

| Implementations So Far |  |  |  |
| :---: | :---: | :---: | :---: |
|  | ${ }^{\text {inerr }}$ | ${ }^{\text {find }}$ | detee |
| - Unsored list | ${ }^{\text {O(1) }}$ | $O_{(m)}$ | ${ }^{\text {On }}$ ( |
| - Sored list |  |  |  |
| - Trees | $\mathrm{O}_{\text {(log n) }}$ | O(log n) |  |
| Hovatow (c) in inerrif |  |  |  |



## A Good Hash Function...

..is easy (fast) to compute ( $\mathrm{O}(1)$ and practically fast).
...distributes the data evenly (hash(a) \% size ? hash(b) \% size).
... uses the whole hash table (for all 0 ? k < size, there's an i such that hash(i) $\%$ size = k).

Good Hash Function for Integers

- Choose
- tableSize is prime
$-\operatorname{hash}(\mathrm{n})=\mathrm{n}$
- Example:
- tableSize $=7$
insert(4)
insert(17)
find(12)
insert(9)
delete(17)


## Collisions

- Pigeonhole principle says we can't avoid all collisions
- try to hash without collision $m$ keys into $n$ slots with $m>n$
- e.g., try to put 7 pigeons into 5 holes

- What do we do when two keys hash to the same entry?
- Separate chaining: put little dictionaries in each entry
${ }^{4}$ shove extra pigeons in one hole!
- Open addressing: pick a next entry to try
- Frequency depends on load factor
load factor $?=\frac{\text { \# of entries in table }}{\text { tableSize }}$


Load Factor in Separate Chaining

- Search cost
- unsuccessful search:
- successful search:
- Desired load factor:


## Open Addressing

What if we only allow one Key at each entry?

- two objects that hash to the same spot can't both go there
- first one there gets the spot
- next one must probe for another spot
- Properties
- ? ? 1
- performance degrades with difficulty of finding right spot



## Probing

- Probing how to:
- First probe - given a key k, hash to h(k)
- Second probe - if $h(k)$ is occupied, $\operatorname{try} h(k)+f(1)$
- Third probe - if $h(k)+f(1)$ is occupied, try $h(k)+f(2)$ - And so forth
- Probing properties
- we force $f(0)=0$
- the $i^{\text {th }}$ probe is to $(h(k)+f(i))$ mod size
- When does the probe fail?
- Does that mean the table is full?


## Linear Probing Example



## Load Factor in Linear Probing

- For any ? < 1 , linear probing will find an empty slot
- Search cost (for large table sizes)
- successful search:

$$
\left.\frac{1}{2}\right\}
$$

- unsuccessful search:

$$
\left.\frac{1}{2}\right\}_{1}^{2} ? \frac{1}{?!? ?}{ }^{3} ?
$$

- Linear probing suffers from primary clustering
- Performance quickly degrades for ? > $1 / 2$



## Quadratic Probing Example

| insert(76) | insert(40) <br> $76 \% 7=6$ | insert(48) <br> $40 \% 7=5$ | insert(5) <br> $5 \% 7=5$ | insert(55) <br> $55 \% 7=6$ |
| :---: | :---: | :---: | :---: | :---: |
| 0 |  |  |  |  |
| 1 |  |  |  |  |

## Quadratic Probing Succeeds

(for ? < $1 / 2$ )

- If size is prime and ? $<1 / 2$, then quadratic probing will find an empty slot in size/2 probes or fewer.
- show for all 0 ? $i, j$ ? size/2 and $i$ ? $j$
$\left(\mathrm{h}(\mathrm{x})+\mathrm{i}^{2}\right.$ ) mod size ? ( $\mathrm{h}(\mathrm{x})+\mathrm{j}^{2}$ ) mod size
- by contradiction: suppose that for some i ? j :
$\left(h(x)+i^{2}\right) \bmod$ size $=\left(h(x)+j^{2}\right) \bmod$ size
$i^{2} \bmod$ size $=j^{2} \bmod$ size
$\left(\mathrm{i}^{2}-\mathrm{j}^{2}\right)$ mod size $=0$
$[(i+j)(i-j)] \bmod$ size $=0$
- but how can $i+j=0$ or $i+j=s i z e$ when
i ? jand $\mathbf{i , j}$ ? size/2?
- same for $i-j \bmod$ size $=0$


## Double Hashing <br> $\mathrm{f}(\mathrm{i})=\mathrm{i}$ ? $\mathrm{hash}_{2}(\mathrm{x})$

- Probe sequence is
$-h_{1}(k) \quad \bmod$ size
$-\left(h_{1}(k)+1 ? h_{2}(x)\right)$ mod size
$-\left(h_{1}(k)+2 ? h_{2}(x)\right)$ mod size
- Goal?


## Load Factor in Quadratic Probing

- For any? < $1 / 2$, quadratic probing will find an empty slot; for greater ?, quadratic probing may find a slot
- Quadratic probing does not suffer from primary clustering
- But what about keys that hash to the same spot?


## A Good Double Hash Function...

... is quick to evaluate.
...differs from the original hash function.
...never evaluates to 0 (mod size).

One good choice is to choose a prime $\mathrm{R}<$ size and: $\operatorname{hash}_{2}(\mathrm{x})=\mathrm{R}-(\mathrm{x} \bmod \mathrm{R})$


Deletion with Open Addressing

| insert(7) |  |
| :---: | :---: |
| 00 |  |
| 11 |  |
| 22 |  |
| 3 |  |
| 4 |  |
| 5 |  |
| 6 |  |

- Solution?
- An insert using open addressing cannot work with a load factor of 1 or more.
- An insert using open addressing with quadratic probing may not work with a load factor of $1 / 2$ or more.
- Whether you use separate chaining or open addressing, large load factors lead to poor performance!
- How can we relieve the pressure on the pigeons?
with a


## Rehashing

- When the load factor gets "too large" (over a constant threshold on ?), rehash all the elements into a new, larger table:
- spreads keys back out, may drastically improve performance
- avoids failure for closed hashing techniques
- allows arbitrarily large tables starting from a small table
- clears out lazily deleted items
- Cost?
- Can we just copy over into a bigger array?


## Load Factor in Double Hashing

- For any ? < 1 , double hashing will find an empty slot (given appropriate table size and hash ${ }_{2}$ )
- Search cost appears to approach optimal (random hash):
- successful search: $\frac{1}{?} \ln \frac{1}{1 ? ?}$
- unsuccessful search: $\frac{1}{1 ? ?}$
- No primary clustering and no secondary clustering
- Cost?

The Squished Pigeon Principle

-

## Extendible Hashing

Hashing technique for huge data sets

- Optimizes to reduce disk accesses
- Each hash bucket fits on one disk block
- Better than B-Trees if order is not important - why?

Table contains:

- Buckets, each fitting in one disk block, with the data
- A directory is used to hash to the correct bucket


## Extendible Hash Table

- Directory entry: key prefix (first $k$ bits) and a pointer to the bucket with all keys starting with its prefix
- Each bucket contains keys matching on first $j$ ? $k$ bits, plus the value associated with each key

insert(11011)?
insert(11011)?


## Splitting the Directory

1. insert(10010)

But, no room to insert and no adoption!
2. Solution: Expand directory
3. Then, it's just a normal split.


How to ensure this uncommon?

If Extendible Hashing Doesn't Cut It
Option 1: Store only pointers/references to the items: (key, value) pairs are in disk

Option 2: Improve Hash + Rehash


## Implementations So Far

|  | insert | find | delete |
| :--- | :--- | :--- | :--- |
| - Unsorted list | $\mathrm{O}(1)$ | $\mathrm{O}(\mathrm{n})$ | $\mathrm{O}(\mathrm{n})$ |
| - Sorted list | $\mathrm{O}(\mathrm{n})$ | $\mathrm{O}(\log \mathrm{n}) ?$ | $\mathrm{O}(\mathrm{n})$ |
| - Trees | $\mathrm{O}(\log \mathrm{n})$ | $\mathrm{O}(\log \mathrm{n})$ | $\mathrm{O}(\log \mathrm{n})$ |
| - Hash Table | $\mathrm{O}(1)$ | $\mathrm{O}(1)$ | $\mathrm{O}(1)$ |

Is there anything a hash table can't do fast?

