

Topics in Probabilistic and Statistical Databases

Lecture 4: Dichotomy Theorems

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Before we start...

- Kate will give an update on OWA

TABLE II
EXAMPLE OF MISSING PROBABILITIES

EMPLOYEE	DEPARTMENT	QUALITY BONUS	SALES
Jon Smith	Toy	0.3 [Great yes]	0.3
		0.4 [Good yes]	[\$30–34K]
		0.2 [Fair *]	0.5
		0.1 [* *]	[\$35–39K]
			0.2 [*]

TABLE III
RELATION FOR PROJECT EXAMPLES

NAME	DIV PRICE	RATING
P.J.	0.3 [10 200]	0.9 [AAA]
	0.2 [20 250]	0.1 [AA]
	0.2 [10 250]	
	0.1 [0 *]	
	0.1 [* 100]	
	0.1 [* *]	
CONTI	1.0 [0 50]	0.5 [BBB]
		0.5 [CCC]

Brief review...

- What are the three different definitions for the complexity of the query evaluation problem ?
- What is #P ?

A Probabilistic Database Design Quiz

- You need to store data extracted from conference Websites
- Extractor has two phases:
 - A classifier checks if the Webpage is about a conference, and returns a confidence c in $(0,1]$
 - A conference-name extractor, returns a name with confidence p
 - A pc-chair extractor, returns a person name, with confidence q

A Probabilistic Database Design Quiz

URL	Conf	P
U1	SIGMOD	$c1 * p1$
U1	SIGCOM	$c1 * p2$
U2	VLDB	$c2 * p3$

URL	Chair	P
U1	Kossman	$c1 * q1$
U2	Gehrke	$c2 * q2$
U2	Milo	$c2 * q3$

There are correlations ! Represent them with I/D-tables only.

Problem Statement

- Given:
 - A disjoint/independent probdb PDB
 - A Boolean conjunctive query Q
- Compute the probability $Q(\text{PDB})$

Three Theorems

- Case 1: CQ¹ on independent databases
 - Review: Hierarchical \rightarrow PTIME, non-h \rightarrow #P-hard
 - Today: extensions to FDs, deterministic relations
- Case 2: CQ¹ on D/I – databases
 - Today in class
- Case 3: CQ on independent databases
 - Start today, continue next time

Case 1: CQ¹+independent

- Review hierarchical queries, safe plans in class
- Review the expression-algorithm

FDs: Worlds v.s. Representation

Product^p

<u>prod</u>	<u>price</u>	color	shape	p
Gizmo	20	red	oval	$p_1 = 0.25$
		blue	square	$p_2 = 0.75$
Camera	80	green	oval	$p_3 = 0.3$
		red	round	$p_4 = 0.3$
		blue	oval	$p_5 = 0.2$
iPod	300	white	square	$p_6 = 0.8$
		black	square	$p_7 = 0.2$

In each possible world: prod \rightarrow price, color, shape

In the representation: prod \rightarrow price

FDs at the Representation Level

$q \text{ :- } R(x), S(x,y), T(y)$

Suppose $x \rightarrow y$ in $S(x,y)$ in the representation

What is the complexity of this query ?

FDs at the Representation Level

$q \text{ :- } R(x), S(x,y), T(y)$

Suppose $x \rightarrow y$ in $S(x,y)$ in the representation

“Reduce” $R(x)$ to $R(x,y)$

$q \text{ :- } R(x,y), S(x,y), T(y)$

Now it is hierarchical

[Dalvi&S' VLDBJ'2007, Olteanu'ICDE2009]

FDs at the Representation Level

$q(x) \text{ :- } R(y), S(x,y,z), T(z)$

Suppose $x \rightarrow y$ in $S(x,y)$ in the representation

What is the complexity now ?

FDs at the Representation Level

Theorem Let q be a query over a schema with FDs at the representation level. Let q' be the “reduced” query (chase ?). Then the evaluation problem of q is reducible in PTIME to the evaluation problem of q' , and vice versa.

Proof in class.

How does this give us a dichotomy theorem ?

Deterministic Relations

- Now add deterministic relations (in class)
 - Notation: R^p = probabilistic, R =deterministic
- What is the complexity of the following queries ? Give theorem in class

$q \text{ :- } R^p(x), S1(x,u), S2(u,v), S3(v,y), T^p(y,z)$

$q \text{ :- } R^p(z,x), S1(x,u), S2(u,z), S3(z,v), S4(v,y), T^p(y)$

$q \text{ :- } R^p(z,x), S1(x,u), S2(u,z), S3(z,v), S4(v,y), T^p(z,y)$

Case 2: CQ¹+Disjoint/independent

- Dichotomy: in [Dalvi et al.'06,Dalvi&S'07]
- Some safe plans also in [Andritsos'2006]
- CQ¹ (conjunctive queries, no self-joins)
- Independent/independent tables are OK

Theorem For all $q \in \text{CQ}^1$

q has a safe plan and is in PTIME, OR
 q is #P-hard

Finding Safe Plans

Algorithm: find a Safe Plan

1. Root variable $u \rightarrow \Pi_{-u}^i$
2. Variable u occurs in a subgoal with constant keys $\rightarrow \Pi_{-u}^D$
3. Connected components \rightarrow Join
4. Single subgoal \rightarrow Leaf node

$q(y) :- R(\underline{x}, y, z)$

Π_{-x}^i

|

Π_{-z}^D

|

$R(\underline{x}, y, z)$

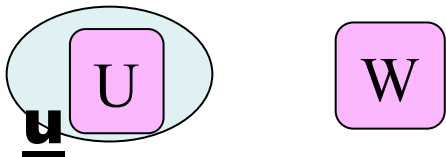
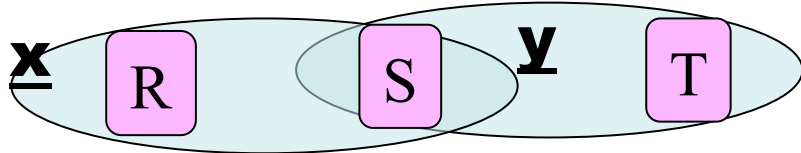
$q1(x^c, y^c) :- R(\underline{x}^c, y^c, z)$

y	P
b	$1-(1-p1-p2)(1-p3-p4)$

\underline{x}	y	P
a1	b	$p1+p2$
a2	b	$p3+p4$

\underline{x}	y	z	P
a1	b	c1	$p1$
	b	c2	$p2$
a2	b	c1	$p3$
	b	c2	$p4$

$R(\underline{x}), S(\underline{x}, \underline{y}), T(\underline{y}), U(\underline{u}, y), W(\underline{a}', u)$



Independent project

$R^p(x)$

Π_{-x}^I

\bowtie_x

$S^p(x,y)$

Π_{-y}^D

\bowtie_y

$T^p(y)$

$U^p(u,y)$

Π_{-u}^D

\bowtie_u

$W^p(\underline{a}', u)$

Disjoint project

Disjoint project

Definitions (in class)

- $q \text{ :- } g_1, \dots, g_k$
- $Sg(q) = \{g_1, \dots, g_k\}$
- $Vars(g_i) = \text{all variables of } g_i$
- $KVars(g_i) = \text{all variables in key positions}$

Algorithm Safe-Eval

- From [Dalvi&S'2007]
- Show on the whiteboard
- Call a query *safe* if the algorithm succeeds
- What are the *unsafe* queries ?

Some Unsafe Queries

hd1 = R(**x**), S(**x**, **y**), T(**y**)

hd2 = R(**x**, y), S(**y**)

hd3 = R(**x**, y), S(x, **y**)

Variants: hd2⁺, hd3⁺ (on the whiteboard)

Plan for Proving Dichotomy

Step 1:

- Show that $hd1$, $hd2$, $hd3$ are #P-hard

Step 2:

- Show that every unsafe query can be “rewritten” to $hd1$, $hd2$, or $hd3$

Step 1

- Show (review) in class the hardness of

$$\text{hd1} = R(\mathbf{x}), S(\mathbf{x}, \mathbf{y}), T(\mathbf{y})$$

Step 1

- Show in class the hardness of

$$\text{hd2} = R(\underline{\mathbf{x}}, y), S(\underline{\mathbf{y}})$$

Then show hd2^+

Step 1

- Show in class the hardness of

$$\text{hd3} = R(\underline{\mathbf{x}}, y), S(x, \underline{\mathbf{y}})$$

Then show hd3^+

Step 2

- The rewrite rule $q \rightarrow q'$ (on the whiteboard)
- q is a final query if for all q' s.t. $q \rightarrow q'$, q' is safe
- Prove:
 - If q is unsafe, then $\exists q'$ final s.t. $q \rightarrow^* q'$
 - The only final queries are $hd1$, $hd2^+$, $hd3^+$
 - This completes the dichotomy (why ?)

The Complexity of the Complexity

- Deciding if a query is hierarchical is in AC^0 (in class)
- Deciding if a query is safe is PTIME complete (in class)

Case 3: CQ, independent tables

- Allow selfjoins
- But restrict again to independent tables

Does the query have a safe plan ?

$q(x) :- R(a, x, y), R(b, x, z), S(y, z, u)$

(a, b = constants)

Does the query have a safe
plan ?

q :- R(a,x), R(y,b)

Does the query have a safe plan ?

Note: no “safe plans” are known ! PTIME algorithm for an inversion-free query is given in terms of expressions, not plans. Example:

$$q :- R(a,x), R(y,b)$$

$$p(q) = p(R(a,b)) + (1 - p(R(a,b))) \left(1 - \left(1 - \prod_{y \in \text{Dom}, y \neq a} (1 - p(R(y,b))) \right) \left(1 - \prod_{x \in \text{Dom}, x \neq b} (1 - p(R(a,x))) \right) \right)$$

Open Problem: what are the natural operators that allow us to compute inversion-free queries in a database engine ?

Does the query have a safe plan ?

Find movies with high reviews from Joe and Jim:

$$q(x) \text{ :- Movie}(x,y), \text{ Match}^p(x,r), \text{ Review}(r,\text{Joe},s), s > 4 \\ \text{Match}^p(x,r'), \text{ Review}(r',\text{Jim},s'), s' > 4$$

Match^p = probabilistic, tuple independent

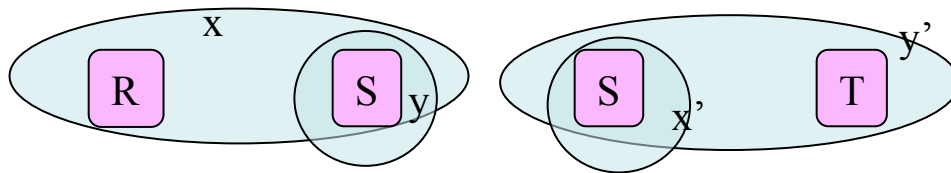
Movie, Review = deterministic

The #P-hard Queries

Hierarchical queries with “inversions”:

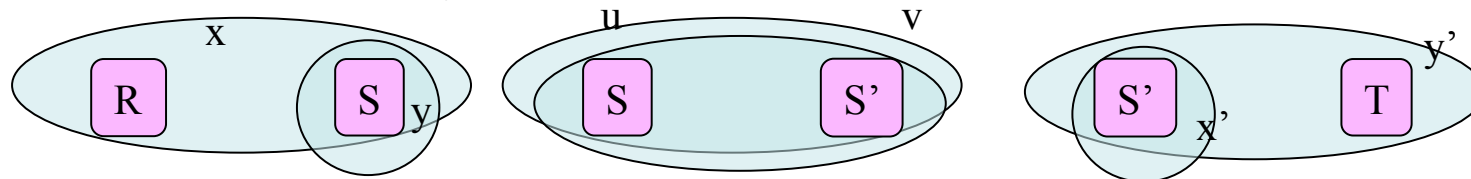
$$hi1 = R(x), S(x,y), S(x',y'), T(y')$$

$x \supset y$ unifies with $x' \subset y'$



$$hi2 = R(x), S(x,y), S(u,v), S'(u,v), S'(x',y'), T(y')$$

$x \supset y$ unifies with $u \equiv v$, which unifies with $x' \subset y'$



The #P-hard Queries

A query with a long inversion:

$$\begin{aligned} \text{hi}_k = & R(\underline{\mathbf{x}}), S_0(\underline{\mathbf{x}}, \underline{\mathbf{y}}), \\ & S_0(\underline{\mathbf{u}}_1, \underline{\mathbf{v}}_1), S_1(\underline{\mathbf{u}}_1, \underline{\mathbf{v}}_1) \\ & S_1(\underline{\mathbf{u}}_2, \underline{\mathbf{v}}_2), S_2(\underline{\mathbf{u}}_2, \underline{\mathbf{v}}_2), \dots \\ & S_k(\underline{\mathbf{x}}', \underline{\mathbf{y}}'), T(\underline{\mathbf{y}}') \end{aligned}$$

The #P-hard Queries

Sometimes inversions are exposed only after making a copy of the query

$$q = R(\underline{x}, \underline{y}), R(\underline{y}, \underline{z})$$

$$\begin{array}{l} R(x, y), R(y, z) \\ R(x', y'), R(y', z') \end{array}$$

Case 3: CQ, independent tables

Let q be hierarchical

$x \subseteq y$ denotes: x is above y in the hierarchy

$x \equiv y$ denotes: $x \subseteq y$ and $y \subseteq x$

Definition An inversion is a chain of unifications:

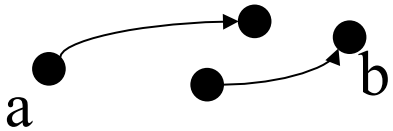
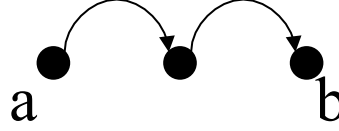


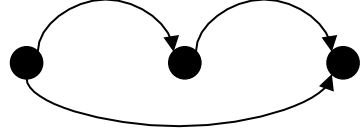
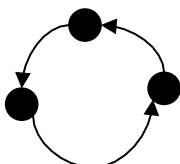
$x \supset y$ with $u_1 \equiv v_1$ with ... with $u_n \equiv v_n$ with $x' \subset y'$

Theorem For all $q \in \text{CQ}$:

If q is non-hierarchical, or has an inversion* then it is #P-hard

Otherwise it is in PTIME

*without “eraser”: see paper.

Query		Complexity	Why
R(a,x), R(y,b)	 <p>A diagram with four nodes. The leftmost node is labeled 'a'. An arrow points from 'a' to a second node. A third node has an arrow pointing to a fourth node labeled 'b'.</p>	PTIME	
R(a,x), R(x,b)	 <p>A diagram with three nodes. The leftmost node is labeled 'a'. An arrow points from 'a' to a middle node. Another arrow points from the middle node to a rightmost node labeled 'b'.</p>	PTIME	
R(x,y), R(y,z)	 <p>A diagram with three nodes. An arrow points from the leftmost node to a middle node. Another arrow points from the middle node to the rightmost node.</p>	#P	Inversion
R(x,y),R(y,z),R(z,u)	 <p>A diagram with four nodes. An arrow points from the leftmost node to a second node. Another arrow points from the second node to a third node. A third arrow points from the third node to the rightmost node.</p>	#P	Non-hierarchical
R(x,y),R(y,z),R(z,x)	 <p>A diagram with three nodes. An arrow points from the leftmost node to a middle node. Another arrow points from the middle node to a rightmost node. A third arrow points from the rightmost node back to the leftmost node, forming a cycle.</p>	#P	Non-hierarchical
R(x,y),R(y,z),R(x,z)	 <p>A diagram with three nodes. An arrow points from the leftmost node to a top node. Another arrow points from the top node to a rightmost node. A third arrow points from the rightmost node back to the leftmost node, forming a cycle.</p>	#P	Non-hierarchical

History

- [Graedel, Gurevitch, Hirsch'98]
 - $L(x,y), R(x,z), S(y), S(z)$ is #P-hard
This is non-hierarchical, with a self-join
- [Dalvi&S'2004]
 - $R(x), S(x,y), T(y)$ is #P-hard
This is non-hierarchical, w/o self-joins
 - Without self-joins: non-hierarchical = #P-hard, and hierarchical = PTIME
- [Dalvi&S'2007]
 - All non-hierarchical queries are #P-hard

Discussion

- Dichotomy theorems
 - Remaining open problems ?
 - Extensions ?
- What role (if any) do ‘safe plans’ in practice ?
 - Only some queries have safe plans, so why bother ?