

CSE/NB 528

Lecture 10: Recurrent Networks (Chapter 7)

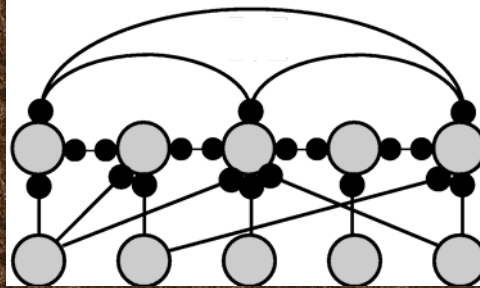


Image from <http://clasdean.la.asu.edu/news/images/ubep2001/neuron3.jpg>
Lecture figures are from Dayan & Abbott's book
<http://people.brandeis.edu/~abbott/book/index.html>

R. Rao, 528: Lecture 10

What's on our platter today?

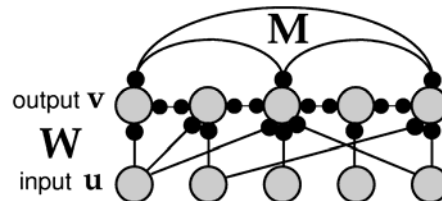


- ◆ Computation in Recurrent Networks
 - ⇒ Linear Recurrent Networks
 - ◆ Stability analysis using eigenvalues
 - ⇒ Nonlinear Recurrent Networks
 - ◆ Can amplify inputs
 - ◆ Can select inputs
 - ◆ Can multiply (gain modulation)
 - ◆ Can store short-term memory
 - ⇒ Associative Memory (Hopfield net)
 - ◆ Showing Stability via Lyapunov function

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Recurrent Networks



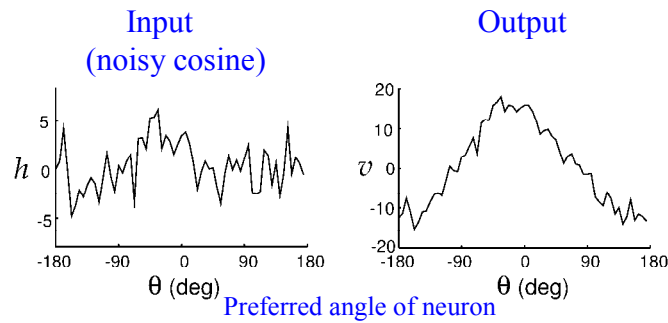
$$\tau \frac{d\mathbf{v}}{dt} = -\mathbf{v} + F(\mathbf{W}\mathbf{u} + \mathbf{M}\mathbf{v})$$

Output Decay Input Feedback

What can a Linear Recurrent Network do?

Analysis based on eigenvectors of recurrent weight matrix

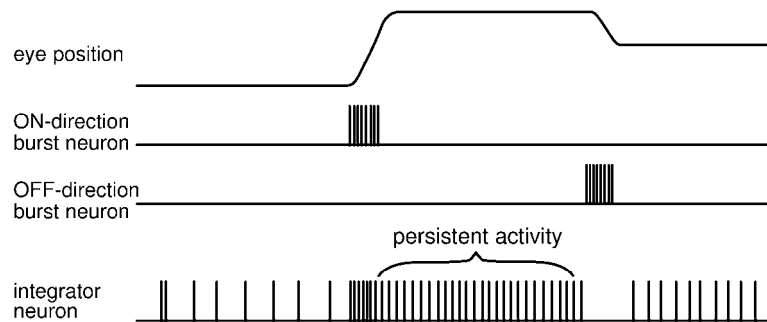
Amplification in a Linear Recurrent Network



$$M(\theta, \theta') = \frac{\lambda_1}{\pi} \cos(\theta - \theta')$$

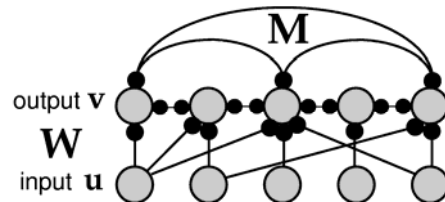
All eigenvalues = 0 except $\lambda_1 = 0.9$ i.e. amplification = $\frac{1}{1 - \lambda_1} = 10$

Input Integration for Maintaining Eye Position



Input: Bursts of spikes from brain stem oculomotor neurons
Output: Memory of eye position in medial vestibular nucleus

Nonlinear Recurrent Networks



Two types of firing-rate models

$$\tau \frac{d\mathbf{I}}{dt} = -\mathbf{I} + \mathbf{W}\mathbf{u} + \mathbf{M} \cdot F(\mathbf{I})$$

Current Dynamics
(firing rate $v = F(I)$)

$$\tau \frac{dv}{dt} = -v + F(\mathbf{W}\mathbf{u} + \mathbf{M}\mathbf{v})$$

Firing-Rate
Dynamics

Output Decay Input Feedback

(Convenient to use $\mathbf{W}\mathbf{u} = \mathbf{h}$)

Continuous Nonlinear Recurrent Networks

$$\tau \frac{dv}{dt} = -v + F(\mathbf{h} + \mathbf{M}\mathbf{v}) \text{ or,}$$

$$\tau \frac{dv_i}{dt} = -v_i + F\left(h_i + \sum_j M_{ij} v_j\right)$$

Discrete case
(small number of neurons)

Continuous case (in the limit of large numbers of neurons):

$$\tau \frac{dv(\theta)}{dt} = -v(\theta) + F\left(h(\theta) + \rho_\theta \int_{-\pi}^{\pi} M(\theta, \theta') v(\theta') d\theta'\right)$$

θ = preferred stimulus of the neuron (e.g. orientation of input)

Example of a Continuous Recurrent Network

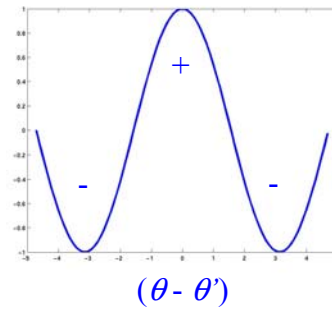
Choose $F =$ rectification nonlinearity:

$$\tau \frac{dv(\theta)}{dt} = -v(\theta) + \left[h(\theta) + \int_{-\pi}^{\pi} M(\theta, \theta') v(\theta') d\theta' \right]^+$$

$$M(\theta, \theta') = \frac{\lambda_1}{\pi} \cos(\theta - \theta')$$

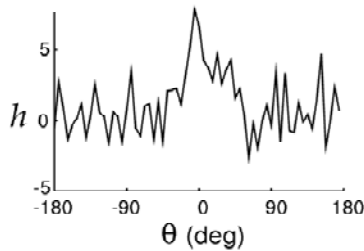
Choose recurrent connections =
cosine function of relative angle

Excitation nearby,
Inhibition further away

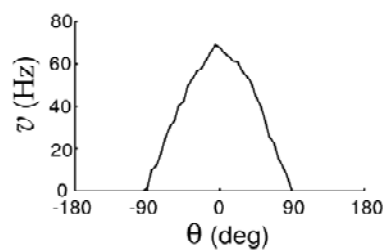


Amplification in a Nonlinear Recurrent Network

Input

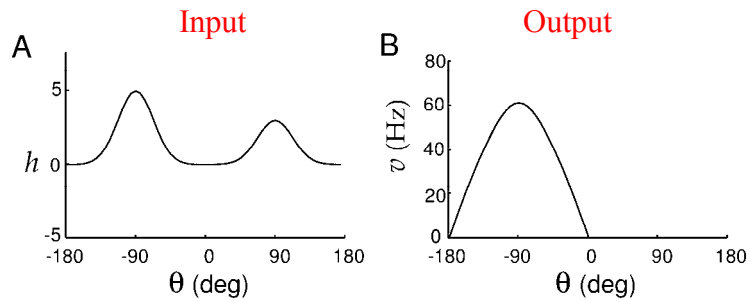


Output



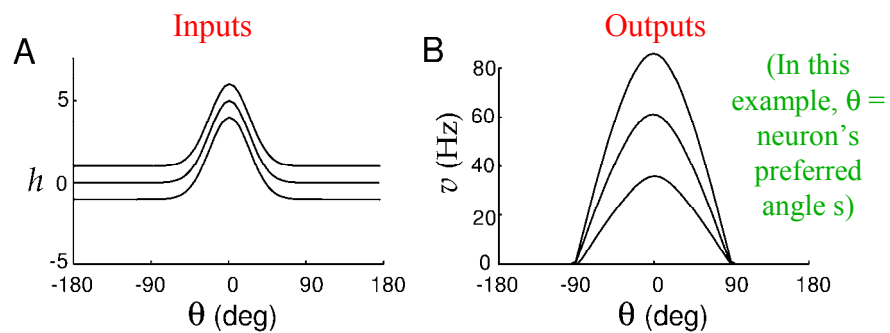
$$\tau \frac{dv(\theta)}{dt} = -v(\theta) + \left[h(\theta) + \frac{\lambda_1}{\pi} \int_{-\pi}^{\pi} \cos(\theta - \theta') v(\theta') d\theta' \right]^+$$

Selective “Attention” in a Nonlinear Recurrent Network



Network performs “winner-takes-all” input selection

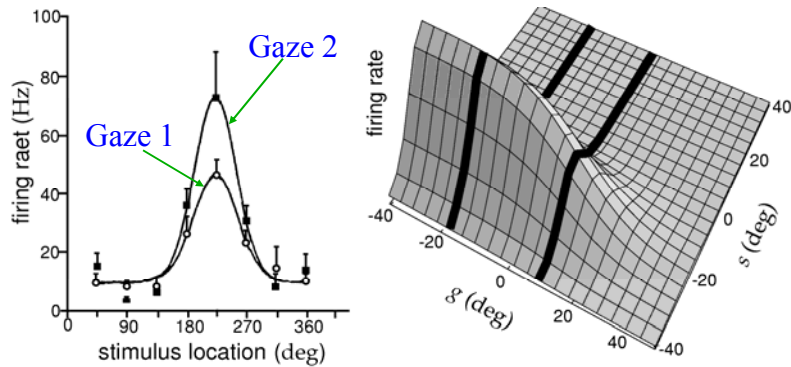
Gain Modulation in a Nonlinear Recurrent Network



Changing the level of input by adding g multiplies the output

If $h = s + g$ ($s =$ stimulus angle on retina, $g =$ gaze angle), then network output is gain-modulated similar to parietal cortex neurons

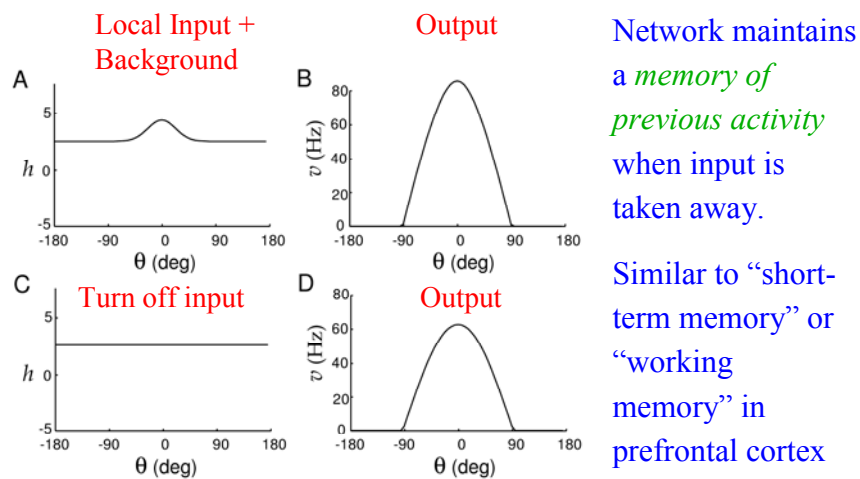
Gain Modulation in Parietal Cortex Neurons



Responses of Area 7a neuron

Example of a gain-modulated tuning curve

Short-Term Memory Storage in a Nonlinear Recurrent Network

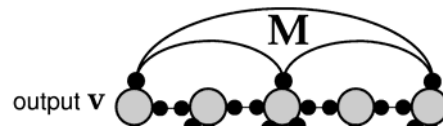


Network maintains a *memory of previous activity* when input is taken away.

Similar to “short-term memory” or “working memory” in prefrontal cortex

Associative Memories (Hopfield Networks)

- ◆ Fully connected, no feedforward inputs



Idea: Store patterns as *fixed points* of this network

$$\tau \frac{d\mathbf{I}}{dt} = -\mathbf{I} + \mathbf{M} \cdot \mathbf{g}(\mathbf{I}) \quad \text{or,}$$

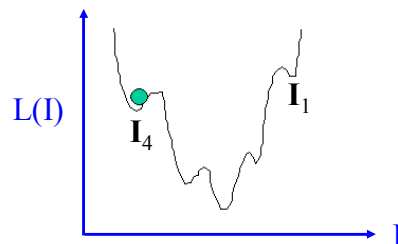
$$\tau \frac{dI_i}{dt} = -I_i + \sum_j M_{ij} v_j \quad \text{where } v_j = g(I_j)$$

$g = \text{sigmoid function}$

Question: Will \mathbf{I} always converge to a fixed point?

Enter...Lyapunov Functions

- ◆ **Idea:** If $d\mathbf{I}/dt$ causes some function $L(\mathbf{I})$ to always decrease or remain constant (i.e. $dL/dt \leq 0$) and L has a lower bound (with $dL/dt = 0$ only if $d\mathbf{I}/dt = 0$), *then $d\mathbf{I}/dt = 0$ eventually*
 - ⇨ **Network converges to a fixed point**
- ◆ L also called “energy” function or “cost” function



Lyapunov for Hopfield networks

- ◆ What is a good Lyapunov function $L(I)$ for Hopfield nets?
- ◆ What constraints are required on the recurrent weights \mathbf{M} ?
- ◆ On-board example: $L(I)$

Next Class: Wrap up of network models

- ◆ Things to do:
 - ⇒ Start reading Chapter 8
 - ⇒ Homework #3 due Tuesday
 - ⇒ Start on mini-project