Reading

Recommended:

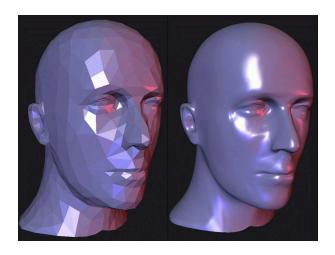
• Stollnitz, DeRose, and Salesin. Wavelets for Computer Graphics: Theory and Applications, 1996, section 10.2.

17. Subdivision surfaces

1

Building complex models

We can extend the idea of subdivision from curves to surfaces...



Subdivision surfaces

Chaikin's use of subdivision for curves inspired similar techniques for subdivision surfaces.

Iteratively refine a **control polyhedron** (or **control mesh**) to produce the limit surface

$$\sigma = \lim_{j \to \infty} M^j$$

using splitting and averaging steps.









3

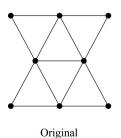
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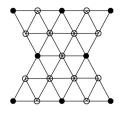
2

Triangular subdivision

There are a variety of ways to subdivide a poylgon mesh.

A common choice for triangle meshes is 4:1 subdivision – each triangular face is split into four subfaces:

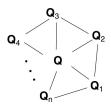


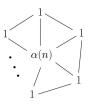


After splitting

Loop averaging step

Once again we can use **masks** for the averaging step:





Vertex neighorhood

Averaging mask

$$\mathbf{Q} \leftarrow \frac{\alpha(n)\mathbf{Q} + \mathbf{Q}_1 + \dots + \mathbf{Q}_n}{\alpha(n) + n}$$

where

$$\alpha(n) = \frac{n(1-\beta(n))}{\beta(n)}$$
 $\beta(n) = \frac{5}{4} - \frac{(3+2\cos(2\pi/n))^2}{32}$

These values, due to Charles Loop, are carefully chosen to ensure smoothness – namely, tangent plane or normal continuity.

Note: tangent plane continuity is also know as G¹ continuity for surfaces.

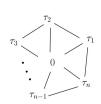
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Loop evaluation and tangent masks

As with subdivision curves, we can split and average a number of times and then push the points to their limit positions.







Evaluation mask

Tangent masks

$$\mathbf{Q}^{\infty} = \frac{\varepsilon(n)\mathbf{Q} + \mathbf{Q}_1 + \dots + \mathbf{Q}_n}{\varepsilon(n) + n}$$

$$\mathbf{T}_1^{\infty} = \tau_1(n)\mathbf{Q}_1 + \tau_2(n)\mathbf{Q}_2 + \dots + \tau_n(n)\mathbf{Q}_n$$

$$\mathbf{T}_2^{\infty} = \tau_n(n)\mathbf{Q}_1 + \tau_1(n)\mathbf{Q}_2 + \dots + \tau_{n-1}(n)\mathbf{Q}_n$$

where

$$\varepsilon(n) = \frac{3n}{\beta(n)} \quad \tau_i(n) = \cos(2\pi i/n)$$

How do we compute the normal?

Recipe for subdivision surfaces

As with subdivision curves, we can now describe a recipe for creating and rendering subdivision surfaces:

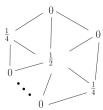
- Subdivide (split+average) the control polyhedron a few times. Use the averaging mask.
- Compute two tangent vectors using the tangent masks.
- Compute the normal from the tangent vectors.
- Push the resulting points to the limit positions.
 Use the evaluation mask.
- Render!

5

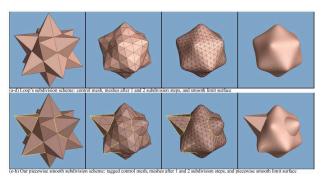
Adding creases without trim curves

In some cases, we want a particular feature such as a crease to be preserved. With NURBS surfaces, this required the use of trim curves.

For subdivision surfaces, we can just modify the subdivision mask:



This gives rise to G⁰ continuous surfaces (i.e., having positional but not tangent plane continuity)



Creases without trim curves, cont.

Here's an example using Catmull-Clark surfaces (based on subdividing quadrilateral meshes):

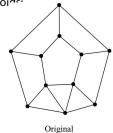


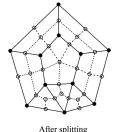
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Face schemes

4:1 subdivision of triangles is sometimes called a **face scheme** for subdivision, as each face begets more faces.

An alternative face scheme starts with arbitrary polygon meshes and inserts vertices along edges and at face centroids.





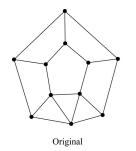
Catmull-Clark subdivision:

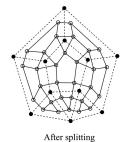


Note: after the first subdivision, all polygons are quadilaterals in this scheme.

Vertex schemes

In a **vertex scheme**, each vertex begets more vertices. In particular, a vertex surrounded by n faces is split into n subvertices, one for each face:





Doo-Sabin subdivision:









The number edges (faces) incident to a vertex is called its **valence**. Edges with only once incident face are on the **boundary**. After splitting in this subdivision scheme, all non-boundary vertices are of valence 4.

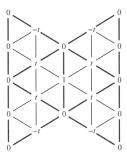
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Interpolating subdivision surfaces

Interpolating schemes are defined by

- splitting
- averaging only new vertices

The following averaging mask is used in **butterfly subdivision**:



Setting t=0 gives the original polyhedron, and increasing small values of t makes the surface smoother, until t=1/8 when the surface is provably G^1 .