



## **CSE332: Data Abstractions**

Lecture 8: Hashing

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## Conclusion of Balanced Trees

- Balanced trees make good dictionaries because they guarantee logarithmic-time find, insert, and delete
  - Essential and beautiful computer science
  - But only if you can maintain balance within the time bound
- AVL trees maintain balance by tracking height and allowing all children to differ in height by at most 1
- B trees maintain balance by keeping nodes at least half full and all leaves at same height
- Other great balanced trees (see text; worth knowing they exist)
  - Red-black trees: all leaves have depth within a factor of 2
  - Splay trees: self-adjusting; amortized guarantee;
     no extra space for height information

# Simple Implementations

For dictionary with *n* key/value pairs

•	Unsorted linked-list	insert <i>O</i> (1)	find <i>O</i> ( <i>n</i> )	delete <i>O</i> ( <i>n</i> )	
•	Unsorted array	<i>O</i> (1)	<i>O</i> ( <i>n</i> )	<i>O</i> ( <i>n</i> )	
•	Sorted linked list	O(n)	<b>O</b> ( <i>n</i> )	<i>O</i> ( <i>n</i> )	
•	Sorted array	O(n)	<b>O</b> (log <i>n</i> )	<i>O</i> ( <i>n</i> )	
•	Balanced tree	<b>O</b> (log <b>n</b> )	<i>O</i> (log <i>n</i> )	<b>O</b> (log <i>n</i>	)
•	Magic array	<i>O</i> (1)	<i>O</i> (1)	<i>O</i> (1)	average case

## Hash Tables

key space (e.g., integers, strings)

- Aim for constant-time find, insert, and delete
  - "On average" under some reasonable assumptions
- A hash table is an array of some fixed size
  Basic idea:
  hash function:
  index = h(key)
  ...

TableSize – 1

## Hash Tables vs. Balanced Trees

- In terms of a Dictionary ADT for just insert, find, delete, hash tables and balanced trees are just different data structures
  - Hash tables O(1) on average (assuming few collisions)
  - Balanced trees O(log n) worst-case
- Constant-time is better, right?
  - Yes, but you need "hashing to behave" (must avoid collisions)
  - Yes, but findMin, findMax, predecessor, successor go from  $O(\log n)$  to O(n), printSorted from O(n) to  $O(n \log n)$
- Moral: If you need to frequently use operations based on sort order, then you may prefer a balanced BST instead.

## Hash Tables

- There are m possible keys (m typically large, even infinite)
- We expect our table to have only n items
- n is much less than m (often written n << m)</li>

#### Many dictionaries have this property

- Compiler: All possible identifiers allowed by the language vs. those used in some file of one program
- Database: All possible student names vs. students enrolled
- AI: All possible chess-board configurations vs.
   those considered by the current player

## Hash Functions

#### An ideal hash function:

- Is fast to compute
- "Rarely" hashes two "used" keys to the same index
  - Often impossible in theory; easy in practice
  - Will handle collisions in later

key space (e.g., integers, strings)

# hash function: index = h(key)

#### hash table

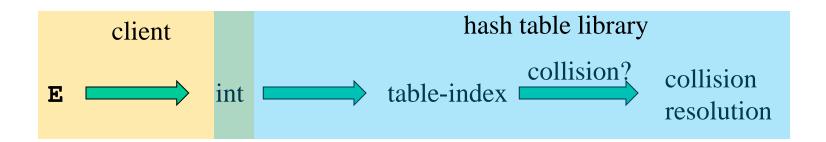
0

• • •

TableSize - 1

## Who Hashes What

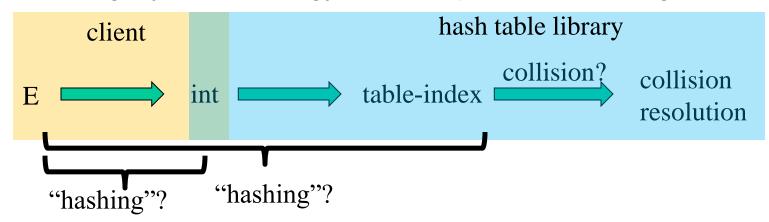
- Hash tables can be generic
  - To store elements of type E, we just need E to be:
    - Comparable: order any two E (as with all dictionaries)
    - 2. Hashable: convert any E to an int
- When hash tables are a reusable library, the division of responsibility generally breaks down into two roles:



 We will learn both roles, but most programmers "in the real world" spend more time as clients while understanding the library

## More on Roles

Some ambiguity in terminology on which parts are "hashing"



Two roles must both contribute to minimizing collisions (heuristically)

- Client should aim for different ints for expected items
  - Avoid "wasting" any part of E or the 32 bits of the int
- Library should aim for putting "similar" ints in different indices
  - conversion to index is almost always "mod table-size"
  - using prime numbers for table-size is common

## What to Hash?

We will focus on two most common things to hash: ints and strings

- If you have objects with several fields, it is usually best to hash most of the "identifying fields" to avoid collisions
- Example:

```
class Person {
    String first; String middle; String last;
    Date birthdate;
}
```

An inherent trade-off: hashing-time vs. collision-avoidance

## Hashing Integers

- key space = integers
- Simple hash function:

- Client: f(x) = x
- Library g(x) = f(x) % TableSize
- Fairly fast and natural
- Example:
  - TableSize = 10
  - Insert 7, 18, 41, 34, 10
  - (As usual, ignoring corresponding data)

0	10
---	----

- 41
- 2
- 3
  - 34
- **5**
- 6
- 7 | ^
  - 18
- 9

8

## Collision Avoidance

- With "x % TableSize" the number of collisions depends on
  - the ints inserted
  - TableSize
- Larger table-size tends to help, but not always
  - Example: 70, 24, 56, 43, 10
     with TableSize = 10 and TableSize = 60
- Technique: Pick table size to be prime. Why?
  - Real-life data tends to have a pattern,
  - "Multiples of 61" are probably less likely than "multiples of 60"
  - We will see some collision strategies do better with prime size

## More Arguments for a Prime Size

#### If TableSize is 60 and...

- Lots of data items are multiples of 2, wasting 50% of table
- Lots of data items are multiples of 5, wasting 80% of table
- Lots of data items are multiples of 10, wasting 90% of table

#### If TableSize is 61...

- Collisions can still happen but 2, 4, 6, 8, ... will fill table
- Collisions can still happen, but 5, 10, 15, 20, ... will fill table
- Collisions can still happen but 10, 20, 30, 40, ... will fill table

In general, if x and y are "co-prime" (means gcd(x,y)==1), then (a \* x) % y == (b \* x) % y if and only if a % y == b % y

 Good to have a TableSize that has no common factors with any "likely pattern" of x

## What if key is not an int?

- If keys are not ints, the client must convert to an int
  - Trade-off: speed and distinct keys hashing to distinct ints
- Common and important example: Strings
  - Key space  $K = s_0 s_1 s_2 ... s_{m-1}$ 
    - where s<sub>i</sub> are chars: s<sub>i</sub> ∈ [0,256]
  - Some choices: Which best avoid collisions?
  - 1.  $h(K) = s_0 \%$  TableSize
  - 2.  $h(K) = \left(\sum_{i=0}^{m-1} S_i\right) \%$  TableSize

3. 
$$h(K) = \left(\sum_{i=0}^{k-1} s_i \cdot 37^i\right)$$
 % TableSize

# Combining Hash Functions

#### A few rules of thumb / tricks:

- 1. Use all 32 bits (careful, that includes negative numbers)
- 2. Use different overlapping bits for different parts of the hash
  - This is why a factor of 37<sup>i</sup> works better than 256<sup>i</sup>
  - Example: "abcde" and "ebcda"
- 3. When smashing two hashes into one hash, use bitwise-xor
  - bitwise-and produces too many 0 bits
  - bitwise-or produces too many 1 bits
- 4. Rely on expertise of others; consult books and other resources
- 5. Advanced: If keys are known ahead of time, a *perfect hash*

## Collision Resolution

#### Collision:

When two keys map to the same location in the hash table

We try to avoid it, but number-of-keys exceeds table size

So hash tables generally need to support collision resolution

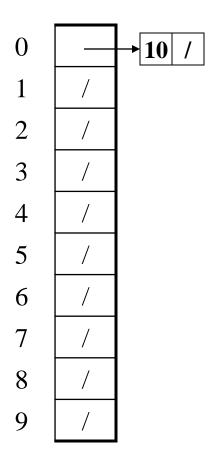
0	/
1	/
2	/
3	/
4	/
5	/
6	/
7	/
8	/
9	/

#### Chaining:

All keys that map to the same table location are kept in a list (a.k.a. a "chain" or "bucket")

As easy as it sounds

#### Example:

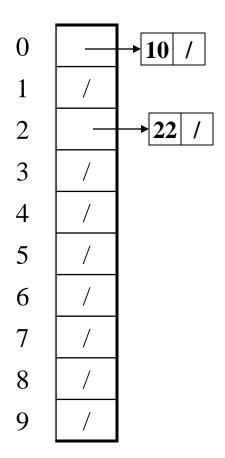


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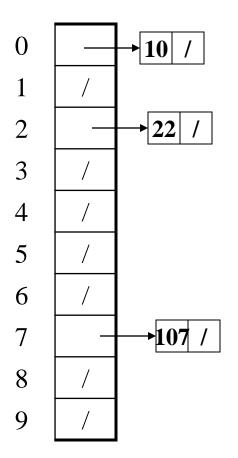


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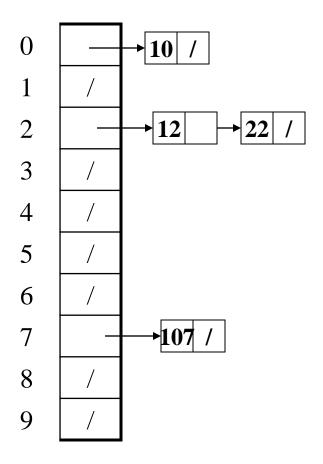


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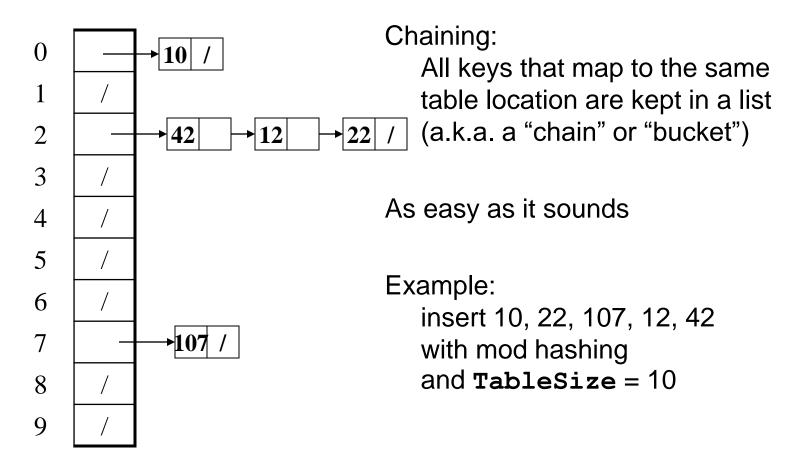


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#### Example:



## Thoughts on Separate Chaining

- Worst-case time for find?
  - Linear
  - But only with really bad luck or bad hash function
  - So not worth avoiding (e.g., with balanced trees at each bucket)
    - Keep small number of items in each bucket
    - Overhead of tree balancing not worthwhile for small n
- Beyond asymptotic complexity, some "data-structure engineering"
  - Linked list, array, or a hybrid
  - Move-to-front list (as in Project 2)
  - Leave one element in the table itself,
     to optimize constant factors for the common case

# More Rigorous Separate Chaining Analysis

Definition: The load factor,  $\lambda$ , of a hash table is

$$\lambda = \frac{N}{\text{TableSize}} \quad \leftarrow \text{number of elements}$$

Under chaining, the average number of elements per bucket is \_\_\_\_

So if some inserts are followed by *random* finds, then on average:

- Each unsuccessful find compares against \_\_\_\_\_ items
- Each successful find compares against \_\_\_\_\_ items
- How big should TableSize be??

## More Rigorous Separate Chaining Analysis

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$$\lambda = \frac{N}{\text{TableSize}} \quad \leftarrow \text{number of elements}$$

Under chaining, the average number of elements per bucket is  $\lambda$ 

So if some inserts are followed by *random* finds, then on average:

- Each unsuccessful find compares against A items
- Each successful find compares against \( \lambda / 2 \) items
- If  $\lambda$  is low, find & insert likely to be O(1)
- We like to keep  $\lambda$  around 1 for separate chaining

# Separate Chaining Deletion?

# Separate Chaining Deletion

- Not too bad
  - Find in table
  - Delete from bucket
- Delete 12
- Similar run-time as insert

