

CSE 473

## Chapter 18

# Machine Learning: Decision Trees

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## Why Learning?

- Learning is essential for unknown environments  
e.g., when designer lacks omniscience
- Learning is necessary in dynamic environments  
Agent can adapt to changes in environment not  
foreseen at design time
- Learning is useful as a system construction  
method  
Expose the agent to reality rather than trying to  
approximate it through equations etc.
- Learning modifies the agent's decision  
mechanisms to improve performance

## Types of Learning

- **Supervised learning:** correct answers for each input is provided  
E.g., decision trees, backprop neural networks
- **Unsupervised learning:** correct answers not given, must discover patterns in input data  
E.g., clustering, principal component analysis
- **Reinforcement learning:** occasional rewards (or punishments) given  
E.g., Q learning, MDPs

## Inductive learning

A form of Supervised Learning:  
Learn a function from examples

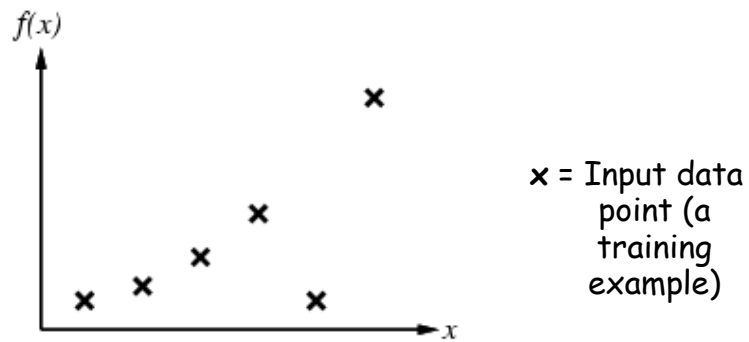
$f$  is the target function. Examples are pairs  $(x, f(x))$

Problem: learn a function ("hypothesis")  $h$   
such that  $h \approx f$  ( $h$  approximates  $f$  as best as possible)  
given a training set of examples

(This is a highly simplified model of real learning:  
Ignores prior knowledge  
Assumes examples are given)

## Inductive learning example

- Construct  $h$  to agree with  $f$  on training set  
 $h$  is **consistent** if it agrees with  $f$  on all training examples
- E.g., curve fitting (regression):

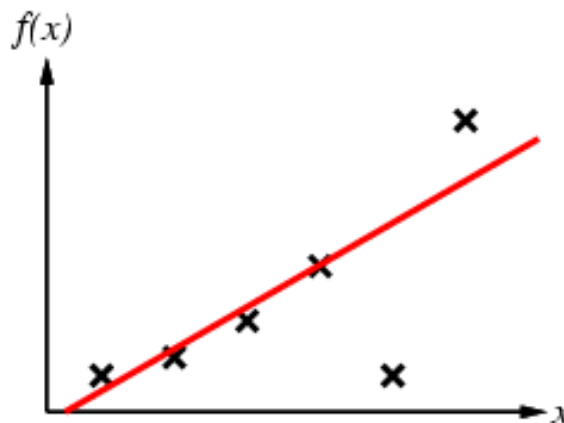


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## Inductive learning example

$h$  = Straight line?

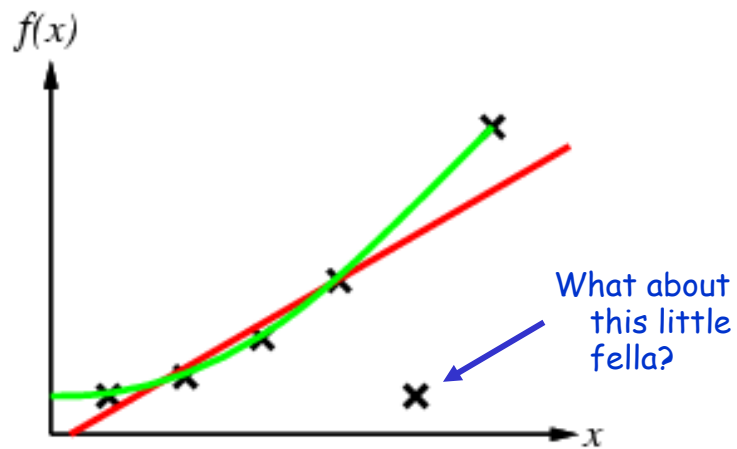


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## Inductive learning example

What about a quadratic function?

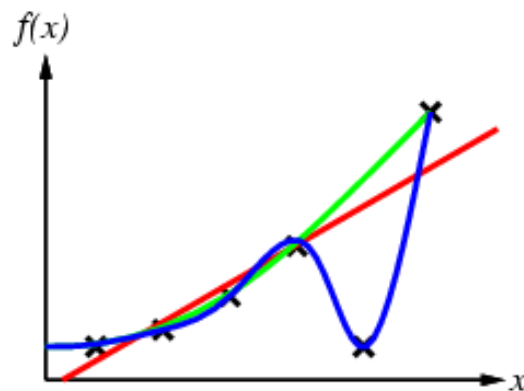


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## Inductive learning example

Finally, a function that satisfies all!

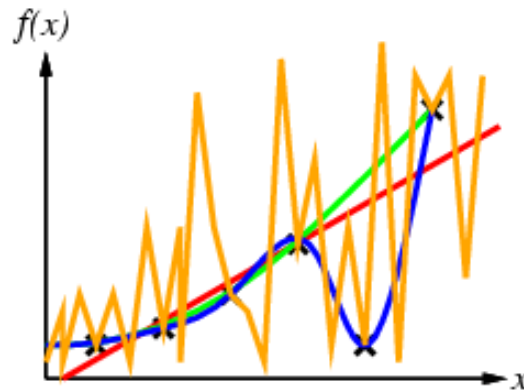


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## Inductive learning example

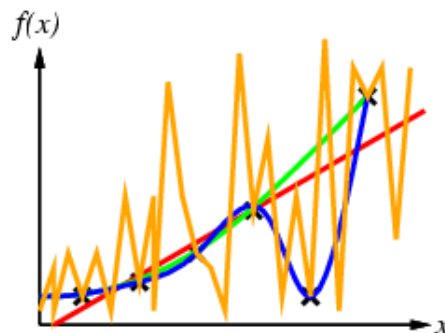
But so does this one...



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## Ockham's razor principle



- Ockham's razor: prefer the simplest hypothesis consistent with data
  - Related to KISS principle ("keep it simple stupid")
  - Smooth blue function preferable over wiggly yellow one
  - If noise known to exist in this data, even linear might be better (the lowest  $x$  might be due to noise)

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## Example data for learning the concept "Good day for tennis"

Day	Outlook	Humid	Wind	PlayTennis?
d1	s	h	w	n
d2	s	h	s	n
d3	o	h	w	y
d4	r	h	w	y
d5	r	n	w	y
d6	r	n	s	y
d7	o	n	s	y
d8	s	h	w	n
d9	s	n	w	y
d10	r	n	w	y
d11	s	n	s	y
d12	o	h	s	y
d13	o	n	w	y
d14	r	h	s	n

- Outlook = sunny, overcast, rain

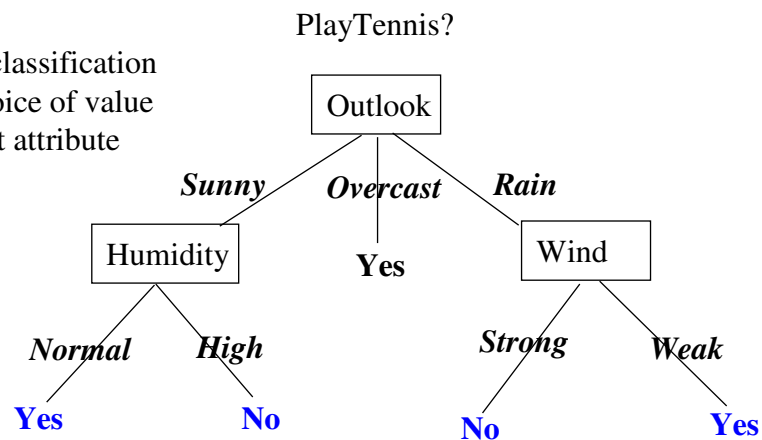
- Humidity = high, normal

- Wind = weak, strong

## A Decision Tree for the Same Data

Leaves = classification

Arcs = choice of value for parent attribute



Decision tree is equivalent to logic in disjunctive normal form

$\text{PlayTennis} \Leftrightarrow (\text{Sunny} \wedge \text{Normal}) \vee \text{Overcast} \vee (\text{Rain} \wedge \text{Weak})$

# Decision Trees

**Input:** Description of an object or a situation through a set of **attributes**

**Output:** a **decision** that is the predicted output value for the input

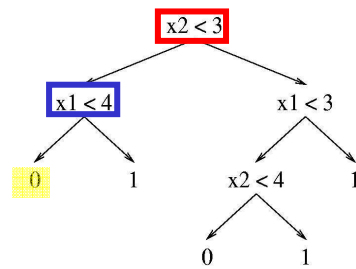
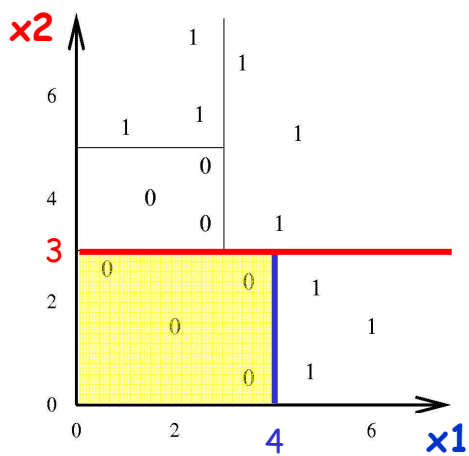
Both **input and output can be discrete or continuous**

**Discrete-valued functions** lead to **classification problems**

Learning a **continuous function** is called **regression**

## Example: Classification of Continuous Valued Inputs

Decision trees divide the feature space into axis-parallel rectangles, and label each rectangle with one of the  $K$  classes.

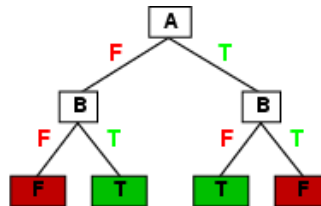


Decision Tree

# Expressiveness

- Decision trees can express any function of the input attributes.
- E.g., for Boolean functions, truth table row → path to leaf:

A	B	A xor B
F	F	F
F	T	T
T	F	T
T	T	F



- Trivially, there is a consistent decision tree for any training set with one path to leaf for each example  
But most likely won't generalize to new examples
- Prefer to find more compact decision trees

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# Learning Decision Trees

Example: When should I wait for a table at a restaurant?

Attributes (features) relevant to *Wait?* decision:

1. **Alternate**: is there an alternative restaurant nearby?
2. **Bar**: is there a comfortable bar area to wait in?
3. **Fri/Sat**: is today Friday or Saturday?
4. **Hungry**: are we hungry?
5. **Patrons**: number of people in the restaurant (None, Some, Full)
6. **Price**: price range (\$, \$\$, \$\$\$)
7. **Raining**: is it raining outside?
8. **Reservation**: have we made a reservation?
9. **Type**: kind of restaurant (French, Italian, Thai, Burger)
10. **WaitEstimate**: estimated waiting time (0-10, 10-30, 30-60, >60)

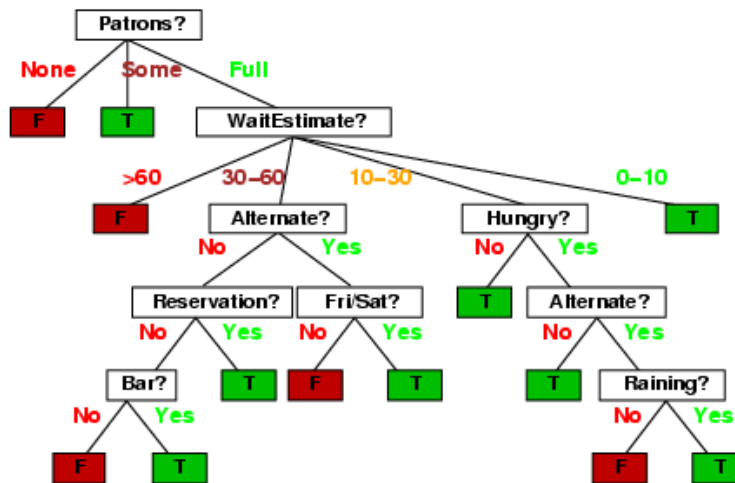
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# Example Decision tree

A decision tree for *Wait?* based on personal "rules of thumb":



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# Input Data for Learning

- Past examples where I did/did not wait for a table:

Example	Attributes										Target Wait
	Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	
X <sub>1</sub>	T	F	F	T	Some	\$\$\$	F	T	French	0-10	T
X <sub>2</sub>	T	F	F	T	Full	\$	F	F	Thai	30-60	F
X <sub>3</sub>	F	T	F	F	Some	\$	F	F	Burger	0-10	T
X <sub>4</sub>	T	F	T	T	Full	\$	F	F	Thai	10-30	T
X <sub>5</sub>	T	F	T	F	Full	\$\$\$	F	T	French	>60	F
X <sub>6</sub>	F	T	F	T	Some	\$\$	T	T	Italian	0-10	T
X <sub>7</sub>	F	T	F	F	None	\$	T	F	Burger	0-10	F
X <sub>8</sub>	F	F	F	T	Some	\$\$	T	T	Thai	0-10	T
X <sub>9</sub>	F	T	T	F	Full	\$	T	F	Burger	>60	F
X <sub>10</sub>	T	T	T	T	Full	\$\$\$	F	T	Italian	10-30	F
X <sub>11</sub>	F	F	F	F	None	\$	F	F	Thai	0-10	F
X <sub>12</sub>	T	T	T	T	Full	\$	F	F	Burger	30-60	T

- Classification of examples is positive (T) or negative (F)

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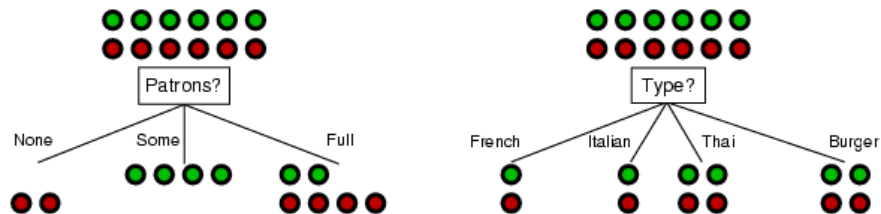
# Decision Tree Learning

- Aim: find a small tree consistent with training examples
- Idea: (recursively) choose "most significant" attribute as root of (sub)tree

```
function DTL(examples, attributes, default) returns a decision tree
  if examples is empty then return default
  else if all examples have the same classification then return the classification
  else if attributes is empty then return MODE(examples)
  else
    best ← CHOOSE-ATTRIBUTE(attributes, examples)
    tree ← a new decision tree with root test best
    for each value  $v_i$  of best do
       $examples_i$  ← {elements of examples with  $best = v_i$ }
      subtree ← DTL( $examples_i$ , attributes - best, MODE(examples))
      add a branch to tree with label  $v_i$  and subtree subtree
    return tree
```

## Choosing an attribute to split on

- Idea: a good attribute splits the examples into subsets that are (ideally) "all positive" or "all negative"



- *Patrons?* is a better choice

## Next Time

- How to choose attributes to split on?  
Using information theory and entropy
- The more, the merrier (and better) -  
combining classifiers  
Ensemble learning via boosting