# CSE 332 Winter 2024 Lecture 18: Dijkstra's, ForkJoin 

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## Single-Source Shortest Path



Find the quickest way to get from UVA to each of these other places

Given a graph $G=(V, E)$ and a start node $s \in V$, for each $v \in V$ find the least-weight path from $s \rightarrow v$ (call this weight $\delta(s, v)$ )

## Dijkstra's Algorithm

- Input: graph with no negative edge weights, start node $s$, end node $t$
- Behavior: Start with node $s$, repeatedly go to the incomplete node "nearest" to $s$, stop when
- Output:
- Distance from start to end
- Distance from start to every node


Dijkstra's Algorithm Start: 0


End: 8
Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path

| Node | Done? |
| :--- | :--- |
| 0 | F |
| 1 | F |
| 2 | F |
| 3 | F |
| 4 | F |
| 5 | F |
| 6 | F |
| 7 | F |
| 8 | F |


| Node | Distance |
| :--- | :--- |
| 0 | 0 |
| 1 | $\infty$ |
| 2 | $\infty$ |
| 3 | $\infty$ |
| 4 | $\infty$ |
| 5 | $\infty$ |
| 6 | $\infty$ |
| 7 |  |
| 8 |  |



Dijkstra's Algorithm Start: 0
End: 8
Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path

| Node | Done? | Node | Distance |
| :--- | :--- | :--- | :--- |
| 0 | T |  |  |
| 1 | F | 0 | 0 |
| 1 | F | 10 |  |
| 2 | F | 12 |  |
| 3 | F | 3 | $\infty$ |
| 4 | F | 5 | $\infty$ |
| 5 | F | 6 | $\infty$ |
| 6 | F | 7 | $\infty$ |
| 7 | F | 8 | $\infty$ |
| 8 | F |  |  |



## Dijkstra's Algorithm

 Start: 0End: 8

| Node | Done? | Node | Distance |
| :--- | :--- | :--- | :--- |
| 0 | T | 0 | 0 |
| 1 | T |  |  |
|  |  | 1 | 10 |
| 2 | F | 2 | 12 |
| 3 | F | 3 | $\infty$ |
| 4 | F | 4 | 18 |
| 5 | F | 5 | $\infty$ |
| 6 | F | 7 | $\infty$ |
| 7 | F | 8 | $\infty$ |
| 8 | F |  | $\infty$ |

Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path


## Dijkstra's Algorithm

 Start: 0End: 8

| Node | Done? | Node | Distance |
| :--- | :--- | :--- | :--- |
| 0 | T | 0 | 0 |
| 1 | T | 1 | 10 |
| 2 | T | 2 | 12 |
| 3 | F | 3 | 15 |
| 4 | F | 4 | 18 |
| 5 | F |  | 5 |
| 6 | F | 6 | 13 |
| 7 | F | 7 | $\infty$ |
| 8 | F | 8 | $\infty$ |

Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path


Dijkstra's Algorithm Start: 0
End: 8
Idea: When a node is the closest undiscovered thing to the start, we have found its shortest path

| Node | Done? | Node | Distance |
| :--- | :--- | :--- | :--- |
| 0 | T | 0 | 0 |
| 1 | T | 1 | 10 |
| 2 | T | 2 | 12 |
| 3 | F |  | 3 |
| 4 | F |  | 14 |
| 5 | T |  | 18 |
| 6 | F | 6 | 13 |
| 7 | F | 7 | $\infty$ |
| 8 | F | 8 | 20 |



## Dijkstra's Algorithm <br> int dijkstras(graph, start, end)\{

$\longrightarrow$ distances $=[\infty, \infty, \infty, . ..] ; / /$ one index per node done= [False,False,False,...]; // one index per node PQ = new minheap();
PQ.insert(0, start); // priority=0, value=start distances[start] = 0; while (!PO isEmpty)\{ current = PQ.deleteMin(); done[current] = true;


## Dijkstra's Algorithm: Running Time

- How many total priority queue operations are necessary?
- How many times is each node added to the priority queue?
- How many times might a node's priority be changed?
-What's the running time of each priority queue operation?
$\cdot \log |V|, 2 E$
- Overall running time:
$\Theta(|E| \log |V|)$


## Dijkstra's Algorithm: Correctness

- Claim: when a node is removed from the priority queue, we have found its shortest path
- Induction over number of completed nodes
- Base Case:
- 1 node done: we removed Start
- Start node is 0 from itself always
- Inductive Step:
- Assume that $i$ nodes are done and we
- Found their shortest paths
- Want to show that when node $i+1$
- was removed, we found its shortest



## Dijkstra's Algorithm: Correctness

- Claim: when a node is removed from the priority queue, its distance is that of the shortest path
- Induction over number of completed nodes
- Base Case: Only the start node removed
- It is indeed 0 away from itself
- Inductive Step:

- If we have correctly found shortest paths for the first $k$ nodes, then when we remove node $k+1$ we have found its shortest path

Dijkstra's Algorithm: Correctness

- Suppose $a$ is the next node removed from the queue. What do we know bout $a$ ?

$$
\begin{aligned}
-S \rightarrow y & >9< \\
S & >x \rightarrow 5
\end{aligned}
$$


$-S \rightarrow r$

## Dijkstra’s Algorithm: Correctness

- Suppose $a$ is the next node removed from the queue.
- No other node incomplete node has a shorter path discovered so far
- Claim: no undiscovered path to $a$ could be shorter
- Consider any other incomplete node $b$ that is 1 edge away from a complete node
- $a$ is the closest node that is one away from a complete node
- Thus no path that includes $b$ can be a shorter path to $a$

- Therefore the shortest path to a must use only complete nodes, and therefore we have found it already!


## Dijkstra’s Algorithm: Correctness

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- Claim: no undiscovered path to $a$ could be shorter
- Consider any other incomplete node $b$ that is 1 edge away from a complete node
- $a$ is the closest node that is one away from a complete node

- No path from $b$ to $a$ can have negative weight
- Thus no path that includes $b$ can be a shorter path to $a$
- Therefore the shortest path to $a$ must use only complete nodes, and therefore we have found it already!


## A Programming Assumption Reconsidered

- So far:
- Programs run by executing one line of code at a time in the order written
- Called Sequential Programming
- Removing this assumptions creates challenges and opportunities
- Programming: Divide computation across several parallel threads, then coordinate (synchronize) across them.
- Algorithms: This parallel processing can speed up computation by increasing throughput (operations done per unit time)
- Data Structures: May need to support concurrent access (multiple parallel processes attempting to use it at once)


## Why Parallelism?

- Pre 2005:


7. Processors "naturally" got faster at an exponential rate ( $\sim 2 x$ faster every $\sim 2$ years)

- Since 2005:
- Some components cannot be improved in the same way due to limitations of physics
- Solution: increase computing speed by just adding more processors


## What to do with the extra processors?

- Time Slicing:
- Your computer is always keeping track of multiple things at once
- running the OS, rendering the display, running Powerpoint, autosaving a document, etc.
- Multiple processors allow for the multiple tasks to be spread across them, so each processor dedicates more time to each one
- Parallelism (our focus):
- Multiple processors collaborate on the same task.


## Parallelism Vs. Concurrency (with Potatoes)

- Sequential:
- The task is completed by just one processor doing one thing at a time
- There is one cook who peels all the potatoes
- Parallelism:
- One task being completed by may threads
- Recruit several cooks to peel a lot of potatoes faster
- Concurrency:
- Parallel tasks using a shared resource
- Several cooks are making their own recipes, but there is only 1 oven


## New Story of Code Execution

## - Old Story:

- One program counter (current statement executing)
- One call stack (with each stack frame holding local variables)
- Objects in the heap created by memory allocation (i.e., new)
- (nothing to do with data structure called a heap)
- New Story:
- Collection of threads each with its own:
- Program Counter
- Call Stack
- Local Variables
- References to objects in a shared heap


## Old Story

Call Stack
Heap Containing Objects and
Call Stack Static Fields
Program Counter
Local Variables (primitives and references to Heap objects)


## New Story

Threads, each with its own unshared:
Call Stack
Program Counter
Local Variables (primitives and references
to Heap objects)


## Needs from Our Programming Language

- A way to create multiple things running at once
- Threads
- Ways to share memory
- References to common objects
- Ways for threads to synchronize
- For now, just wait for other threads to finish their work


## Parallelism Example (not real code)

## - Goal: Find the sum of an array

- Idea: 4 processors will each find the sum of one quarter of the array, then we can add up those 4 results

Note: This FORALL construct does not exist, but it's similar to how we'll actually do it.

```
int sum(int[] arr){
    res = new int[4];
    len = arr.length;
    FORALL(i=0; i < 4; i++) { //parallel iterations
        res[i] = sumRange(arr,i*len/4,(i+1)*len/4); }
    return res[0]+res[1]+res[2]+res[3];
}
int sumRange(int[] arr, int lo, int hi) {
    result = 0;
    for(j=lo; j < hi; j++)
        result += arr[j]; return result;
}
```


## Java.lang.Thread

- To run a new thread:

1. Define a subclass $\mathbf{C}$ of java.lang.Thread, overriding run
2. Create an object of class $\mathbf{C}$
3. Call that object's start method

- start sets off a new thread, using run as its "main"
- Calling "run" directly causes the program to execute "run" sequentially


## Back to Summing an Array

- Goal: Find the sum of an array
- Idea: 4 threads each find the sum of one quarter of the array
- Process:
- Create 4 thread objects, each given a portion of the work
- Call start() on each thread object to run it in parallel
- Wait for threads to finish using join()
- Add together their 4 answers for the final result



## First Attempt (part 1, defining Thread Object)

class SumThread extends java.lang.Thread \{
int lo; // fields, assigned in the constructor
int hi; // so threads know what to do.
int[] arr;
int ans $=0$; // result

SumThread(int[] a, int I, int h) \{
lo=l; hi=h; arr=a;
\}
public void run() \{//override must have this type
for(int i=lo; i < hi; i++)
ans += arr[i];
\}

## First Attempt (part 2, Creating Thread Objects)

```
class SumThread extends java.lang.Thread {
    int lo, int hi, int[] arr; // fields to know what to do
    int ans = 0; // result
    SumThread(int[] a, int l, int h) {...}
    public void run(){ ... }// override }
int sum(int[] arr){ // can be a static method
    int len = arr.length;
    int ans = 0;
    SumThread[] ts = new SumThread[4];
    for(int i=0; i < 4; i++) // do parallel computations
        ts[i] = new SumThread(arr,i*len/4,(i+1)*len/4);
    for(int i=0; i < 4; i++) // combine results
        ans += ts[i].ans;
    return ans;
}
```


## First Attempt (part 3, Running Thread Objects)

```
class SumThread extends java.lang.Thread {
    int lo, int hi, int[] arr; // fields to know what to do
    int ans = 0; // result
    SumThread(int[] a, int l, int h) { ... }
    public void run(){ ... } // override }
int sum(int[] arr){ // can be a static method
    int len = arr.length;
    int ans = 0;
    SumThread[] ts = new SumThread[4];
    for(int i=0; i < 4; i++){ // do parallel computations
        ts[i] = new SumThread(arr,i*len/4,(i+1)*len/4);
        ts[i].start(); // start not run}
    for(int i=0; i < 4; i++) // combine results
        ans += ts[i].ans;
    return ans; }
```


## First Attempt (part 4, Synchronizing)

class SumThread extends java.lang.Thread \{
int lo, int hi, int[] arr; // fields to know what to do
int ans = 0; // result
SumThread(int[] a, int I, int h) \{ ... \}
public void run() $\{.$.$\} // override \}$
int sum(int[] arr)\{ // can be a static method
int len = arr.length;
int ans = 0;
SumThread[] ts = new SumThread[4];
for(int $i=0 ; i<4 ; i++)\{/ /$ do parallel computations
ts[i] = new SumThread(arr,i*len/4,(i+1)*len/4);
ts[i].start(); // start not run\}
for(int $i=0 ; i<4 ; i++) / /$ combine results
ts[i].join(); // wait for thread to finish!
ans += ts[i].ans;
return ans; \}

## Join

- Causes program to pause until the other thread completes its run method
- Avoids a race condition
- Without join the other thread's ans field may not have its final answer yet


## Flaws With this Attempt

int sum(int[] arr, int numTs) $\{/ /$ can be a static method

```
Different machines have different numbers
of processors!
Making the thread count a parameter helps make your program more efficient
and reusable across computers
```

int ans = 0;
SumThread[] ts = new SumThread[numTs]; for(int i=0; i < numTs; $\mathrm{i}++$ ) $/ / /$ do parallel computations ts[i] = new SumThread(arr,i*len/numTs,(i+1)*len/numTs); ts[i].start(); // start not run\}
for(int i=0; i < numTs; i++) // combine results
ts[i].join(); // wait for thread to finish!
ans += ts[i].ans;
return ans; \}

## Flaws With this Attempt

- Even If we make the number of threads equal the number of processors, the OS is doing time slicing, so we might not have all processors available right now
- For some problems, not all subproblems will take the same amount of time:
- E.g. determining whether all integers in an array are prime.


## One Potential Solution: More Threads!

- Identify an "optimal" workload per thread
- E.g. maybe it's not worth splitting the work if the array is shorter than 1000
- Split the array into chunks using this "sequential Cutoff"
- numTs = len/SEQ_CUTOFF;
- Problem: One process is still responsible for summing all len/1000 results
- Process is still linear time


## A Better Solution: Divide and Conquer!

- Idea: Each thread checks its problem size. If its smaller than the sequential cutoff, it will sum everything sequentially. Otherwise it will split the problem in half across two separate threads.


## Merge Sort

| 5 | 8 | 2 | 9 | 4 | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |

- If the list is of length 1 or 0 , it's already sorted, so just return it

| 5 | 8 | 2 | 9 | 4 | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |

- Split the list into two "sublists" of (roughly) equal length

| 2 | 5 | 8 | 1 | 4 | 9 |
| :--- | :--- | :--- | :--- | :--- | :--- |

- Sort both lists recursively

| 2 | 5 | 8 | 1 | 4 | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
| 1 | 2 | 4 | 5 | 8 | 9 |

## Parallel Sum

| 5 | 8 | 2 | 9 | 4 | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |

5

- Base Case:
- If the list's length is smaller than the Sequential Cutoff, find the sum sequentially


| 9 | 4 | 1 |
| :--- | :--- | :--- |

## - Divide:

- Split the list into two "sublists" of (roughly) equal length, create a thread to sum each sublist.
- Conquer:
- Call start() for each thread
- Combine:
- Sum together the answers from each thread

```
Divide and Conquer with Threads
class SumThread extends java.lang.Thread {
    public void run(){ // override
        if(hi - lo < SEQUENTIAL_CUTOFF) // "base case"
        for(int i=lo; i < hi; i++) ans += arr[i];
        else {
            SumThread left = new SumThread(arr,lo,(hi+lo)/2); // divide
            SumThread right= new SumThread(arr,(hi+lo)/2,hi); // divide
            left.start(); // conquer
            right.start(); // conquer
            left.join(); // don't move this up a line - why?
            right.join();
            ans = left.ans + right.ans; // combine
    }
    }
}
int sum(int[] arr){ // just make one thread!
    SumThread t = new SumThread(arr,0,arr.length);
    t.run();
    return t.ans; }
```


## Small optimization

- Instead of calling two separate threads for the two subproblems, create one parallel thread (using start) and one sequential thread (using run)

```
Divide and Conquer with Threads (optimized)
class SumThread extends java.lang.Thread {
    public void run(){ // override
                        if(hi - lo < SEQUENTIAL_CUTOFF) // "base case"
                for(int i=lo; i < hi; i++) ans += arr[i];
        else {
            SumThread left = new SumThread(arr,lo,(hi+lo)/2); // divide
            SumThread right= new SumThread(arr,(hi+lo)/2,hi); // divide
            left.start(); // conquer
            right.run(); // conquer
            left.join(); // don't move this up a line - why?
            //right.join();
                        ans = left.ans + right.ans; // combine
    }
    }
}
int sum(int[] arr){ // just make one thread!
    SumThread t = new SumThread(arr,0,arr.length);
    t.run();
    return t.ans; }
```


## ForkJoin Framework

- This strategy is common enough that Java (and C++, and C\#, and...) provides a library to do it for you!

| What you would do in Threads | What to instead in ForkJoin |
| :--- | :--- |
| Subclass Thread | Subclass RecursiveTask<V> |
| Override run | Override compute |
| Store the answer in a field | Return a V from compute |
| Call start | Call fork |
| join synchronizes only | join synchronizes and returns the answer |
| Call run to execute sequentially | Call compute to execute sequentially |
| Have a topmost thread and call run | Create a pool and call invoke |

## Divide and Conquer with ForkJoin

```
class SumTask extends RecursiveTask {
    int lo; int hi; int[] arr; // fields to know what to do
    SumTask(int[] a, int I, int h) { ... }
    protected Integer compute(){// return answer
    if(hi - lo < SEQUENTIAL_CUTOFF) { // base case
        int ans = 0; // local var, not a field
        for(int i=lo; i < hi; i++) {
        ans += arr[i]; return ans; }
    else {
        SumTask left = new SumTask(arr,lo,(hi+lo)/2); // divide
        SumTask right= new SumTask(arr,(hi+lo)/2,hi); // divide
        left.fork(); // fork a thread and calls compute (conquer)
        int rightAns = right.compute(); //call compute directly (conquer)
        int leftAns = left.join(); // get result from left
        return leftAns + rightAns; // combine
    }
}
}
```


## Divide and Conquer with ForkJoin (continued)

static final ForkJoinPool POOL = new ForkJoinPool();
int sum(int[] arr)\{
SumTask task = new SumTask(arr,0,arr.length)
return POOL.invoke(task); // invoke returns the value compute returns

## Section

- Working with examples of ForkJoin
- Make sure to bring your laptops!
- And charge it!

