

CSE 544

Principles of Database Management Systems

Fall 2016

Lecture 6 – Datalog (2)

Announcements

Homework 2 posted, due Friday, Nov. 4th

- SimpleDB

References

- **Reading:**
Joe Hellerstein, “The Declarative Imperative,”
SIGMOD Record 2010
- R&G Chapter 24
- Phokion Kolaitis’ tutorial on database theory at Simon’s
<https://simons.berkeley.edu/sites/default/files/docs/5241/simons16-21.pdf>
- Daniel Zinn, Todd J. Green, Bertram Ludäscher: Win-move is coordination-free (sometimes). ICDT 2012

Review

- What is datalog?
- What is the naïve evaluation algorithm?
- What is the seminaive algorithm?

Outline

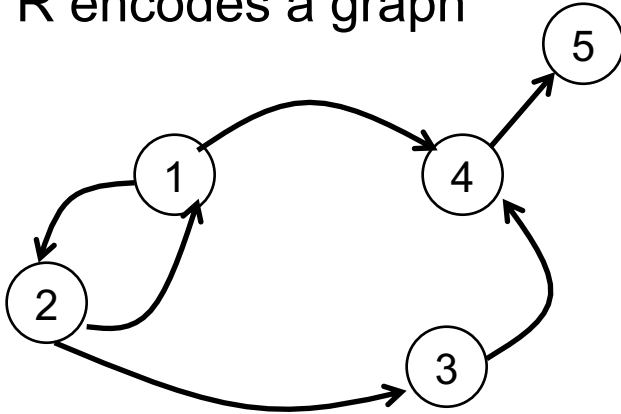
- Magic sets
- Extending datalog with negation and aggregates

Magic Sets

- Problem: datalog programs compute a lot, but sometimes we need only very little
- Prolog computes top-down and retrieves very little
datalog computes bottom up retrieves a lot
- (Prolog has other issues: left recursive prolog never terminates!)
- Magic sets transform a datalog program P into a new program P' , such that $\text{bottom-up}(P') = \text{top-down}(P)$

Example 1

R encodes a graph



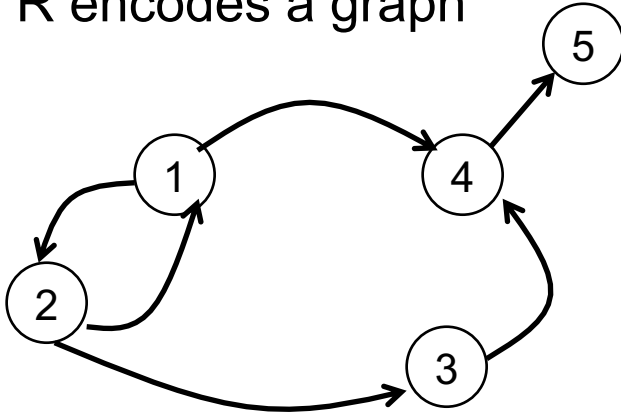
```
T(x,y) :- E(x,y)
T(x,y) :- T(x,z),E(z,y)
Q(y)   :- T(3,y)
```

a constant

Bottom-up evaluation
very inefficient

Example 1

R encodes a graph



Manual optimization:

```
Q(y) :- E(3,y)
Q(y) :- Q(x),E(x,y)
```

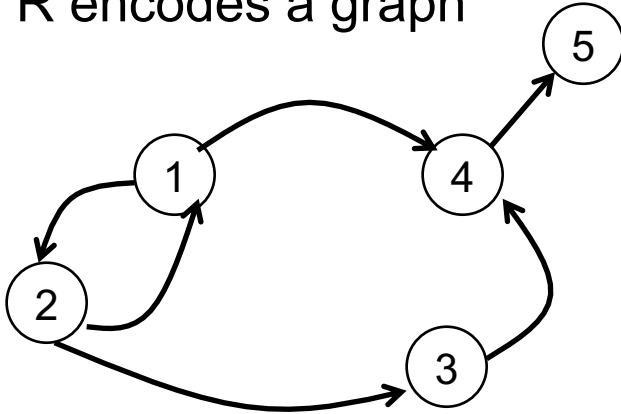
```
T(x,y) :- E(x,y)
T(x,y) :- T(x,z),E(z,y)
Q(y) :- T(3,y)
```

a constant

Bottom-up evaluation
very inefficient

Example 2

R encodes a graph



Same generation

```
SG(x,x) :- V(x)
SG(x,y) :- Up(x,u),SG(u,v),Dn(u,y)
Q(y) :- SG(1,y)
```

Manual optimization???

If we define
 $Up(a,b) = E(b,a)$
 $Dn(a,b) = E(a,b)$
then $SG = \text{"same generation"}$

Magic Set Rewriting (simplified)

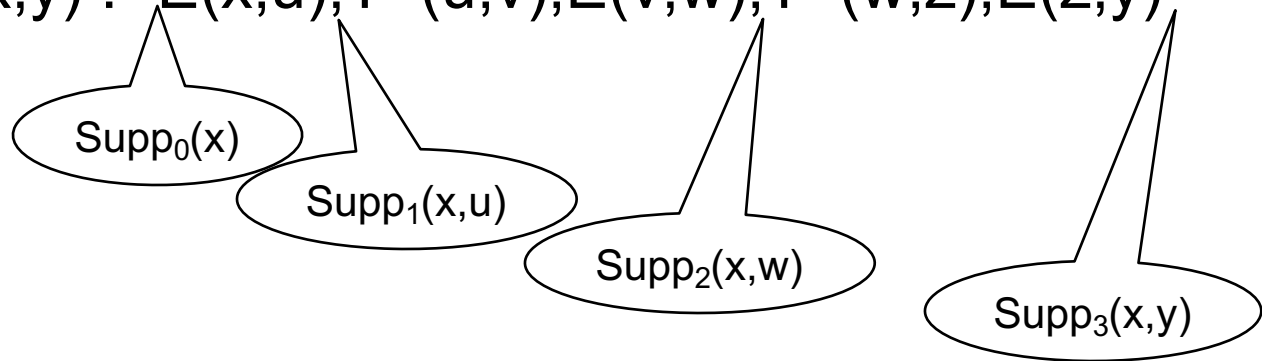
- For each IDB predicate create “adorned” versions, with binding patterns
- For each adorned IDB P , create a predicate Magic_P
- For each rule, create several rules, one for each possible adornment of the head:
 - Allow information to flow left-to-right (“sideways information passing”), and this defines the required adornments of the IDB’s in the body
 - If there are k IDB’s in the body, create $k+1$ supplementary relations Supp_i , which guard the set of bound variables passed on to the i ’th IDB
- New rules defining Magic_P : one for the query, and one for each Supp_i preceding an occurrence of P in a body

Adorned predicate

- b=bound, f=free
- $T^{bf}(x,y)$ means:
 - The values of x are known
 - The values of y are not known (need to be retrieved)
- Need to create all combinations: T^{bf} , T^{fb}
- Side-ways information passing means that we adorn rules allowing information to flow left-to-right
 - E.g. $T(x,y) :- E(x,u),T(u,v),E(v,w),T(w,z),E(z,y)$
 - Adorned: $T^{bf}(x,y) :- E(x,u),T^{bf}(u,v),E(v,w),T^{bf}(w,z),E(z,y)$

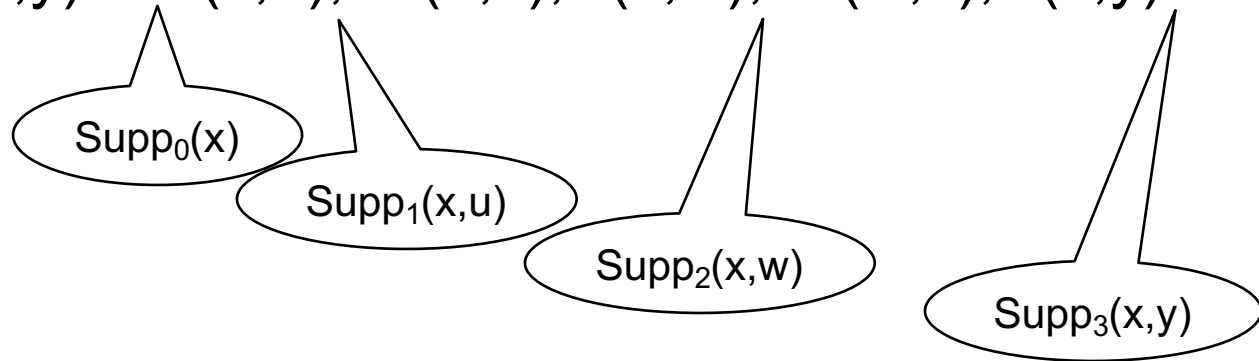
Supplementary Relations

- Given adornment $T^{\text{bf}}(x,y)$, a new predicate $\text{Supp}(x)$ contains the (small!) set of values x for which we want to compute $T^{\text{bf}}(x,y)$
- E.g. $T^{\text{bf}}(x,y) \text{ :- } E(x,u), T^{\text{bf}}(u,v), E(v,w), T^{\text{bf}}(w,z), E(z,y)$



Supp Rules

- E.g. $T^{bf}(x,y) :- E(x,u), T^{bf}(u,v), E(v,w), T^{bf}(w,z), E(z,y)$



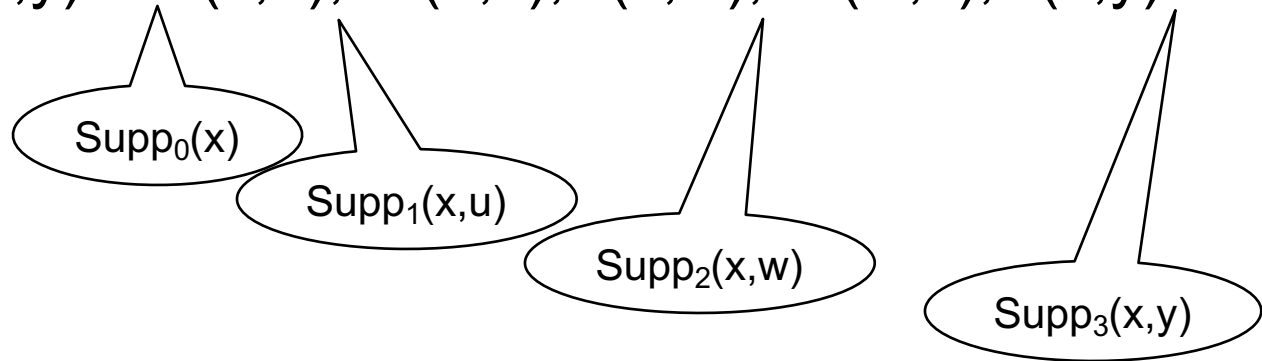
Becomes:

- $Supp_0(x) :- Magic_{T^{bf}}(x)$ /* next slide ... */
- $Supp_1(x,u) :- Supp_0(x), E(x,u)$
- $Supp_2(x,w) :- Supp_1(x,u), T^{bf}(u,v), E(v,w)$
- $Supp_3(x,y) :- Supp_2(x,w), T^{bf}(w,z), E(z,y)$
- $T^{bf}(x,y) :- Supp_3(x,y)$

$Supp_0$ and $Supp_3$
are redundant

Adding the Magic Predicate

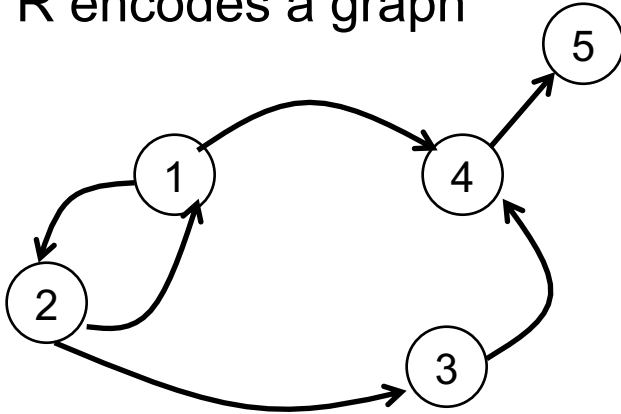
- E.g. $T^{\text{bf}}(x,y) \text{ :- } E(x,u), T^{\text{bf}}(u,v), E(v,w), T^{\text{bf}}(w,z), E(z,y)$



- $\text{Magic}_{T^{\text{bf}}}(x)$ = the set of bounded values of x for which we need to compute $T^{\text{bf}}(x,y)$
- E.g.
 - $\text{Magic}_{T^{\text{bf}}}(3) \text{ :- } \quad \quad \quad /* \text{ if the query is } Q(y) \text{ :- } T(3,y) \quad */$
 - $\text{Magic}_{T^{\text{bf}}}(u) \text{ :- } \text{Supp}_1(x,u) \quad /* \text{ need to compute } T^{\text{bf}}(u,v) \quad */$
 - $\text{Magic}_{T^{\text{bf}}}(w) \text{ :- } \text{Supp}_2(x,w) \quad /* \text{ need to compute } T^{\text{bf}}(w,z) \quad */$

Example 1

R encodes a graph



Original:

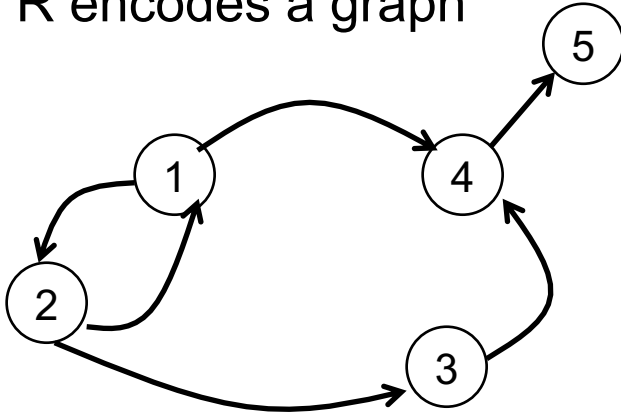
```
T(x,y) :- E(x,y)
T(x,y) :- T(x,z),E(z,y)
Q(y) :- T(3,y)
```

Adorned:

Magic Sets

Example 1

R encodes a graph



Original:

```
T(x,y) :- E(x,y)
T(x,y) :- T(x,z),E(z,y)
Q(y) :- T(3,y)
```

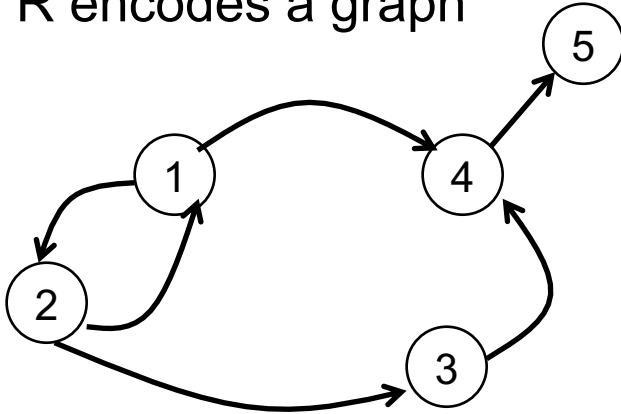
Adorned:

```
Tbf(x,y) :- E(x,y)
Tbf(x,y) :- Tbf(x,z),E(z,y)
Q(y) :- Tbf(3,y)
```

Magic Sets

Example 1

R encodes a graph



Original:

```
T(x,y) :- E(x,y)
T(x,y) :- T(x,z),E(z,y)
Q(y) :- T(3,y)
```

Adorned:

```
Tbf(x,y) :- E(x,y)
Tbf(x,y) :- Tbf(x,z),E(z,y)
Q(y) :- Tbf(3,y)
```

Magic Sets

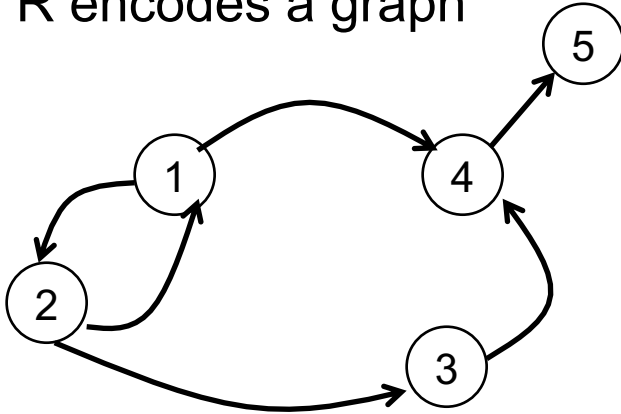
```
Supp0(x) :- MagicTbf(x)
Supp1(x,y) :- Supp0(x),E(x,y)
Tbf(x,y) :- Supp1(x,y)
```

```
Supp'0(x) :- MagicTbf(x)
Supp'1(x,z) :- Supp'0(x), Tbf(x,z)
Supp'2(x,y) :- Supp'1(x,z), E(z,y)
Tbf(x,y) :- Supp'2(x,y)
```

```
MagicTbf(3) :-
MagicTbf(x) :- Supp'0(x) /* redundant */
```

Example 1

R encodes a graph



Original:

```
T(x,y) :- E(x,y)
T(x,y) :- T(x,z),E(z,y)
Q(y) :- T(3,y)
```

Adorned:

```
Tbf(x,y) :- E(x,y)
Tbf(x,y) :- Tbf(x,z),E(z,y)
Q(y) :- Tbf(3,y)
```

Magic Sets

```
Supp0(x) :- MagicTbf(x)
Supp1(x,y) :- Supp0(x),E(x,y)
Tbf(x,y) :- Supp1(x,y)
```

```
Supp'0(x) :- MagicTbf(x)
Supp'1(x,z) :- Supp'0(x), Tbf(x,z)
Supp'2(x,y) :- Supp'1(x,y), E(z,y)
```

```
MagicTbf(3) :-
MagicTbf(x) :- Supp'0(x) /* redundant */
```

Show computation
on white board

Adding Negation: Datalog⁻

Adding Negation: Datalog⁻

Example: compute the complement of the transitive closure

```
T(x,y) :- R(x,y)
T(x,y) :- T(x,z), R(z,y)
CT(x,y) :- Node(x), Node(y), not T(x,y)
```

What does this mean??

Recursion and Negation Don't Like Each Other

EDB: $I = \{ R(a) \}$

$S(x) :- R(x), \text{ not } T(x)$
 $T(x) :- R(x), \text{ not } S(x)$

What are the possible outcomes of S and T?

Recursion and Negation Don't Like Each Other

EDB: $I = \{ R(a) \}$

$S(x) :- R(x), \text{ not } T(x)$
 $T(x) :- R(x), \text{ not } S(x)$

What are the possible outcomes of S and T?

$J_1 = \{ \}$

$J_2 = \{ S(a) \}$

$J_3 = \{ T(a) \}$

$J_4 = \{ S(a), T(a) \}$

Adding Negation: datalog^-

- **Solution 1: Stratified Datalog⁻**
 - Rules must be partitioned into strata
 - IDB predicates defined in strata $\leq k$ may be negated in strata $\geq k+1$
- **Solution 2: Inflationary-fixpoint Datalog⁻**
 - Fire rules and always add facts (never retract)
 - Stop when nothing new is added
 - Always terminates (why ?)
- **Solution 3: Partial-fixpoint Datalog^{-,*}**
 - Fire rules, adding/retracting facts as needed
 - Stop when reaching a fixpoint
 - May not terminate
- **Solution 4: Well-founded semantics**

What semantics does the paper use?

Discussion in Class

The *Declarative Imperative* paper:

- What are the extensions to datalog in Dedalus?
- What is the main usage of Dedalus described in the paper?
- What limitations of datalog does the paper describe?

Semantics of a Datalog Program

Three different, equivalent semantics:

- Minimal model semantics
- Least fixpoint semantics
- Proof-theoretic semantics (will not discuss)

Minimal Model Semantics

To each rule r: $P(x_1 \dots x_k) \text{ :- } R_1(\dots), R_2(\dots), \dots$

Minimal Model Semantics

To each rule r : $P(x_1 \dots x_k) \text{ :- } R_1(\dots), R_2(\dots), \dots$

All variables in the rule

Associate the logical sentence Σ_r : $\forall z_1 \dots \forall z_n. [(R_1(\dots) \wedge R_2(\dots) \wedge \dots) \rightarrow P(\dots)]$

Minimal Model Semantics

To each rule r : $P(x_1 \dots x_k) :- R_1(\dots), R_2(\dots), \dots$

All variables in the rule

Associate the logical sentence Σ_r : $\forall z_1 \dots \forall z_n. [(R_1(\dots) \wedge R_2(\dots) \wedge \dots) \rightarrow P(\dots)]$

Same as: $\forall x_1 \dots \forall x_k. [\exists y_1 \dots \exists y_m. (R_1(\dots) \wedge R_2(\dots) \wedge \dots) \rightarrow P(\dots)]$

Head variables

Existential variables

Minimal Model Semantics

To each rule r : $P(x_1 \dots x_k) :- R_1(\dots), R_2(\dots), \dots$

All variables in the rule

Associate the logical sentence Σ_r : $\forall z_1 \dots \forall z_n. [(R_1(\dots) \wedge R_2(\dots) \wedge \dots) \rightarrow P(\dots)]$

Same as: $\forall x_1 \dots \forall x_k. [\exists y_1 \dots \exists y_m. (R_1(\dots) \wedge R_2(\dots) \wedge \dots) \rightarrow P(\dots)]$

Head variables

Existential variables

Definition. If P is a datalog program, Σ_P is the set of all logical sentences associated to its rules.

Minimal Model Semantics

To each rule r: $P(x_1 \dots x_k) :- R_1(\dots), R_2(\dots), \dots$

All variables in the rule

Associate the logical sentence Σ_r : $\forall z_1 \dots \forall z_n. [(R_1(\dots) \wedge R_2(\dots) \wedge \dots) \rightarrow P(\dots)]$

Same as: $\forall x_1 \dots \forall x_k. [\exists y_1 \dots \exists y_m. (R_1(\dots) \wedge R_2(\dots) \wedge \dots) \rightarrow P(\dots)]$

Head variables

Existential variables

Definition. If P is a datalog program,
 Σ_P is the set of all logical sentences associated to its rules.

Example. Rule: $T(x,y) :- R(x,z), T(z,y)$

Sentence: $\forall x. \forall y. \forall z. (R(x,z) \wedge T(z,y) \rightarrow T(x,y))$
 $\equiv \forall x. \forall y. (\exists z. R(x,z) \wedge T(z,y) \rightarrow T(x,y))$

Minimal Model Semantics

Definition. A pair (I, J) where I is an EDB and J is an IDB is a *model* for P , if $(I, J) \models \Sigma_P$

Definition. Given an EDB database instance I and a datalog program P , the minimal model, denoted $J = \mathbf{P}(I)$ is a minimal database instance J s.t. $(I, J) \models \Sigma_P$

Theorem. The minimal model always exists, and is unique.

Minimal Model Semantics

Definition. A pair (I,J) where I is an EDB and J is an IDB is a *model* for P , if $(I,J) \models \Sigma_P$

Definition. Given an EDB database instance I and a datalog program P , the minimal model, denoted $J = \mathbf{P}(I)$ is a minimal database instance J s.t. $(I,J) \models \Sigma_P$

Theorem. The minimal model always exists, and is unique.

Example:



Which of these IDBs are *models*?
Which are *minimal models*?

R=

1	2
2	3
3	4
4	5

$T(x,y) :- R(x,y)$
 $T(x,y) :- R(x,z), T(z,y)$

T=

1	2
2	3
3	4
4	5
1	3
2	4
3	5

$\Sigma_P:$ $\forall x \forall y (R(x,y) \rightarrow T(x,y))$
 $\forall x \forall y (R(x,z) \wedge T(z,y) \rightarrow T(x,y))$

Minimal Model Semantics

Definition. A pair (I,J) where I is an EDB and J is an IDB is a *model* for P , if $(I,J) \models \Sigma_P$

Definition. Given an EDB database instance I and a datalog program P , the minimal model, denoted $J = \mathbf{P}(I)$ is a minimal database instance J s.t. $(I,J) \models \Sigma_P$

Theorem. The minimal model always exists, and is unique.

Example:



Which of these IDBs are *models*?
Which are *minimal models*?

R=

1	2
2	3
3	4
4	5

$T(x,y) :- R(x,y)$
 $T(x,y) :- R(x,z), T(z,y)$

T=

1	2
2	3
3	4
4	5
1	3
2	4
3	5

$\Sigma_P: \forall x \forall y (R(x,y) \rightarrow T(x,y))$
 $\forall x \forall y (R(x,z) \wedge T(z,y) \rightarrow T(x,y))$

T=

1	2
2	3
3	4
4	5
1	3
2	4
3	5
1	4
2	5
1	5

Minimal Model Semantics

Definition. A pair (I, J) where I is an EDB and J is an IDB is a *model* for P , if $(I, J) \models \Sigma_P$

Definition. Given an EDB database instance I and a datalog program P , the minimal model, denoted $J = \mathbf{P}(I)$ is a minimal database instance J s.t. $(I, J) \models \Sigma_P$

Theorem. The minimal model always exists, and is unique.

Example:



Which of these IDBs are *models*?
Which are *minimal models*?

R=

1	2
2	3
3	4
4	5

$T(x,y) :- R(x,y)$
 $T(x,y) :- R(x,z), T(z,y)$

T=

1	2
2	3
3	4
4	5
1	3
2	4
3	5

$\Sigma_P: \forall x \forall y (R(x,y) \rightarrow T(x,y))$
 $\forall x \forall y (R(x,z) \wedge T(z,y) \rightarrow T(x,y))$

T=

1	2
2	3
3	4
4	5
1	3
2	4
3	5
1	4
2	5
1	5

T=

...	...
i	j

$\forall i < j$

Grounding

- A grounding of an atom is obtained by substituting its variables with constants from the active domain
- Examples:
 - $T(5,2)$ is a grounding of $T(x,y)$
 - $T(5,5)$ is a grounding of $T(x,y)$
 - $T(5,5)$ is a grounding of $T(x,x)$
 - $T(5,2)$ is not a grounding of $T(x,x)$
- A grounding of a rule is obtained by substituting its variables with constants from the active domain
- Examples:
 - $(T(5,2) \leftarrow R(5,7), T(7,2))$ is a grounding of $(T(x,y) :- R(x,z), T(z,y))$

Minimal Fixpoint Semantics

Definition. Fix an EDB I , and a datalog program P .

The *immediate consequence* operator T_P is defined as follows.

For any IDB J :

$$\begin{aligned} T_P(J) &= \text{all IDB facts that are immediate consequences from } I \text{ and } J: \\ &= \{H \mid (H \leftarrow B_1, \dots, B_m) \in \text{ground}(P), J \models B_1, \dots, B_m\} \end{aligned}$$

Fact. For any datalog program P , the immediate consequence operator is monotone. In other words, if $J_1 \subseteq J_2$ then $T_P(J_1) \subseteq T_P(J_2)$.

Minimal Fixpoint Semantics

Definition. Fix an EDB I , and a datalog program P .

The *immediate consequence* operator T_P is defined as follows.

For any IDB J :

$$\begin{aligned} T_P(J) &= \text{all IDB facts that are immediate consequences from } I \text{ and } J: \\ &= \{H \mid (H \leftarrow B_1, \dots, B_m) \in \text{ground}(P), J \models B_1, \dots, B_m\} \end{aligned}$$

Fact. For any datalog program P , the immediate consequence operator is monotone. In other words, if $J_1 \subseteq J_2$ then $T_P(J_1) \subseteq T_P(J_2)$.

Theorem. The immediate consequence operator has a unique, minimal fixpoint J : $\text{fix}(T_P) = J$, where J is the minimal instance with the property $T_P(J) = J$.

Proof: using Knaster-Tarski's theorem for monotone functions.

The fixpoint is given by:

$$\text{fix}(T_P) = J_0 \cup J_1 \cup J_2 \cup \dots \quad \text{where } J_0 = \emptyset, \quad J_{k+1} = T_P(J_k)$$

Minimal Fixpoint Semantics



$$T(x,y) \text{ :- } R(x,y)$$

$$T(x,y) \text{ :- } R(x,z), T(z,y)$$

R=

1	2
2	3
3	4
4	5

T =

--	--

$J_0 = \emptyset$

$J_1 = T_P(J_0)$

1	2
2	3
3	4
4	5

$J_2 = T_P(J_1)$

1	2
2	3
3	4
4	5
1	3
2	4
3	5

$J_3 = T_P(J_2)$

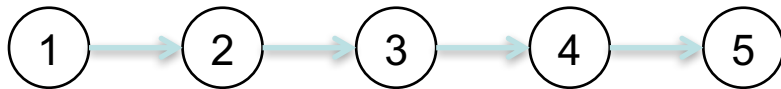
1	2
2	3
3	4
4	5
1	3
2	4
3	5
1	4
2	5

$J_4 = T_P(J_3)$

1	2
2	3
3	4
4	5
1	3
2	4
3	5
1	4
2	5
1	5

Proof Theoretic Semantics

Every fact in the IDB has a *derivation tree*, or *proof tree* justifying its existence.

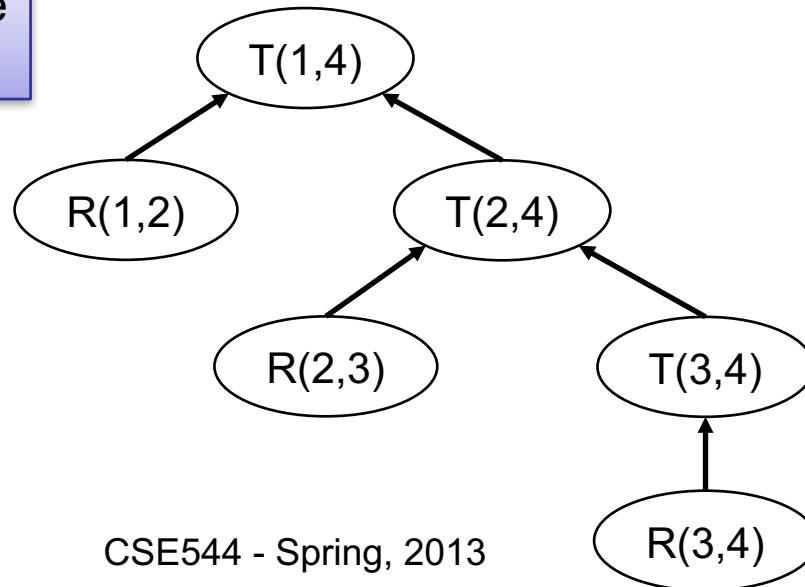


$T(x,y) \text{ :- } R(x,y)$
 $T(x,y) \text{ :- } R(x,z), T(z,y)$

R=

1	2
2	3
3	4
4	5

Derivation tree
of $T(1,4)$



Adding Negation: Datalog⁻

Example: compute the complement of the transitive closure

```
T(x,y) :- R(x,y)
T(x,y) :- T(x,z), R(z,y)
CT(x,y) :- Node(x), Node(y), not T(x,y)
```

What does this mean??

Recursion and Negation Don't Like Each Other

EDB: $I = \{ R(a) \}$

$S(x) :- R(x), \text{ not } T(x)$ $T(x) :- R(x), \text{ not } S(x)$
--

Which IDBs are models of **P**?

$J_1 = \{ \}$

$J_2 = \{ S(a) \}$

$J_3 = \{ T(a) \}$

$J_4 = \{ S(a), T(a) \}$

Recursion and Negation Don't Like Each Other

EDB: $I = \{ R(a) \}$

$S(x) :- R(x), \text{ not } T(x)$
 $T(x) :- R(x), \text{ not } S(x)$

Which IDBs are models of **P**?

$J_1 = \{ \}$

No: both
rules fail

$J_2 = \{ S(a) \}$

Yes: the facts in J_2 are
 $R(a), S(a), \neg T(a)$
and both rules are *true*.

$J_3 = \{ T(a) \}$

Yes

$J_4 = \{ S(a), T(a) \}$

Yes

There is no *minimal* model!

Recursion and Negation

Don't Like Each Other

EDB: $I = \{ R(a) \}$

$S(x) :- R(x), \text{ not } T(x)$
 $T(x) :- R(x), \text{ not } S(x)$

Which IDBs are models of **P**?

$J_1 = \{ \}$

No: both
rules fail

$J_2 = \{ S(a) \}$

Yes: the facts in J_2 are
 $R(a), S(a), \neg T(a)$
and both rules are *true*.

$J_3 = \{ T(a) \}$

Yes

$J_4 = \{ S(a), T(a) \}$

Yes

There is no *minimal* model!

There is no minimal fixpoint!
(Why does Knaster-Tarski's
theorem fail?)

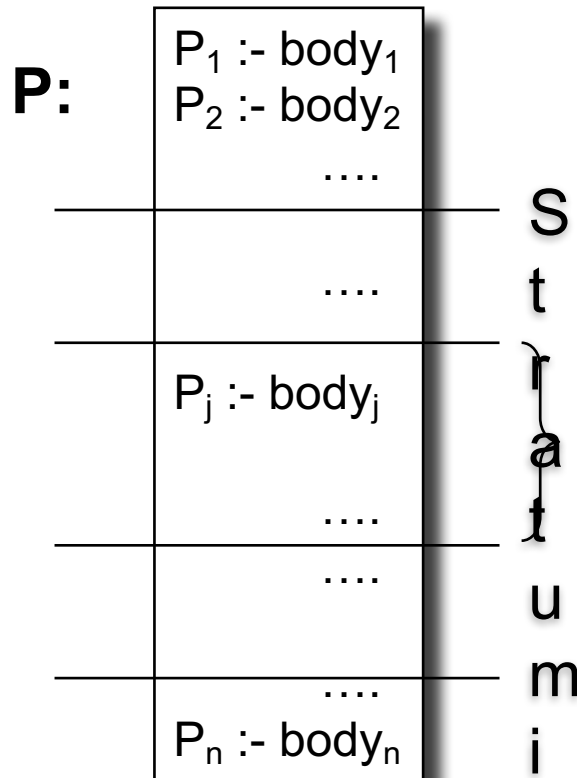
Adding Negation: datalog^-

- **Solution 1: Stratified Datalog⁻**
 - Rules must be partitioned into strata
 - IDB predicates defined in strata $\leq k$ may be negated in strata $\geq k+1$
- **Solution 2: Inflationary-fixpoint Datalog⁻**
 - Fire rules and always add facts (never retract)
 - Stop when nothing new is added
 - Always terminates (why ?)
- **Solution 3: Partial-fixpoint Datalog^{-,*}**
 - Fire rules, adding/retracting facts as needed
 - Stop when reaching a fixpoint
 - May not terminate
- **Solution 4: Well-founded semantics**

Stratified datalog⁻

A datalog⁻ program is *stratified* if its rules can be partitioned into k strata, such that:

- If an IDB predicate P appears negated in a rule in stratum i, then it can only appear in the head of a rule in strata 1, 2, ..., i-1



Note: a datalog⁻ program either is stratified or it ain't!

Which programs are stratified?

$T(x,y) :- R(x,y)$
 $T(x,y) :- T(x,z), R(z,y)$
 $CT(x,y) :- \text{Node}(x), \text{Node}(y), \text{not } T(x,y)$

$S(x) :- R(x), \text{not } T(x)$
 $T(x) :- R(x), \text{not } S(x)$

Stratified datalog[⊥]

- Evaluation algorithm for stratified datalog[⊥]:
- For each stratum $i = 1, 2, \dots$, do:
 - Treat all IDB's defined in prior strata as EBS
 - Evaluate the IDB's defined in stratum i , using either the naïve or the semi-naïve algorithm

Does this compute a minimal model?

```
T(x,y) :- R(x,y)
T(x,y) :- T(x,z), R(z,y)
```

```
CT(x,y) :- Node(x), Node(y), not T(x,y)
```

Stratified datalog[⊥]

- Evaluation algorithm for stratified datalog[⊥]:
- For each stratum $i = 1, 2, \dots$, do:
 - Treat all IDB's defined in prior strata as EBS
 - Evaluate the IDB's defined in stratum i , using either the naïve or the semi-naïve algorithm

Does this compute a minimal model?

NO:

$J_1 = \{ T = \text{transitive closure, CT} = \text{its complement} \}$

$J_2 = \{ T = \text{all pairs of nodes, CT} = \text{empty} \}$

$T(x,y) :- R(x,y)$
 $T(x,y) :- T(x,z), R(z,y)$

$CT(x,y) :- \text{Node}(x), \text{Node}(y), \text{not } T(x,y)$

Inflationary-fixpoint datalog[⊥]

Let \mathbf{P} be any datalog[⊥] program, and I an EDB.

Let $T_{\mathbf{P}}(J)$ be the *immediate consequence* operator.

Let $F(J) = J \cup T_{\mathbf{P}}(J)$ be the *inflationary immediate consequence* operator.

Define the sequence: $J_0 = \emptyset$, $J_{n+1} = F(J_n)$, for $n \geq 0$.

Definition. The inflationary fixpoint semantics of \mathbf{P} is $J = J_n$ where n is such that $J_{n+1} = J_n$

Why does there always exist an n such that $J_n = F(J_n)$?

Find the inflationary semantics for:

```
T(x,y) :- R(x,y)
T(x,y) :- T(x,z), R(z,y)
CT(x,y) :- Node(x), Node(y), not T(x,y)
```

```
S(x) :- R(x), not T(x)
T(x) :- R(x), not S(x)
```


Inflationary-fixpoint datalog⁺

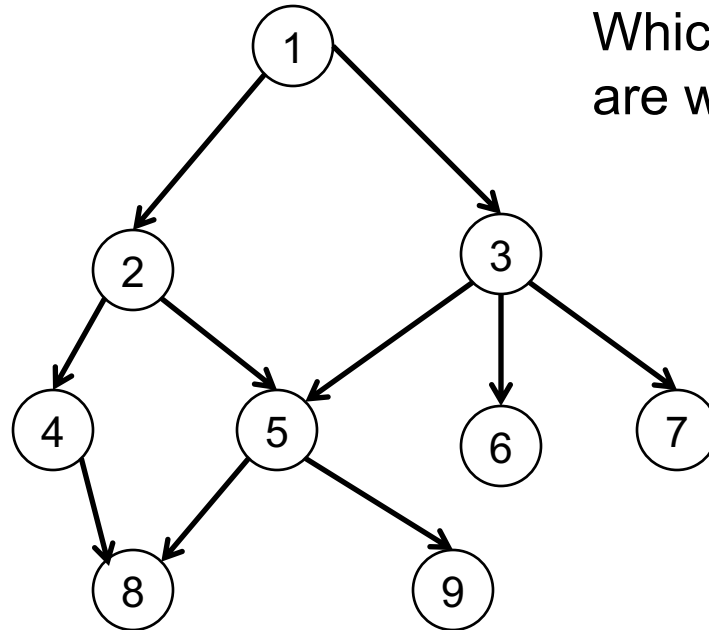
- Evaluation for Inflationary-fixpoint datalog⁺
- Use the naïve, or the semi-naïve algorithm
- Inhibit any optimization that rely on monotonicity (e.g. out of order execution)

Well-Founded Semantics

- The lecture follows:
Daniel Zinn, Todd J. Green, Bertram Ludäscher: Win-move is coordination-free (sometimes). ICDT 2012

Example: Win-Move Game

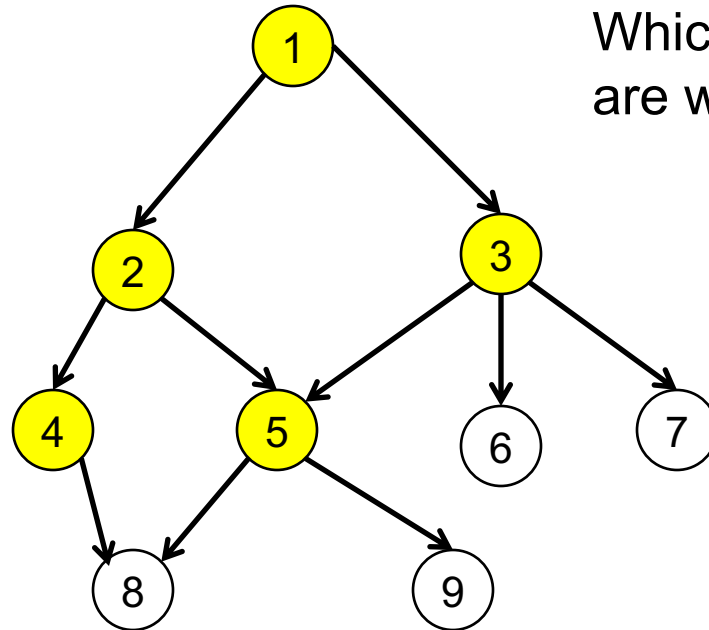
$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$



Which nodes are winning?

Example: Win-Move Game

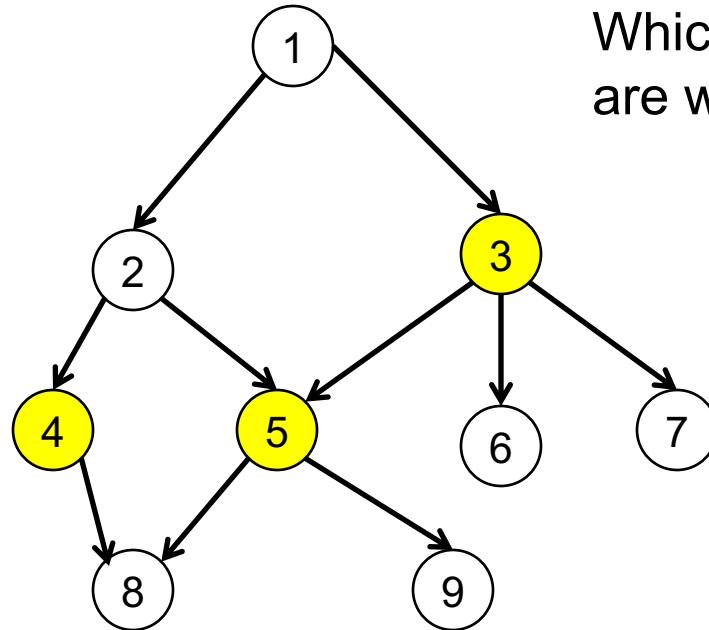
$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$



Which nodes are winning?

Example: Win-Move Game

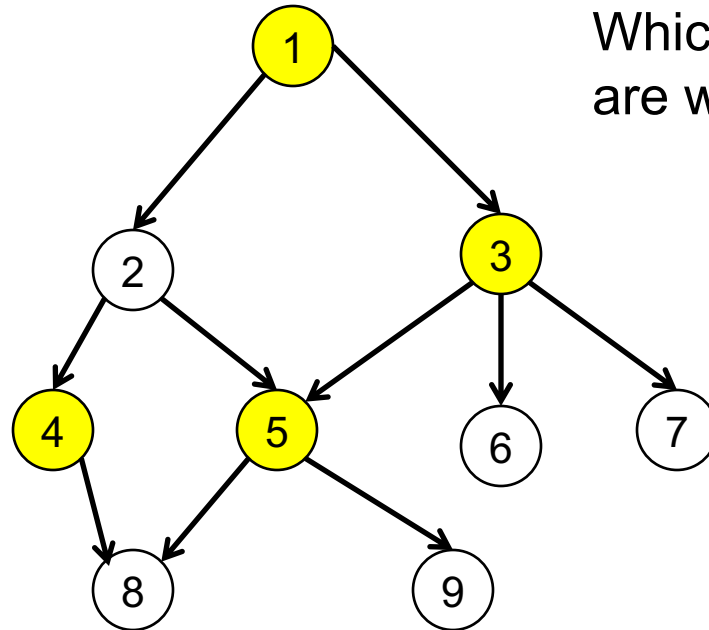
$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$



Which nodes are winning?

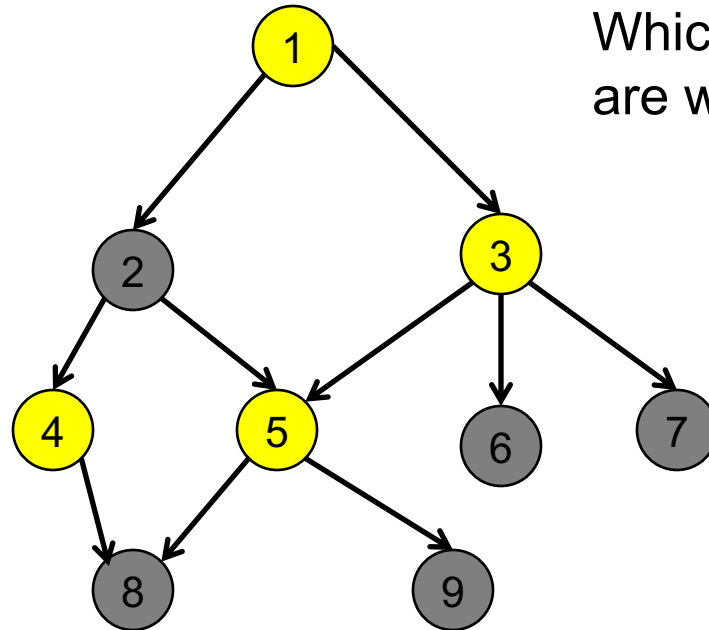
Example: Win-Move Game

$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$



Example: Win-Move Game

$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$



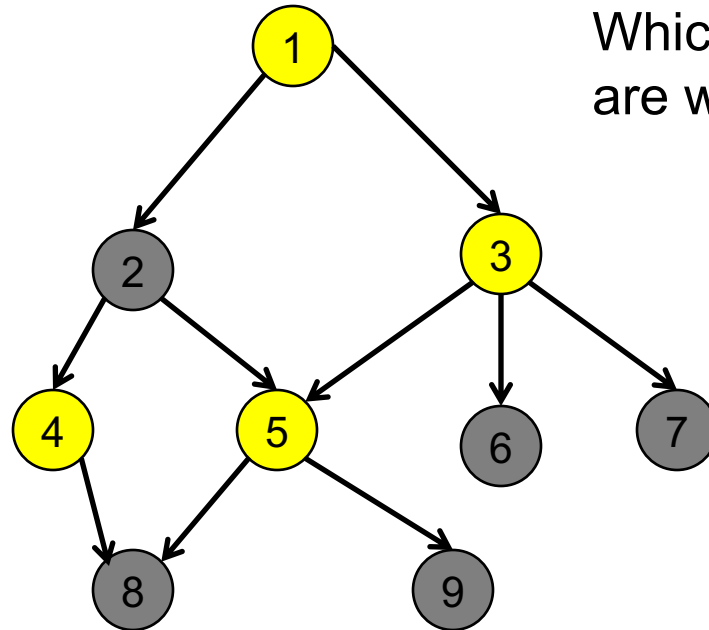
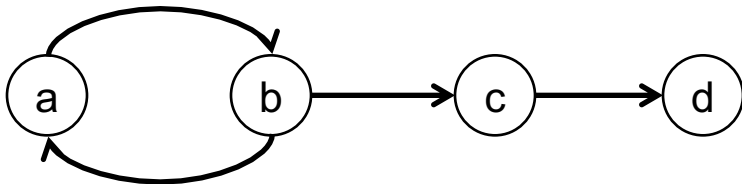
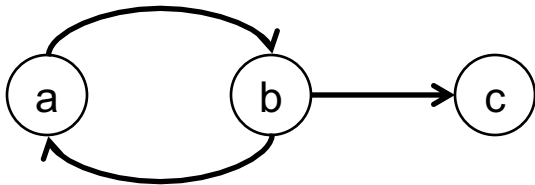
Which nodes are winning?

$\text{Win}(1), \text{Win}(3), \text{Win}(4), \text{Win}(5)$
 $\neg\text{Win}(2), \neg\text{Win}(6), \neg\text{Win}(7), \neg\text{Win}(8), \neg\text{Win}(9)$

Example: Win-Move Game

$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$

What about these?



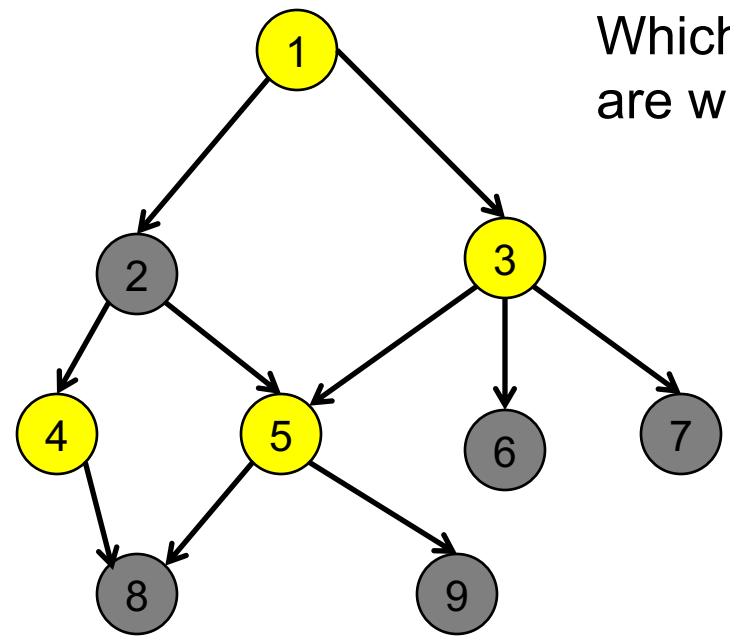
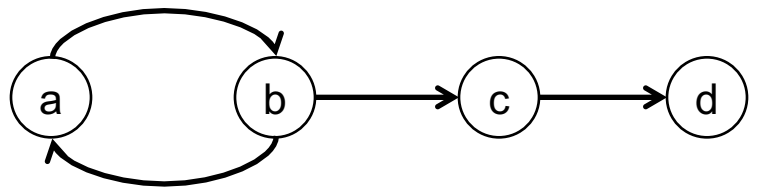
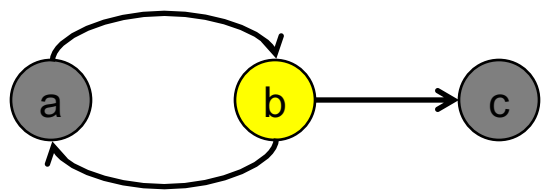
Which nodes are winning?

$\text{Win}(1), \text{Win}(3), \text{Win}(4), \text{Win}(5)$
 $\neg\text{Win}(2), \neg\text{Win}(6), \neg\text{Win}(7), \neg\text{Win}(8), \neg\text{Win}(9)$

Example: Win-Move Game

$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$

What about these?



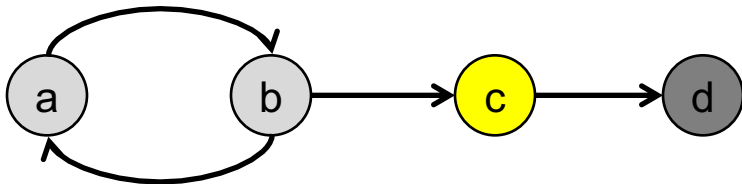
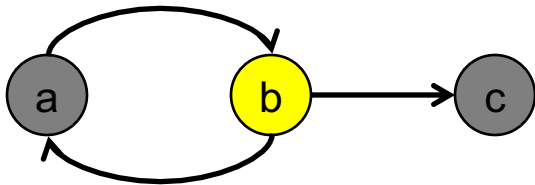
Which nodes are winning?

$\text{Win}(1), \text{Win}(3), \text{Win}(4), \text{Win}(5)$
 $\neg\text{Win}(2), \neg\text{Win}(6), \neg\text{Win}(7), \neg\text{Win}(8), \neg\text{Win}(9)$

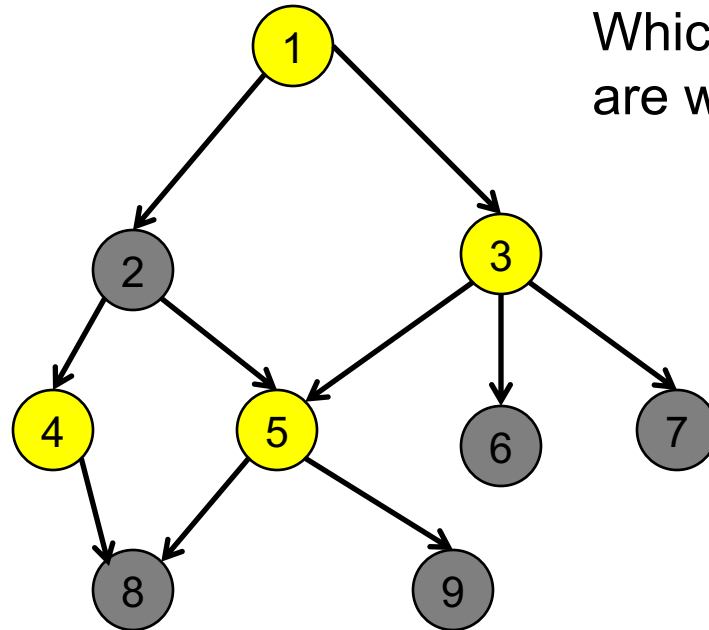
Example: Win-Move Game

$\text{Win}(X) \text{ :- Move}(X,Y), \neg\text{Win}(Y)$

What about these?



$\text{Win}(c), \neg\text{Win}(d)$
a and b are neither winning nor losing



Which nodes are winning?

$\text{Win}(1), \text{Win}(3), \text{Win}(4), \text{Win}(5)$
 $\neg\text{Win}(2), \neg\text{Win}(6), \neg\text{Win}(7), \neg\text{Win}(8), \neg\text{Win}(9)$

Well-founded Semantics

Let P be any datalog⁻ program

Let I be instances of both EDB and IDB (note: was only EDB before)

Let $T_{P,I}(J)$ be the *immediate consequence* operator defined as follows:

$$T_{P,I}(J) = \{H \mid (H :- B_1, \dots, B_m, \neg C_1, \dots, \neg C_n) \in \text{ground}(P), \\ J \models B_1, \dots, B_m, I \models \neg C_1, \dots, \neg C_n \}$$

Note that $T_{P,I}(J)$ is monotone in J , hence has a Least Fix Point (lfp).

Let $\Gamma_P(I) = \text{lfp}(T_{P,I})$

Note that $\Gamma_P(I)$ is antimonotone in the IDB's: $I \subseteq I'$ implies $\Gamma_P(I) \supseteq \Gamma_P(I')$

$\Gamma_P^2(I)$ ($:= \Gamma_P(\Gamma_P(I))$) is monotone: has Least Fix Point (lfp), Greatest Fix Point (gfp)

Definition. The well-founded semantics is defined on ground facts A as:

$W_P(A) = \text{true}$	if $A \in \text{lfp}(\Gamma_P^2)$
$W_P(A) = \text{false}$	if $A \notin \text{gfp}(\Gamma_P^2)$
$W_P(A) = \text{undefined}$	if $A \in \text{gfp}(\Gamma_P^2) - \text{lfp}(\Gamma_P^2)$

Well-founded Semantics

Note how we compute the lfp and gfp of $\Gamma_P^2(I)$.

Apply Γ_P repeatedly:

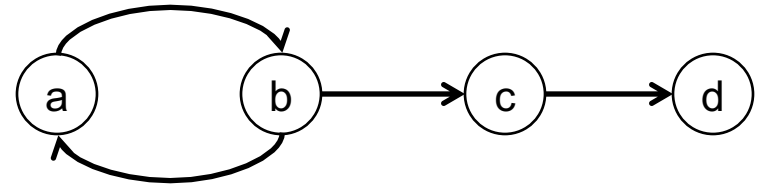
- Odd iterations increase \rightarrow towards lfp
- Even iterations decrease \rightarrow towards gfp

Denoting $I_k = T_{P,I}(T_{P,I}(T_{P,I}(\dots T_{P,I}(\emptyset) \dots)))$ (k times)

$$\emptyset \subseteq I_2 \subseteq I_4 \subseteq I_6 \subseteq \dots \subseteq \text{lfp}(\Gamma_P^2(I)) \subseteq \text{gfp}(\Gamma_P^2(I)) \subseteq \dots \subseteq I_5 \subseteq I_3 \subseteq I_1 \subseteq \text{Domain}^k$$

Example: Win-Move Game

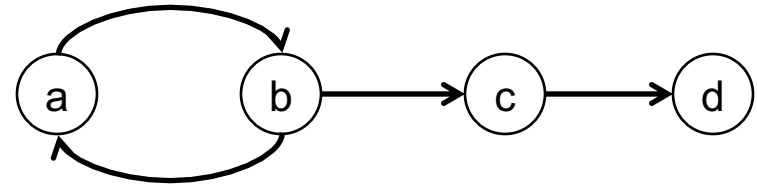
$\text{Win}(X) \text{ :- Move}(X, Y), \neg \text{Win}(Y)$



$T_{P,I}(J)$ says: “fix $\neg \text{Win}$ according to I, and Win according to J”

Example: Win-Move Game

$\text{Win}(X) \text{ :- Move}(X, Y), \neg \text{Win}(Y)$



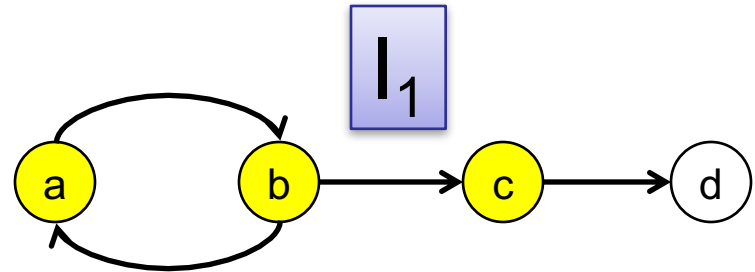
$T_{P,I}(J)$ says: “fix $\neg \text{Win}$ according to I , and Win according to J ”

Start with $I_0 = \emptyset$ ($= \{\neg \text{Win}(a), \neg \text{Win}(b), \neg \text{Win}(c), \neg \text{Win}(d)\}$)

$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

Example: Win-Move Game

$\text{Win}(X) :- \text{Move}(X, Y), \neg \text{Win}(Y)$



$T_{P,I}(J)$ says: “fix $\neg \text{Win}$ according to I , and Win according to J ”

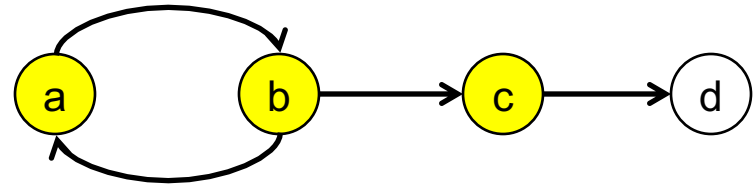
Start with $I_0 = \emptyset$ ($= \{\neg \text{Win}(a), \neg \text{Win}(b), \neg \text{Win}(c), \neg \text{Win}(d)\}$)

$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_1 = \{\text{Win}(a), \text{Win}(b), \text{Win}(c), \neg \text{Win}(d)\}$

Example: Win-Move Game

Win(X) :- Move(X,Y), ¬Win(Y)



$T_{P,I}(J)$ says: “fix \neg Win according to I, and Win according to J”

Start with $I_0 = \emptyset$ (= { \neg Win(a), \neg Win(b), \neg Win(c), \neg Win(d)})

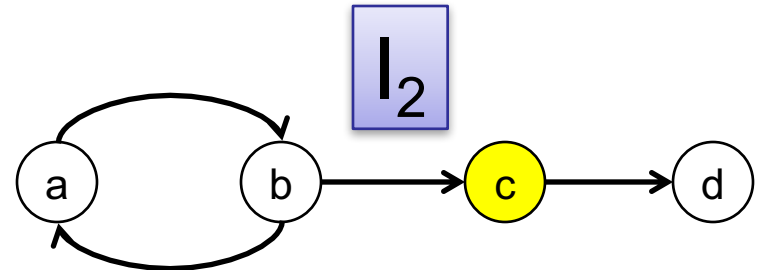
$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_1 = \{\text{Win}(a), \text{Win}(b), \text{Win}(c), \neg\text{Win}(d)\}$

$I_2 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

Example: Win-Move Game

$\text{Win}(X) :- \text{Move}(X, Y), \neg \text{Win}(Y)$



$T_{P,I}(J)$ says: “fix $\neg \text{Win}$ according to I , and Win according to J ”

Start with $I_0 = \emptyset$ ($= \{\neg \text{Win}(a), \neg \text{Win}(b), \neg \text{Win}(c), \neg \text{Win}(d)\}$)

$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

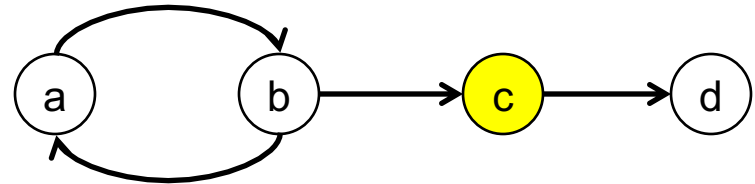
$I_1 = \{\text{Win}(a), \text{Win}(b), \text{Win}(c), \neg \text{Win}(d)\}$

$I_2 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_2 = \{\neg \text{Win}(a), \neg \text{Win}(b), \text{Win}(c), \neg \text{Win}(d)\}$

Example: Win-Move Game

Win(X) :- Move(X,Y), ¬Win(Y)



$T_{P,I}(J)$ says: “fix \neg Win according to I, and Win according to J”

Start with $I_0 = \emptyset$ ($= \{\neg\text{Win}(a), \neg\text{Win}(b), \neg\text{Win}(c), \neg\text{Win}(d)\}$)

$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_1 = \{\text{Win}(a), \text{Win}(b), \text{Win}(c), \neg\text{Win}(d)\}$

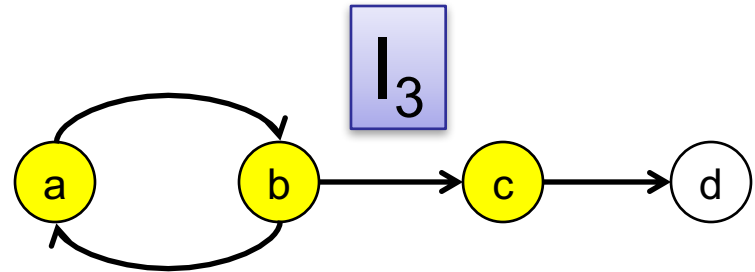
$I_2 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_2 = \{\neg\text{Win}(a), \neg\text{Win}(b), \text{Win}(c), \neg\text{Win}(d)\}$

$I_3 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

Example: Win-Move Game

Win(X) :- Move(X,Y), ¬Win(Y)



$T_{P,I}(J)$ says: “fix \neg Win according to I, and Win according to J”

Start with $I_0 = \emptyset$ ($= \{\neg\text{Win}(a), \neg\text{Win}(b), \neg\text{Win}(c), \neg\text{Win}(d)\}$)

$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_1 = \{\text{Win}(a), \text{Win}(b), \text{Win}(c), \neg\text{Win}(d)\}$

$I_2 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

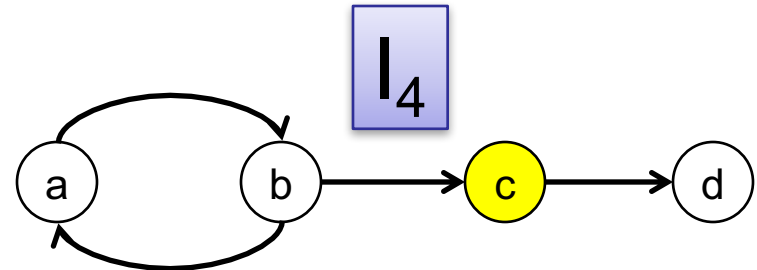
$I_2 = \{\neg\text{Win}(a), \neg\text{Win}(b), \text{Win}(c), \neg\text{Win}(d)\}$

$I_3 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_3 = I_1 =$ have reached the gfp

Example: Win-Move Game

$\text{Win}(X) :- \text{Move}(X, Y), \neg \text{Win}(Y)$



$T_{P,I}(J)$ says: “fix $\neg \text{Win}$ according to I , and Win according to J ”

Start with $I_0 = \emptyset$ ($= \{\neg \text{Win}(a), \neg \text{Win}(b), \neg \text{Win}(c), \neg \text{Win}(d)\}$)

$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_1 = \{\text{Win}(a), \text{Win}(b), \text{Win}(c), \neg \text{Win}(d)\}$

$I_2 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_2 = \{\neg \text{Win}(a), \neg \text{Win}(b), \text{Win}(c), \neg \text{Win}(d)\}$

$I_3 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

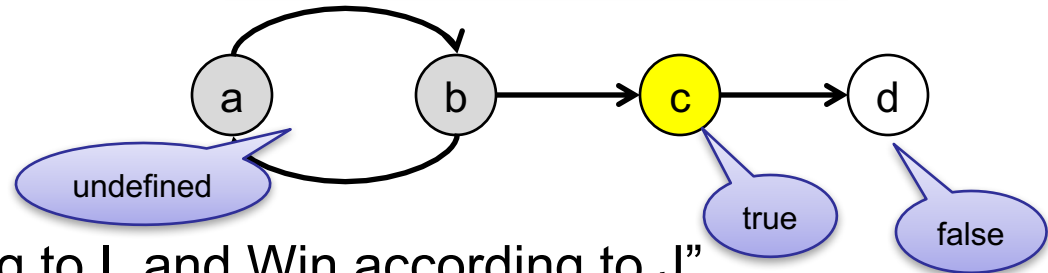
$I_3 = I_1 =$ have reached the gfp

$I_4 = I_2 =$ have reached the lfp

Example: Win-Move Game

Well founded semantics:

$\text{Win}(X) :- \text{Move}(X, Y), \neg \text{Win}(Y)$



$T_{P,I}(J)$ says: “fix $\neg \text{Win}$ according to I , and Win according to J ”

Start with $I_0 = \emptyset$ ($= \{\neg \text{Win}(a), \neg \text{Win}(b), \neg \text{Win}(c), \neg \text{Win}(d)\}$)

$I_1 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_1 = \{\text{Win}(a), \text{Win}(b), \text{Win}(c), \neg \text{Win}(d)\}$

$I_2 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_2 = \{\neg \text{Win}(a), \neg \text{Win}(b), \text{Win}(c), \neg \text{Win}(d)\}$

$I_3 = \Gamma_P(I) = \text{lfp}(T_{P,I}) = \emptyset \cup T_{P,I}(\emptyset) \cup T_{P,I}(T_{P,I}(\emptyset)) \cup T_{P,I}(T_{P,I}(T_{P,I}(\emptyset))) \cup \dots$

$I_3 = I_1 =$ have reached the gfp

$I_4 = I_2 =$ have reached the lfp

Discussion

- Which semantics does Daedalus adopt?

Discussion

Comparing datalog⁻

- Compute the complement of the transitive closure in inflationary datalog⁻
- Compare the expressive power of:
 - Stratified datalog⁻
 - Inflationary fixpoint datalog⁻
 - Partial fixpoint datalog⁻