

























(extra space)



















Eveneire	
Exercise	
Use union-by-size. Keep the first argument as root if there's a tie.	
How many nodes does each Find access?	
1. Starting with distinct sets a,b,c,d,e,f,g	
- Union(a,c)	
 Union(b,d) 	
 Union(a,e) 	
 Union(g,h) 	
– Find(c)	
 Union(b,h) 	
 Union(e,f) 	
 Union(f,a) 	
 Union(b,c) 	
- Find(c)	
– Find(h)	
 Find(g) 	
2. Modify the above to also use Path Compression. Does it help?	
3. Using union-by-size, what is the worst case depth of any node? Construct	
a sequence of union operations that produces this for a depth of 5.	





int Find(Object x) {
 // x had better be in
 // the set!
 int xID = hTable[x];
 int i = xID;

// Get the root for
// this set
while(up[xID] != -1) {
 xID = up[xID];
}

// Change the parent for // all nodes along the path while(up[i] != -1) { temp = up[i]; up[i] = xID; i = temp; } return xID; }

(New?) runtime for Find():

Interlude: A Really Slow Function

Ackermann created a <u>really</u> big function A(x, y) with the inverse ? (x, y) which is <u>really</u> small

How fast does ? (x, y) grow? ? (x, y) = 4 for x far larger than the number of atoms in the universe (2³⁰⁰)

? shows up in:

- Computation Geometry (surface complexity)

- Combinatorics of sequences

Complex Complexity of Union-by-Size + Path Compression

Tarjan proved that, with these optimizations, *m* union and find operations on a set of *n* elements have worst case complexity of O(m??(m, n))

For **all** practical purposes this is amortized constant time: $O(m\mathfrak{A})$ for *m* operations!

In some practical cases, one or both optimizations is unnecessary, because trees do not naturally get very deep.

Disjoint Sets ADT Summary

- Also known as Union-Find or Disjoint Set Union/Find
- Simple, efficient implementation – With union-by-size and path compression
- · Great asymptotic bounds
- Kind of weird at first glance, but lots of applications