CSE 332 Autumn 2023 Lecture 16: Sorting

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Properties to consider

- Running time
 - What is the worst case running time?
 - What is the best case?
 - Does the algorithm run faster if the list is close to sorted?
 - If so, we call it Adaptive
- Memory Usage
 - How much memory does the algorithm use in addition to the array?
 - If $\Theta(1)$ then we call it In-Place
 - Sorts things by only swapping things in the same array we started with.
- What happens when there is a "tie"?
 - If "tied" elements are guaranteed to remain in the same relative order, this is called a Stable Sort
 - E.g. a stable sort guarantees that, after sorting by the first initial and then by last initial, "N.J.B." will come before "S.C.B"

Properties of Selection Sort

- In-Place?
 - Yes!
- Adaptive?
 - No
- Stable?
 - Yes!
 - As long as you always pick the left-most element when there's a "tie"

Properties of Insertion Sort

- In-Place?
 - Yes!
- Adaptive?
 - Yes!
- Stable?
 - Yes!
 - As long as you don't swap when there's a tie
- Online!
 - You can begin sorting the list before you have all the elements
 - "Insert" items as they arrive

Properties of Heap Sort

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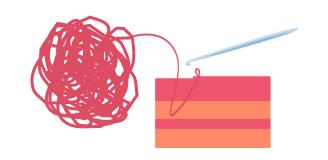
- Worst Case Running time:
 - $\Theta(n \log n)$
- In-Place?
 - Yes!
- Adaptive?
 - No
- Stable?
 - No

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Divide And Conquer Sorting

- Divide and Conquer:
 - Recursive algorithm design technique
 - Solve a large problem by breaking it up into smaller versions of the same problem

Divide and Conquer





• If the problem is "small" then solve directly and return



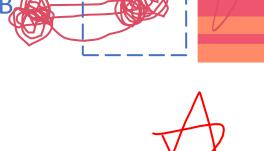
Break the problem into subproblem(s), each smaller instances

Conquer:

Solve subproblem(s) recursively

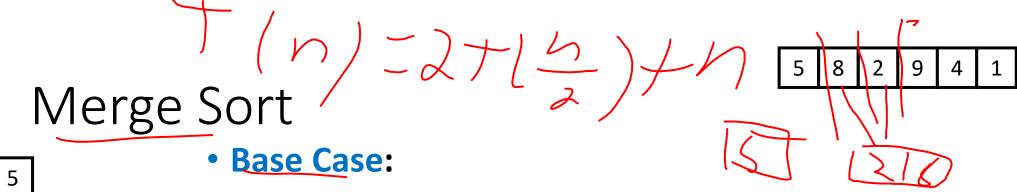


Use solutions to subproblems to solve original problem



Divide and Conquer Template Pseudocode

```
def my_DandC(problem){
   // Base Case
  if (problem.size() <= small_value){</pre>
    return solve(problem); // directly solve (e.g., brute force)
  // Divide
  List subproblems = divide(problem);
  // Conquer
  solutions = new List();
  for (sub : subproblems){
    subsolution = my DandC(sub);
    solutions.add(subsolution);
  // Combine
  return combine(solutions);
```



• If the list is of length 1 or 0, it's already sorted, so just return it



• Split the list into two "sublists" of (roughly) equal length



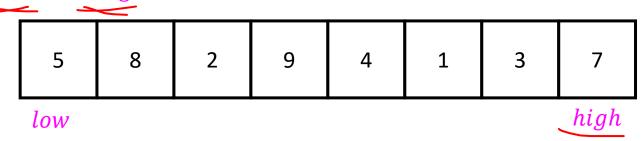
Sort both lists recursively



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Merge Sort In Action!

Sort between indices *low* and *high*



Base Case: if low == high then that range is already sorted!

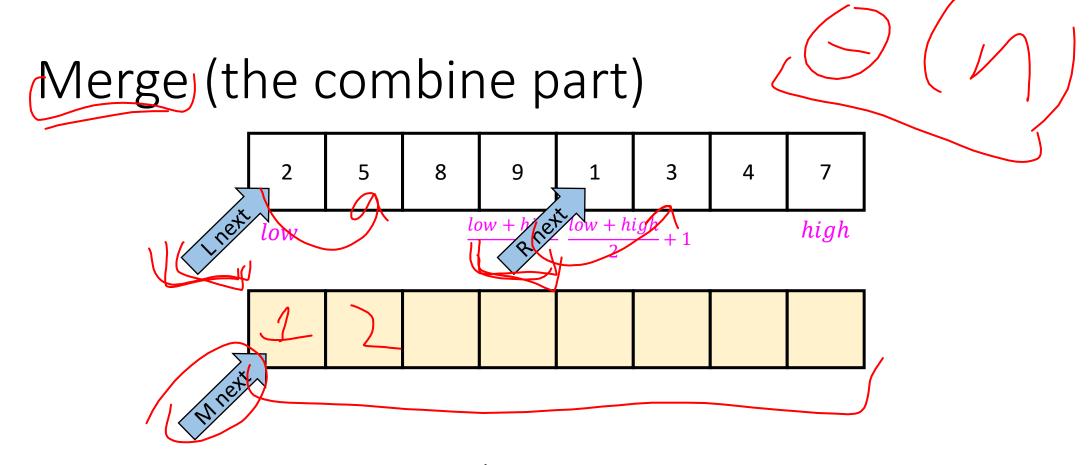
low

Divide and Conquer: Otherwise call mergesort on ranges $(low, \frac{low+high}{2})$ and $(\frac{low+high}{2} + 1, high)$

After Recursion:

2 5 8 9 1 3 4 7

high



Create a new array to merge into, and 3 pointers/indices:

- L_next: the smallest "unmerged" thing on the left
- R_next: the smallest "unmerged" thing on the right
- M_next: where the next smallest thing goes in the merged array

One-by-one: put the smallest of L_next and R_next into M_next, then advance both M_next and whichever of L/R was used.

Merge Sort Pseudocode

```
void mergesort(myArray){
      ms helper(myArray, 0, myArray.length());
void mshelper(myArray, low, high){
      if (low == high){return;} // Base Case
      mid = (low+high)/2;
      ms_helper(low, mid);
      ms helper(mid+1, high);
      merge(myArray, low, mid, high);
```

Merge Pseudocode

```
void merge(myArray, low, mid, high){
       merged = new int[high-low+1]; // or whatever type is in myArray
       I next = low;
       r next = high;
       m next = 0;
       while (I next <= mid && r next <= high){
               if (myArray[l next] <= myArray[r next]){</pre>
                       merged[m_next++] = myArray[l_next++];
               else{
                       merged[m_next++] = myArray[r_next++];
       while (I_next <= mid){ merged[m_next++] = myArray[I_next++]; }
       while (r next <= high){ merged[m next++] = myArray[r next++]; }
       for(i=0; i<=merged.length; i++){ myArray[i+low] = merged[i];}
```

Analyzing Merge Sort

- 1. Identify time required to Divide and Combine
- 2. Identify all subproblems and their sizes
- 3. Use recurrence relation to express recursive running time
- 4. Solve and express running time asymptotically
- Divide: 0 comparisons
- Conquer: recursively sort two lists of size $\frac{n}{2}$
- Combine: *n* comparisons
- Recurrence:

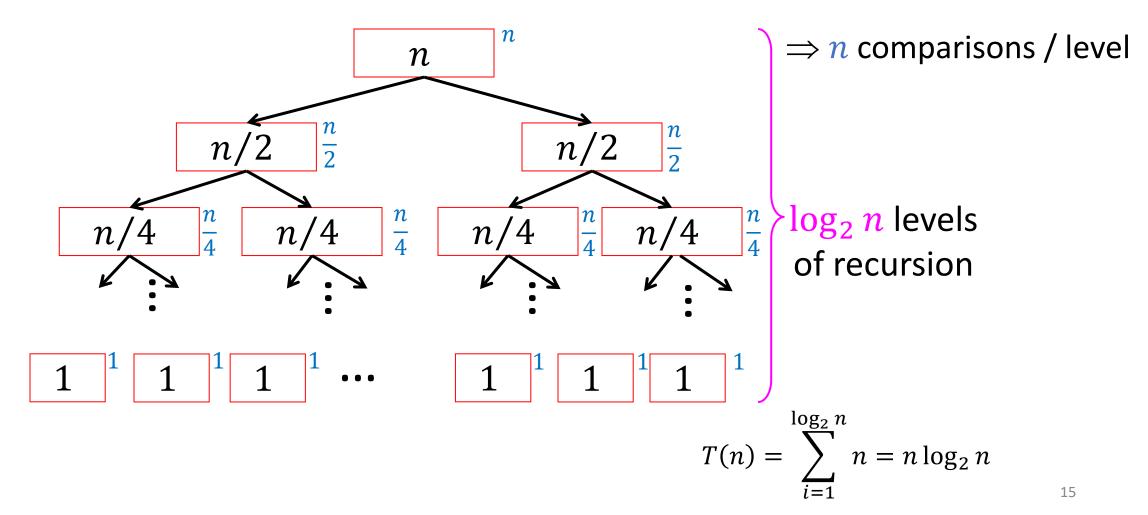
$$T(n) = 0 + T\left(\frac{n}{2}\right) + T\left(\frac{n}{2}\right) + n$$

$$T(n) = 2T\left(\frac{n}{2}\right) + n$$

Red box represents a problem instance

Blue value represents time spent at that level of recursion

$$T(n) = 2T(\frac{n}{2}) + n$$



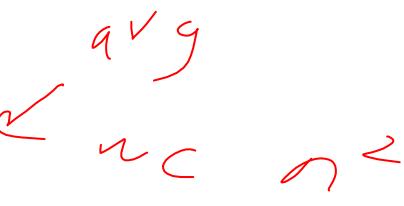
Properties of Merge Sort

- Worst Case Running time:
 - $\Theta(n \log n)$
- In-Place?
 - No!
- Adaptive?
 - No!
- Stable?
 - Yes!
 - As long as in a tie you always pick l_next

Quicksort

- Like Mergesort:
 - Divide and conquer
 - $O(n \log n)$ run time (kind of...)
- Unlike Mergesort:
 - Divide step is the "hard" part
 - Typically faster than Mergesort





Quicksort

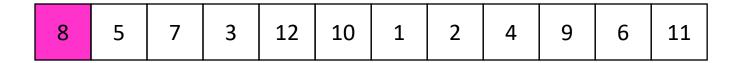
Idea: pick a pivot element, recursively sort two sublists around that element

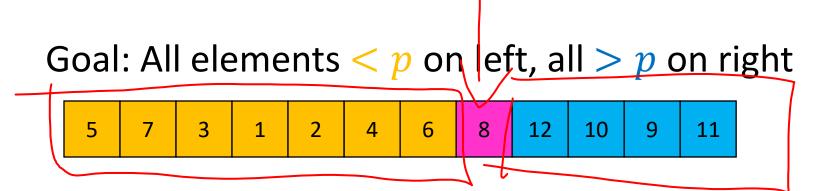
- Divide; select pivot element p, Partition(p)
- Conquer:/recursively sort left and right sublists /
- Combine: Nothing!

Partition (Divide step)

Given: a list, a pivot p

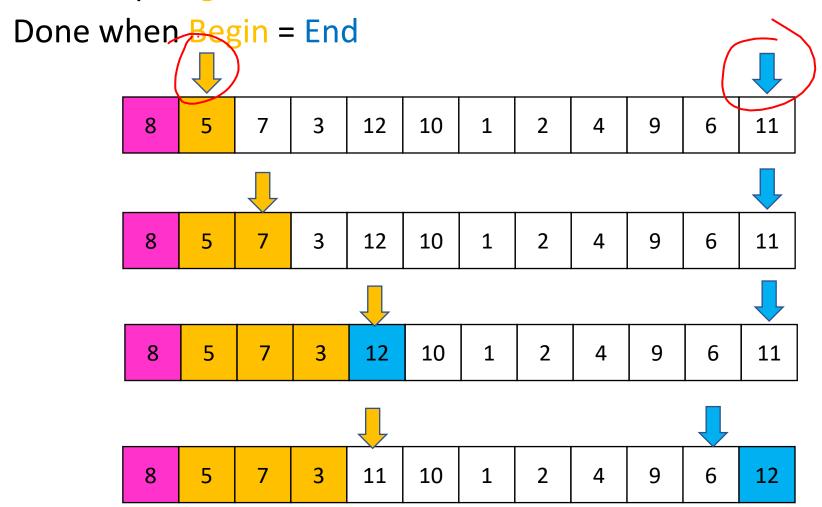
Start: unordered list





If Begin value < p, move Begin right

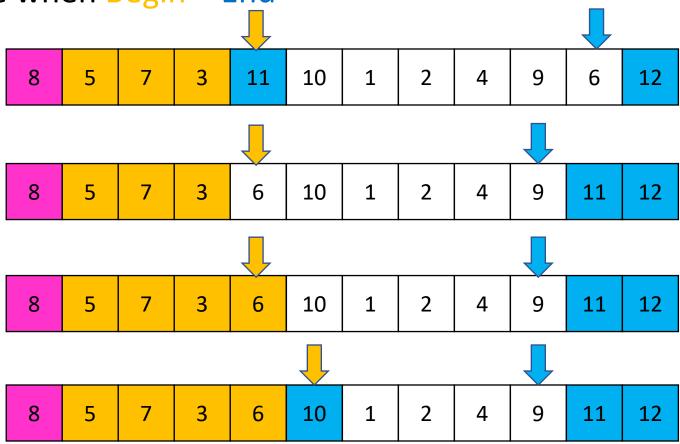
Else swap Begin value with End value, move End Left



If Begin value < p, move Begin right

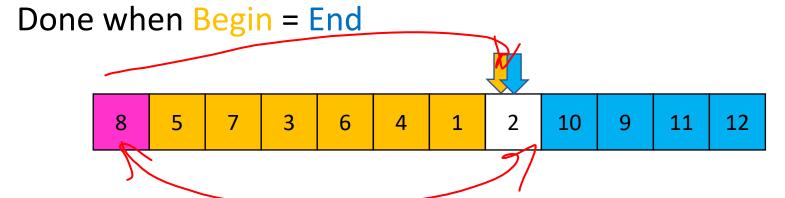
Else swap Begin value with End value, move End Left

Done when Begin = End



If Begin value < p, move Begin right

Else swap Begin value with End value, move End Left

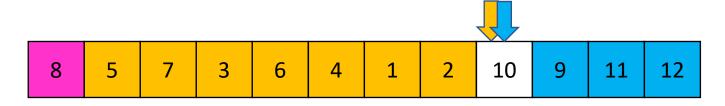


Case 1: meet at element < p

Swap p with pointer position (2 in this case)

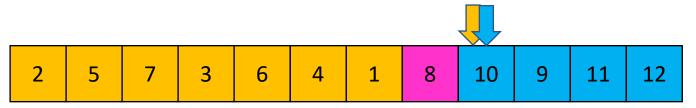


If Begin value < p, move Begin right Else swap Begin value with End value, move End Left Done when Begin = End



Case 2: meet at element > p

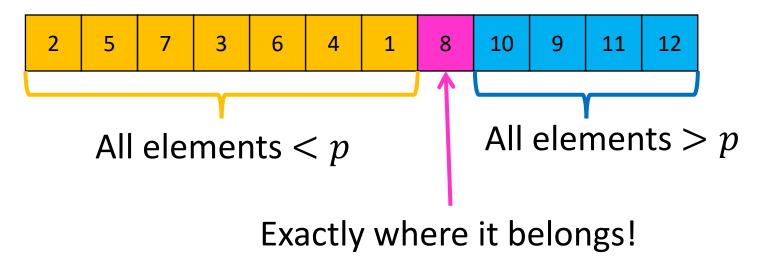
Swap p with value to the left (2 in this case)



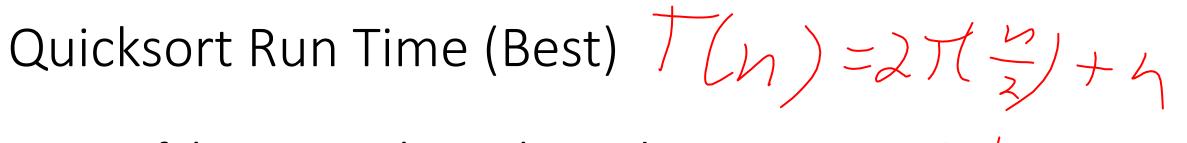
Partition Summary

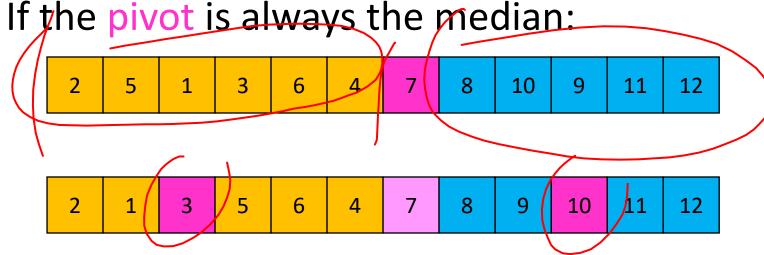
- 1. Put p at beginning of list
- 2. Put a pointer (Begin) just after p, and a pointer (End) at the end of the list
- 3. While Begin < End:
 - 1. If Begin value < p, move Begin right
 - 2. Else swap Begin value with End value, move End Left
- 4. If pointers meet at element < p: Swap p with pointer position
- 5. Else If pointers meet at element > p: Swap p with value to the left

Conquer



Recursively sort Left and Right sublists





Then we divide in half each time

$$T(n) = 2T\left(\frac{n}{2}\right) + n$$
$$T(n) = O(n\log n)$$

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Quicksort Run Time (Worst)

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If the pivot is always at the extreme:

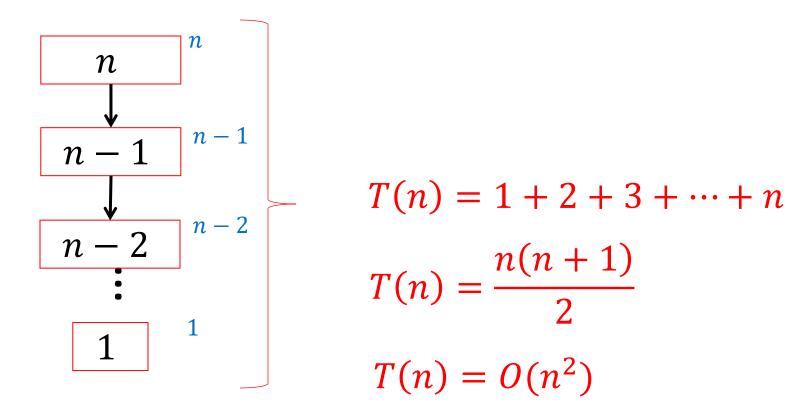
Then we shorten by 1 each time

$$T(n) = T(n-1) + n$$

$$T(n) = O(n^2)$$

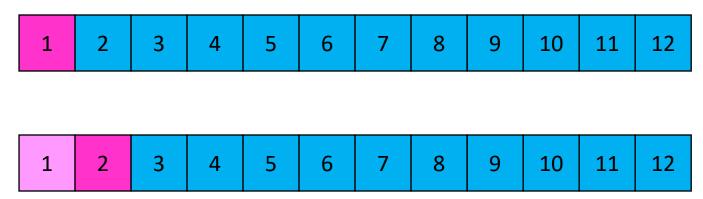
Quicksort Run Time (Worst)

$$T(n) = T(n-1) + n$$



Quicksort on a (nearly) Sorted List

First element always yields unbalanced pivot



So we shorten by 1 each time

$$T(n) = T(n-1) + n$$

$$T(n) = O(n^2)$$

Good Pivot

- What makes a good Pivot?
 - Roughly even split between left and right
 - Ideally: median
- There are ways to find the median in linear time, but it's complicated and slow and you're better off using mergesort
- In Practice:
 - Pick a random value as a pivot
 - Pick the middle of 3 random values as the pivot

Properties of Quick Sort

- Worst Case Running time:
 - $\Theta(n^2)$
 - But $\Theta(n \log n)$ average! And typically faster than mergesort!
- In-Place?
 -Debatable
- Adaptive?
 - No!
- Stable?
 - No!

More Formal Definition

• Input:

- An array *A* of items
- A comparison function for these items
 - Given two items x and y, we can determine whether x < y, x > y, or x = y

• Output:

- A permutation of A such that if $i \leq j$ then $A[i] \leq A[j]$
- Permutation: a sequence of the same items but perhaps in a different order

Improving Running time

- Recall our definition of the sorting problem:
 - Input:
 - An array *A* of items
 - A comparison function for these items
 - Given two items x and y, we can determine whether x < y, x > y, or x = y
 - Output:
 - A permutation of A such that if $i \leq j$ then $A[i] \leq A[j]$
- Under this definition, it is impossible to write an algorithm faster than $n \log n$ asymptotically.
- Observation:
 - Sometimes there might be ways to determine the position of values without comparisons!

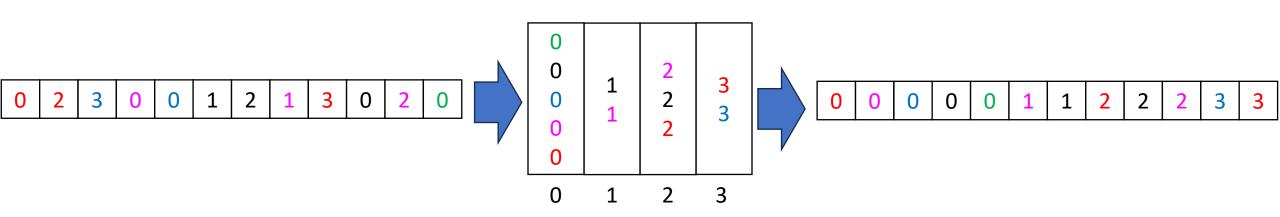
"Linear Time" Sorting Algorithms

- Useable when you are able to make additional assumptions about the contents of your list (beyond the ability to compare)
 - Examples:
 - The list contains only positive integers less than k
 - The number of distinct values in the list is much smaller than the length of the list
- The running time expression will always have a term other than the list's length to account for this assumption
 - Examples:
 - Running time might be $\Theta(k \cdot n)$ where k is the range/count of values

BucketSort

• Assumes the array contains integers between 0 and k-1 (or some other small range)

- Idea:
 - Use each value as an index into an array of size k
 - Add the item into the "bucket" at that index (e.g. linked list)
 - Get sorted array by "appending" all the buckets



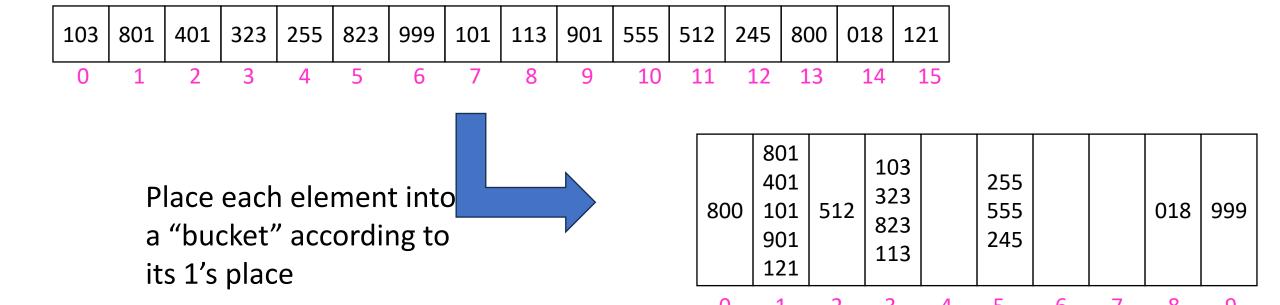
BucketSort Running Time

- Create array of k buckets
 - Either $\Theta(k)$ or $\Theta(1)$ depending on some things...
- Insert all n things into buckets
 - $\Theta(n)$
- Empty buckets into an array
 - $\Theta(n+k)$
- Overall:
 - $\Theta(n+k)$
- When is this better than mergesort?

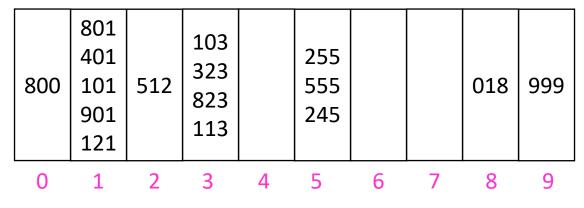
Properties of BucketSort

- In-Place?
 - No
- Adaptive?
 - No
- Stable?
 - Yes!

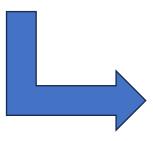
- Radix: The base of a number system
 - We'll use base 10, most implementations will use larger bases
- Idea:
 - BucketSort by each digit, one at a time, from least significant to most significant

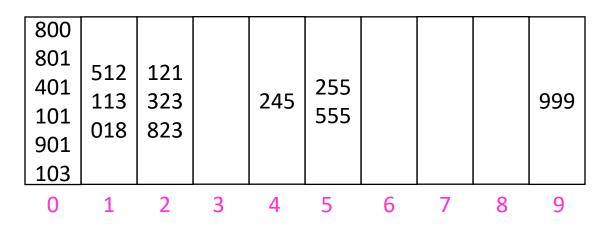


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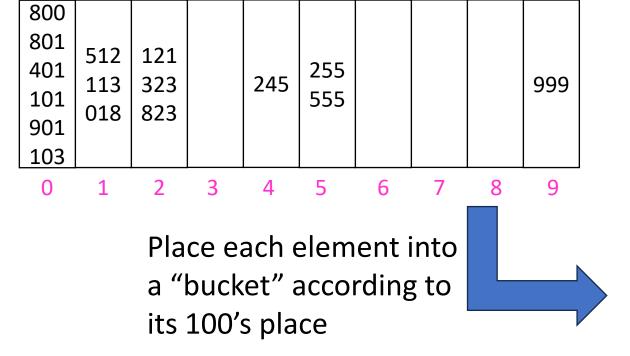


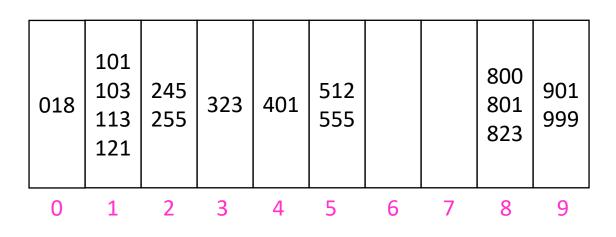
Place each element into a "bucket" according to its 10's place



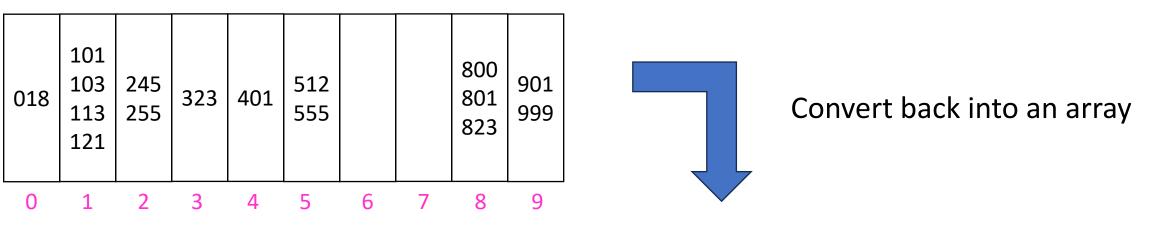


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018	811	103	113	121	245	255	323	401	512	555	800	801	823	901	999	
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	•

RadixSort Running Time

- Suppose largest value is *m*
- Choose a radix (base of representation) b
- BucketSort all n things using b buckets
 - $\Theta(n+k)$
- Repeat once per each digit
 - $\log_b m$ iterations
- Overall:
 - $\Theta(n \log_b m + b \log_b m)$
- In practice, you can select the value of b to optimize running time
- When is this better than mergesort?