### CSE 544 Principles of Database Management Systems

#### Lectures 9 -10: Query optimization

#### Announcements

- HW3 (SimpleDB) is due next Friday!
- Reading assignment was due today

#### **Query Optimization Motivation**



## What We Already Know

- There exists many logical plans...
- ... and for each, there exist many physical plans
- Optimizer chooses the logical/physical plan with the smallest <u>estimated</u> cost

## **Discussion of the Paper**

- Query parsing/authorization
- Query rewriting:
  - Is salary < 75k and salary > 100k implausible?
  - What is semantic optimization?
- Query optimizer
  - Will discuss in detail...
  - What is query re-optimization?
    Predictable performance (IBM) v.s. self-tuning (Microsoft)
  - What is the "halloween problem"?
- Query execution
  - What are BP-tuples v.s. M-tuples? What is the *pin-count*?
- Access methods: will discuss

## **Query Optimization**

Three major components:

- 1. Cardinality and cost estimation
- 2. Search space
- 3. Plan enumeration algorithms

## Estimating Cost of a Query Plan

Goal: compute the cost of an entire physical query plan

- We already know how to compute the cost of each physical operator if we knew the T(R) and B(R) for each of its arguments
- Goal: estimate T(R) for each intermediate result R B(R) can be derived from T(R)

### Statistics on Base Data

- Collected information for each database relation
  - Number of tuples (cardinality) T(R)
  - Number of physical pages B(R), clustering info
  - Indexes, number of keys in the index V(R,a)
  - Statistical information on attributes
    - Min value, max value, number distinct values
    - Histograms
  - Correlations between columns (hard)
- Collection approach: periodic, using sampling

### Size Estimation

# Projection: output size same as input size $T(\Pi(R)) = T(R)$

#### Selection: the size decreases by <u>selectivity factor</u> $\theta$ T( $\sigma_{pred}(R)$ ) = T(R) \* $\theta_{pred}$

#### **Selectivity Factors**

- A = c /\*  $\sigma_{A=c}(R)$  \*/ - Selectivity = 1/V(R,A)
- A < c /\*  $\sigma_{A < c}(R)^*/$ - Selectivity = (c - min(R, A))/(max(R,A) - min(R,A))
- c1 < A < c2 /\*  $\sigma_{c1 < A < c2}(R)$ \*/ - Selectivity = (c2 - c1)/(max(R,A) - min(R,A))
- Multiple predicates: assume independence

### **Estimating Result Sizes**

- $Join \; R \; \bowtie_{R.A=S.B} \; S$
- Take product of cardinalities of relations R and S
- Apply this selectivity factor: 1/ (MAX(V(R,A), V(S,B))
- Why? Will explain next...

### Assumptions

- <u>Containment of values</u>: if V(R,A) ≤ V(S,B), then the set of A values of R is included in the set of B values of S
  - Note: this indeed holds when A is a foreign key in R, and B is a key in S
- <u>Preservation of values</u>: for any other attribute C,
  V(R ⋈<sub>A=B</sub> S, C) = V(R, C) (or V(S, C))

– This is only needed higher up in the plan

## Selectivity of R $\bowtie_{A=B} S$

Assume  $V(R,A) \leq V(S,B)$ 

- Each tuple t in R joins with T(S)/V(S,B) tuples in S
- Hence  $T(R \bowtie_{A=B} S) = T(R) T(S) / V(S,B)$

In general:  $T(R \bowtie_{A=B} S) = T(R) T(S) / max(V(R,A),V(S,B))$ 

## Computing the Cost of a Plan

- Estimate <u>cardinality</u> in a bottom-up fashion
  - Cardinality is the <u>size</u> of a relation (nb of tuples)
  - Compute size of all intermediate relations in plan
- Estimate <u>cost</u> by using the estimated cardinalities
- Extensive example next...

































#### **R**MS in Postgres

#### **Courtesy of Walter Cai**



## Simplifications

 We considered only IO cost; in general we need IO+CPU

 We assumed that all index pages were in memory: sometimes we need to add the cost of fetching index pages from disk

- Statistics on data maintained by the RDBMS
- Makes size estimation much more accurate (hence, cost estimations are more accurate)

Employee(<u>ssn</u>, name, age)

T(Employee) = 25000, V(Empolyee, age) = 50min(age) = 19, max(age) = 68

 $\sigma_{age=48}$ (Empolyee) = ?  $\sigma_{age>28 \text{ and } age<35}$ (Empolyee) = ?

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Estimate = 25000 / 50 = 500 Estimate = 25000 \* 6 / 50 = 3000

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Age:	020	2029	30-39	40-49	50-59	> 60
Tuples	200	800	5000	12000	6500	500

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Age:	020	2029	30-39	40-49	50-59	> 60
Tuples	200	800	5000	12000	6500	500

Estimate = 1200 Estimate = 1\*80 + 5\*500 = 2580

## **Types of Histograms**

 How should we determine the bucket boundaries in a histogram ?

## **Types of Histograms**

- How should we determine the bucket boundaries in a histogram ?
- Eq-Width
- Eq-Depth
- Compressed
- V-Optimal histograms



#### **Eq-width**:

Age:	020	2029	30-39	40-49	50-59	> 60
Tuples	200	800	5000	12000	6500	500

#### **Eq-depth**:

Age:	020	2029	30-39	40-49	50-59	> 60
Tuples	1800	2000	2100	2200	1900	1800

Compressed: store separately highly frequent values: (48,1900)

## V-Optimal Histograms

- Defines bucket boundaries in an optimal way, to minimize the error over all point queries
- Computed rather expensively, using dynamic programming
- Modern databases systems use V-optimal histograms or some variations

#### Discussion

- Small number of buckets
  - Hundreds, or thousands, but not more
  - WHY ?
- Not updated during database update, but recomputed periodically
  - WHY ?
- Multidimensional histograms rarely used
  - WHY ?

## **Query Optimization**

#### Three major components:

- 1. Cardinality and cost estimation
- 2. Search space
  - Access path selection
  - Rewrite rules

#### 3. Plan enumeration algorithms

#### Access Path

Access path: a way to retrieve tuples from a table

- A file scan, or
- An index *plus* a matching selection condition

Usually the access path implements a selection  $\sigma_P(R)$ , where the predicate P is called <u>search argument</u> SARG (see paper)

Supplier(sid,sname,scity,sstate) Selection condition: sid > 300 ^ scity='Seattle' Indexes: clustered B+-tree on sid; B+-tree on scity

V(Supplier,scity) = 20 Max(Supplier, sid) = 1000, Min(Supplier,sid) =1 B(Supplier) = 100, T(Supplier) = 1000

Which access path should we use?

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1. Sequential scan: cost = 100

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Which access path should we use?

- 1. Sequential scan: cost = 100
- 2. Index scan on sid: cost = 7/10 \* 100 = 70

Supplier(sid,sname,scity,sstate) Selection condition: sid > 300 ^ scity='Seattle' Indexes: clustered B+-tree on sid; B+-tree on scity

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Which access path should we use?

- 1. Sequential scan: cost = 100
- 2. Index scan on sid: cost = 7/10 \* 100 = 70
- 3. Index scan on scity: cost = 1000/20 = 50

#### **Rewrite Rules**

- The optimizer's search space is defined by the set of rewrite rules that it implements
- More rewrite rules means that more plans are being explored

### **Relational Algebra Laws**

#### Selections

- Commutative:  $\sigma_{c1}(\sigma_{c2}(R))$  same as  $\sigma_{c2}(\sigma_{c1}(R))$
- Cascading:  $\sigma_{c1 \land c2}(R)$  same as  $\sigma_{c2}(\sigma_{c1}(R))$

#### • Projections

- Cascading

#### • Joins

- Commutative :  $R \bowtie S$  same as  $S \bowtie R$
- Associative:  $R \bowtie (S \bowtie T)$  same as  $(R \bowtie S) \bowtie T$

#### **Selections and Joins**

R(A, B), S(C,D)

 $\sigma_{A=v}(R(A,B) \bowtie_{B=C} S(C,D)) =$ 

#### **Selections and Joins**

R(A, B), S(C,D)

$$\sigma_{A=v}(R(A,B) \bowtie_{B=C} S(C,D)) = (\sigma_{A=v}(R(A,B))) \bowtie_{B=C} S(C,D)$$

The simplest optimizers use <u>only</u> this rule Called <u>heuristic-based opimtizer</u> In general: <u>cost-based optimizer</u>

### Group-by and Join

R(A, B), S(C,D)

 $\gamma_{A, sum(D)}(R(A,B) \bowtie_{B=C} S(C,D)) =$ 

### Group-by and Join

R(A, B), S(C,D)

 $\begin{array}{l} \gamma_{\mathsf{A, sum}(\mathsf{D})}(\mathsf{R}(\mathsf{A},\mathsf{B}) \bowtie_{\mathsf{B}=\mathsf{C}} \mathsf{S}(\mathsf{C},\mathsf{D})) = \\ \gamma_{\mathsf{A, sum}(\mathsf{D})}(\mathsf{R}(\mathsf{A},\mathsf{B}) \bowtie_{\mathsf{B}=\mathsf{C}} (\gamma_{\mathsf{C, sum}(\mathsf{D})} \mathsf{S}(\mathsf{C},\mathsf{D}))) \end{array}$ 

These are very powerful laws. They were introduced only in the 90's.

### Search Space Challenges

- Search space is huge!
  - Many possible equivalent trees (logical)
  - Many implementations for each operator (physical)
  - Many access paths for each relation (physical)
- Cannot consider ALL plans
- Want a search space that includes low-cost plans
- Typical compromises:
  - Only left-deep plans
  - Only plans without cartesian products
  - Always push selections down to the leaves



## **Query Optimization**

#### Three major components:

- 1. Cardinality and cost estimation
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## Two Types of Optimizers

- Heuristic-based optimizers:
  - Apply greedily rules that always improve plan
    - Typically: push selections down
  - Very limited: no longer used today
- Cost-based optimizers:
  - Use a cost model to estimate the cost of each plan
  - Select the "cheapest" plan
  - We focus on cost-based optimizers

### Three Approaches to Search Space Enumeration

- Complete plans
- Bottom-up plans
- Top-down plans

#### **Complete Plans**



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#### **Bottom-up Partial Plans**



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#### **Top-down Partial Plans**



Why is this best for rewrite rules?

## Two Types of Plan Enumeration Algorithms

- Dynamic programming (in class)
  - Based on System R (aka Selinger) style optimizer[1979]
  - Limited to joins: *join reordering algorithm*
  - Bottom-up
- Rule-based algorithm (will not discuss)
  - Database of rules (=algebraic laws)
  - Usually: dynamic programming
  - Usually: top-down

## System R Search Space (1979)

- Only left-deep plans
  - Enable dynamic programming for enumeration
  - Facilitate tuple pipelining from outer relation
- Consider plans with all "interesting orders"
- Perform cross-products after all other joins (heuristic)
- Only consider nested loop & sort-merge joins
- Consider both file scan and indexes
- Try to evaluate predicates early

## System R Enumeration Algorithm

- Idea: use dynamic programming
- For each subset of {R1, ..., Rn}, compute the best plan for that subset
- In increasing order of set cardinality:
  - Step 1: for {R1}, {R2}, …, {Rn}
  - Step 2: for {R1,R2}, {R1,R3}, ..., {Rn-1, Rn}

- ...

- Step n: for {R1, …, Rn}
- It is a bottom-up strategy
- A subset of {R1, ..., Rn} is also called a *subquery*

- For each subquery Q ⊆{R1, ..., Rn} compute the following:
  - Size(Q)
  - A best plan for Q: Plan(Q)
  - The cost of that plan: Cost(Q)

- **Step 1**: Enumerate all single-relation plans
  - Consider selections on attributes of relation
  - Consider all possible access paths
  - Consider attributes that are not needed
  - Compute cost for each plan
  - Keep cheapest plan per "interesting" output order

- Step 2: Generate all two-relation plans
  - For each each single-relation plan from step 1
  - Consider that plan as outer relation
  - Consider every other relation as inner relation
  - Compute cost for each plan
  - Keep cheapest plan per "interesting" output order

- **Step 3**: Generate all three-relation plans
  - For each each two-relation plan from step 2
  - Consider that plan as outer relation
  - Consider every other relation as inner relation
  - Compute cost for each plan
  - Keep cheapest plan per "interesting" output order
- Steps 4 through n: repeat until plan contains all the relations in the query

## **Commercial Query Optimizers**

DB2, Informix, Microsoft SQL Server, Oracle 8

- Inspired by System R
  - Left-deep plans and dynamic programming
  - Cost-based optimization (CPU and IO)
- Go beyond System R style of optimization
  - Also consider right-deep and bushy plans (e.g., Oracle and DB2)
  - Variety of additional strategies for generating plans (e.g., DB2 and SQL Server)

## **Other Query Optimizers**

#### Randomized plan generation

- Genetic algorithm
- PostgreSQL uses it for queries with many joins

#### • Rule-based

- *Extensible* collection of rules
- Rule = Algebraic law with a direction
- Algorithm for firing these rules
  - Generate many alternative plans, in some order
  - Prune by cost
- Startburst (later DB2) and Volcano (later SQL Server)