

Review of Eigenvectors and Eigenvalues

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Definition

The eigenvectors \mathbf{x} and eigenvalues λ of a matrix A satisfy

$$A\mathbf{x} = \lambda\mathbf{x}$$

If A is an $n \times n$ matrix, then \mathbf{x} is an $n \times 1$ vector, and λ is a constant.

The equation can be rewritten as $(A - \lambda I)\mathbf{x} = 0$, where I is the $n \times n$ identity matrix.

Computing Eigenvalues

Since \mathbf{x} is required to be nonzero, the eigenvalues must satisfy

$$\det(A - \lambda I) = 0$$

which is called the *characteristic equation*. Solving it for values of λ gives the eigenvalues of matrix A .

2 X 2 Example

$$A = \begin{bmatrix} 1 & -2 \\ 3 & -4 \end{bmatrix} \quad \text{so } A - \lambda I = \begin{bmatrix} 1 - \lambda & -2 \\ 3 & -4 - \lambda \end{bmatrix}$$

$$\begin{aligned} \det(A - \lambda I) &= (1 - \lambda)(-4 - \lambda) - (3)(-2) \\ &= \lambda^2 + 3\lambda + 2 \end{aligned}$$

Set $\lambda^2 + 3\lambda + 2$ to 0

$$\text{Then } \lambda = \frac{-3 \pm \sqrt{9-8}}{2}$$

So the two values of λ are -1 and -2.

Finding the Eigenvectors

Once you have the eigenvalues, you can plug them into the equation $A\mathbf{x} = \lambda\mathbf{x}$ to find the corresponding sets of eigenvectors \mathbf{x} .

$$\begin{bmatrix} 1 & -2 \\ 3 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = -1 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \text{so} \quad \begin{aligned} x_1 - 2x_2 &= -x_1 \\ 3x_1 - 4x_2 &= -x_2 \end{aligned}$$

(1)	$2x_1 - 2x_2 = 0$
(2)	$3x_1 - 3x_2 = 0$

These equations are not independent. If you multiply (2) by $2/3$, you get (1).

The simplest form of (1) and (2) is $x_1 - x_2 = 0$, or just $x_1 = x_2$.

Since $x_1 = x_2$, we can represent all eigenvectors for eigenvalue -1 as **multiples of a simple basis vector**:

$$E = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \text{ where } t \text{ is a parameter.}$$

So $[1 \ 1]^T$, $[4 \ 4]^T$, $[3000 \ 3000]^T$ are all possible eigenvectors for eigenvalue -1.

For the second eigenvalue (-2) we get

$$\begin{bmatrix} 1 & -2 \\ 3 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = -2 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \text{so} \quad \begin{aligned} x_1 - 2x_2 &= -2x_1 \\ 3x_1 - 4x_2 &= -2x_2 \end{aligned}$$

(1)	$3x_1 - 2x_2 = 0$
(2)	$3x_1 - 2x_2 = 0$

so eigenvectors are of the form $t \begin{bmatrix} 2 \\ 3 \end{bmatrix}$.

Generalization for 2 X 2 Matrices

$$\text{If } A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \text{ then } \lambda = \frac{(a + d) \pm \sqrt{(a+d)^2 - 4(ad - bc)}}{2}$$

The discriminant (the part under the square root), can be simplified to get $\sqrt{(a-d)^2 + 4bc}$.

If $b = c$, this becomes $\sqrt{(a-d)^2 + (2b)^2}$

Since the discriminant is the sum of 2 squares, it has real roots.

We will be seeing some 2 x 2 matrices where indeed $b = c$, so we'll be guaranteed a real-valued solution for the eigenvalues.

Another observation we will use:

For 2 x 2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$,

$\lambda_1 + \lambda_2 = a + d$, which is called **trace(A)**

and

$\lambda_1\lambda_2 = ad - bc$, which is called **det(A)**.

Finally, zero is an eigenvalue of A if and only if A is singular and $\det(A) = 0$.