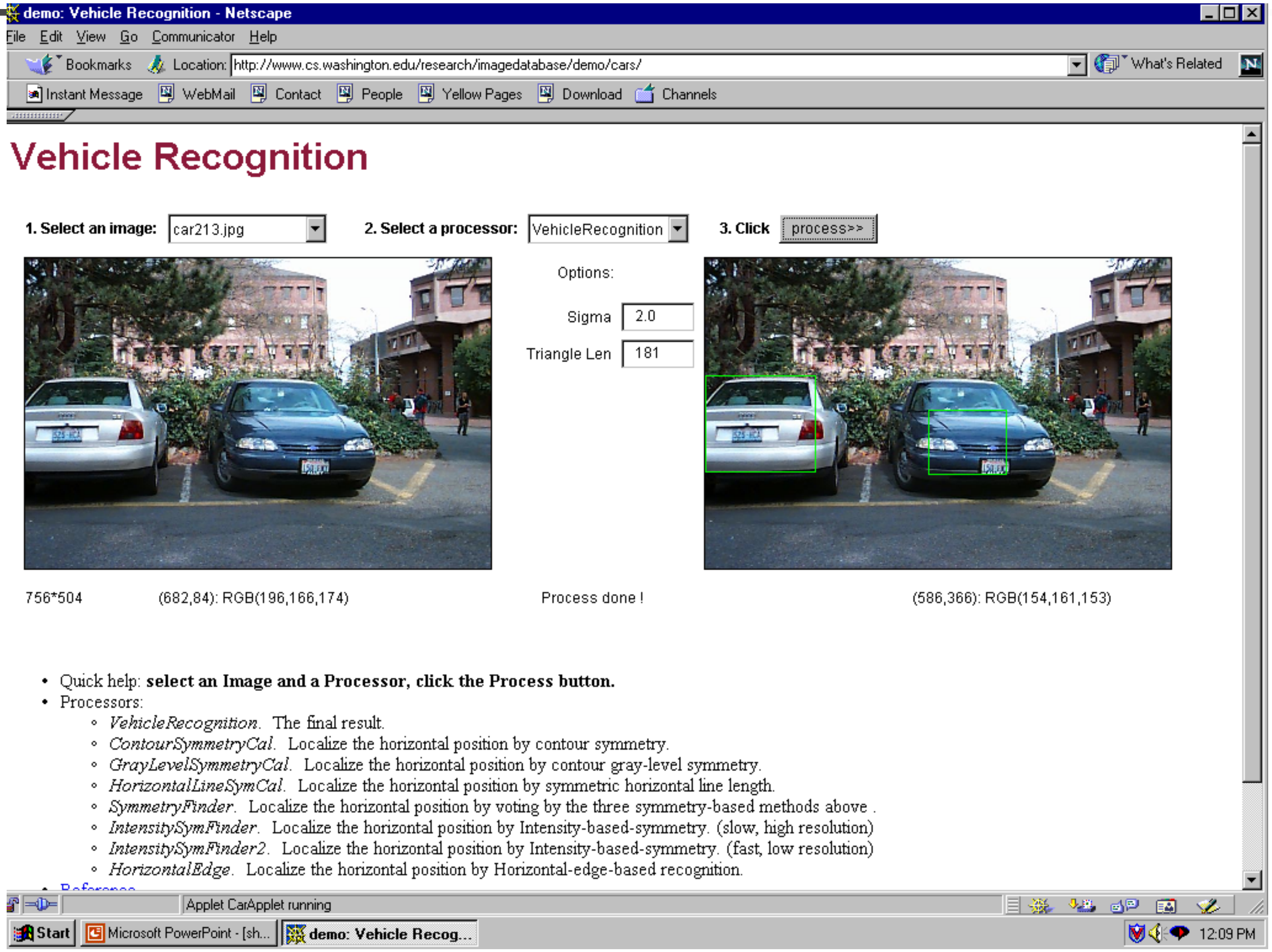
Overall Approach

- Develop object recognizers for common objects
- Use these recognizers to design a new set of both low- and mid-level features
- Design a learning system that can use these features to recognize classes of objects

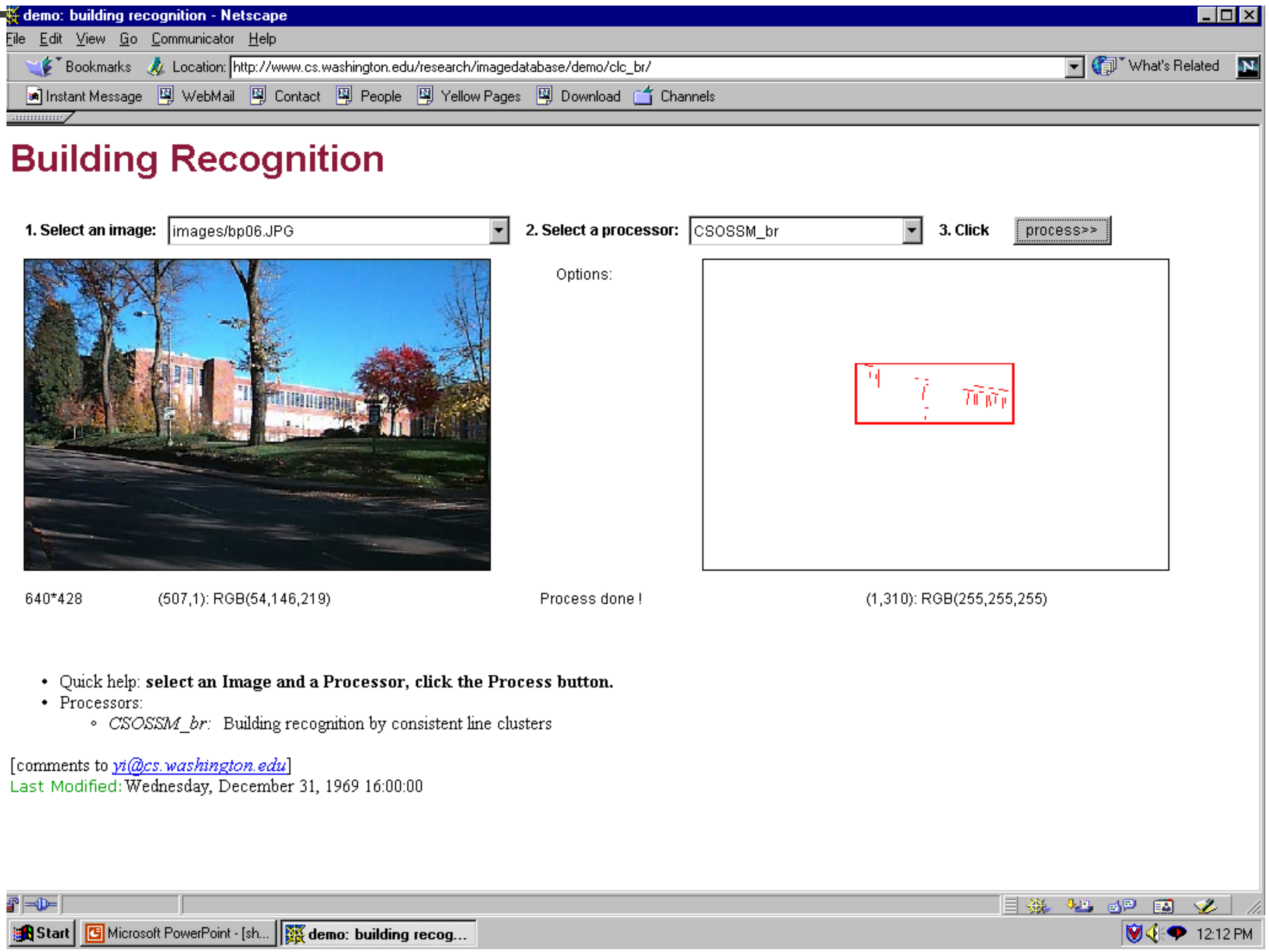
Boat Recognition



Vehicle Recognition



Building Recognition



Building Features: Consistent Line Clusters (CLC)

A **Consistent Line Cluster** is a set of lines that are homogeneous in terms of some line features.

- **Color-CLC**: The lines have the same color feature.
- **Orientation-CLC**: The lines are parallel to each other or converge to a common vanishing point.
- **Spatially-CLC**: The lines are in close proximity to each other.

Color-CLC

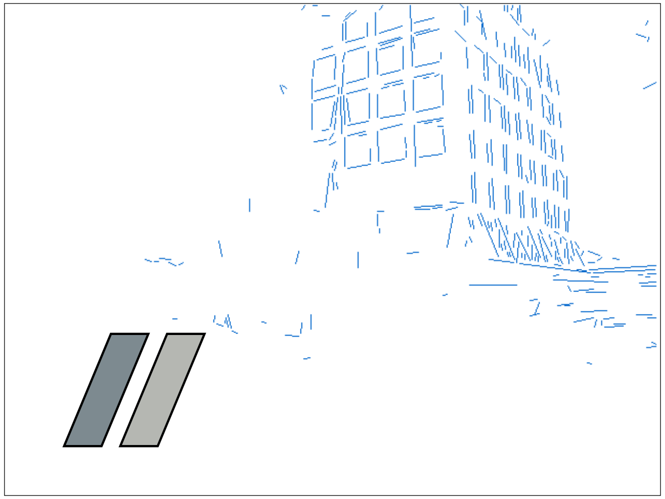
- Color feature of lines: color pair (c_1,c_2)
- Color pair space:

  RGB (256^3*256^3) Too big!

  Dominant colors (20*20)
- Finding the color pairs:

  One line $\rightarrow$ Several color pairs
- Constructing Color-CLC: use clustering

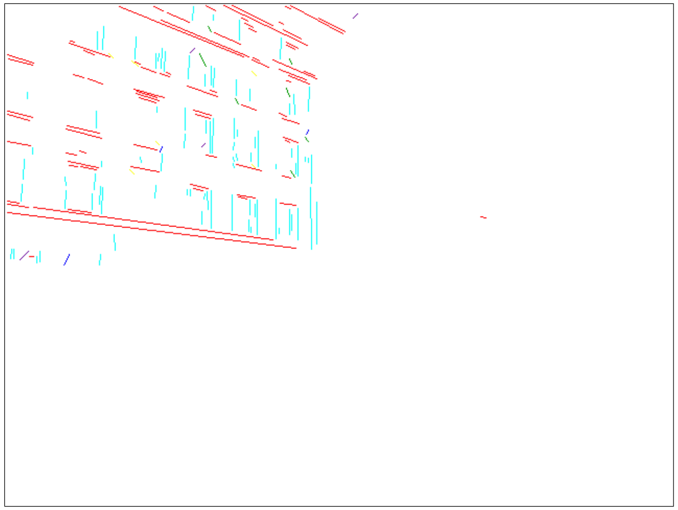
Color-CLC

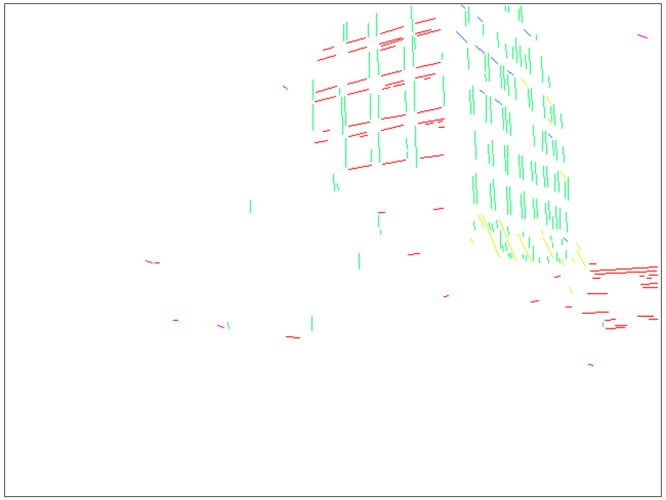


Orientation-CLC

- The lines in an Orientation-CLC are parallel to each other in the 3D world
- The parallel lines of an object in a 2D image can be:
  - Parallel in 2D
  - Converging to a vanishing point (perspective)

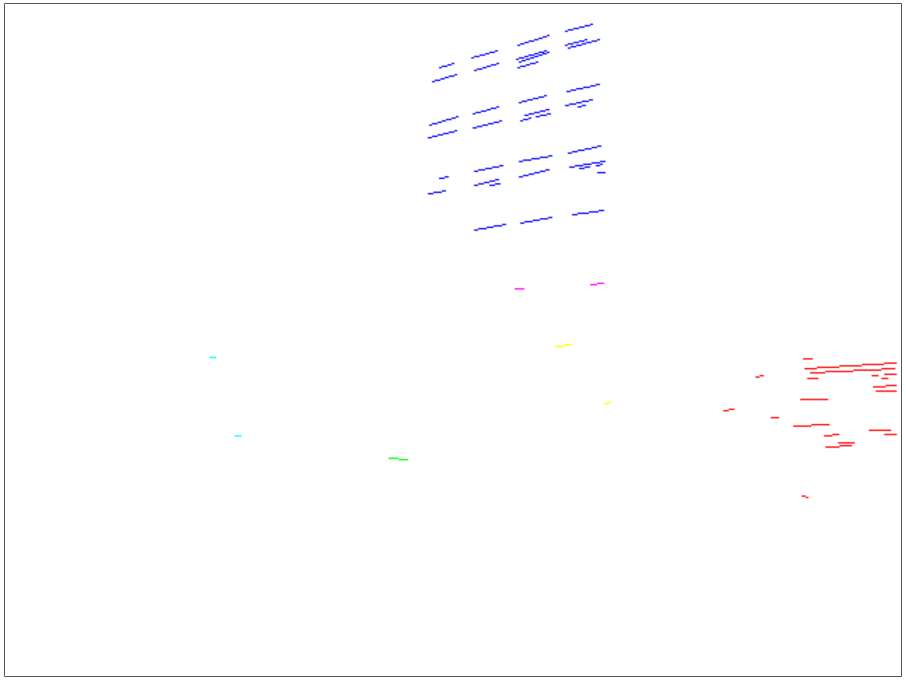
Orientation-CLC





Spatially-CLC

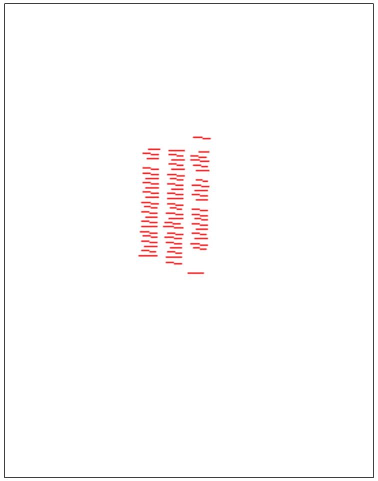
- Vertical position clustering
- Horizontal position clustering

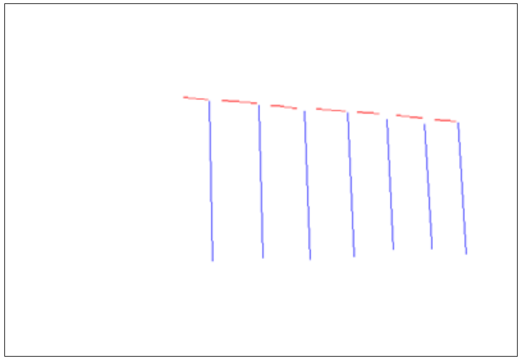


Building Recognition by CLC

Two types of buildings → Two criteria

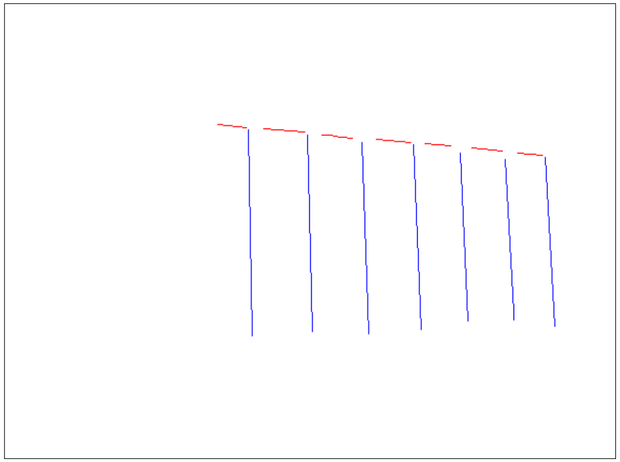
- Inter-relationship criterion
- Intra-relationship criterion





Inter-relationship criterion

$$(N_{c1} > T_{i1} \text{ or } N_{c2} > T_{i1}) \text{ and } (N_{c1} + N_{c2}) > T_{i2}$$

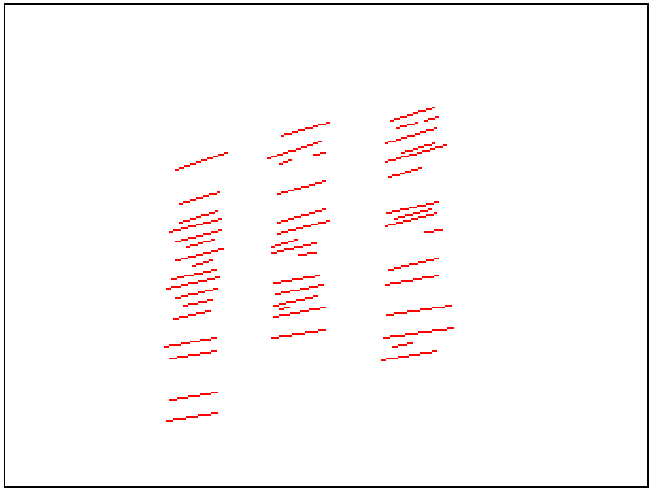


N_{c1} = number of intersecting lines in cluster 1

N_{c2} = number of intersecting lines in cluster 2

Intra-relationship criterion

$$|S_o| > T_{j1} \text{ or } w(S_o) > T_{j2}$$



S_0 = set of heavily overlapping lines in a cluster

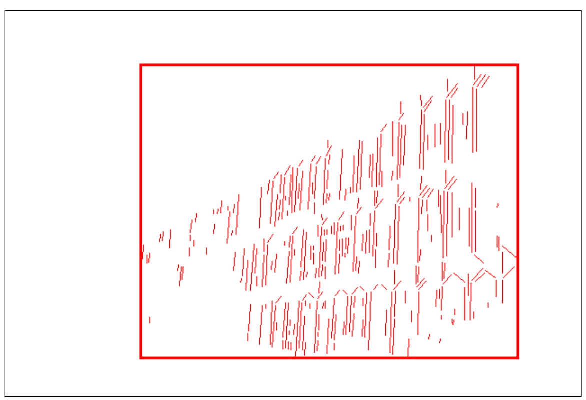
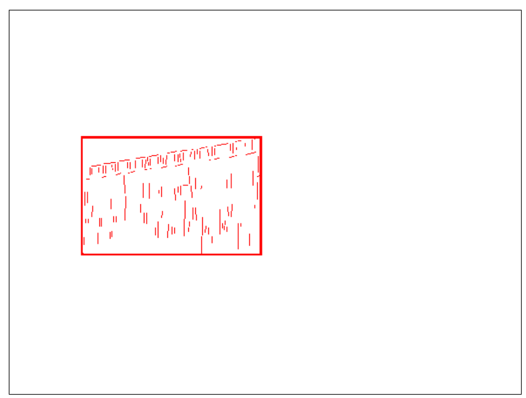
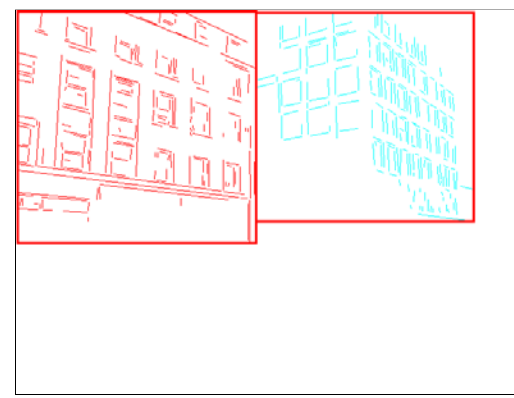
Experimental Evaluation

- Object Recognition
  - 97 well-patterned buildings (bp): 97/97
  - 44 not well-patterned buildings (bnp): 42/44
  - 16 not patterned non-buildings (nbnp): 15/16 (one false positive)
  - 25 patterned non-buildings (nbp): 0/25
- CBIR

Experimental Evaluation

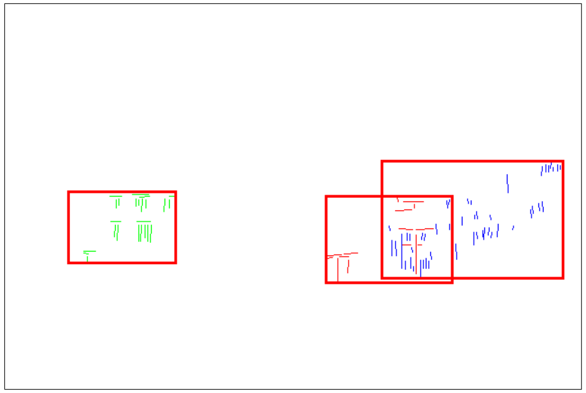
Well-Patterned Buildings

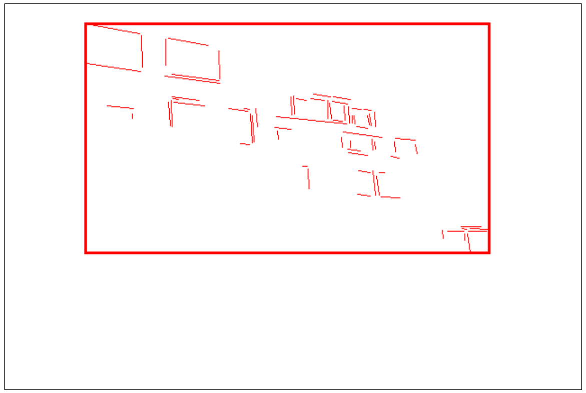


Experimental Evaluation

Non-Well-Patterned Buildings



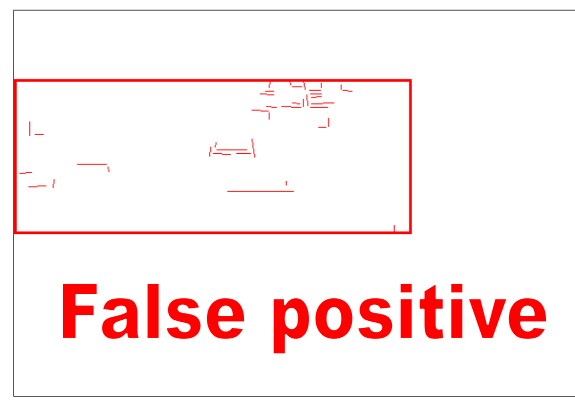


Experimental Evaluation

Non-Well-Patterned Non-Buildings



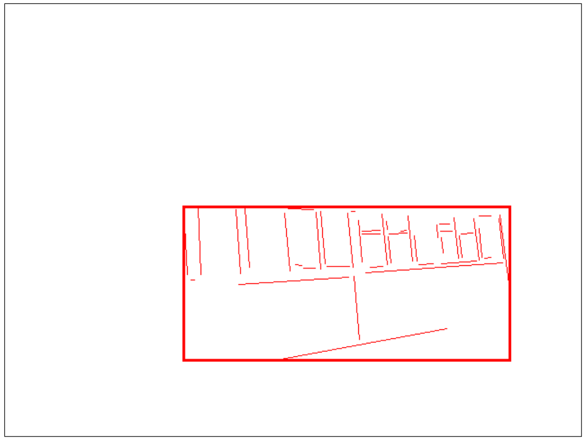
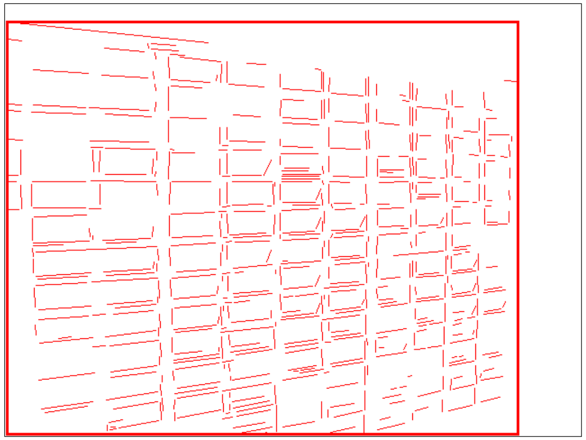
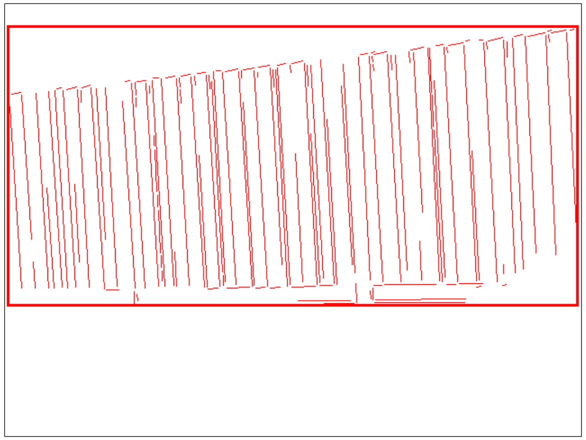


Experimental Evaluation

Well-Patterned Non-Buildings (false positives)



Experimental Evaluation (CBIR)

	Total Positive Classification (#)	Total Negative Classification (#)	False positive (#)	False negative (#)	Accuracy (%)
Arborgreens	0	47	0	0	100
Campusinfall	27	21	0	5	89.6
Cannonbeach	30	18	0	6	87.5
Yellowstone	4	44	4	0	91.7

Experimental Evaluation (CBIR)

False positives from Yellowstone