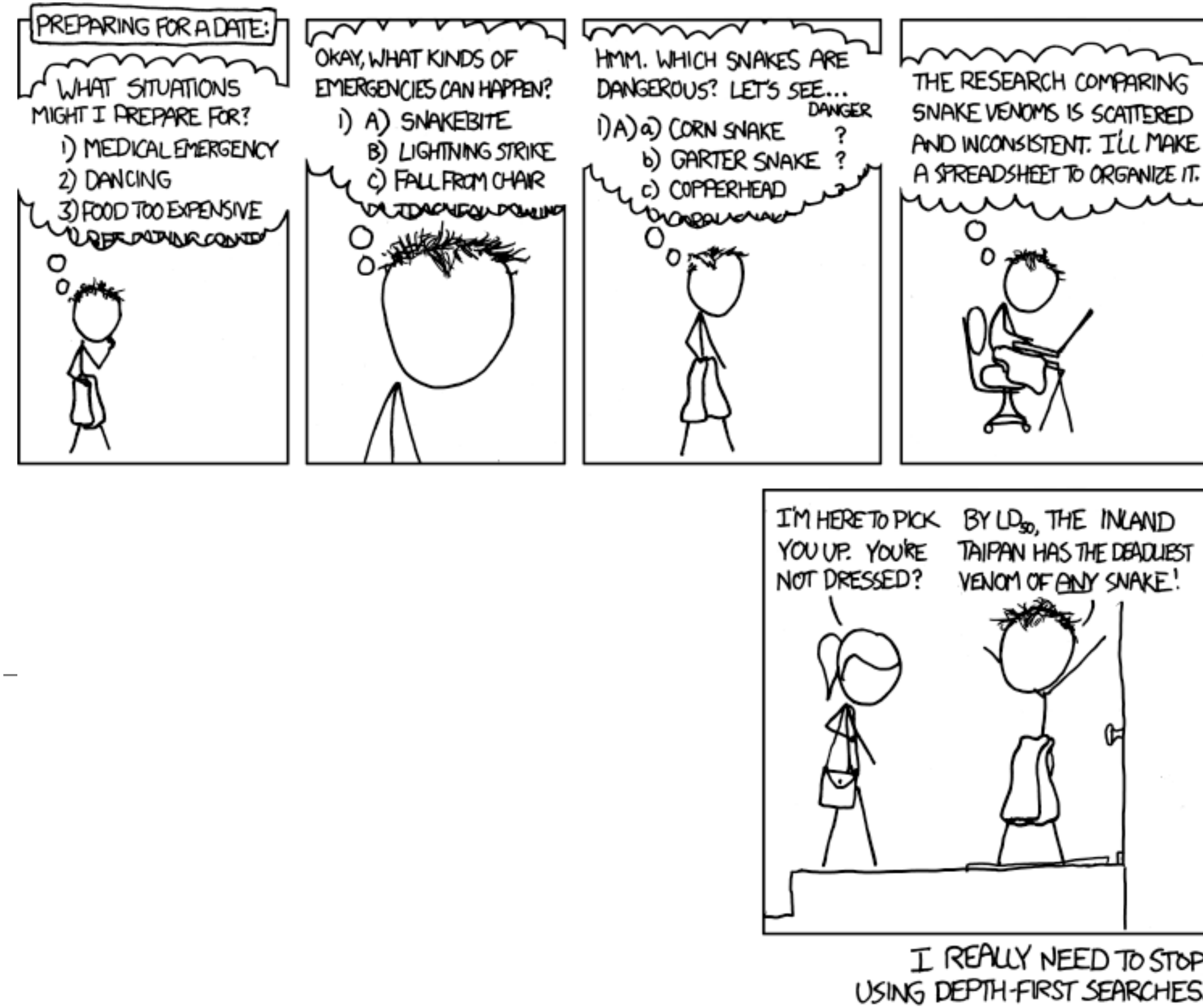
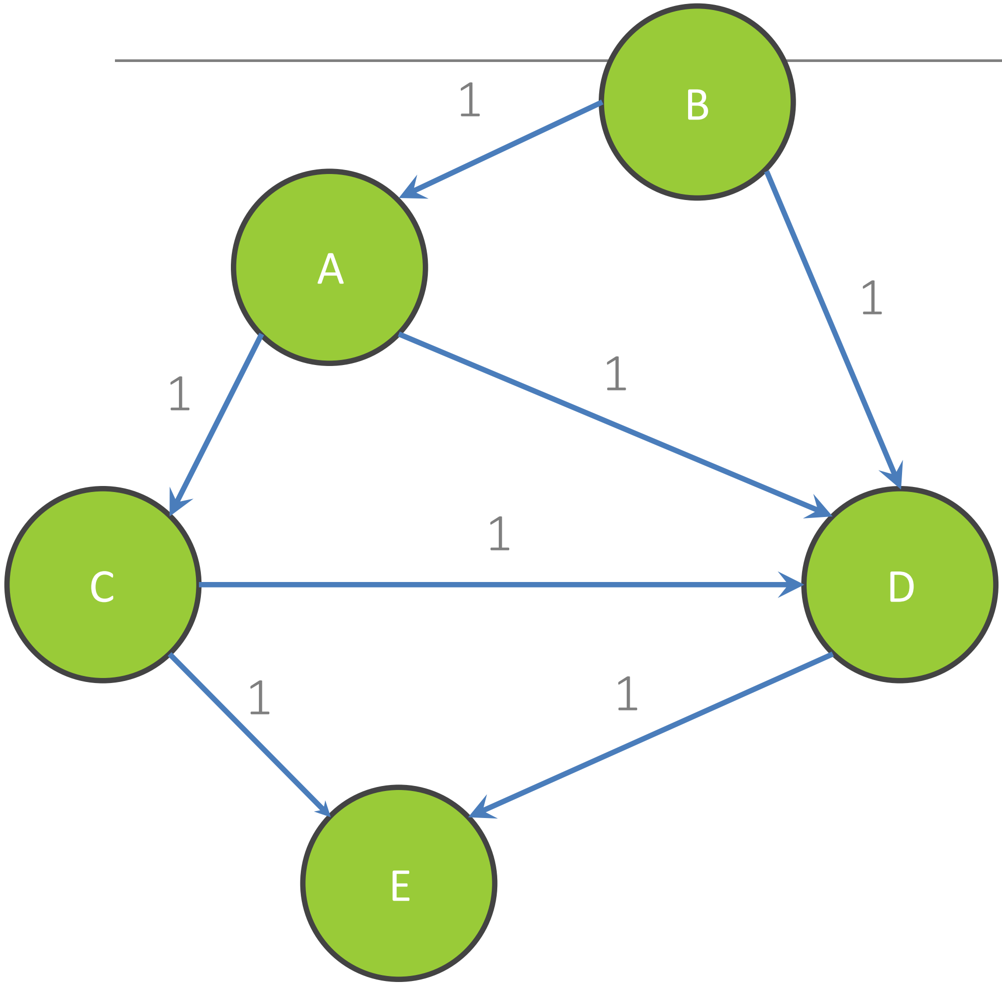

PREPARING FOR A DATE:
WHAT SITUATIONS MIGHT I PREPARE FOR?
1) MEDICAL EMERGENCY
2) DANCING
3) FOOD TOO EXPENSIVE
OKAY, WHAT KINDS OF EMERGENCIES CAN HAPPEN?
1) A) SNAKEBITE
B) LIGHTNING STRIKE
C) FALL FROM CHAIR
HMM. WHICH SNAKES ARE DANGEROUS? LET'S SEE...
DANGER
1) A) a) CORN SNAKE ?
b) GARTER SNAKE ?
c) COPPERHEAD ?
THE RESEARCH COMPARING SNAKE VENOMS IS SCATTERED AND INCONSISTENT. I'LL MAKE A SPREADSHEET TO ORGANIZE IT.
I'M HERE TO PICK YOU UP. YOU'RE NOT DRESSED?
BY LD$_{50}$, THE INLAND TAIPAN HAS THE DEADLIEST VENOM OF ANY SNAKE!
I REALLY NEED TO STOP USING DEPTH-FIRST SEARCHES.

Section 6:
Dijkstra's Algorithm

SLIDES ADAPTED FROM ALEX MARIAKAKIS

WITH MATERIAL KELLEN DONOHUE, DAVID MAILHOT, AND DAN GROSSMAN

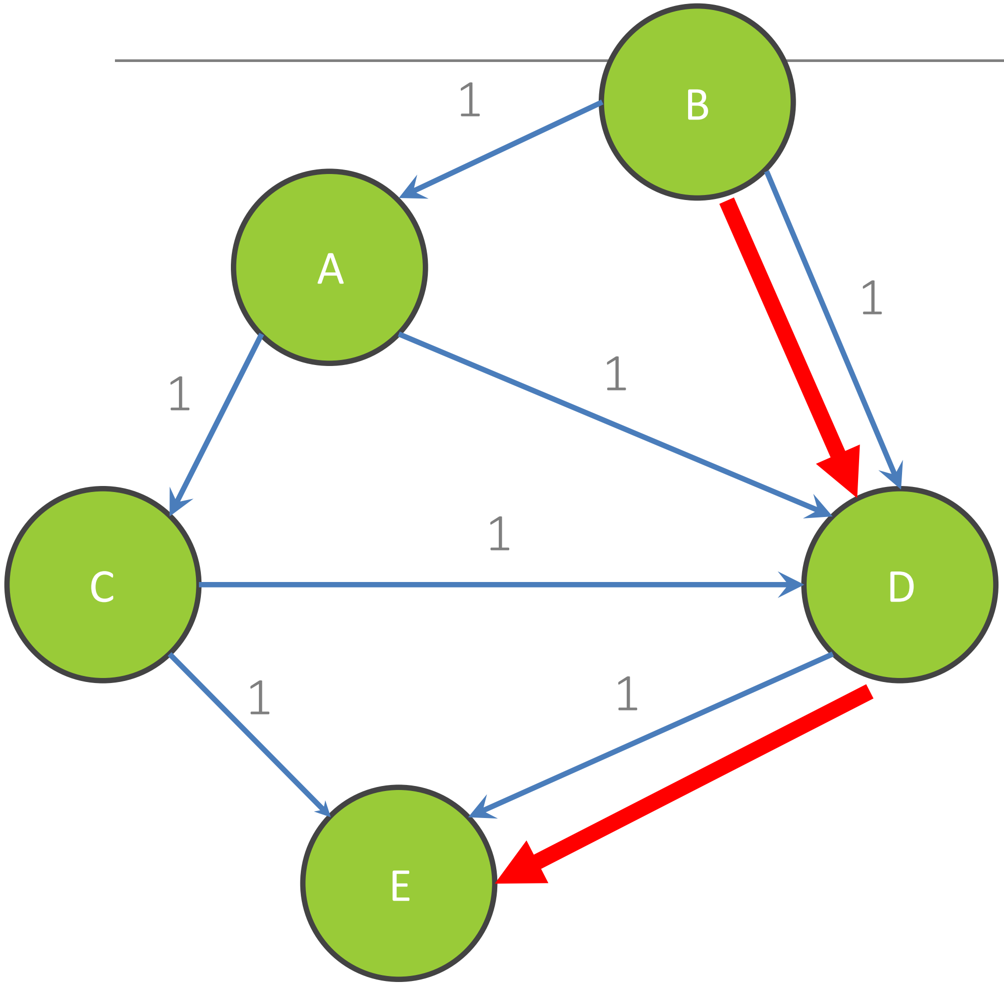
Review: Shortest Paths with BFS



From Node B

Destination	Path	Cost
A	<B,A>	1
B	<B>	0
C	<B,A,C>	2
D	<B,D>	1
E	<B,D,E>	2

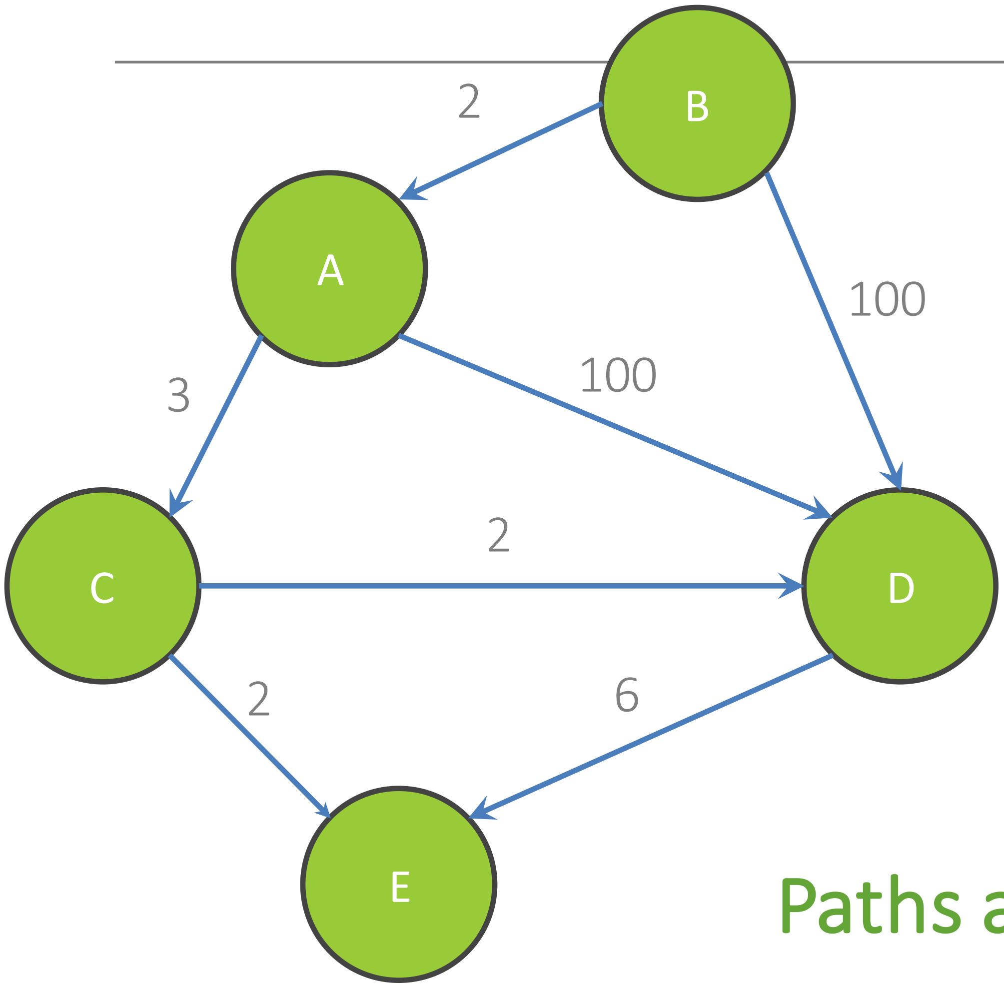
Review: Shortest Paths with BFS



From Node B

Destination	Path	Cost
A	<B,A>	1
B	<B>	0
C	<B,A,C>	2
D	<B,D>	1
E	<B,D,E>	2

Shortest Paths with Weights

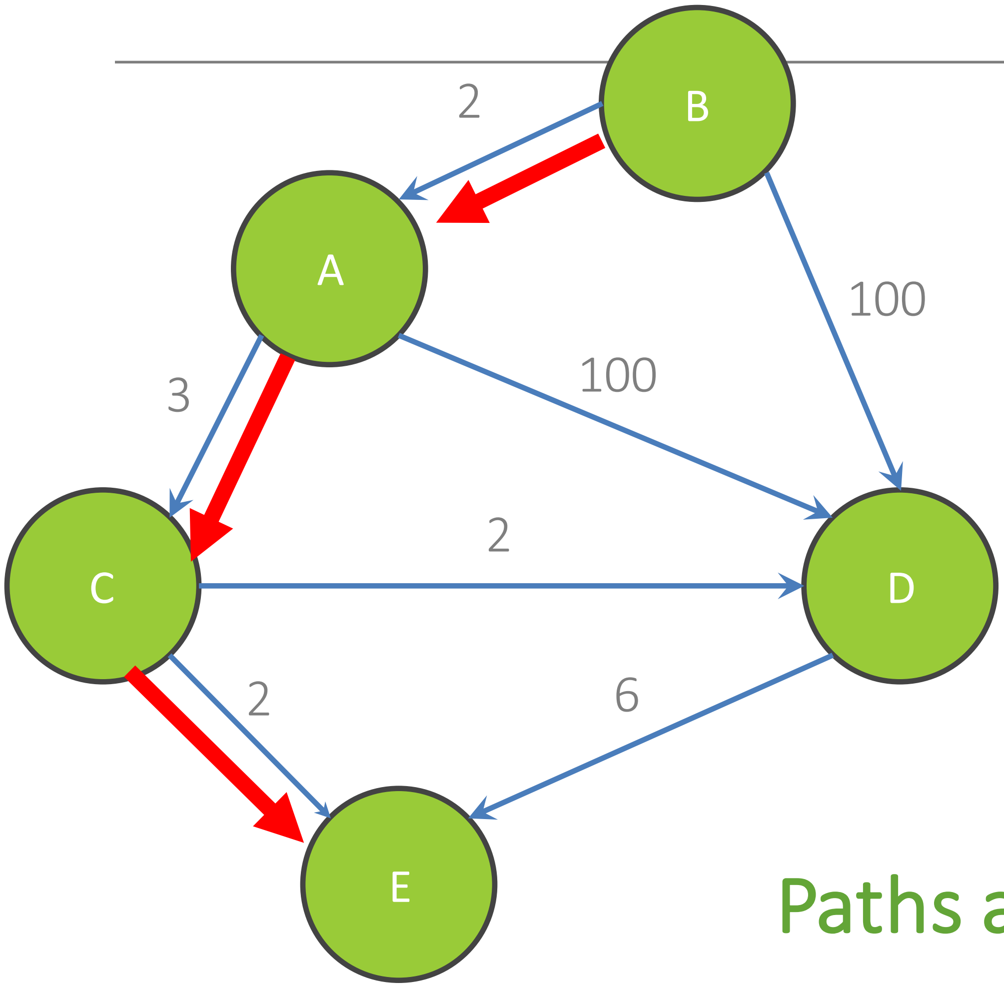


From Node B

Destination	Path	Cost
A	<B,A>	2
B	<B>	0
C	<B,A,C>	5
D	<B,A,C,D>	7
E	<B,A,C,E>	7

Paths are not the same!

Shortest Paths with Weights



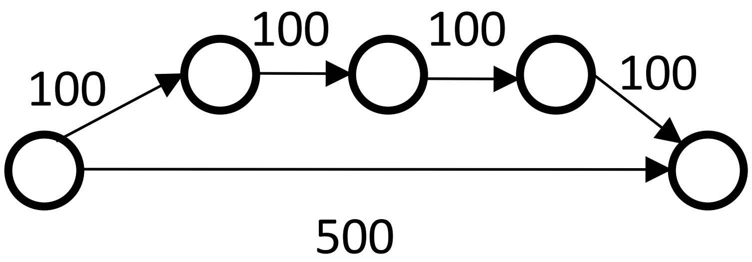
From Node B

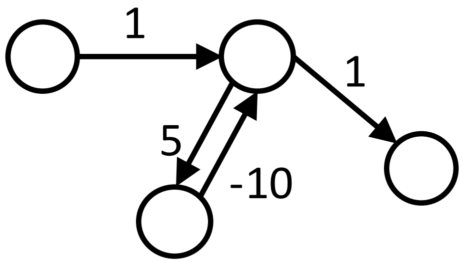
Destination	Path	Cost
A	<B,A>	2
B	<B>	0
C	<B,A,C>	5
D	<B,A,C,D>	7
E	<B,A,C,E>	7

Paths are not the same!

Goal: Smallest cost? Or fewest edges?

BFS vs. Dijkstra's





BFS doesn't work because path with minimal cost ≠ path with fewest edges

Also, Dijkstra's works if the weights are non-negative

What happens if there is a negative edge?

- Minimize cost by repeating the cycle forever

Dijkstra’s Algorithm

Named after its inventor Edsger Dijkstra (1930-2002)

- Truly one of the “founders” of computer science;
- This is just one of his many contributions

The idea: reminiscent of BFS, but adapted to handle weights

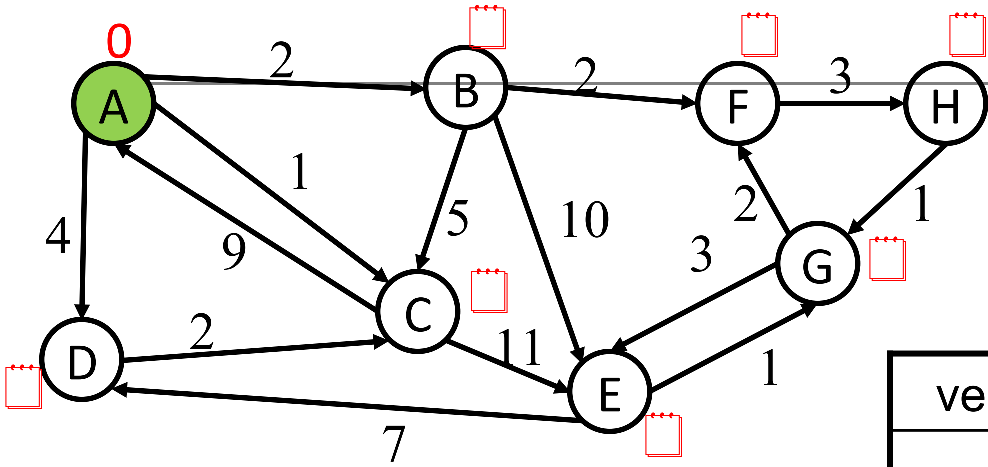
- Grow the set of nodes whose shortest distance has been computed
- Nodes not in the set will have a “best distance so far”
- A **PRIORITY QUEUE** will turn out to be useful for efficiency – We’ll cover this later in the slide deck

Dijkstra's Algorithm

1. For each node `v`, set `v.cost = ∞` and `v.known = false`
2. Set `source.cost = 0`
3. While there are unknown nodes in the graph
   a) Select the unknown node `v` with lowest cost
   b) Mark `v` as known
   c) For each edge `(v,u)` with weight `w`,

```
c1 = v.cost + w // cost of best path through v to u
c2 = u.cost     // cost of best path to u previously known
if(c1 < c2)     // if the new path through v is better,update
     u.cost = c1
     u.path = v
```

Example #1

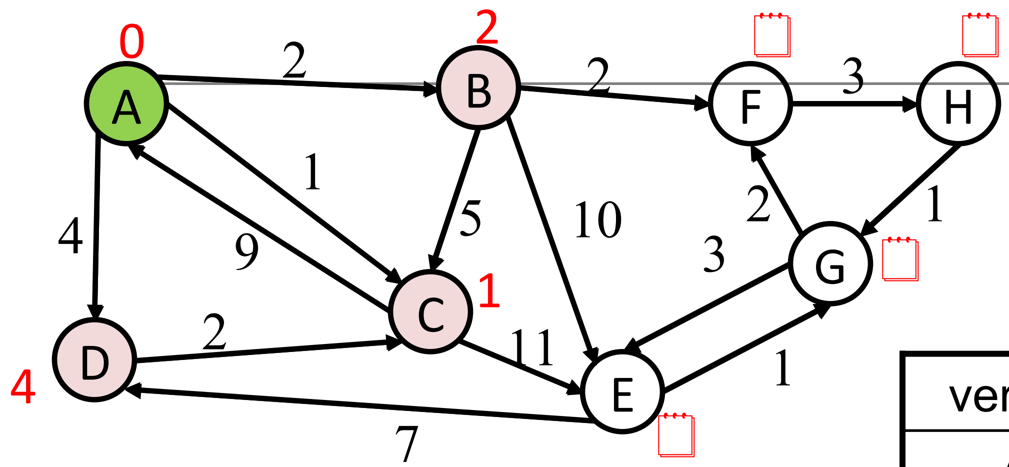


Goal: Fully explore the graph

vertex	known?	cost	path
A	Y	0	
B		∞	
C		∞	
D		∞	
E		∞	
F		∞	
G		∞	
H		∞	

Order Added to Known Set:

Example #1

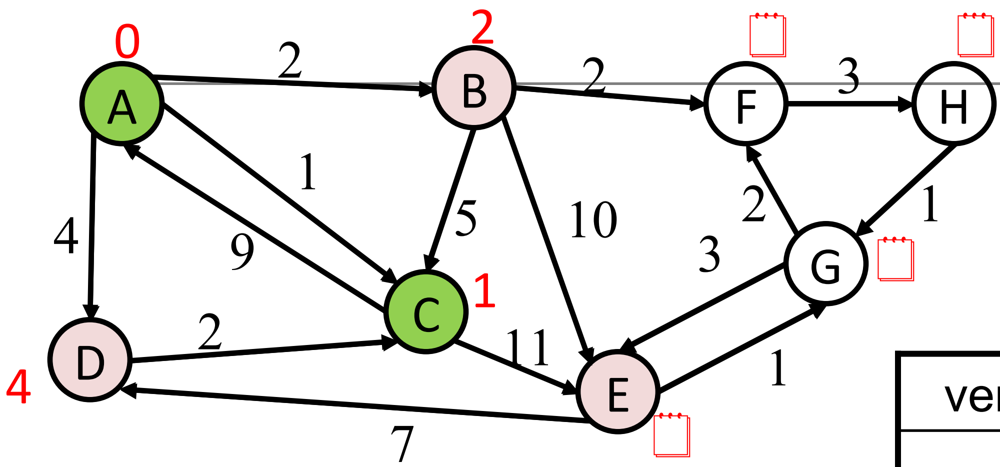


vertex	known?	cost	path
A	Y	0	
B		≤ 2	A
C		≤ 1	A
D		≤ 4	A
E		∞	
F		∞	
G		∞	
H		∞	

Order Added to Known Set:

A

Example #1

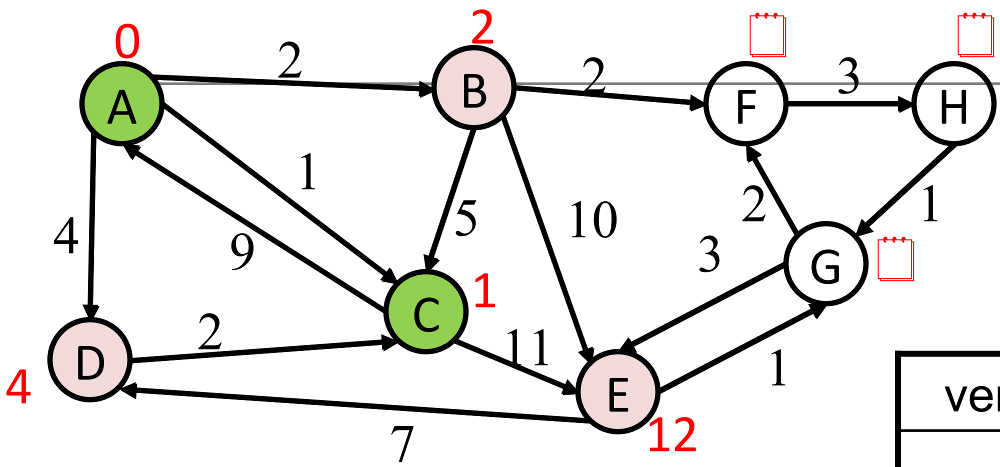


vertex	known?	cost	path
A	Y	0	
B		≤ 2	A
C	Y	1	A
D		≤ 4	A
E		∞	
F		∞	
G		∞	
H		∞	

Order Added to Known Set:

A, C

Example #1

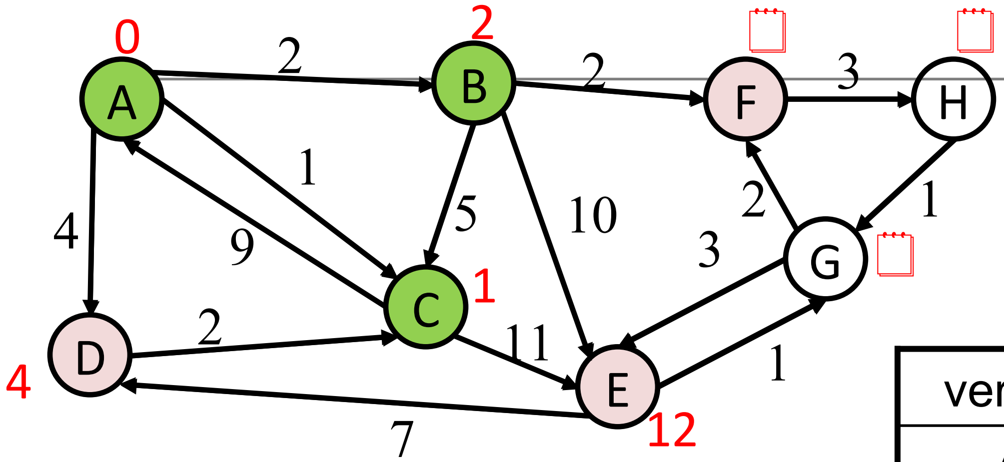


vertex	known?	cost	path
A	Y	0	
B		≤ 2	A
C	Y	1	A
D		≤ 4	A
E		≤ 12	C
F		∞	
G		∞	
H		∞	

Order Added to Known Set:

A, C

Example #1

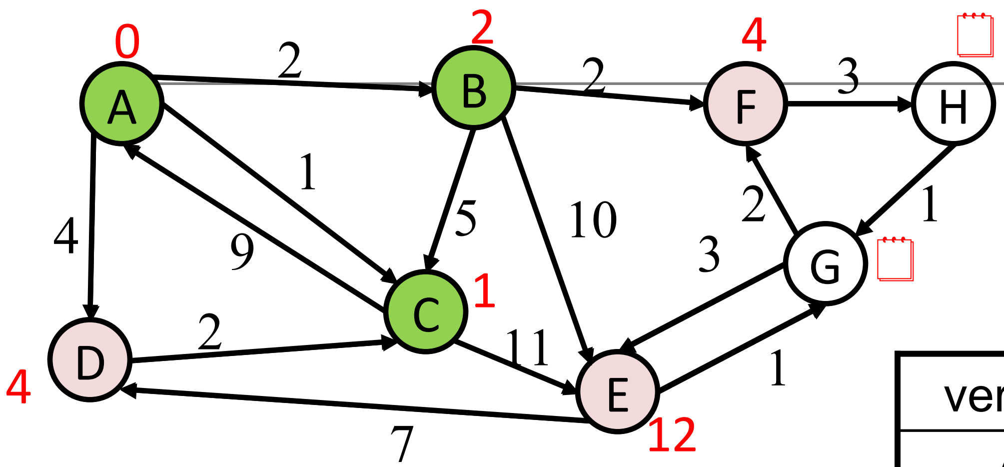


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D		≤ 4	A
E		≤ 12	C
F		∞	
G		∞	
H		∞	

<u>Order Added to Known Set:</u>

A, C, B

Example #1

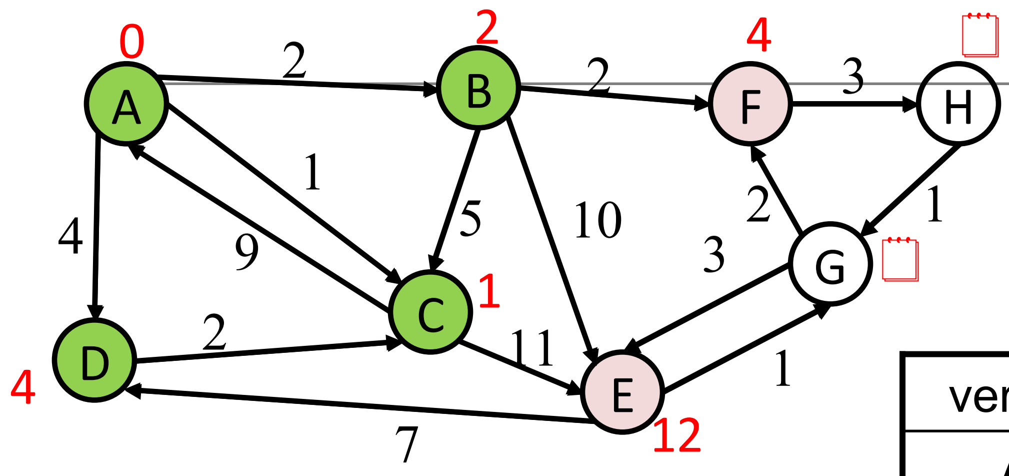


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D		≤ 4	A
E		≤ 12	C
F		≤ 4	B
G		∞	
H		∞	

Order Added to Known Set:

A, C, B

Example #1

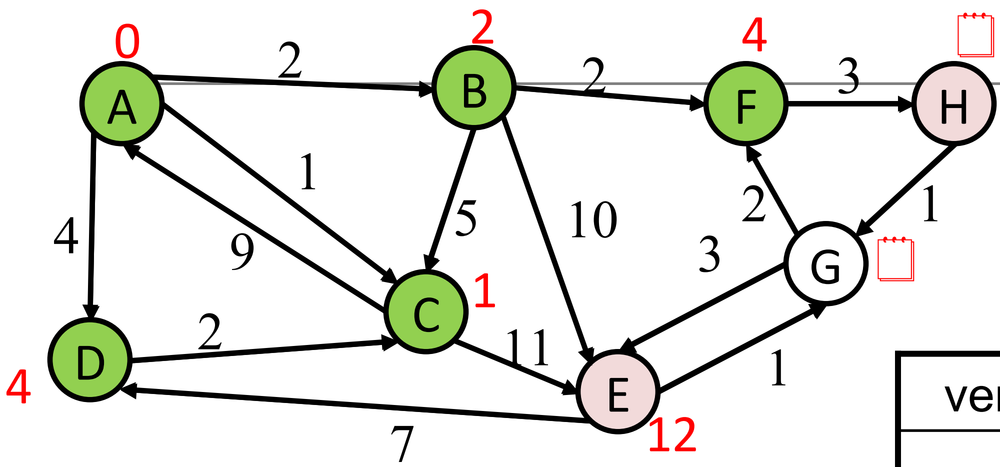


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E		≤ 12	C
F		≤ 4	B
G		∞	
H		∞	

<u>Order Added to Known Set:</u>

A, C, B, D

Example #1

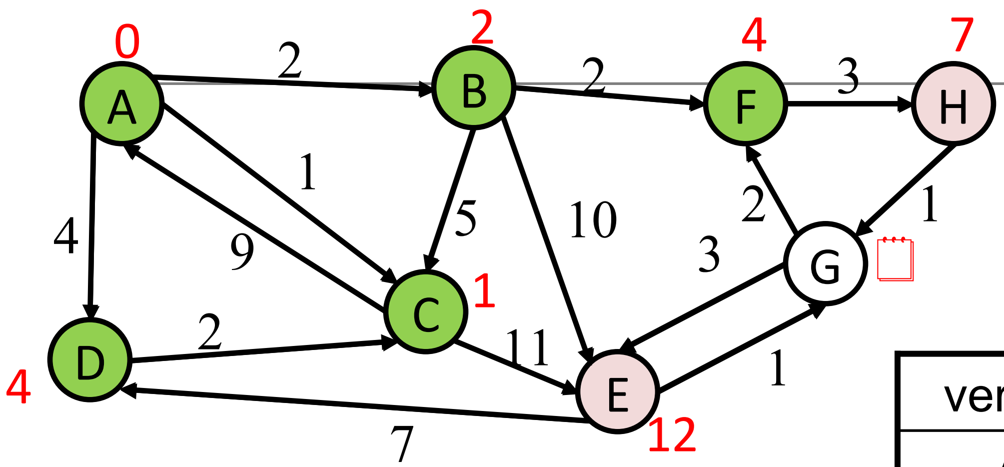


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E		≤ 12	C
F	Y	4	B
G		∞	
H		∞	

Order Added to Known Set:

A, C, B, D, F

Example #1

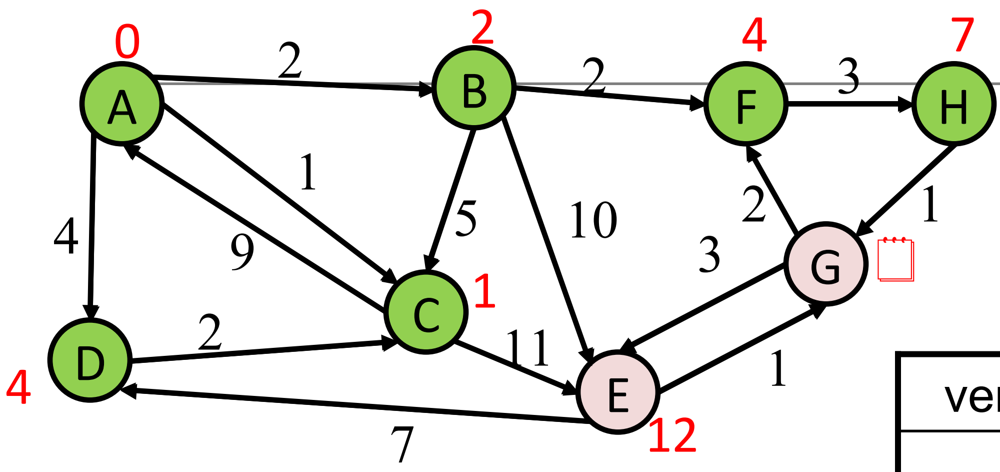


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E		≤ 12	C
F	Y	4	B
G		∞	
H		≤ 7	F

<u>Order Added to Known Set:</u>

A, C, B, D, F

Example #1

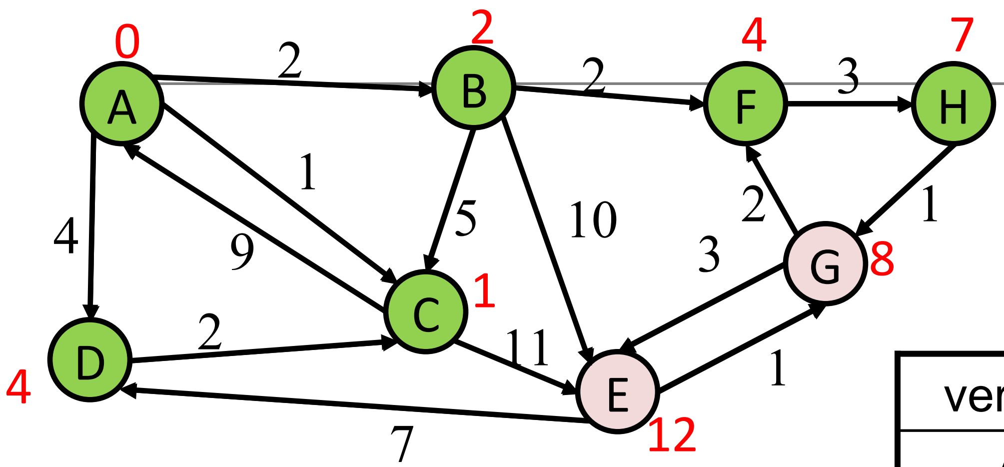


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E		≤ 12	C
F	Y	4	B
G		∞	
H	Y	7	F

<u>Order Added to Known Set:</u>

A, C, B, D, F, H

Example #1

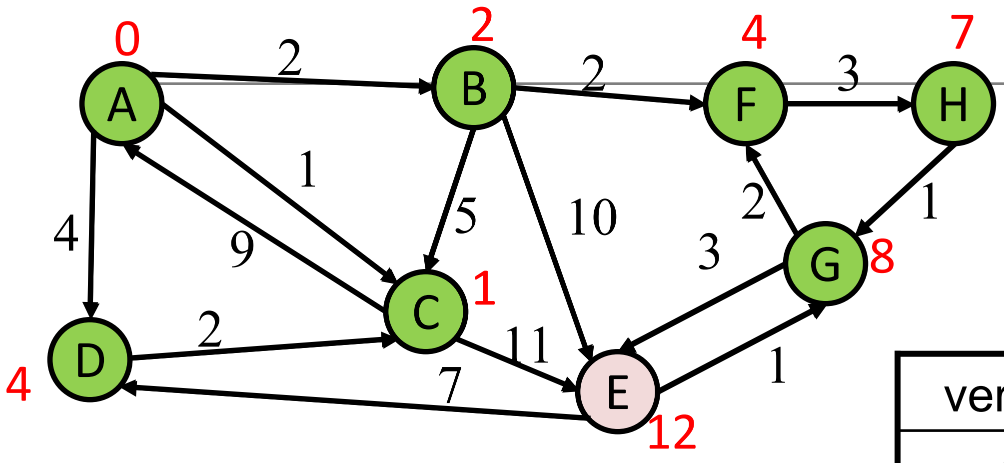


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E		≤ 12	C
F	Y	4	B
G		≤ 8	H
H	Y	7	F

Order Added to Known Set:

A, C, B, D, F, H

Example #1

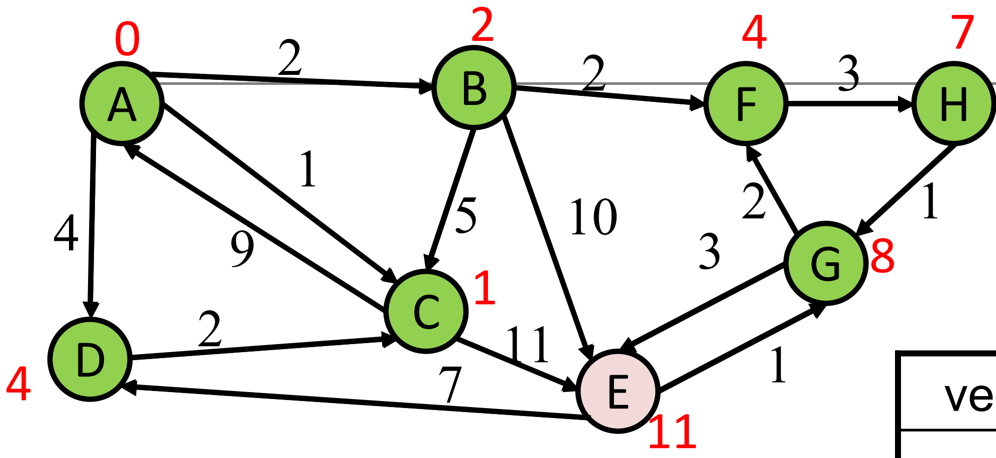


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E		≤ 12	C
F	Y	4	B
G	Y	8	H
H	Y	7	F

Order Added to Known Set:

A, C, B, D, F, H, G

Example #1

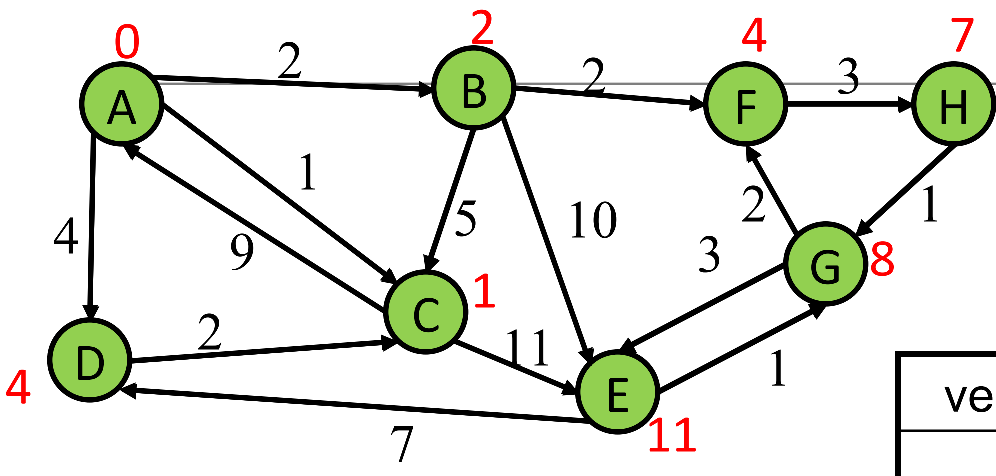


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E		≤ 11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

Order Added to Known Set:

A, C, B, D, F, H, G

Example #1

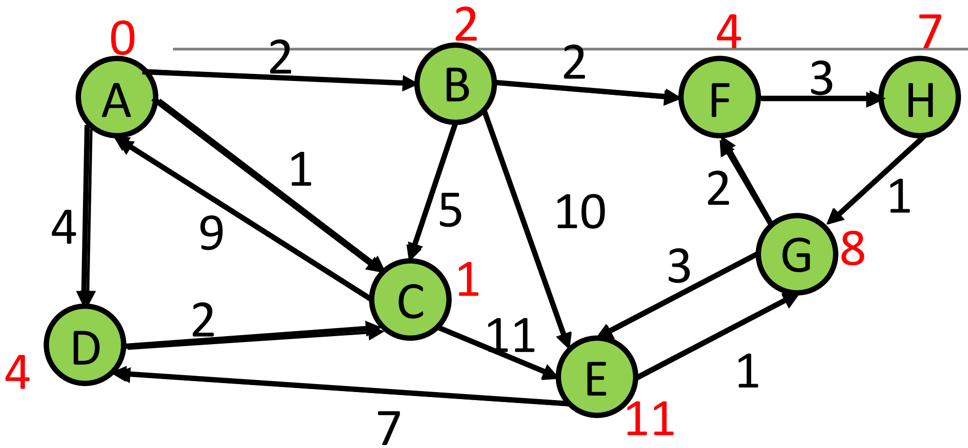


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

Order Added to Known Set:

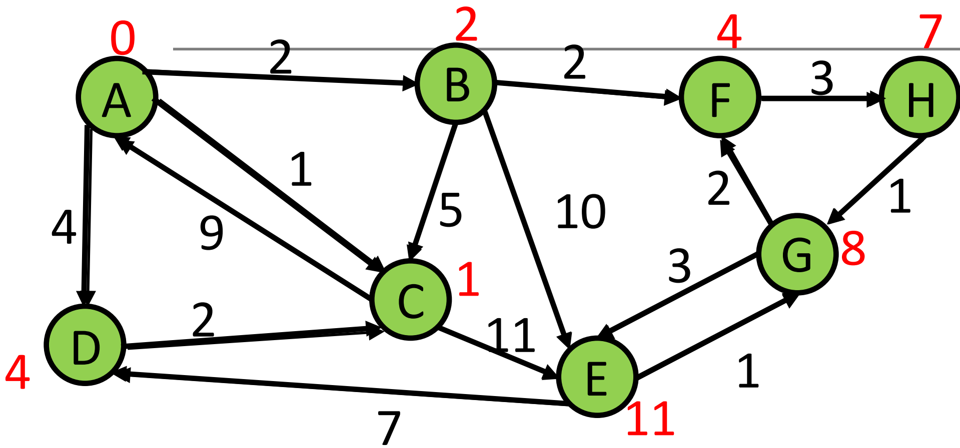
A, C, B, D, F, H, G, E

Interpreting the Results



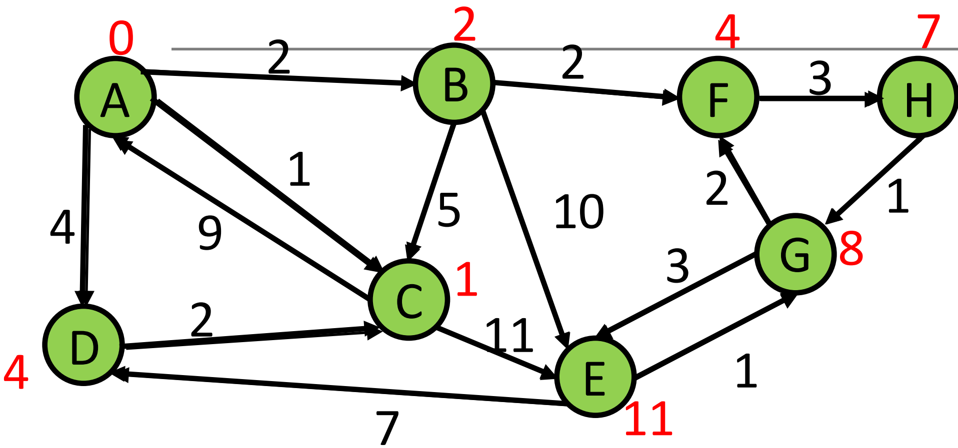
vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

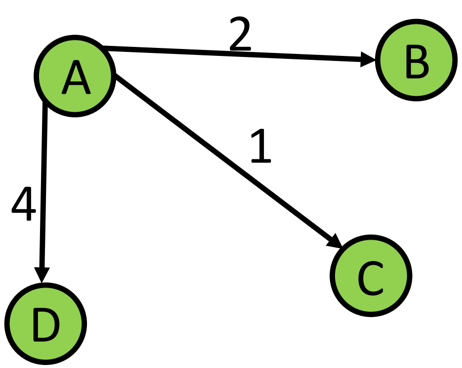
Interpreting the Results



vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

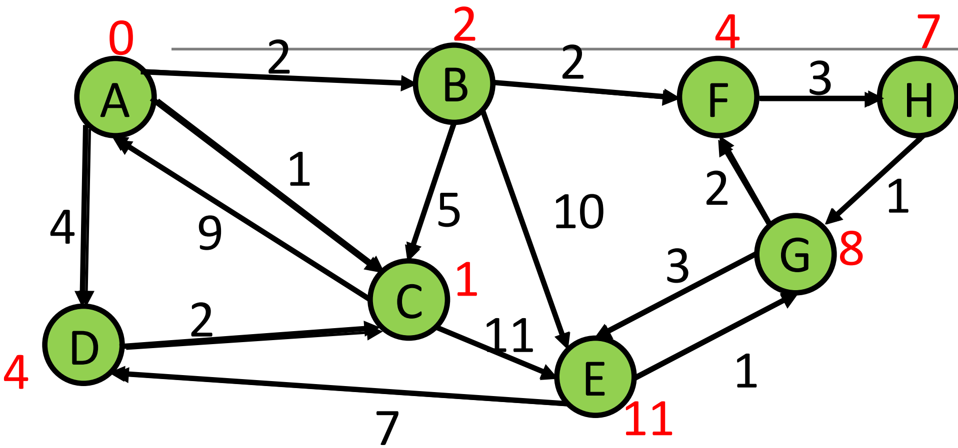
Interpreting the Results

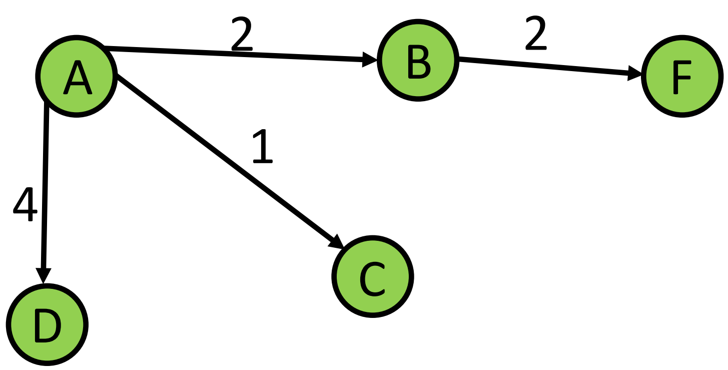




vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

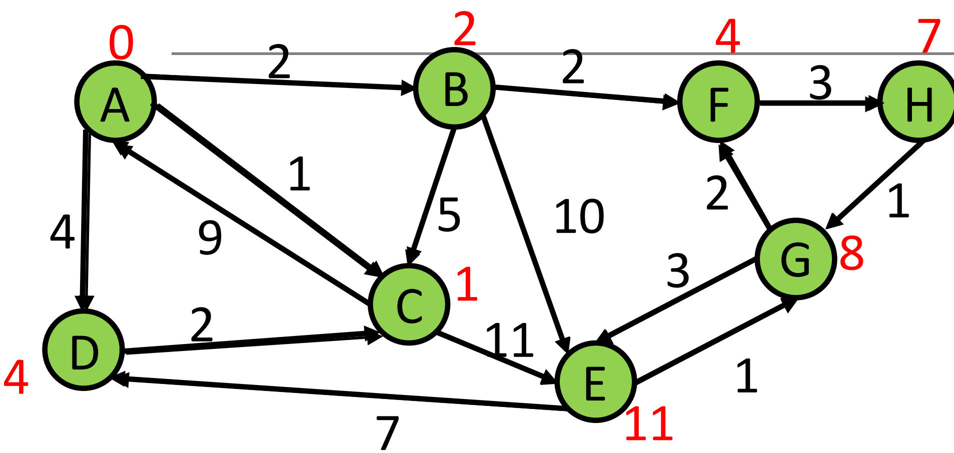
Interpreting the Results

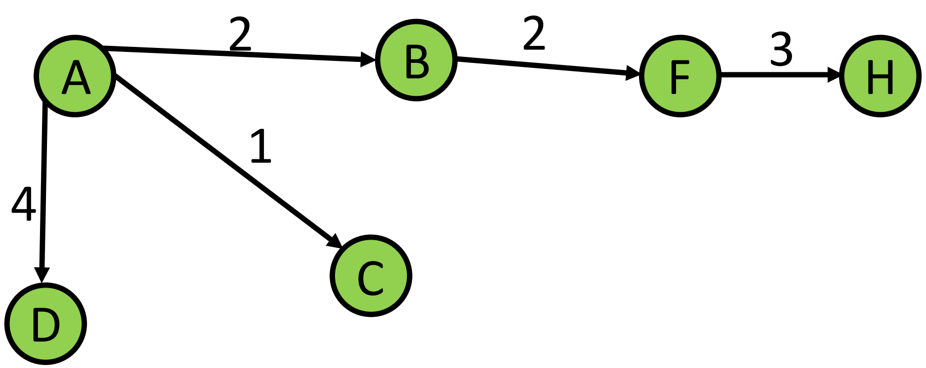




vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

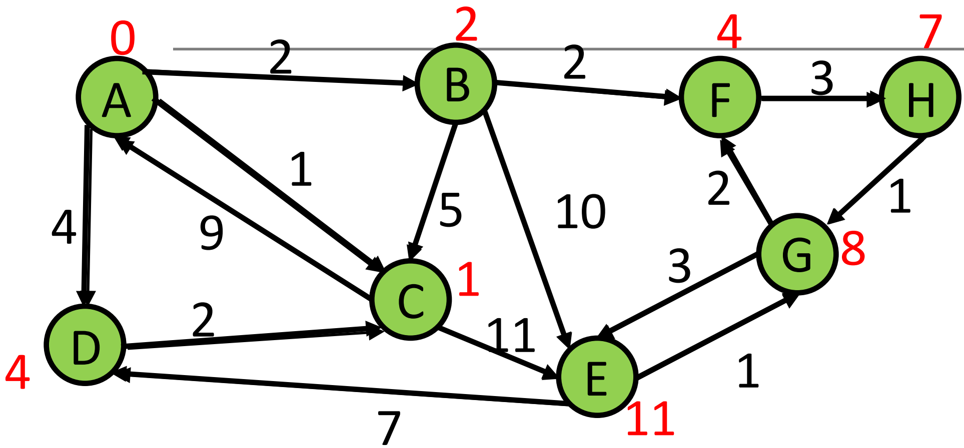
Interpreting the Results



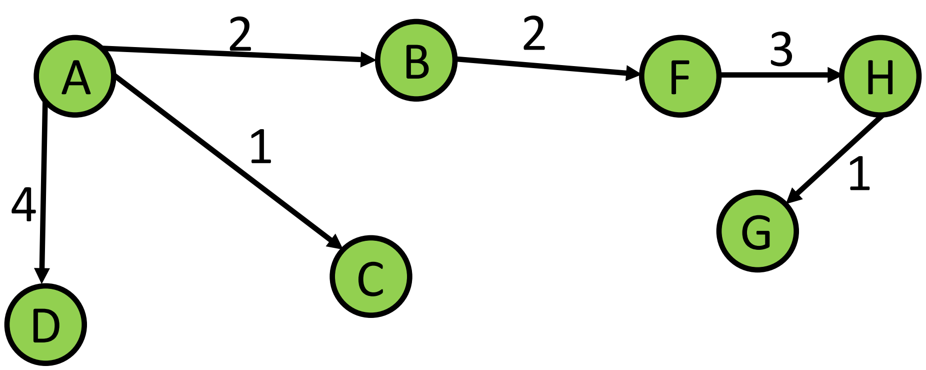


vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

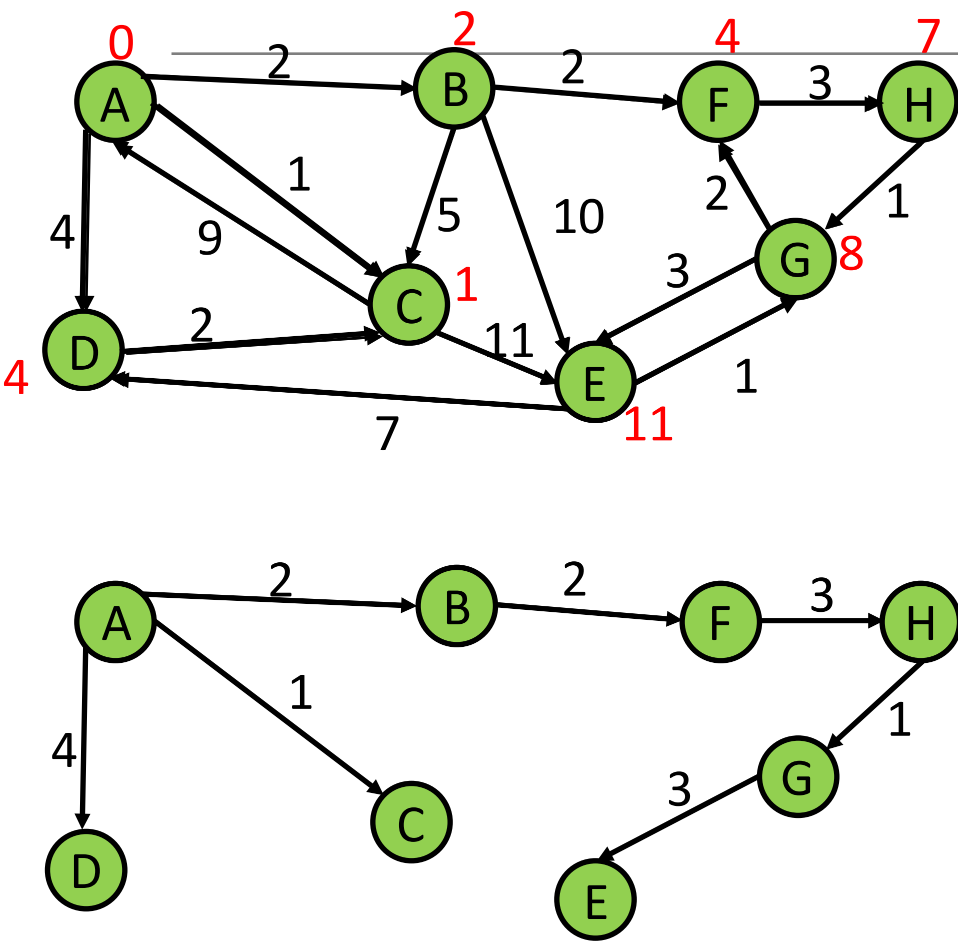
Interpreting the Results



vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

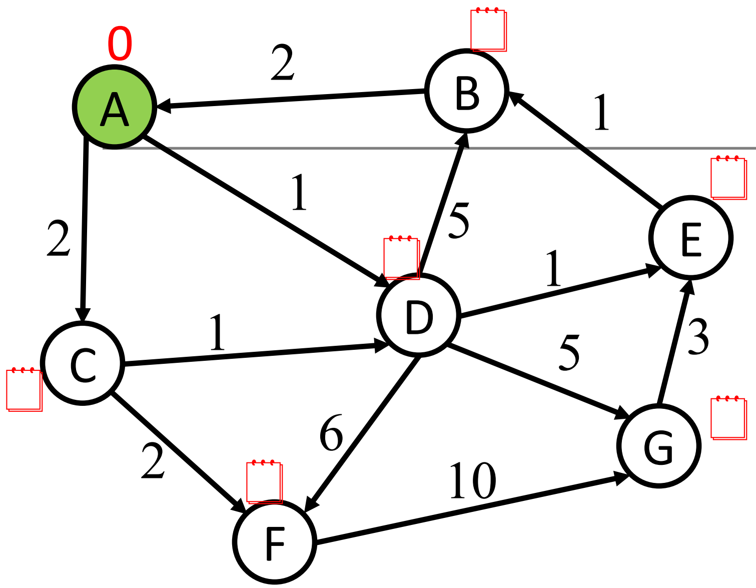


Interpreting the Results



vertex	known?	cost	path
A	Y	0	
B	Y	2	A
C	Y	1	A
D	Y	4	A
E	Y	11	G
F	Y	4	B
G	Y	8	H
H	Y	7	F

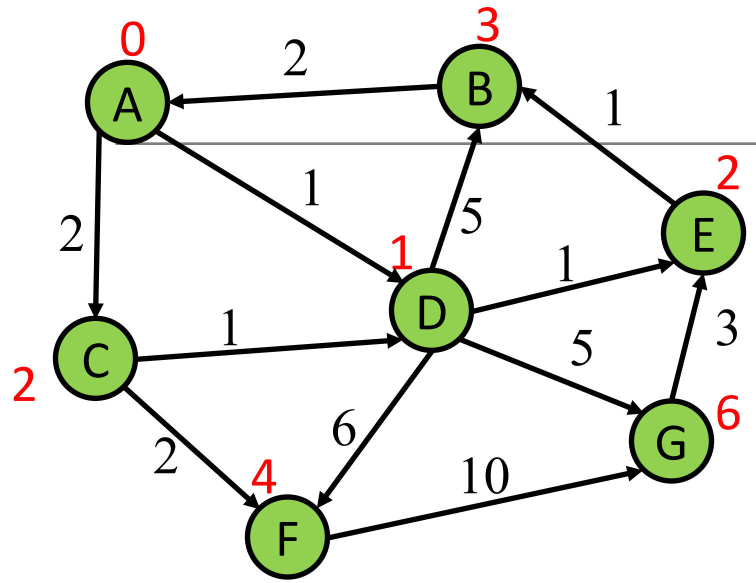
Example #2



Order Added to Known Set:

vertex	known?	cost	path
A	Y	0	
B		∞	
C		∞	
D		∞	
E		∞	
F		∞	
G		∞	

Example #2



Order Added to Known Set:

A, D, C, E, B, F, G

vertex	known?	cost	path
A	Y	0	
B	Y	3	E
C	Y	2	A
D	Y	1	A
E	Y	2	D
F	Y	4	C
G	Y	6	D

Pseudocode

```
// pre-condition: start is the node to start at
// initialize things
active = new empty priority queue of paths
    from start to a given node
    // A path's “priority” in the queue is the total
    // cost of that path.

finished = new empty set of nodes
    // Holds nodes for which we know the
    // minimum-cost path from start.

// We know path start->start has cost 0
Add a path from start to itself to active
```

Pseudocode (cont.)

```
while active is non-empty:
      minPath = active.removeMin()
      minDest = destination node in minPath

      if minDest is in finished:
          continue

      for each edge e = ⟨minDest, child⟩:
          if child is not in finished:
              newPath = minPath + e
              add newPath to active

      add minDest to finished
```

Priority Queue

Increase efficiency by considering lowest cost unknown vertex with sorting instead of looking at all vertices

PriorityQueue is like a queue, but returns elements by lowest value instead of FIFO

Priority Queue

Increase efficiency by considering lowest cost unknown vertex with sorting instead of looking at all vertices

PriorityQueue is like a queue, but returns elements by lowest value instead of FIFO

Two ways to implement:

1. Comparable
   a) class Node implements Comparable<Node>
   b) public int compareTo(other)
2. Comparator
   a) class NodeComparator extends Comparator<Node>
   b) new PriorityQueue(new NodeComparator())