

CSE 490 G
Introduction to Data Compression
Winter 2006

Lossy Image Compression
Transform Coding
JPEG

Lossy Image Compression Methods

- DCT Compression
 - JPEG
- Wavelet Compression
 - SPIHT
 - UWIC (University of Washington Image Coder)
 - EBCOT (JPEG 2000)
- Scalar quantization (SQ).
- Vector quantization (VQ).

CSE 490g - Lecture 11 - Winter 2006

2

JPEG Standard

- JPEG - Joint Photographic Experts Group
 - Current image compression standard. Uses discrete cosine transform, scalar quantization, and Huffman coding.
- JPEG 2000 uses wavelet compression.

CSE 490g - Lecture 11 - Winter 2006

3

Barbara



32:1 compression ratio
.25 bits/pixel (8 bits)

CSE 490g - Lecture 11 - Winter 2006

4

JPEG



CSE 490g - Lecture 11 - Winter 2006

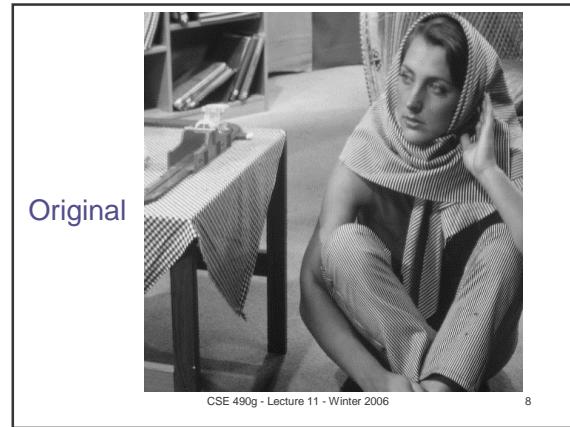
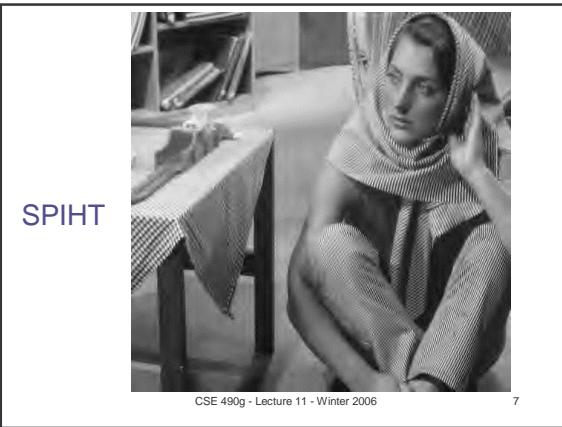
5

VQ



CSE 490g - Lecture 11 - Winter 2006

6



Images and the Eye

- Images are meant to be viewed by the human eye (usually).
- The eye is very good at “interpolation”, that is, the eye can tolerate some distortion. So lossy compression is not necessarily bad. The eye has more acuity for **luminance (gray scale)** than **chrominance (color)**.
 - Gray scale is more important than color.
 - Compression is usually done in the YUV color coordinates, Y for luminance and U,V for color.
 - U and V should be compressed more than Y
 - This is why we will concentrate on compressing gray scale (8 bits per pixel) images.

CSE 490g - Lecture 11 - Winter 2006

9

Distortion

```

graph LR
    original[x] --> Encoder[Encoder]
    Encoder -- y --> Decoder[Decoder]
    Decoder -- "x-hat" --> x_hat[x-hat]
  
```

- Lossy compression: $x \neq \hat{x}$
- Measure of distortion is commonly mean squared error (MSE). Assume x has n real components (pixels).

$$MSE = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{x}_i)^2$$

CSE 490g - Lecture 11 - Winter 2006

10

PSNR

- Peak Signal to Noise Ratio (PSNR) is the standard way to measure fidelity.

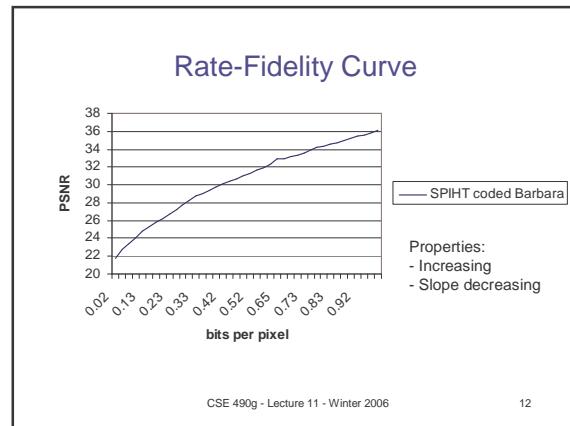
$$PSNR = 10 \log_{10} \left(\frac{m^2}{MSE} \right)$$

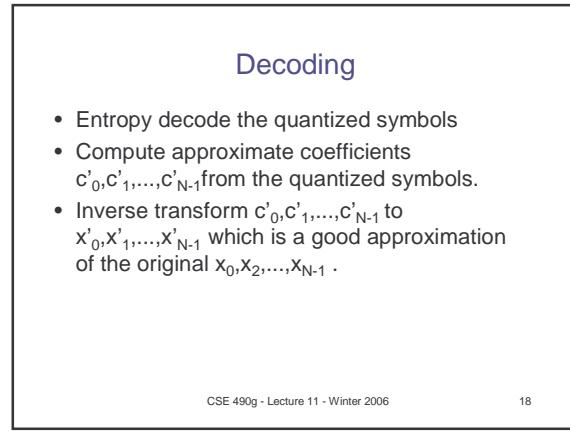
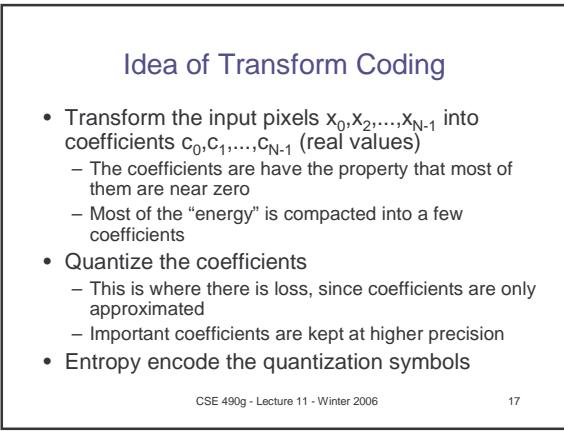
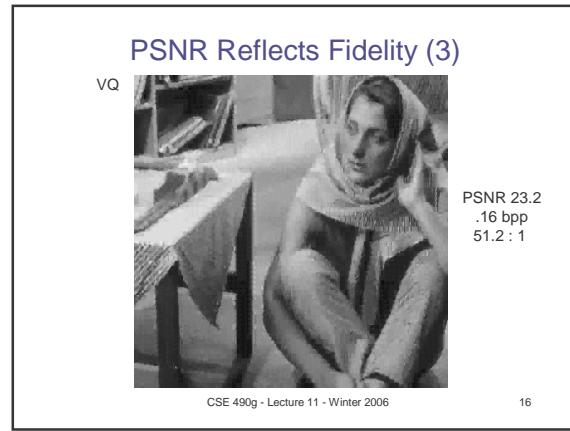
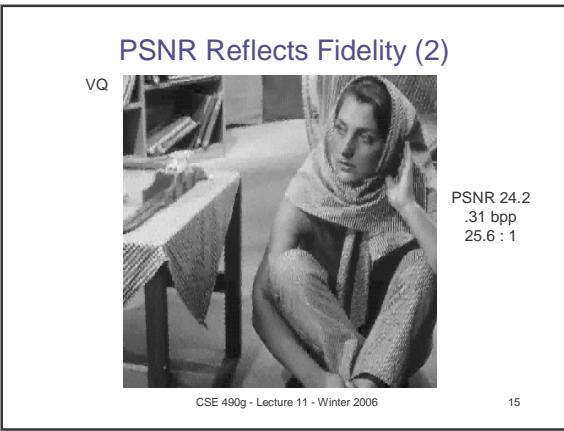
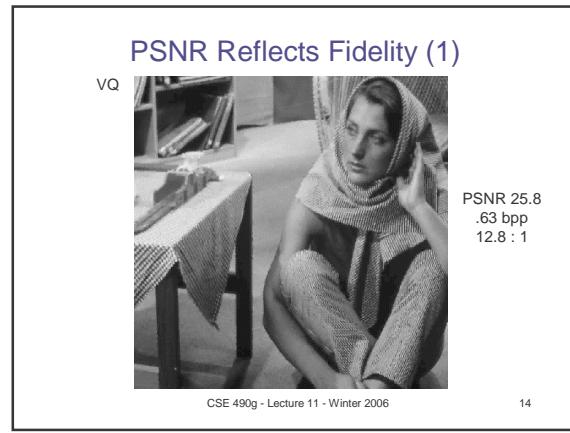
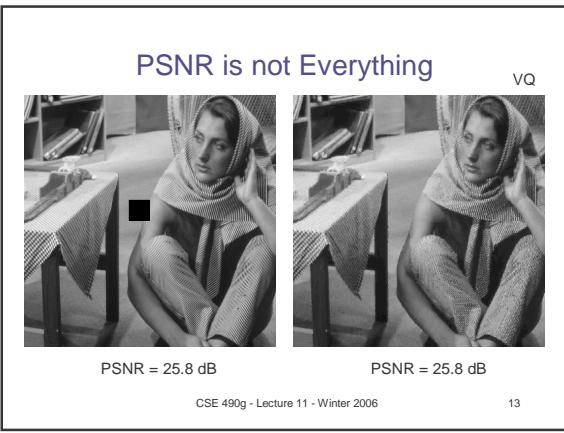
where m is the maximum value of a pixel possible.
For gray scale images (8 bits per pixel) $m = 255$.

- PSNR is measured in decibels (dB).
 - .5 to 1 dB is said to be a perceptible difference.
 - Decent images start at about 30 dB

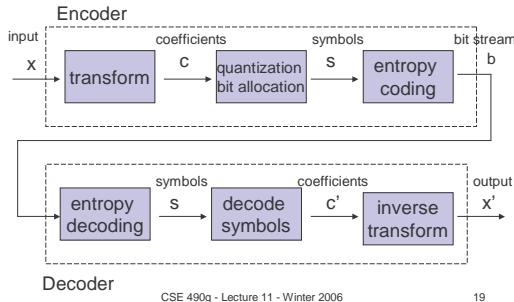
CSE 490g - Lecture 11 - Winter 2006

11





Block Diagram of Transform Coding



CSE 490g - Lecture 11 - Winter 2006

19

Mathematical Properties of Transforms

- Linear Transformation - Defined by a real $n \times n$ matrix $A = (a_{ij})$

$$\begin{bmatrix} a_{00} & \dots & a_{0,N-1} \\ \vdots & \ddots & \vdots \\ a_{N-1,0} & \dots & a_{N-1,N-1} \end{bmatrix} \begin{bmatrix} x_0 \\ \vdots \\ x_{N-1} \end{bmatrix} = \begin{bmatrix} c_0 \\ \vdots \\ c_{N-1} \end{bmatrix}$$

- Orthonormality $A^{-1} = A^T$ (transpose)

CSE 490g - Lecture 11 - Winter 2006

20

Why Coefficients

$$A^T c = x$$

$$\begin{bmatrix} a_{00} & \dots & a_{N-1,0} \\ \vdots & \ddots & \vdots \\ a_{0,N-1} & \dots & a_{N-1,N-1} \end{bmatrix} \begin{bmatrix} c_0 \\ \vdots \\ c_{N-1} \end{bmatrix} = \begin{bmatrix} x_0 \\ \vdots \\ x_{N-1} \end{bmatrix}$$

$$\begin{bmatrix} a_{00} \\ \vdots \\ a_{0,N-1} \end{bmatrix} c_0 + \dots + \begin{bmatrix} a_{N-1,0} \\ \vdots \\ a_{N-1,N-1} \end{bmatrix} c_{N-1} = \begin{bmatrix} x_0 \\ \vdots \\ x_{N-1} \end{bmatrix}$$

basis vectors coefficients

CSE 490g - Lecture 11 - Winter 2006

21

Why Orthonormality

- The energy of the data equals the energy of the coefficients

$$\sum_{i=0}^{N-1} c_i^2 = c^T c = (Ax)^T (Ax)$$

$$= (x^T A^T)(Ax) = x^T (A^T A)x = x^T x = \sum_{i=0}^{N-1} x_i^2$$

CSE 490g - Lecture 11 - Winter 2006

22

Squared Error is Preserved with Orthonormal Transformations

- In lossy coding we only send an approximation c'_i of c_i because it takes fewer bits to transmit the approximation.

Let $c_i = c'_i + \varepsilon_i$

$$\sum_{i=0}^{N-1} \varepsilon_i^2 = \sum_{i=0}^{N-1} (c_i - c'_i)^2 = (c - c')^T (c - c') = (Ax - Ax')^T (Ax - Ax')$$

$$= (A(x - x'))^T (A(x - x')) = ((x - x')^T A^T)(A(x - x'))$$

$$= (x - x')^T (A^T A)(x - x') = (x - x')^T (x - x')$$

$$= \sum_{i=0}^{N-1} (x_i - x'_i)^2 \quad \text{Squared error in original.}$$

CSE 490g - Lecture 11 - Winter 2006

23

Compaction Example

$$A = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$A^2 = A \Rightarrow A^{-1} = A$$

$$A^T = A = A^{-1} \quad \text{orthonormal}$$

$$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} b \\ b \end{bmatrix} = \begin{bmatrix} \sqrt{2}b \\ 0 \end{bmatrix} \quad \text{compaction}$$

CSE 490g - Lecture 11 - Winter 2006

24

Discrete Cosine Transform

$$d_{ij} = \begin{cases} \sqrt{\frac{1}{N}} & i=0 \\ \sqrt{\frac{2}{N}} \cos\left(\frac{(2j+1)i\pi}{2N}\right) & i>0 \end{cases}$$

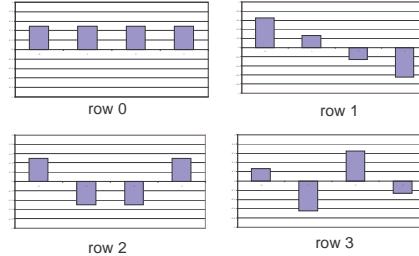
$N = 4$

$$D = \begin{bmatrix} .5 & .5 & .5 & .5 \\ .65328 & .270598 & -.270598 & -.65328 \\ .5 & -.5 & -.5 & .5 \\ .270598 & -.65328 & .65328 & -.270598 \end{bmatrix}$$

CSE 490g - Lecture 11 - Winter 2006

25

Basis Vectors



CSE 490g - Lecture 11 - Winter 2006

26

Decomposition in Terms of Basis Vectors

$$\begin{bmatrix} .5 \\ .5 \\ .5 \\ .5 \end{bmatrix} c_0 + \begin{bmatrix} .653281 \\ .270598 \\ -.270598 \\ -.653281 \end{bmatrix} c_1 + \begin{bmatrix} .5 \\ -.5 \\ -.5 \\ -.5 \end{bmatrix} c_2 + \begin{bmatrix} .270598 \\ -.653281 \\ .653281 \\ -.270598 \end{bmatrix} c_3 = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

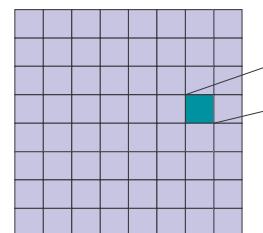
DC coefficient AC coefficients

CSE 490g - Lecture 11 - Winter 2006

27

Block Transform

Image



CSE 490g - Lecture 11 - Winter 2006

28

2-Dimensional Block Transform

Block of pixels X

x ₀₀	x ₀₁	x ₀₂	x ₀₃
x ₁₀	x ₁₁	x ₁₂	x ₁₃
x ₂₀	x ₂₁	x ₂₂	x ₂₃
x ₃₀	x ₃₁	x ₃₂	x ₃₃

Transform

$$A = \begin{bmatrix} a_{00} & a_{01} & a_{02} & a_{03} \\ a_{10} & a_{11} & a_{12} & a_{13} \\ a_{20} & a_{21} & a_{22} & a_{23} \\ a_{30} & a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\text{Transform rows } r_{ij} = \sum_{k=0}^{N-1} a_{kj} x_{ik}$$

$$\text{Transform columns } c_j = \sum_{m=0}^{N-1} a_{mj} r_{mj} = \sum_{m=0}^{N-1} a_{mj} \sum_{k=0}^{N-1} a_{kj} x_{mk} = \sum_{m=0}^{N-1} \sum_{k=0}^{N-1} a_{mj} a_{kj} x_{mk}$$

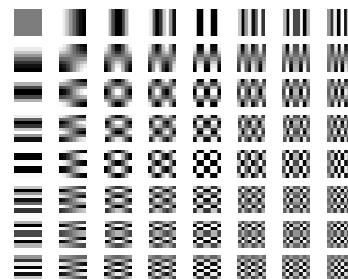
Summary

$$C = AXA^T$$

CSE 490g - Lecture 11 - Winter 2006

29

8x8 DCT Basis



CSE 490g - Lecture 11 - Winter 2006

30

Importance of Coefficients

- The DC coefficient is the most important.
- The AC coefficients become less important as they are farther from the DC coefficient.
- Example Bit Allocation

8 7 5 3 2 1 0 0	compression 55 bits for 64 pixels = .86 bpp
7 5 3 2 1 0 0 0	
5 3 2 1 0 0 0 0	
3 2 1 0 0 0 0 0	
2 1 0 0 0 0 0 0	
1 0 0 0 0 0 0 0	
0 0 0 0 0 0 0 0	
0 0 0 0 0 0 0 0	

CSE 490g - Lecture 11 - Winter 2006

31

Quantization

- For a $n \times n$ block we construct a $n \times n$ matrix Q such that Q_{ij} indicates how many quantization levels to use for coefficient c_{ij} .
- Encode c_{ij} with the **label**

$$s_{ij} = \left\lceil \frac{c_{ij}}{Q_{ij}} + 0.5 \right\rceil \quad \text{Larger } Q_{ij} \text{ indicates fewer levels.}$$

- Decode s_{ij} to

$$c'_{ij} = s_{ij} Q_{ij}$$

CSE 490g - Lecture 11 - Winter 2006

32

Example Quantization

- $c = 54.2, Q = 24 \quad s = \left\lceil \frac{54.2}{24} + 0.5 \right\rceil = 2$
 $c' = 2 \cdot 24 = 48$
- $c = 54.2, Q = 12 \quad s = \left\lceil \frac{54.2}{12} + 0.5 \right\rceil = 5$
 $c' = 5 \cdot 12 = 60$
- $c = 54.2, Q = 6 \quad s = \left\lceil \frac{54.2}{6} + 0.5 \right\rceil = 9$
 $c' = 9 \cdot 6 = 54$

CSE 490g - Lecture 11 - Winter 2006

33

Example Quantization Table

16	11	10	16	24	40	51	61
12	12	14	19	26	58	60	55
14	13	16	24	40	57	69	56
14	17	22	29	51	87	80	62
18	33	37	56	68	109	103	77
24	35	55	64	81	104	113	92
49	64	78	87	103	121	120	101
72	92	95	98	112	100	103	99

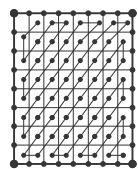
Increase the bit rate = halve the table
Decrease the bit rate = double the table

CSE 490g - Lecture 11 - Winter 2006

34

Zig-Zag Coding

- DC label is coded separately.
- AC labels are usually coded in zig-zag order using a special entropy coding to take advantage the ordering of the bit allocation (quantization).



CSE 490g - Lecture 11 - Winter 2006

35

JPEG (1987)

- Let $P = [p_{ij}]$, $0 < i, j < N$ be an image with $0 < p_{ij} < 256$.
- Center the pixels around zero
– $x_{ij} = p_{ij} - 128$
- Code 8x8 blocks of P using DCT
- Choose a quantization table.
– The table depends on the desired quality and is built into JPEG
- Quantize the coefficients according to the quantization table.
– The quantization symbols can be positive or negative.
- Transmit the labels (in a coded way) for each block.

CSE 490g - Lecture 11 - Winter 2006

36

Block Transmission

- DC coefficient
 - DC coefficients don't change much from block to neighboring block. Hence, their labels change even less.
 - Predictive coding using differences is used to code the DC label.
- AC coefficients
 - Do a zig-zag coding.

CSE 490g - Lecture 11 - Winter 2006

37

Example Block of Labels

5	2	0	0	0	0	0	0	0
-8	0	0	0	0	0	0	0	0
3	1	1	0	0	0	0	0	0
1	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0

Coding order of AC labels
2 -8 3 0 0 0 0 1 1 0 0 1 0 0
CSE 490g - Lecture 11 - Winter 2006

38

Coding Labels

- Categories of labels
 - 1 {0}
 - 2 {-1, 1}
 - 3 {-3,-2,2,3}
 - 4 {-7,-6,-5,-4,4,5 6 7}
- Label is indicated by two numbers C,B
- Examples

label	C,B
0	1
2	3, 2
-4	4, 3

CSE 490g - Lecture 11 - Winter 2006

39

Coding AC Label Sequence

- A symbol has three parts (Z,C,B)
 - Z for number of zeros preceding a label $0 \leq Z \leq 15$
 - C for the category of the label
 - B for a C-1 bit number for the actual label
- End of Block symbol (EOB) means the rest of the block is zeros. EOB = (0,0,-)
- Example: 2 -8 3 0 0 0 0 1 1 0 0 1 0 0
 $(0,3,2)(0,5,7)(0,3,3)(4,2,1)(0,2,1)(2,2,1)(2,0,0,-)$

CSE 490g - Lecture 11 - Winter 2006

40

Coding AC Label Sequence

- Z,C have a prefix code
 - B is a C-1 bit number
- | | | Partial prefix code table | | | |
|---|---|---------------------------|-----------|-------------|----------|
| | | C | | | |
| | | 0 | 1 | 2 | 3 |
| Z | 0 | 1010 | 00 | 01 | 100 |
| | 1 | 1100 | 11011 | | 11110001 |
| | 2 | 1110 | 11110001 | 1111101111 | |
| | 3 | 111010 | 111110111 | 11111110101 | |
- (0,3,2) (0,5,7) (0,3,3) (4,2,1) (0,2,1) (2,2,1) (0,0,-)
100 10 11010 0111 100 11 111111000 1 01 1 11111001 1 1010
46 bits representing 64 pixels = .72 bpp

CSE 490g - Lecture 11 - Winter 2006

41

Notes on Transform Coding

- Video Coding
 - MPEG – uses DCT
 - H.263, H.264 – uses DCT
- Audio Coding
 - MP3 = MPEG 1- Layer 3 uses DCT
- Alternative Transforms
 - Lapped transforms remove some of the blocking artifacts.
 - Wavelet transforms do not need to use blocks at all.

CSE 490g - Lecture 11 - Winter 2006

42