# **Texture Mapping**

Brian Curless CSE 457 Autumn 2010 Reading

#### Required

Angel, 86, 8.7, 8.9, 8.10, 9.13-9.13.2

#### Recommen de d

 Paul S. Heckbert. Survey of texture mapping. IEEE Computer Graphics and Applications 6(11): 56-67. November 1986.

#### Optional

- Woo, Neider, & Davis, Chapter 9
- James F. Blinn and Martin E. Newell. Texture and reflection in computer generated images.
  Communications of the ACM 19(10): 542--547, October 1976.

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## Texture mapping



Texture mapping (Wooet al., fig. 9-1)

Texture mapping allows you to take a simple polygon and give it the appearance of something much more complex.

- Due to Ed Catmull, PhD thesis, 1974
- · Refined by Blinn & Newell, 1976

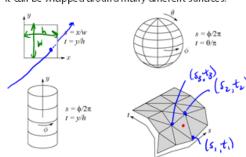
A texture can modulate just about any parameter – diffuse color, specular color, specular exponent, ...

### Implementing texture mapping

A texture lives in it own abstract image coordinates paramaterized by (s,t) in the range ([0..1], [0..1]):



It can be wrapped around many different surfaces:



With a ray caster, we can do the sphere and cylinder mappings directly (as we will see later). For z-buffers, everything gets converted to a triangle mesh with associated (s,t) coordinates.

Note: if the surface moves/deforms, the texture goes with it.

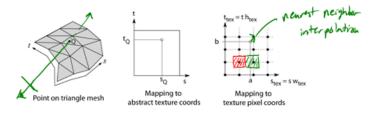
## Mapping to texture image coords

The texture is usually stored as an image. Thus, we need to convert from abstract texture coordinate:

(s,t) in the range ([0..1], [0..1])

to texture image coordinates:

$$(s_{tex'}t_{tex})$$
 in the range  $([0...w_{tex}], [0...h_{tex}])$ 

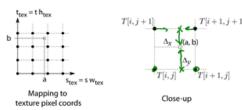


Q: What do you do when the texture sample you need lands between texture pixels?

#### Texture resampling

We need to resample the texture:





Thus, we seek to solve for:  $T(a,b) = T(i + \Delta_x, j + \Delta_y)$ 

A common choice is bilinear interpolation:

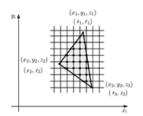
$$\begin{split} \mathsf{T}(i+\Delta_x,j) &= \underline{-\left(1-\Delta_x\right)} \; \mathsf{T}[i,j] \quad + \quad \underline{-\Delta_x} \; \mathsf{T}[i+1,j] \\ \mathsf{T}(i+\Delta_x,j+1) &= \underline{-\left(1-\Delta_x\right)} \; \mathsf{T}[i,j+1] \; + \quad \underline{-\Delta_x} \; \; \mathsf{T}[i+1,j+1] \\ \mathsf{T}(i+\Delta_x,j+\Delta_y) &= \underline{-\left(1-\Delta_y\right)} \; \mathsf{T}(i+\Delta_x,j) \; + \; \underline{-\Delta_y} \; \mathsf{T}(i+\Delta_x,j+1) \\ &= \underline{-\left(1-\Delta_x\right)} \; \underbrace{-\left(1-\Delta_y\right)} \; \mathsf{T}[i,j+1] \; + \; \underline{-\Delta_x} \; \underbrace{-\left(1-\Delta_y\right)} \; \mathsf{T}[i+1,j+1] \\ &= \underline{-\left(1-\Delta_x\right)} \; \underbrace{-\Delta_x} \; \underbrace{-\Delta_y} \; \mathsf{T}[i+1,j+1] \; + \; \underline{-\Delta_x} \; \underbrace{-\Delta_y} \; \mathsf{T}[i+1,j+1] \; + \; \underline{-\Delta_x} \; \underbrace{-\Delta_y} \; \mathsf{T}[i+1,j+1] \end{split}$$

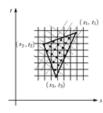
# Texture mapping and the z-buffer

Texture-mapping can also be handled in z-buffer algorithms.

Meth od:

- Scan conversion is done in screen space, as
- Each pixel is colored according to the texture
- · Texture coordinates are found by Gouraud-style interpolation



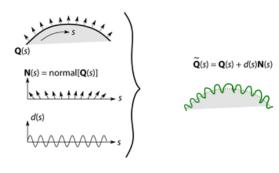


Note: Mapping is more complicated to handle perspective correctly!

# Displacement mapping

Textures can be used for more than just color.

In displacement mapping, a texture is used to perturb the surface geometry itself. Here's the idea in 2D:



- These displacements "animate" with the surface
- In 3D, you would of course have (s,t) parameters instead of just s.

Suppose Q is a simple surface, like a sphere. Will it take  $\sqrt{\ell_S}$ more work to render the modified surface  $\tilde{\mathbf{Q}}$ ?



# **Bump mapping**

In bump mapping, a texture is used to perturb the

- Use the original, simpler geometry, Q(s), for hidden surfaces
- Use the normal from the displacement map for shading:

 $\tilde{\mathbf{N}} = \operatorname{normal}[\tilde{\mathbf{Q}}(s)]$ 



What artifacts in the images would reveal that bump mapping is a fake?

perspective deference Occlusions wrong Silhmettes wrong Shadows wrong

## Displacement vs. bump mapping

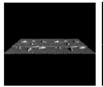
Input texture



Rendered as displacement map over a rectangular surface









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# Displacement vs. bump mapping (cont'd)





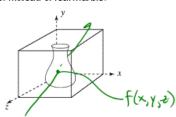
Original rendering

Rendering with bump map wrapped around a cylinder

Bump map and rendering by Wyvern Aldinger

#### Solid textures

Q: What kinds of artifacts might you see from using a marble veneer instead of real marble?



One solution is to use solid textures:

- Use model-space coordinates to index into a 3D
- Like "carving" the object from the material

One difficulty of solid texturing is coming up with the textures.

#### Solid textures (cont'd)

Here's an example for a vase cut from a solid marble texture:



Solid marble texture by Ken Perlin, (Foley, IV-21)

#### Solid textures (cont'd)

 $\operatorname{in}(x,y,z) = \operatorname{shift}(x,y,z) = \operatorname{out}(x,y,z) = \operatorname{stripes}(x)$   $\operatorname{Kunoise}(x,y,z)$   $\operatorname{stripes}(x+\operatorname{shift}(x,y,z))$ 













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# **Environment mapping**







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In **environment mapping** (also known as **reflection mapping**), a texture is used to model an object's environment:

- · Rays are bounced off objects into environment
- Color of the environment used to determine color of the illumination
- Environment mapping works well when there is just a single object – or in conjunction with ray tracing

This can be readily implemented (without interreflection) using a fragment shader, where the texture is stored in a "cube map" instead of a sphere.

With a ray tracer, the concept is easily extended to handle refraction as well as reflection (and interreflection).

### Summary

What to take home from this lecture:

- 1. The meaning of the boldfaced terms.
- Familiarity with the various kinds of texture mapping, including their strengths and limitations.