

CSE 322, Fall 2010

Nondeterministic Finite State Machines

Concatenation

Defn: For any $X, Y \subseteq \Sigma^*$, define

$$X \cdot Y = \{xy \mid x \in X \ \& \ y \in Y\}$$

Ex:

$$X = \{a, ab\}$$

$$Y = \{\epsilon, b, bb\}$$

$$X \cdot Y = \{a, ab, abb, abbb\}$$

$$Y \cdot X = \{a, ab, ba, bab, bba, bbab\}$$

$$\text{note } |X \cdot Y| \leq |X| \cdot |Y|$$

1

2

Power

$$\begin{aligned} L^2 &= L \cdot L \\ L^3 &= L \cdot L \cdot L \\ &\vdots \\ L^1 &= L \\ L^0 &= \{\epsilon\} \end{aligned}$$

$$\forall n \geq 0 \quad L^n = \begin{cases} L \cdot L^{n-1} & \text{if } n \geq 1 \\ \{\epsilon\} & \text{if } n = 0 \end{cases}$$

Eg

$$\begin{aligned} \Sigma^2 &= \{w \mid |w| = 2\} \\ \Sigma^n &= \{w \mid |w| = n\} \\ (\Sigma \cup \{\epsilon\})^n &= \{w \mid |w| \leq n\} \end{aligned}$$

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$$X, Y \subseteq \Sigma^*$$

$$X \cdot Y = \{x \cdot y \mid x \in X \ \& \ y \in Y\}$$

Examples

$$L_{\text{oddparity}} \cdot L_{\text{oddparity}} = L_{\text{even}}$$

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$X, Y \subseteq \Sigma^*$
 $X \cdot Y = \{x \cdot y \mid x \in X \& y \in Y\}$
 Examples
 $L_{\text{odd parity}} \cdot L_{\text{odd parity}} = L_{\text{even}} - \{\epsilon\}$
 $L_{\text{odd parity}} \cdot L_{\text{even}} = L_{\text{odd}}$

$X, Y \subseteq \Sigma^*$
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 Examples
 $L_{\text{odd parity}} \cdot L_{\text{odd parity}} = L_{\text{even}} - \{\epsilon\}$
 $L_{\text{odd parity}} \cdot L_{\text{even}} = L_{\text{odd}}$
 $A \cdot B \stackrel{?}{=} \overset{\uparrow}{\text{refruit}} \overset{\leftarrow}{\text{fruits}} \overset{\uparrow}{\text{Fruit}} \left. \vphantom{A \cdot B} \right\} \text{possible?}$

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 $\Sigma^* \cdot \emptyset = \emptyset \quad \left. \vphantom{\Sigma^* \cdot \emptyset} \right\} \text{yes}$
 $X \cdot Y \stackrel{?}{=} Y \cdot X \quad \left. \vphantom{X \cdot Y} \right\} \text{always?}$

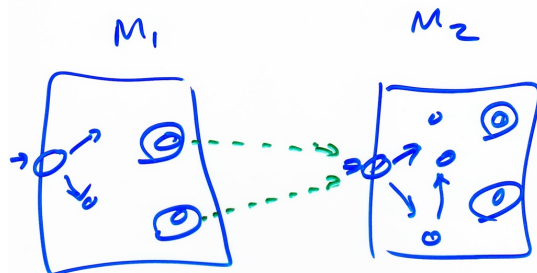
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 $X \cdot Y = \{x \cdot y \mid x \in X \& y \in Y\}$
 Examples
 $L_{\text{odd parity}} \cdot L_{\text{odd parity}} = L_{\text{even}} = \{\epsilon, 0\}^*$
 $L_{\text{odd parity}} \cdot L_{\text{even}} = L_{\text{odd}}$
 $A \cdot B \stackrel{?}{=} C \left[\begin{array}{l} \text{possible?} \\ \text{yes} \end{array} \right.$
 $\Sigma^* \cdot \emptyset = \emptyset$
 $X \cdot Y \stackrel{?}{=} Y \cdot X \left[\begin{array}{l} \text{always?} \\ \text{+ nice?} \\ \text{no} \end{array} \right.$
 $\{0\} \cdot \{1\} \neq \{1\} \cdot \{0\}$

Q:

- Is the class of regular languages closed under concatenation?
- Again, for Java programs, say, it's not too hard to prove this.
- What about finite automata? Inability to back up the input tape is one issue...

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An idea for closure under concatenation, but not clear how to do it – may need to stay in M_1 for several visits to F before jumping to M_2 .

E.g.:

$\{\text{even parity}\} \cdot \{\text{exactly 5 1's}\}$
 which 1 is 5th from end?

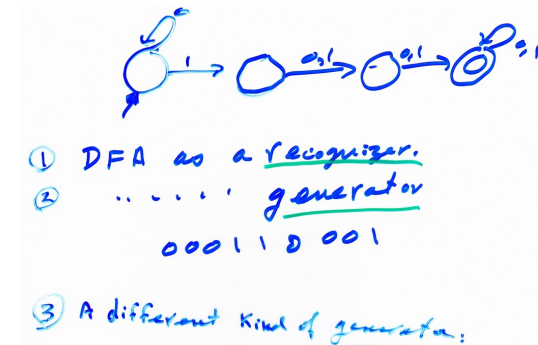


FIGURE 1.27

101, 11
 0101, 011
 00101, 0011
 111101, 11111
 1010, 0110
 10100, 01101

11

12

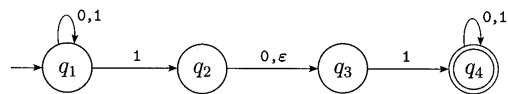
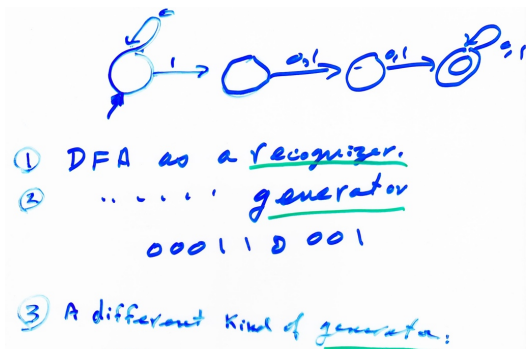


FIGURE 1.27

④ Q. What would it mean/how could we define an equivalent recognizer
 A. Non determinism

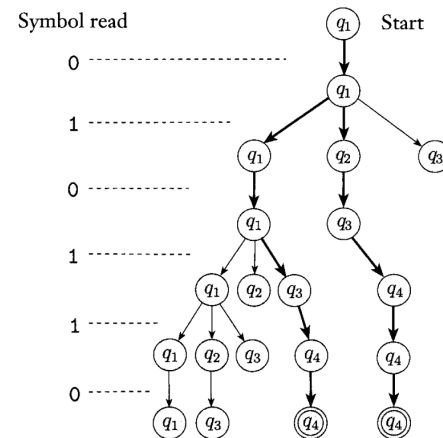
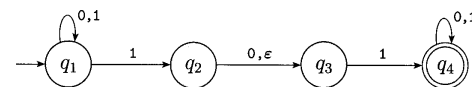


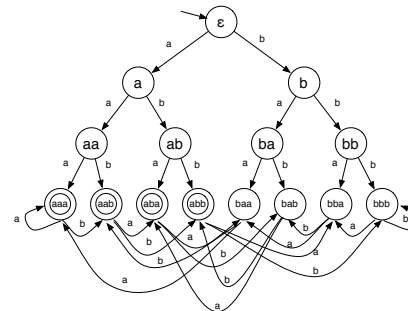
FIGURE 1.29

nondeterministic
 A finite state machine
 $M = (Q, \Sigma, \delta, q_0, F)$
 where finite
 - Q is a set (states)
 - $q_0 \in Q$ start state
 - Σ is a finite set (alphabet)
 - $F \subseteq Q$ Final states
 Accepting state

~~$\delta: Q \times \Sigma \rightarrow Q$ + transition function~~
 $\delta: Q \times (\Sigma \cup \{\epsilon\}) \rightarrow 2^Q$ + transition function

E.g. for $L = \{a^n b^n\}$
 $\delta(q_1, a) = \{q_1\}$
 $\delta(q_1, b) = \{q_1, q_2\}$
 $\delta(q_2, a) = \{q_2\}$

$L = \{w \text{ in } \{a,b\}^* \mid \text{3rd letter from the right end of } w \text{ is "a"}\}$



$L = \{ w \text{ in } \{a,b\}^* \mid \text{3rd letter from the right end of } w \text{ is "a"} \}$

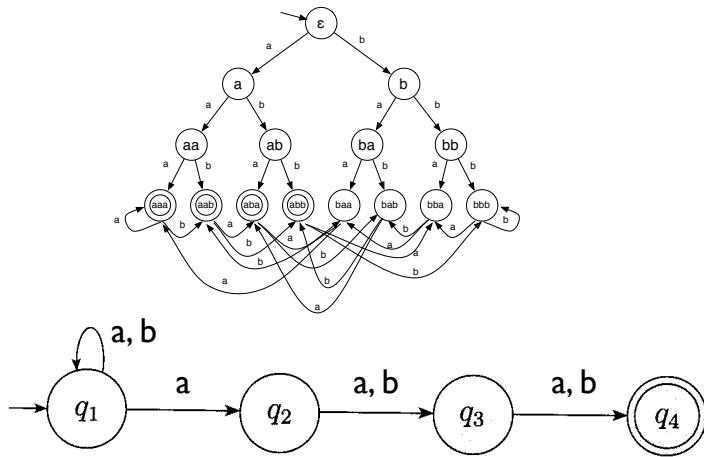


FIGURE 1.31

DEFN ("might be in state g")
M might end in state g after reading $w \in \Sigma^*$ if

- (1) $w = w_1 w_2 \dots w_n$
 where $w_i \in \Sigma \cup \{\epsilon\}$
- (2) \exists state $r_0, r_1, r_2, \dots, r_n \in Q$
 s.t. (a) $r_0 = q_0$
 (b) $\forall 1 \leq i \leq n$
 $r_i \in \delta(r_{i-1}, w_i) = \{r_i\}$
 (c) $r_n = g$

Fact: g is unique because δ is a function, basically.

Defn M accepts $w \in \Sigma^* \iff$ ^{some} the state, g , reached by M after reading w is an accepting state, i.e., $g \in F$.

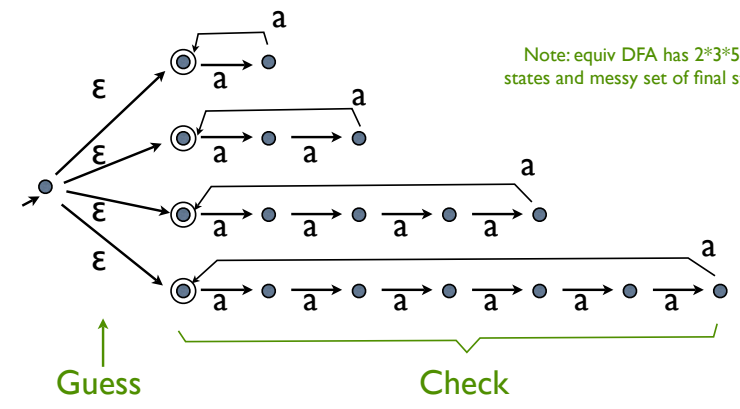
Defn The language recognized by M, $L(M) = \{ w \in \Sigma^* \mid M \text{ accepts } w \}$.

Note Every M recognizes exactly one language. Implicitly, it "recognizes" both strings it must accept and those it must reject.

Very important: note that "might be in a non-final state" does not imply "reject".

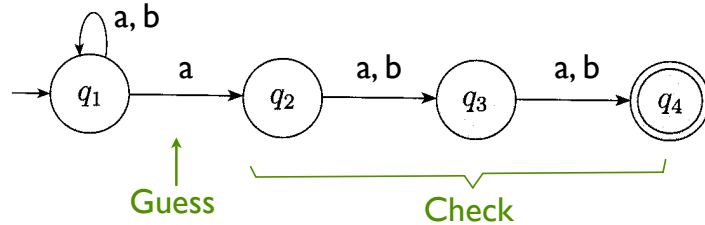
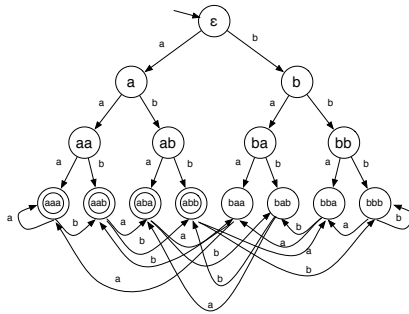
to show M on w :
 Accepts—show one path ending in F
 Rejects—show all paths fail to end in F

Example "guess & check":
 $L = \{ a^n \mid n \text{ is a multiple of } 2, 3, 5 \text{ or } 7 \}$



Note: equiv DFA has $2 \cdot 3 \cdot 5 \cdot 7$ states and messy set of final states

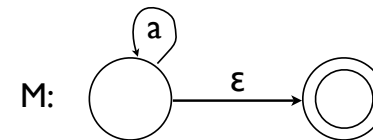
$L = \{ w \text{ in } \{a,b\}^* \mid \text{3rd letter from the right end of } w \text{ is "a"} \}$



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(Non-)Example

$L = \{ a^p \mid p \text{ is prime} \}$



Q: is M deterministic?

Q: Does M accept a^p for every prime p ?

Q: does $L(M) = L$?

Q: but, doesn't it always guess right?

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Nondeterminism: How

- View it as a *generator* of a language
- View it as a *recognizer* of a language
 - “build the tree”
 - explore all paths
 - guess-and-check

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Nondeterminism: Why

- *Specifications*: say, clearly & concisely, *what*, not *how*
- Precise, and often *concise* specification
 - “do A or B, but I don't yet know/don't want clutter of saying which”
 - Sometimes *exponentially* more concise - “3rd letter from end”
- Natural model of incompletely specified/partially known systems
 - if correct wrt a partial spec, then correct wrt *any* implementation consistent with that spec
 - “is state ‘reactor boiling / control rods out’ unreachable, even allowing for unknown behavior of subsystem X”?

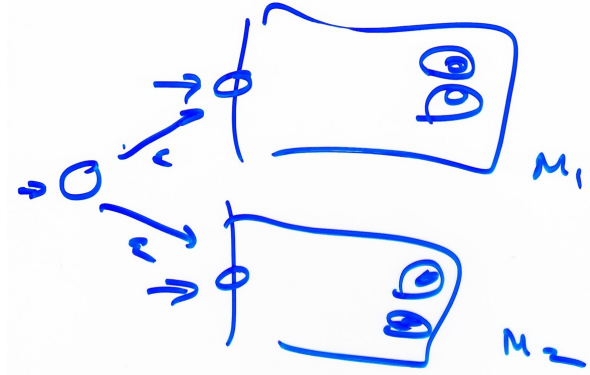
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Kleene Star

- Defn: $L^* = \bigcup_{n \geq 0} L^n$
- Examples
 - Σ^* : a simple special case
 - $L = \{ a^p b \mid p \text{ is prime} \}$
 $L^* = \{ \epsilon \} \cup \{ a^{p_1} b a^{p_2} b \dots b a^{p_k} b \mid k \geq 1, \text{ and each } p_i \text{ is prime} \}$

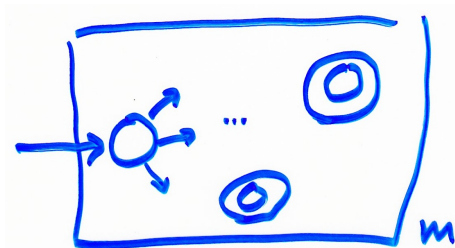
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Closure under union



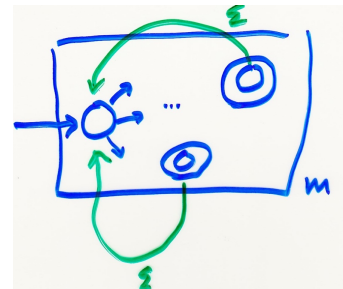
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Given NFA M , can build one for $L(M)^*$?



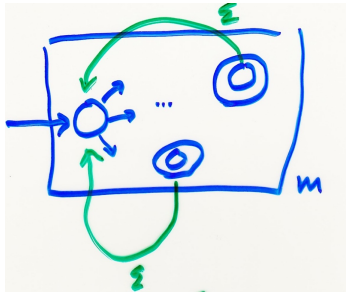
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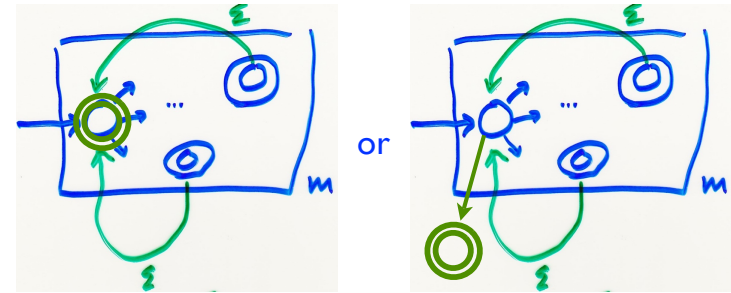
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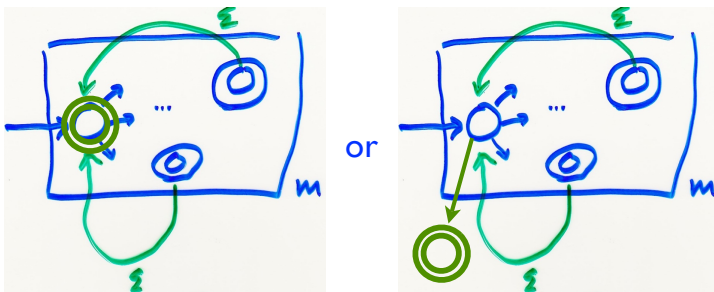


No
(may reject ϵ)

Given NFA M , can build one for $L(M)^*$?

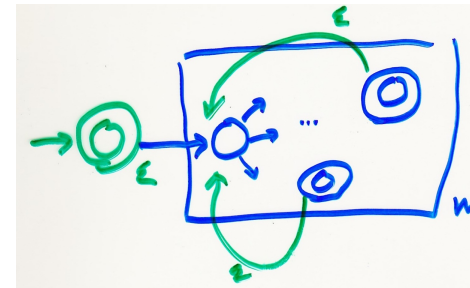


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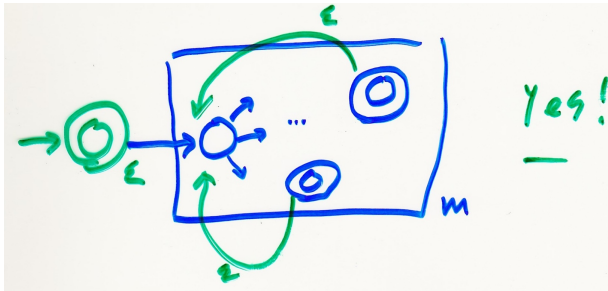


No, may accept extra stuff (if M can loop back to start before reaching F)

Given NFA M , can build one for $L(M)^*$?



Given NFA M , can build one for $L(M)^*$?

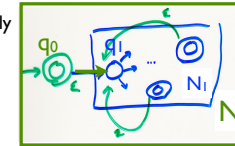


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Closure under $*$

General strategy: such proofs are usually *constructive*, i.e., given a (generic) NFA N_1 , we *construct* a “new” NFA, N . In this case:

[Notation changed slightly to match Thm 1.49 in Sipser; see it for careful description of N vs N_1]

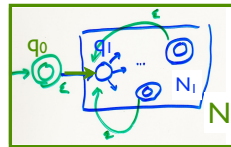


N_1 , “Old”: blue
 N , “New”: blue + green

Then prove the correctness of the construction, i.e., that $L(N) = (L(N_1))^*$. Proof idea: connect computation trace(s) of “old” NFA to ones in “new” NFA, where a “trace” means, recalling the definition of “ M could be in state q after reading w ,” the/a sequence of states/transitions/edges M follows/could follow on some input.

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Closure under $*$, II



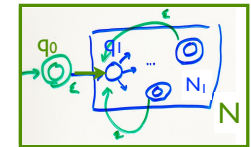
For the correctness proof, there are usually 2 directions, namely: $(L(N_1))^* \subseteq L(N)$ and $L(N) \subseteq (L(N_1))^*$

1) $(L(N_1))^* \subseteq L(N)$, or, equivalently, given any $k \geq 0$ and any k strings x_1, x_2, \dots, x_k , each in $L(N_1)$, show that their concatenation $x_1 \cdot x_2 \cdot \dots \cdot x_k = x$ is in $L(N)$. For this direction, let $r_{i0}, r_{i1}, r_{i2}, \dots, r_{ini}$ be an accepting trace (in N_1) for x_i , $1 \leq i \leq k$. Note $q_1 = r_{i0}$, (why?) and $r_{ini} \in F$ (why?) The key idea is that you can glue these together using the new start state and the new ϵ transitions (green state/arrows) to build an accepting trace in N for x .
 Namely: $q_0, r_{10}, r_{11}, r_{12}, \dots, r_{1n_1}, r_{20}, r_{21}, r_{22}, \dots, r_{2n_2}, \dots, r_{k0}, \dots, r_{kn_k} \in F$. This is a valid accepting trace in N since all transitions in that sequence are either transitions of N_1 , hence in N , or are ϵ transitions from a final state of N_1 to N_1 's start state $q_1 = r_{10} = r_{20} = \dots$, hence again in N . $\therefore x \in L(N)$.

Trace really should be $r_{i0}, a_{i0}, r_{i1}, a_{i1}, \dots$ i.e. alternately $\in Q, \in \Sigma \cup \{\epsilon\}$, but slides are small & I'm being lazy.

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Closure under $*$, III



2) $L(N) \subseteq (L(N_1))^*$, or equivalently, given any x in $L(N)$, show that it can be broken into $k \geq 0$ substrings x_1, x_2, \dots, x_k , (i.e., $x = x_1 \cdot x_2 \cdot \dots \cdot x_k$) so that each is in $L(N_1)$. For this direction, suppose $q_0 = r_0, r_1, r_2, \dots, r_n \in F$ is an accepting trace (in N) for x . Note that $r_1 = q_1$, since the only transition leaving q_0 goes to q_1 (and is labeled ϵ). Let x_1 be the concatenation of all edge labels up to (but excluding) the next green edge (i.e., an ϵ -move from a final state back to q_1). Note that $x_1 \in L(N_1)$, since the *included* transitions are all present in N_1 and run from its start state to a final state, so they are an accepting trace in N_1 . Similarly, let x_2 be the concatenation of all edge labels up to the next green edge, ..., and x_k those after the last green edge. By the same reasoning, each $x_i \in L(N_1)$, for each $1 \leq i \leq k$. Finally, note that $x = x_1 \cdot x_2 \cdot \dots \cdot x_k$ since the excluded transitions are all ϵ -moves. $\therefore x \in (L(N_1))^*$ QED

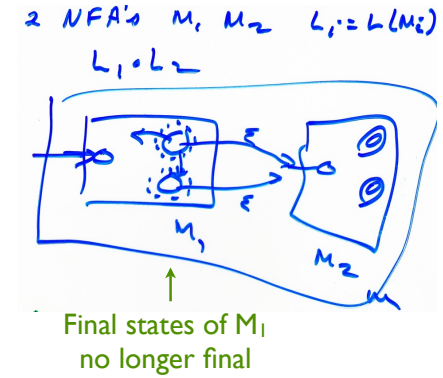
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Closure under *, Leftovers

There are a few points in the proof above that I deliberately didn't address. I strongly suggest that you think about them and see if you can fill in missing details and/or explain why they actually *are* covered, even if not explicitly mentioned. I suggest you *write* it (but no need to turn it in).

- Are $x = \epsilon / k = 0$ correctly handled, or do you need to say more?
- Is it a problem if N_1 's start state is a final state?
- Is it a problem if N_1 includes ϵ -moves from (some or all states in) F to q_1 ?
- Is there anything else I omitted?

Closure under Concatenation



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NFA == DFA, or not?

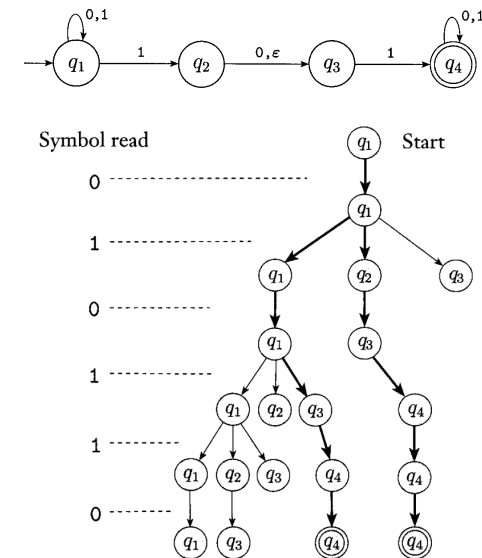


FIGURE 1.29

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Defn M_1 & M_2 equivalent if $L(M_1) = L(M_2)$

Theorem 1.39

\forall nfa $N \exists$ equivalent dfa M

given $N = (Q, \Sigma, \delta, q_0, F)$

build $M = (Q', \Sigma, \delta', q_0', F')$

(warm up: no ϵ -moves)

$$Q' = 2^Q$$

$$q_0' = \{q_0\}$$

$$F' = \{R \subseteq Q \mid R \cap F \neq \emptyset\}$$

$$\forall a \in \Sigma, \forall R \subseteq Q:$$

$$\delta'(R, a) = \bigcup_{r \in R} \delta(r, a)$$

$L = \{w \text{ in } \{a,b\}^* \mid \text{3rd letter from the right end of } w \text{ is "a"}\}$

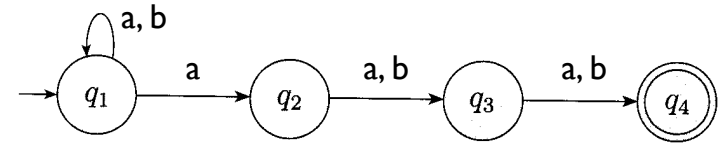
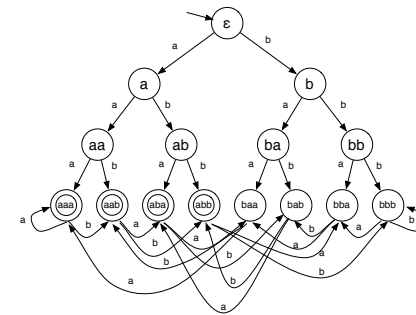
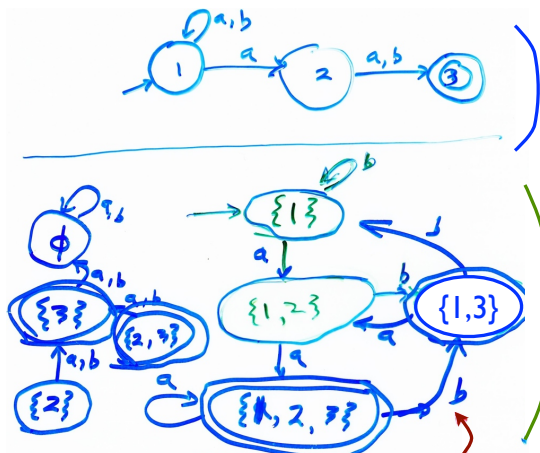


FIGURE 1.31

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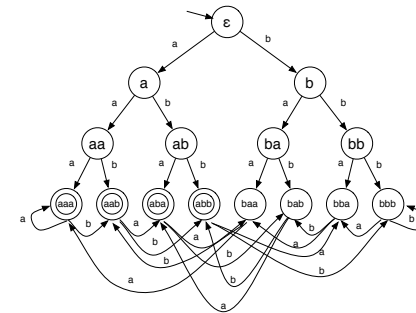


A 3-state NFA

The equivalent $2^3 = 8$ -state DFA, built as in Theorem 1.39 (4 states on left are not reachable from start state but are part of the DFA.)

$\forall a \in \Sigma, \forall R \subseteq Q:$
 $\delta'(R, a) = \bigcup_{r \in R} \delta(r, a)$
 An example transition:
 $\delta'(\{1,2,3\}, b) = \delta(1,b) \cup \delta(2,b) \cup \delta(3,b) = \{1\} \cup \{3\} \cup \emptyset = \{1,3\}$

$L = \{w \text{ in } \{a,b\}^* \mid \text{3rd letter from the right end of } w \text{ is "a"}\}$



Exercise: apply the construction to the NFA below. Note: You will not get the DFA above (but it will be equivalent).

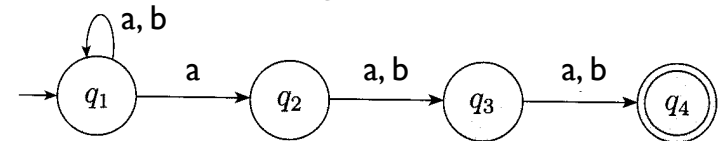


FIGURE 1.31

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The text's assertion that the construction given in the proof of Theorem 1.39 (1st ed: 1.19) is "obviously correct" is a little breezy. Here is an outline of a somewhat more formal correctness proof. I will only handle the case where the NFA has no ϵ -transitions. Notation is as in the book.

For any $x \in \Sigma^*$, define

$$Q_{N,x} = \{r \in Q \mid N \text{ could be in state } r \text{ after reading } x\}, \text{ and}$$

$$Q_{M,x} = \text{the state } R \in Q' \text{ that } M \text{ would be in after reading } x.$$

The key idea in the proof is that these two sets are identical, i.e., that the single state of the DFA faithfully reflects the complete range of possible states of the NFA. The proof is by induction on $|x|$.

BASIS: ($|x| = 0$.) Obviously $x = \epsilon$. Then

$$Q_{N,\epsilon} = \{q_0\} = q'_0 = Q_{M,\epsilon}.$$

The first and third equalities follow from the definitions of "moves" for NFAs and DFAs, respectively, and the middle equality follows from the construction of M .

INDUCTION: ($|x| = n > 0$.) Suppose $Q_{N,y} = Q_{M,y}$ for all strings $y \in \Sigma^*$ with $|y| < n$, and let $x \in \Sigma^*$ be an arbitrary string with $|x| = n > 0$. Since x is not empty, there must be some $y \in \Sigma^*$ and some $a \in \Sigma$ such that $x = ya$. For any $r \in Q$,

- (1) N could be in state r after reading $x = ya$
- \Leftrightarrow there is some $r' \in Q$ such that N could be in r' after reading y and $r \in \delta(r', a)$ (2)
- $\Leftrightarrow r \in \bigcup_{r' \in Q_{N,y}} \delta(r', a)$ (3)

reflects the complete range of possible states of the NFA. The proof is by induction on $|x|$.

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- $\Leftrightarrow r \in \bigcup_{r' \in Q_{N,y}} \delta(r', a)$ (3)
- $\Leftrightarrow r \in \delta'(Q_{N,y}, a)$ (4)
- $\Leftrightarrow r \in \delta'(Q_{M,y}, a)$ (5)
- $\Leftrightarrow r \in Q_{M,x}$ (6)

The equivalence of (1) and (2) follows from the definition of "moves" for NFAs: the last step must be a move from some state reached after reading y . The equivalence of (2) and (3) is just set theory. The equivalence of (3) and (4) follows from the definition of δ' . The equivalence of (4) and (5) follows from the induction hypothesis. The equivalence of (5) and (6) follows from the definition of "moves" for DFAs.

Given the equivalence established above, it's easy to see that $L(N) = L(M)$, since N accepts x if and only if it can reach a final state after reading x , which will be true if and only if $Q_{N,x}$ contains a final state, which happens if and only if $Q_{M,x} \in F'$.

Defn M_1 & M_2 equivalent if $L(M_1) = L(M_2)$

Theorem 1.39

\forall nfa $N \exists$ equivalent dfa M

given $N = (Q, \Sigma, \delta, q_0, F)$

build $M = (Q', \Sigma, \delta', q'_0, F')$

(warm up: no ϵ -moves)

$$Q' = 2^Q$$

$$q'_0 = \{q_0\}$$

$$F' = \{R \subseteq Q \mid R \cap F \neq \emptyset\}$$

$\forall a \in \Sigma, \forall R \subseteq Q:$

$$\delta'(R, a) = \bigcup_{r \in R} \delta(r, a)$$

No ϵ -moves

Defn M_1 & M_2 equivalent if $L(M_1) = L(M_2)$

Theorem 1.39

\forall nfa $N \exists$ equivalent dfa M

given $N = (Q, \Sigma, \delta, q_0, F)$

build $M = (Q', \Sigma, \delta', q'_0, F')$

(warm up: no ϵ -moves) \rightarrow Full version: with ϵ -moves

$$Q' = 2^Q$$

$$q'_0 = E(\{q_0\})$$

$$F' = \{R \subseteq Q \mid R \cap F \neq \emptyset\}$$

$\forall a \in \Sigma, \forall R \subseteq Q:$

$$\delta'(R, a) = \bigcup_{r \in R} E(\delta(r, a))$$

$\forall R \subseteq Q$
 $E(R) = \{q \mid q \text{ reachable by one or more } \epsilon\text{-moves from some } r \in R\}$

~~No ϵ -moves~~

Yes, ϵ -moves.

NB: do ϵ -moves before start, after other moves, not both before & after each move.

