

Ray Tracing

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CSE 557
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(Peter Henry)

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Reading

Required:

- ♦ Section 2.7
- ♦ Chapter 4
- ♦ Section 13.1 - 13.2

Further reading:

- ♦ T. Whitted. An improved illumination model for shaded display. Communications of the ACM 23(6), 343-349, 1980.
- ♦ A. Glassner. An Introduction to Ray Tracing. Academic Press, 1989.
- ♦ K. Turkowski, "Properties of Surface Normal Transformations," Graphics Gems, 1990, pp. 539-547.

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Geometric optics

Modern theories of light treat it as both a wave and a particle.

We will take a combined and somewhat simpler view of light – the view of **geometric optics**.

Here are the rules of geometric optics:

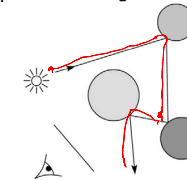
- ♦ Light is a flow of photons with wavelengths. We'll call these flows "light rays."
- ♦ Light rays travel in straight lines in free space.
- ♦ Light rays do not interfere with each other as they cross.
- ♦ Light rays obey the laws of reflection and refraction.
- ♦ Light rays travel from the light sources to the eye, but the physics is invariant under path reversal (reciprocity).

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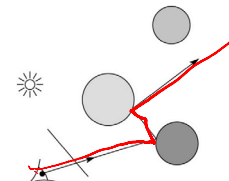
Eye vs. light ray tracing

Where does light begin?

At the light: light ray tracing (a.k.a., forward ray tracing or photon tracing)



At the eye: eye ray tracing (a.k.a., backward ray tracing)



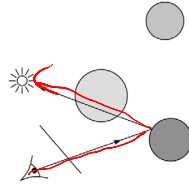
We will generally follow rays from the eye into the scene.

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Precursors to ray tracing

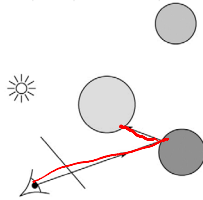
Local illumination

- Cast one eye ray, then shade according to light



Appel (1968)

- Cast one eye ray + one ray to light

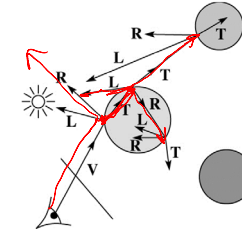


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Whitted ray-tracing algorithm

In 1980, Turner Whitted introduced ray tracing to the graphics community.

- Combines eye ray tracing + rays to light
- Recursively traces rays



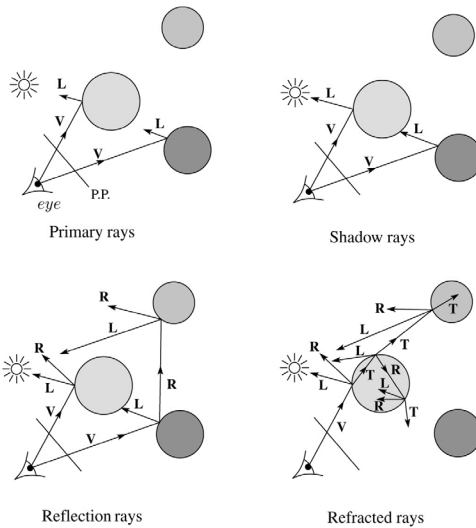
Algorithm:

- For each pixel, trace a **primary ray** in direction V to the first visible surface.
- For each intersection, trace **secondary rays**:
 - Shadow rays** in directions L_i to light sources
 - Reflected ray** in direction R .
 - Refracted ray or transmitted ray** in direction T .

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Whitted algorithm (cont'd)

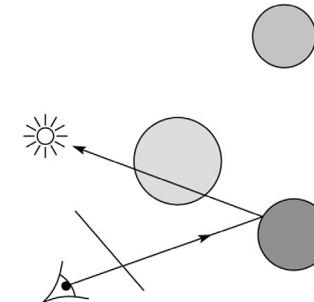
Let's look at this in stages:



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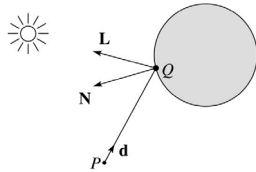
Ray casting and local illumination

Now let's actually build the ray tracer in stages. We'll start with ray casting and local illumination:



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Direct illumination



A ray is defined by an origin P and a unit direction d and is parameterized by $t > 0$.

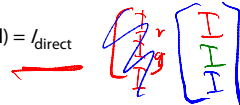
$$r(t) = P + td$$

Let $I(P, d)$ be the intensity seen along a ray. Then:

$$I(P, d) = I_{\text{direct}}$$

where

- I_{direct} is computed from the Blinn-Phong model



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Shading in "Trace"

The Trace project uses a version of the Blinn-Phong shading equation we derived in class, with two modifications:

- Distance attenuation is clamped to be at most 1:

$$A_j^{\text{dist}} = \min\left\{1, \frac{1}{a_j + b_j r_j + c_j r_j^2}\right\}$$

- Shadow attenuation A^{shadow} is included.

Here's what it should look like:

$$I = k_o + k_g I_a + \sum_j A_j^{\text{shadow}} A_j^{\text{dist}} I_{L_j} B_j [k_d (\mathbf{N} \cdot \mathbf{L}_j) + k_s (\mathbf{N} \cdot \mathbf{H}_j)^{n_s}]$$

This is the shading equation to use in the Trace project!

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Ray-tracing pseudocode

We build a ray traced image by casting rays through each of the pixels.

function *tracelImage*(scene):

for each pixel (i,j) in image

$A = \text{pixelToWorld}(i,j)$

$P = \text{COP}$

$d = (A - P) / \|A - P\|$

$I(i,j) = \text{traceRay}(\text{scene}, P, d)$

end for

end function

function *traceRay*(scene, P, d):

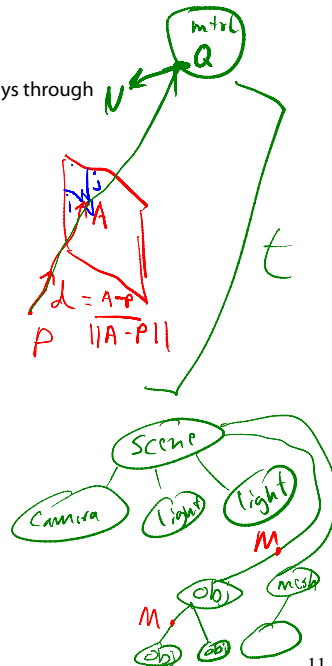
$(t, \mathbf{N}, \text{mtrl}) \leftarrow \text{scene.intersect}(P, d)$

$Q \leftarrow \text{ray}(P, d)$ evaluated at t

$I = \text{shade}(\mathbf{N}, d, \text{scene}, \text{mtrl}, Q)$

return I

end function



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Shading pseudocode

Next, we need to calculate the color returned by the *shade* function.

function *shade*(mtrl, scene, Q, N, d):

$I \leftarrow \text{mtrl}.k_o + \text{mtrl}.k_g * I_a$

for each light source Light **do**:

$\text{atten} = \text{Light} \rightarrow \text{distanceAttenuation}(Q)$

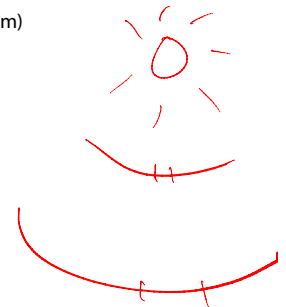
$L = \text{Light} \rightarrow \text{getDirection}(Q)$

$I \leftarrow I + \text{atten} * (\text{diffuse term} + \text{specular term})$

end for

return I

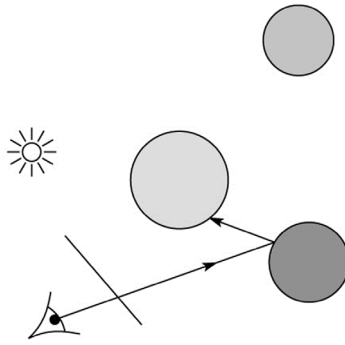
end function



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Ray casting with shadows

Now we'll add shadows by casting shadow rays:



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Shading with shadows

To include shadows, we need to modify the shade function:

```

function shade(mtrl, scene, Q, N, d):
    I ← mtrl.ke + mtrl.ka * Il
    for each light source Light do:
        atten = Light -> distanceAttenuation(Q) *
            Light -> shadowAttenuation(Q, scene)
        L = Light -> getDirection(Q)
        I ← I + atten*(diffuse term + specular term)
    end for
    return I
end function
    
```

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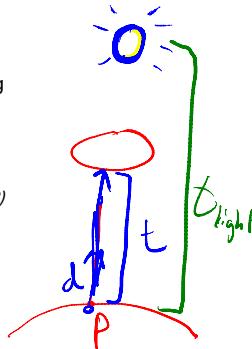
Shadow attenuation

Computing a shadow can be as simple as checking to see if a ray makes it to the light source.

For a point light source:

```

function PointLight::shadowAttenuation(scene, P)
    d = getDirection(P)
    (t, N, mtrl) ← scene.intersect(P, d)
    Compute tlight
    if (t < tlight) then:
        atten = (0, 0, 0)
    else
        atten = (1, 1, 1)
    end if
    return atten
end function
    
```



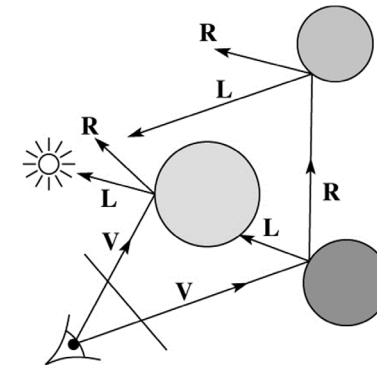
Note: we will later handle color-filtered shadowing, so this function needs to return a *color* value.

For a directional light, $t_{\text{light}} = \infty$.

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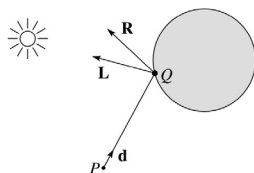
Recursive ray tracing with reflection

Now we'll add reflection:



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Shading with reflection



Let $I(P, \mathbf{d})$ be the intensity seen along a ray. Then:

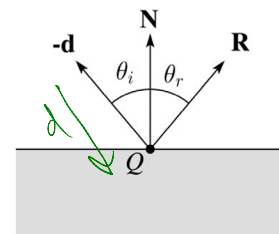
$$I(P, \mathbf{d}) = I_{\text{direct}} + I_{\text{reflected}}$$

where

- I_{direct} is computed from the Blinn-Phong model, plus shadow attenuation
- $I_{\text{reflected}} = k_r I(Q, \mathbf{R})$

Typically, we set $k_r = k_s$. (k_r is a color value.)

Reflection



Law of reflection:

$$\theta_i = \theta_r$$

\mathbf{R} is co-planar with \mathbf{d} and \mathbf{N} .

Ray-tracing pseudocode, revisited

```

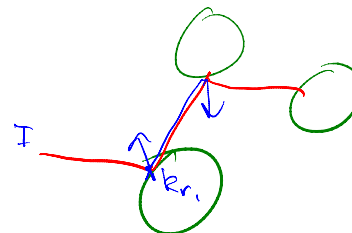
function traceRay(scene, P, d):
    (t, N, mtrl) ← scene.intersect(P, d)
    Q ← ray(P, d) evaluated at t
    I = shade(scene, mtrl, Q, N, -d)
    R = reflectDirection(N, -d)
    I ← I + mtrl.kr * traceRay(scene, Q, R)
    return I
end function
    
```

Terminating recursion

Q: How do you bottom out of recursive ray tracing?

Possibilities:

implement: max level "d"



$$I = I_1 + k_{r_1} (I_2 + k_{r_2} (I_3 + \dots))$$

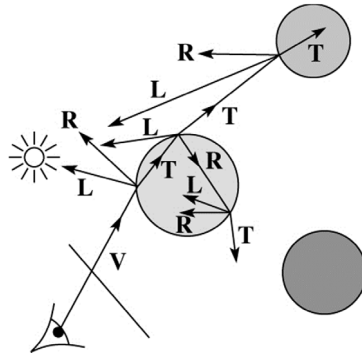
bounces

$$\prod_{i=1}^n k_{r_i} < \text{thresh}$$

thresh

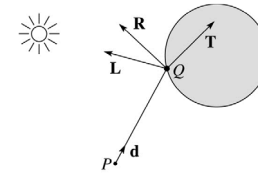
Whitted ray tracing

Finally, we'll add refraction, giving us the Whitted ray tracing model:



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Shading with reflection and refraction



Let $I(P, \mathbf{d})$ be the intensity seen along a ray. Then:

$$I(P, \mathbf{d}) = I_{\text{direct}} + I_{\text{reflected}} + I_{\text{transmitted}}$$

where

- I_{direct} is computed from the Blinn-Phong model, plus shadow attenuation
- $I_{\text{reflected}} = k_r I(Q, \mathbf{R})$
- $I_{\text{transmitted}} = k_t I(Q, \mathbf{T})$

Typically, we set $k_r = k_s$ and $k_t = 1 - k_s$ (or $(0,0,0)$, if opaque, where k_r is a color value).

[Generally, k_r and k_t are determined by "Fresnel reflection," which depends on angle of incidence and changes the polarization of the light. This is discussed in Shirley's textbook and can be implemented for extra credit.]

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Refraction

Snell's law of refraction:

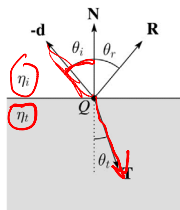
$$n_i \sin \theta_i = n_t \sin \theta_t$$

where n_i, n_t are **indices of refraction**.

In all cases, **R** and **T** are co-planar with **d** and **N**.

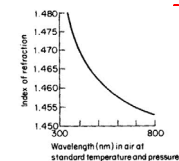
The index of refraction is material dependent.

It can also vary with wavelength, an effect called **dispersion** that explains the colorful light rainbows from prisms. (We will generally assume no dispersion.)



rarer denser

Medium	Index of refraction
Vacuum	1
Air	1.0003
Water	1.33
Fused quartz	1.46
Glass, crown	1.52
Glass, dense flint	1.66
Diamond	2.42



Index of refraction variation for fused quartz

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Total Internal Reflection

The equation for the angle of refraction can be computed from Snell's law:

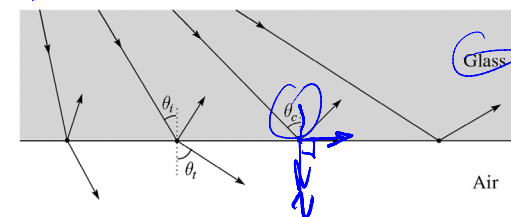
$$\sin \theta_t = \frac{n_i}{n_t} \sin \theta_i$$

$$\theta_t = \sin^{-1} \left(\frac{n_i}{n_t} \sin \theta_i \right)$$

What happens when $n_i > n_t$?

When θ_i is exactly 90° , we say that θ_i has achieved the "critical angle" θ_c .

For $\theta_i > \theta_c$, **no rays are transmitted**, and only reflection occurs, a phenomenon known as "total internal reflection" or TIR.



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Shirley's notation

Shirley uses different symbols. Here is the translation between them:

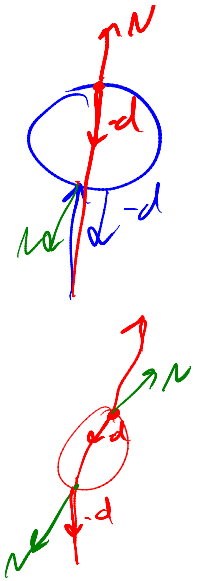
$r = R$
 $t = T$
 $\phi = \theta_t$
 $\theta = \theta_r = \theta_i$
 $n = \eta_i$
 $n_t = \eta_t$

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Ray-tracing pseudocode, revisited

```

function traceRay(scene, P, d):
    (t, N, mtrl) ← scene.intersect(P, d)
    Q ← ray(P, d) evaluated at t
    I = shade(scene, mtrl, Q, N, -d)
    R = reflectDirection(N, -d)
    I ← I + mtrl.kr * traceRay(scene, Q, R)
    if ray is entering object then
        n_i = index_of_air
        n_t = mtrl.index
    else
        n_i = mtrl.index
        n_t = index_of_air
    if (not TIR(n_i, n_t, N, -d)) then
        T = refractDirection(n_i, n_t, N, -d)
        I ← I + mtrl.kt * traceRay(scene, Q, T)
    end if
    return I
end function
    
```



Q: How do we decide if a ray is entering the object?

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Terminating recursion, incl. refraction

Q: Now how do you bottom out of recursive ray tracing?

Simple: max depth

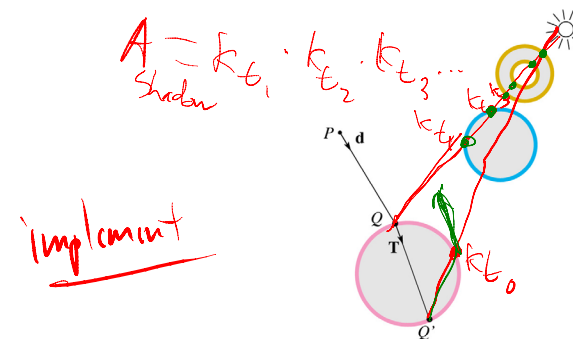
"bounces"

$\prod_{i=1}^n \{k_r \text{ or } k_t\} < \text{thresh}$

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Shadow attenuation (cont'd)

Q: What if there are transparent objects along a path to the light source?

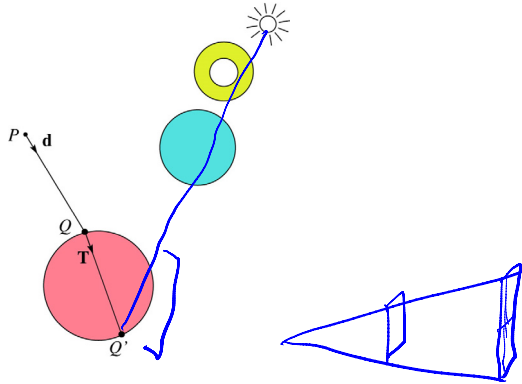


We'll take the view that the color is really only at the surface, like a glass object with a colored transparency coating on it. In this case, we multiply in the transparency constant, k_t , every time an object is entered or exited, possibly more than once for the same object.

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Shadow attenuation (cont'd)

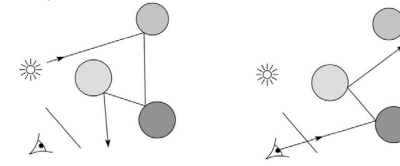
Another model would be to treat the glass as solidly colored in the interior. Shirley's textbook describes a the resulting volumetric attenuation based on Beer's Law, which you can implement for extra credit.



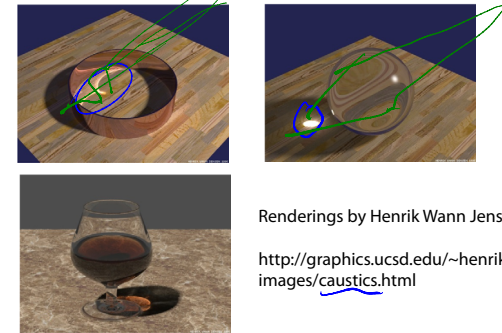
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Photon mapping

Combine light ray tracing (photon tracing) and eye ray tracing:



...to get **photon mapping**.



Renderings by Henrik Wann Jensen:

<http://graphics.ucsd.edu/~henrik/images/caustics.html>

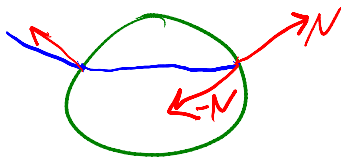
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Normals and shading when inside

When a ray is inside an object and intersects the object's surface on the way out, the normal will be pointing **away** from the ray (i.e., the normal always points to the outside by default).

You must **negate** the normal before doing any of the shading, reflection, and refraction that follows.

Finally, when shading a point inside of an object, apply k_t to the ambient component, since that "ambient light" had to pass through the object to get there in the first place.

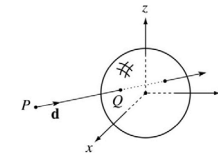


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Intersecting rays with spheres

Now we've done everything except figure out what that "scene.intersect(P, \mathbf{d})" function does.

Mostly, it calls each object to find out the t value at which the ray intersects the object. Let's start with intersecting spheres...



Given:

- The coordinates of a point along a ray passing through P in the direction \mathbf{d} are:

$$\begin{aligned} x &= P_x + td_x \\ y &= P_y + td_y \\ z &= P_z + td_z \end{aligned}$$

$$r(t) = P + t \cdot d$$

- A unit sphere S centered at the origin defined by the equation:

$$x^2 + y^2 + z^2 = 1$$

$$\begin{aligned} (P_x + td_x)^2 &+ \\ (P_y + td_y)^2 &+ \\ (P_z + td_z)^2 &= 1 \end{aligned}$$

Find: The t at which the ray intersects S .

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Intersecting rays with spheres

Solution by substitution:

$$x^2 + y^2 + z^2 - 1 = 0$$

$$(P_x + td_x)^2 + (P_y + td_y)^2 + (P_z + td_z)^2 - 1 = 0$$

$$\rightarrow at^2 + bt + c = 0$$

where

$$a = d_x^2 + d_y^2 + d_z^2$$

$$b = 2(P_x d_x + P_y d_y + P_z d_z)$$

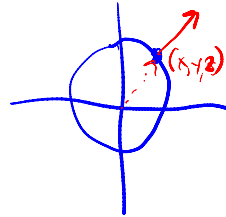
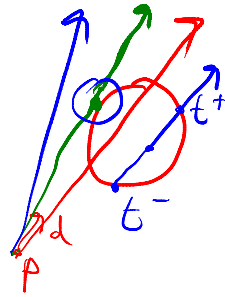
$$c = P_x^2 + P_y^2 + P_z^2 - 1$$

Q: What are the solutions of the quadratic equation in t and what do they mean?

$$t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

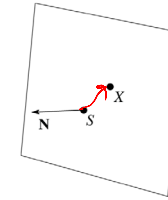
Q: What is the normal to the sphere at a point (x, y, z) on the sphere?

$$N = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$



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Ray-plane intersection



$$ax + by + cz = d$$

$$Ax + By + Cz = D$$

Next, we will consider intersecting a ray with a plane.

To do this, we first need to define the plane equation.

Given a point S on a plane with normal N , how would we determine if a point X is on the plane? Hint: start by forming the vector $X - S$.

$$N \cdot (X - S) = 0$$

$$N \cdot X - N \cdot S = 0$$

$$N \cdot X = N \cdot S$$

$$N_x x + N_y y + N_z z = N \cdot S$$

This is the plane equation!

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Ray-triangle intersection

$$\vec{n} \cdot \vec{x} = k$$

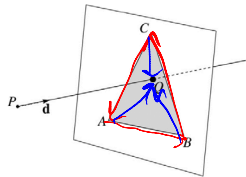
$$\vec{n} \cdot (P + t\vec{d}) = k$$

$$\vec{n} \cdot P + \vec{n} \cdot t\vec{d} = k$$

$$\vec{n} \cdot P + t\vec{n} \cdot \vec{d} = k$$

$$t \cdot \vec{n} \cdot \vec{d} = k - \vec{n} \cdot P$$

$$t = \frac{k - \vec{n} \cdot P}{\vec{n} \cdot \vec{d}}$$



To intersect with a triangle, we first solve for the equation of its supporting plane.

How might we compute the (un-normalized) normal?

$$(\vec{B} - \vec{A}) \times (\vec{C} - \vec{A}) = \vec{n}$$

$$\hat{n} = \frac{\vec{n}}{\|\vec{n}\|}$$

Given this normal, how would we compute k ?

$$\hat{n} \cdot \vec{A} = \hat{n} \cdot \vec{C} = \hat{n} \cdot \vec{B} = k$$

Using these coefficients, we can solve for Q . Now, we need to decide if Q is inside or outside of the triangle.

Solution 1: Compute barycentric coordinates from 3D points.

What do you do with the barycentric coordinates?

$$(\vec{B} - \vec{A}) \times (\vec{Q} - \vec{A}) \cdot \vec{n} \geq 0$$

$$(\vec{C} - \vec{B}) \times (\vec{Q} - \vec{B}) \cdot \vec{n} \geq 0$$

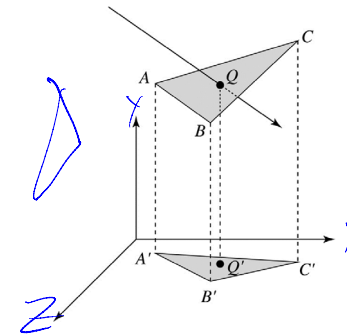
$$(\vec{A} - \vec{C}) \times (\vec{Q} - \vec{C}) \cdot \vec{n} \geq 0$$

$$\text{all } [0, 1]$$

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2D inside-outside test

Without loss of generality, we can make this determination after projecting down a dimension:



If Q' is inside of $A'B'C'$, then Q is inside of ABC .

Why is this projection desirable? *cheaper cross products*

Which axis should you "project away"?

which normal component is largest

$$Q = \alpha \cdot A + \beta \cdot B + \gamma \cdot C$$

$$Q' = \alpha \cdot A' + \beta \cdot B' + \gamma \cdot C'$$

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Interpolating vertex properties

The barycentric coordinates can also be used to interpolate vertex properties such as:

- material properties
- texture coordinates
- normals

For example:

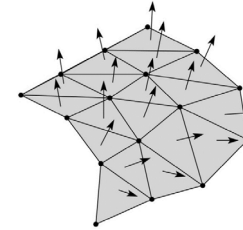
$$k_d(Q) = \alpha k_d(A) + \beta k_d(B) + \gamma k_d(C)$$

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Per-face normals for triangle meshes

We will be shading and calculating reflections and refractions based on surface normals.

For a triangle mesh, we can make the natural assumption that each triangle has a constant normal (the normal of its supporting plane):



Recall the Blinn-Phong shading equation for a single light source (no ambient or emissive):

$$I = I_L B [k_d (\mathbf{N} \cdot \mathbf{L}) + k_s (\mathbf{N} \cdot \mathbf{H})^n] \approx \text{constant}$$

Typically, \mathbf{L} and \mathbf{V} vary only a small amount over each triangle, if at all. Now assume constant material properties over the mesh. How will shading vary within a triangle?

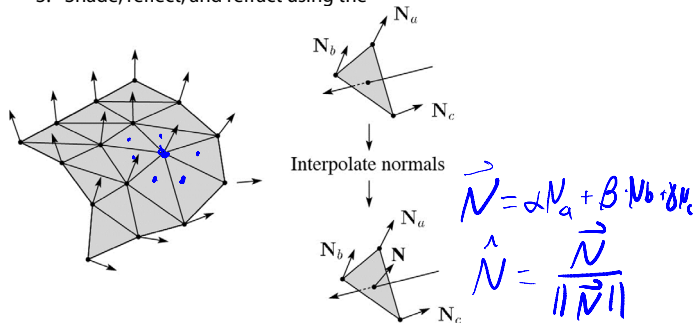
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Phong interpolated normals

To get smoother results, we can "hallucinate" normals that vary smoothly within a triangle, a process called **Phong interpolation**. (Not the same as "Phong shading.")

Here's how it works:

1. Compute normals at the vertices.
2. Interpolate normals and normalize.
3. Shade, reflect, and refract using the



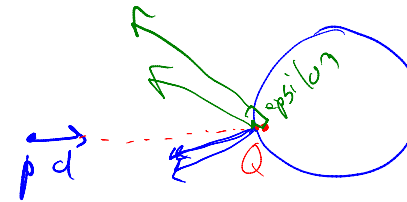
Q: How do we interpolate to get \mathbf{N} ?
(Don't forget to normalize!!)

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Epsilons

Due to finite precision arithmetic, we do not always get the exact intersection at a surface.

Q: What kinds of problems might this cause?



Q: How might we resolve this?

$t > \text{Epsilon}$ instead of $t > 0$
e.g. 0.0001

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Intersecting with xformed geometry

In general, objects will be placed using transformations. What if the object being intersected were transformed by a matrix M ?

Apply M^{-1} to the ray first and intersect in object (local) coordinates!



$$M^{-1}(Q = P + dt)$$

$$M^{-1}Q = M^{-1}P + M^{-1}d \cdot t$$

$$M^{-1}Q = P' + d' \cdot t$$

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Intersecting with xformed geometry

The intersected normal is in object (local) coordinates. How do we transform it to world coordinates?

The diagram shows a ray intersecting a square in world coordinates. The normal N' is shown in object coordinates. An arrow labeled M points to the right, where the normal is transformed to N in world coordinates. The transformation matrix M is shown as a 2x2 matrix with a translation component t . The normal N is shown as a vector in world coordinates.

Handwritten notes and equations:

- $(-0.707, 0.707)$
- $M = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
- $\tilde{m} = \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix}$ (circled in red)
- $M = \begin{bmatrix} A & t \\ 0 & 0 & 0 & 1 \end{bmatrix}$
- $N = \tilde{m} \cdot N'$
- $N = (-0.707, 3 \cdot (0.707))$
- $M = \begin{bmatrix} A^{-T} & t \\ 0 & 0 & 0 & 1 \end{bmatrix}$
- $A^T = A^{-1}$
- $A = A^{-T}$ for rotation
- M works for rotation

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