

# Announcements

- Nebojsa Jojic talks Fri, Mon Tues
- Project 1 → "plan" to me this Thurs  
- presentation (due date) Apr 23
- Office hours Wed 2:30-3:30

4 BP

1 EM

1 GC

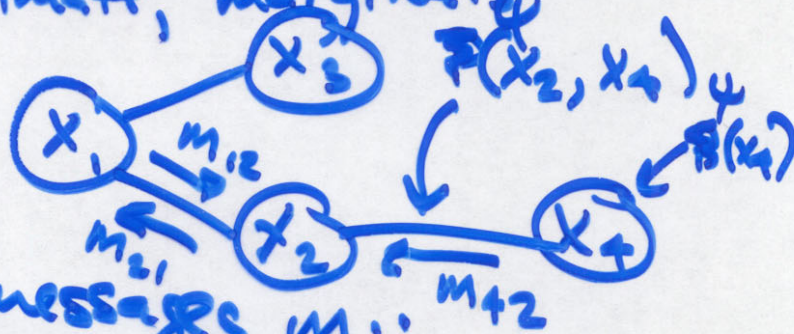
## TODAY

1. recap BP
2. app in vision
3. discuss

## RECAP BP

- given  $x_1, \dots, x_n$ ,  $\psi(x_i, x_j)$  or  $\psi(x_i | x_j)$   
→ inference: find most probable values  
MAP estimate, marginals

- graphical model

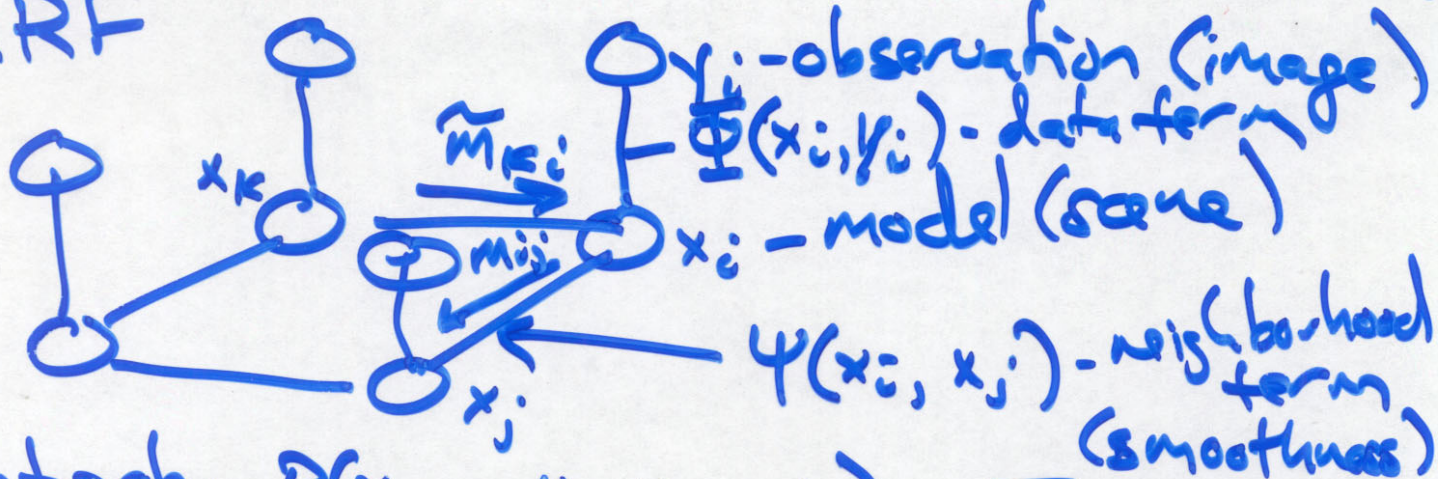


- solve by passing messages  $m_{ij}$ 
  - repeat until fixed point
  - order is flexible → faster convergence
- no loops - provably converges to right answer
- loops - often still works



# Basic Formulation for vision probs (Freeman)

MRF



joint prob:  $P(x_1, \dots, x_n, y_1, \dots, y_n) \sim \prod \Psi(x_i, x_j) \prod \Phi(x_i, y_i)$

messages from  $x_i$  to  $x_j$

$$m_{ij}(x_j) = \alpha \sum_{x_i} \Psi(x_i, x_j) \Phi(x_i, y_i) \prod_{k \in N(i) - j} m_{ki}(x_i)$$

(a vector)  $\rightarrow$  gives info about  $x_j$

belief of node  $i$ :  $b_i(x_i) = \alpha \Phi(x_i, y_i) \prod_{j \in N(i)} m_{ji}(x_i)$

$\uparrow$  marginal probs (sum-product alg)

MAP: replace  $\sum$  with Max  
 "max-product" alg

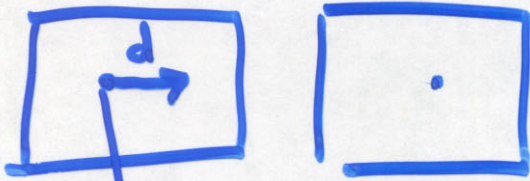
can write these updates in matrix form  
 (see your's (see notes))

- but be careful  $\begin{bmatrix} a \\ b \\ c \end{bmatrix} * \begin{bmatrix} d \\ e \\ f \end{bmatrix} = \begin{bmatrix} ad \\ be \\ cf \end{bmatrix}$



# Stereo

Prob:  $\forall$  pixels in left image  
find  $d$



$x_i$  = disparity at pixel

$y_i$  = intensity diff

$$\Phi(x_i, y_i) = Ke^{-y_i^2}$$

data term

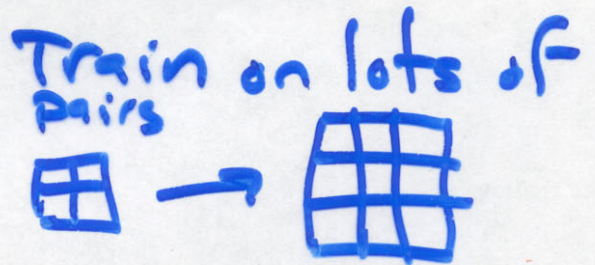
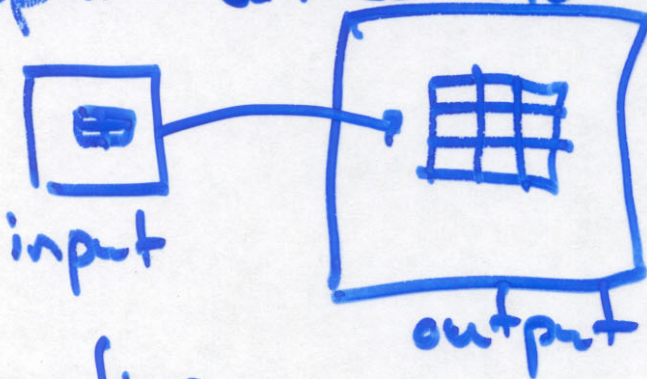
$$\Psi(x_i, x_j) = Ke^{-v(x_i, x_j)}$$

~~$v(x_i, x_j)$~~

$$v(x_i, x_j) = \begin{cases} 0 & \text{if } x_i = x_j \\ \text{penalty} & \text{otherwise} \end{cases}$$

$f(\Delta \Sigma_i)$

# Super-resolution



- Objectives use
- training data to predict high res patch  
data term  $\Phi(x_i, y_i) = Ke^{-\|x_i - y_i\|^2}$   
 $\uparrow$  training patch       $\uparrow$  observed patch
  - make sure neighboring patches fit together