## Pointers and Lists

CSE 326
Data Structures
Unit 2

Reading: Section 3.2 The List ADT

## Records and Pointers

- Record (also called a struct)
, Group data together that are related
x : complex pointer
real_part : real
imaginary_part : real
, To access the fields we use "dot" notation.
X.real_part
X.imaginary_part


## Basic Types and Arrays

- Basic Types
, integer, real (floating point), boolean ( 0,1 ), character
- Arrays
, A[0..99] : integer array



## Record Definition

- Record definition creates a new type Definition
record complex : ( real_part : real,
imaginary_part : real
)
Use in a declaration
X : complex


## Pointer

- A pointer is a reference to a variable or record (or object in Java world).

- In C, if $X$ is of type pointer to $Y$ then * $X$ is of type Y


## Simple Linked List

- A linked list
, Group data together in a flexible, dynamic way.
, We'll describe several list ADTs later.

record node : (
data : integer,
next : node pointer
)


## Creating a Record

- We use the "new" operator to create a record.

```
P : pointer to blob;
\({ }_{P} \square\) (null pointer)
```

P := new blob;


Sparse Polynomials

- $10+4 x^{2}+20 x^{40}+8 x^{86}$


Exponents in Increasing order

| record poly : $($ |  |
| :--- | :--- |
| exp |  |
| exp : integer, |  |
| coef : integer, |  |
| next : poly pointer |  |
| coef |  |
| next |  |

Identically Zero Polynomial

$$
\begin{aligned}
& \mathrm{P} \square \\
& \quad \text { null pointer } \\
& \mathrm{P} \square \\
& \square \\
& \hline
\end{aligned}
$$

## Addition of Polynomials

$$
10+4 x^{2}+20 x^{40}+8 x^{86}
$$


$7 x+10 x^{2}-8 x^{86}$


## Recursive Addition

```
Add(P, Q : poly pointer): poly pointer{
R : poly pointer
    case {
        P = null : R := Q ;
        Q = null : R := P ;
        P.exp < Q.exp : R := P
        R.next := Add(P.next,Q);
        P.exp > Q.exp : R := Q
        R.next := Add(P,Q.next)
            P.exp = Q.exp : R := P ;
                        R.coef := P.coef + Q.coef ;
                        R.next := Add(P.next,Q.next);
        }
        return R
}
```

Example (first call)


## During the Recursive Call

Add


Represent return values

## The Recursive Call



## After the Recursive Call



## The final picture



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## Unneeded nodes to Garbage

- How would you force the unneeded node to be garbage in the code on slide 11?
- Suggestions?


## Notes on Addition

- Addition is destructive, that is, the original polynomials are gone after the operation.
- We don’t salvage "garbage" nodes. Let's talk about this.
- We don't consider the case when the coefficients cancel. Let's talk about this.


## Memory Management Global Allocator

- Global Allocator's store - always get and return blocks to global allocator an area in the memory from which we can dynamically allocate memory.
- The user (the program) must 'free' the memory when done.


## Memory Management Garbage Collection

- Garbage collection - run time system recovers inaccessible blocks from time-to-time. Used in Lisp, Smalltalk, Java.
+ No need to return blocks to an allocator.
- Care must be taken to make unneeded blocks inaccessible.
- When garbage collection kicks in there may be undesirable response time.


## Use of <br> Global Allocator

```
P.exp = Q.exp : R := P ;
    R.coef := P.coef + Q.coef ;
    if R.coef = 0 then
        R := Add(P.next,Q.next);
        Free(P); Free(Q);
    else
        R.next := Add(P.next,Q.next);
        Free(Q);
```

\}

## Simple Examples of List Use

- Polynomials
, $25+4 x^{2}+75 x^{85}$
- Unbounded Integers
, 4576809099383658390187457649494578
- Text
, "This is an example of text"


Unbounded Integers Base 10


- 348
$Y$ : node pointer



## List Implementations

- Two types of implementation:
, Array-Based
, Pointer-Based


## List: Array Implementation

## List: Array Implementation

- Basic Idea:
, Pre-allocate a big array of size MAX_SIZE
, Keep track of current size using a variable count
, Shift elements when you have to insert or delete

| 0 | 1 | 2 | 3 | $\cdots$ | count-1 |  | MAX_SIZE-1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{A}_{1}$ | $\mathrm{~A}_{2}$ | $\mathrm{~A}_{3}$ | $\mathrm{~A}_{4}$ | $\cdots$ | $\mathrm{~A}_{\mathrm{N}}$ |  |  |

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| Insert Z in 3rd position $\Omega$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 1 | 2 | 3 | 4 | 5 |  | MAX_SIZE-1 |
| A | B | C | D | E | F |  |  |
|  |  | $\square$ |  | $\checkmark$ |  |  |  |
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | MAX_SIZE-1 |
| A | B | Z | C | D | E | F |  |

## Array List Insert Running Time

- Running time for a list with N elements?
- On average, must move half the elements to make room - assuming insertions at positions are equally likely
- Worst case is insert at position 0 . Must move all N items one position before the insert
- This is $\mathrm{O}(\mathrm{N})$ running time. Probably too slow
- On the other hand - we can access the kth item in $O(1)$.


## List: Pointer Implementation

- Basic Idea:
, Allocate little blocks of memory (nodes) as elements are added to the list
, Keep track of list by linking the nodes together
, Change links when you want to insert or delete



## Pointer-based Insert (after p)



Insert the value $\mathbf{v}$ after $\mathbf{P}$
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Linked List with Header Node


Advantage: "insert after" and "delete after" can be done at the beginning of the list.

## Insertion After

```
InsertAfter(p : node pointer, v : value_type): {
    x : node pointer;
    x := new node;
    x.value := v;
    x.next := p.next;
    p.next := x;
}
Note: cannot swap two last lines (why?)
```


## Pointer Implementation Issues

- Whenever you break a list, your code should fix the list up as soon as possible
, Draw pictures of the list to visualize what needs to be done
- Pay special attention to boundary conditions:
, Empty list
, Single item - same item is both first and last
, Two items - first, last, but no middle items
, Three or more items - first, last, and middle items


## Pointer List Insert Running Time

- Running time for a list with N elements?
- Insert takes constant time (O(1))
- Does not depend on list size
- Compare to array based list which is $\mathrm{O}(\mathrm{N})$


## Delete After

```
DeleteAfter(p : node pointer): {
    temp : node pointer;
    temp = p.next;
    p.next = temp.next; //p.next.next
    free(temp);
\}
```

Note: p points to the node that comes before the deleted node!
temp - the node to be removed.

## Doubly Linked Lists

- findPrevious (and hence Delete) is slow [O(N)] because we cannot go directly to previous node
- Solution: Keep a "previous" pointer at each node



## Reverse a linked list

```
Reverse(t : node pointer): node pointer {
    rev : node pointer;
    temp: node pointer;
    rev = NULL;
    while(t !=NULL) {
        temp = t.next;
        t.next = rev;
        rev = t;
        t = temp;
    }
    return (rev); rev: the 'already reversed' part.
}
```



```
    Why do we need temp?
```


## Double Link Pros and Cons

- Advantage
, Delete (not DeleteAfter) and FindPrev are faster
- Disadvantages:
, More space used up (double the number of pointers at each node)
, More book-keeping for updating the two pointers at each node (pretty negligible overhead)


## Implementing Pointers in Arrays - "Cursor Implementation"

- This is needed in languages like Fortran, Basic, and assembly language
- Easiest when number of records is known ahead of time.
- Each record field of a basic type is associated with an array.
- A pointer field is an unsigned integer indicating an array index.


## Idea

| Pointer World | Nonpointer World |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | D | N |  |
| n nodes | 1 |  |  | - D[ ] : basic type array |
| data next | 2 |  |  | - N[ ] : integer array |
|  |  |  |  | - Pointer is an integer |
| data next | 3 |  |  | - null is 0 |
|  | 4 |  |  | - p.data is $\mathrm{D}[\mathrm{p}]$ |
| data : basic type | 5 |  | - | - p.next is $N[p]$ |
| next : node pointer |  |  |  | - Free list needed for node |
|  |  |  |  | allocation |
|  | n |  |  |  |

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## Example of Use

$\mathrm{L}_{\square}|\mathrm{a} \rightarrow \mathrm{b}| \rightarrow \mathrm{c} \mid \longrightarrow$ null
$\mathrm{n}=8$


```
InsertFront(L : integer, x : basic type) {
```

    q : integer
    if not(Free \(=0\) ) then \(q\) := Free
        else return "overflow";
    Free := N[Free];
    D[q] := x;
    \(\mathrm{N}[\mathrm{q}]:=\mathrm{L}\)
    \(\mathrm{L}:=\mathrm{q}\);
    \}

## Initialization

Free $=n$

| D |  |
| :---: | :---: |
| 1 |  |
| 2 |  |
| 3 |  |
| 4 |  |
| 5 | - |
| . |  |
| . |  |
| n |  |

## Try DeleteFront

- Define the cursor implementation of DeleteFront which removes the first member of the list when there is one.
, Remember to add garbage to free list.

```
DeleteFront(L : integer) {
???
}
```


## DeleteFront Solution

```
DeleteFront(L : integer) {
    q : integer;
    if L = 0 then return "underflow"
    else {
        q := L;
        L := N[L];
        N[q] := Free;
        Free := q;
    }
}
```

