# CSE 332 Winter 2024 Lecture 6: Priority Queues and Recurrences

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### ADT: Priority Queue

- What is it?
  - A collection of items and their "priorities"
  - Allows quick access/removal to the "top priority" thing
- What Operations do we need?
  - insert(item, priority)
    - Add a new item to the PQ with indicated priority
      - Usually, smaller priority value means more important
    - deleteMin
      - Remove and return the "top priority" item from the queue
  - Is\_empty
    - Indicate whether or not there are items still on the queue
- Note: the "priority" value can be any type/class so long as it's comparable (i.e. you can use "<" or "compareTo" with it)</li>

### Thinking through implementations

Data Structure	Worst case time to insert	Worst case time to deleteMin
Unsorted Array	$\Theta(1)$	$\Theta(n)$
Unsorted Linked List	Θ(1)	$\Theta(n)$
Sorted Array	$\Theta(n)$	$\Theta(n)$
Sorted Linked List	$\Theta(n)$	$\Theta(1)$
Binary Search Tree	$\Theta(n)$	$\Theta(n)$
Binary Heap	$\Theta(\log n)$	$\Theta(\log n)$
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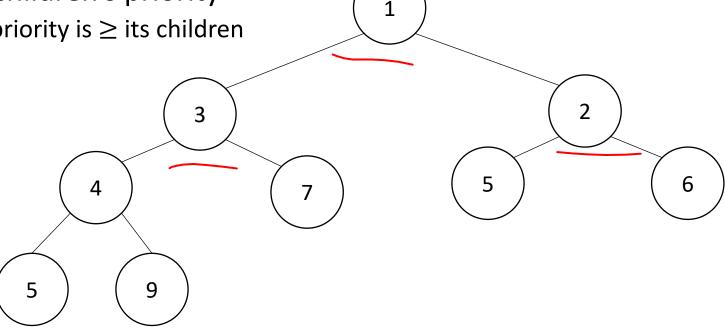
Note: Assume we know the maximum size of the PQ in advance

#### Trees for Heaps

• Binary Trees: • The branching factor is 2 • Every node has  $\leq$  2 children Tree T 1 • Complete Tree: • All "layers" are full, except the bottom • Bottom layer filled left-to-right 2 3 5 6 4 7 5 9

(Min) Heap Data Structure

- Keep items in a complete binary tree
- Maintain the "(Min) Heap Property" of the tree
  - Every node's priority is  $\leq$  its children's priority
  - Max Heap Property: every node's priority is  $\geq$  its children

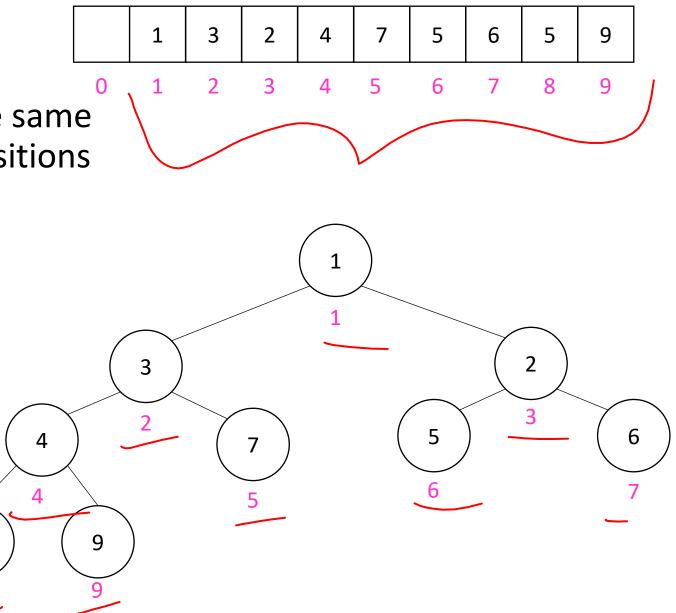


### Representing a Heap

 Every complete binary tree with the same number of nodes uses the same positions and edges

5

- Use an array to represent the heap
- Index of root: 1
- Parent of node *i*:
- Left child of node *i*:
- Right child of node  $i: \bigvee$
- Location of the leaves:



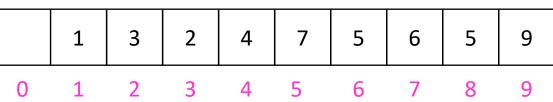


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#### Representing a Heap



2

3

6

5

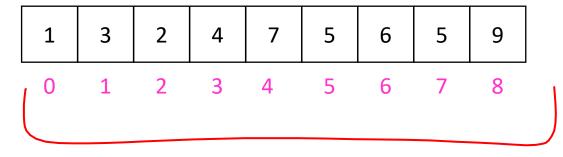
- Every complete binary tree with the same number of nodes uses the same positions and edges
- Use an array to represent the heap
- Index of root: 1
- Parent of node  $i: \frac{i}{2}$
- Left child of node *i*: 2*i*
- Right child of node i: 2i + 1
- Location of the leaves: last

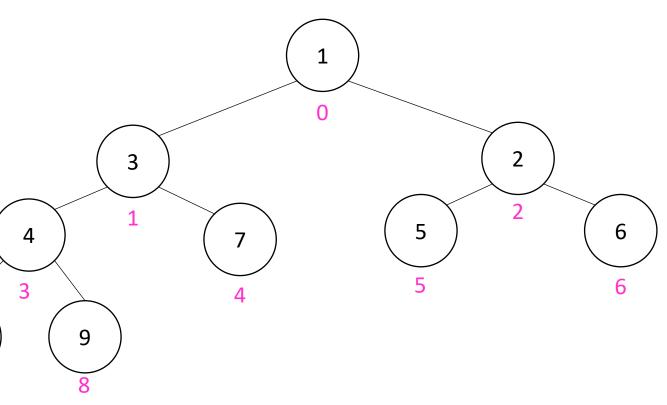
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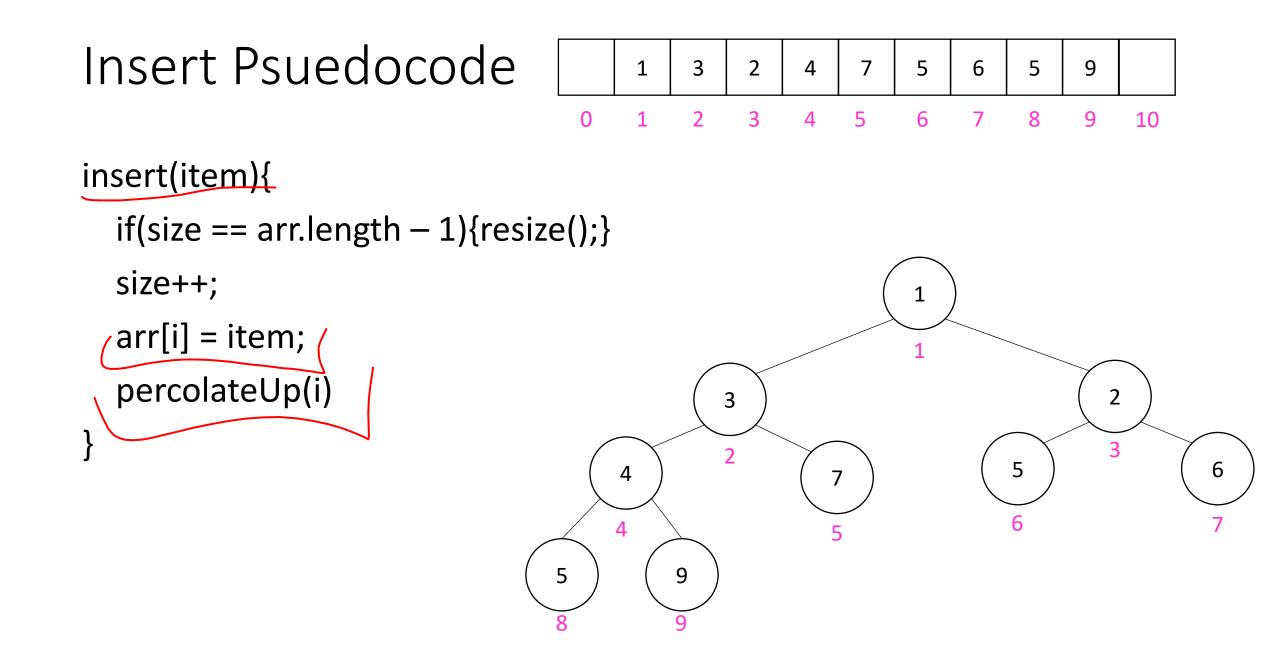
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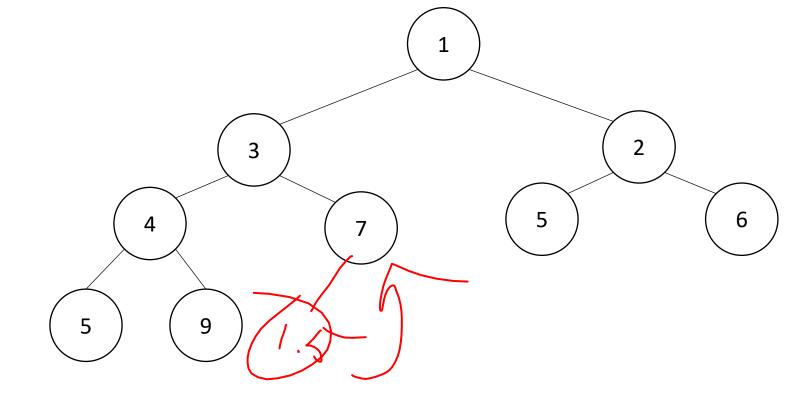
- Use an array to represent the heap
- Index of root: 🗸
- Parent of node  $i \begin{pmatrix} i+1 \\ 2 \end{pmatrix} 1$
- Left child of node i: 2(i + 1) i
- Right child of node i: 2(i + 1)
- Location of the leaves: last







# Heap Insert 1.5



insert(item){

put item in the "next open" spot (keep tree complete)
while (item.priority < parent(item).priority){
 swap item with parent</pre>

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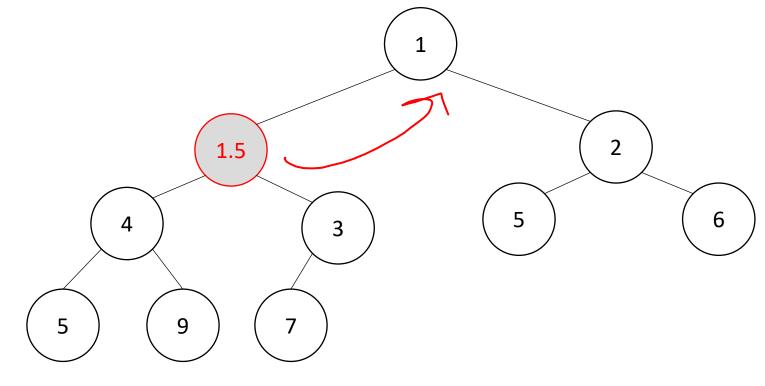
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– Percolate Up

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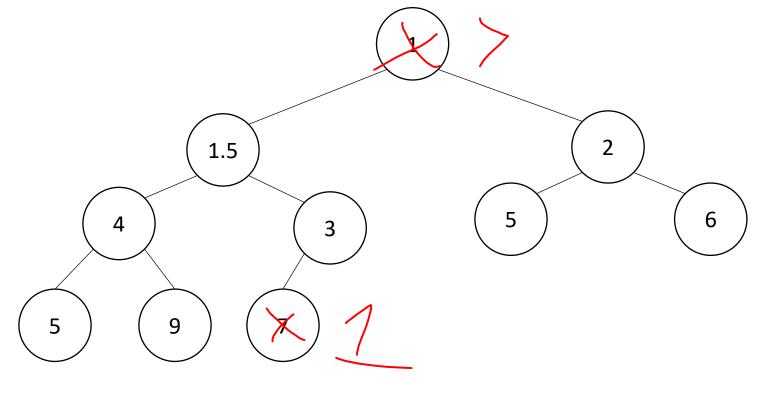
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deleteMin(){

- min = root
- br = bottom-right item
- move br to the root
- while(br > either of its children){
   swap br with its smallest child

```
}
```



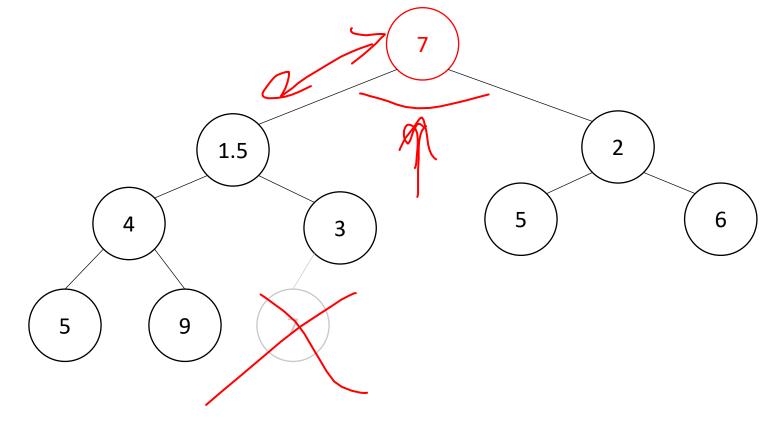
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 $\begin{array}{c} 7 \\ 7 \\ 4 \\ 9 \end{array}$ 

Percolate Down

5

deleteMin(){

min = root

return min

br = bottom-right item

move br to the root

```
while(br > either of its children){
   swap br with its smallest child
}
```

<sup>–</sup> Percolate Down

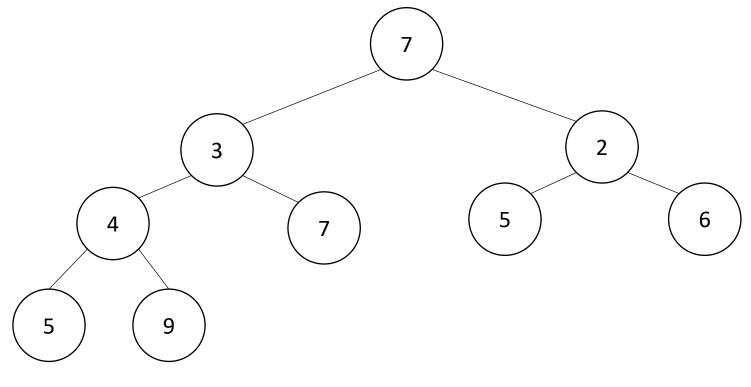
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move br to the root

while(br > either of its children){
 swap br with its smallest child



# Percolate Up and Down (for a Min Heap)

- Goal: restore the "Heap Property"
- Percolate Up:
  - Take a node that may be smaller than a parent, repeatedly swap with a parent until it is larger than its parent
- Percolate Down:
  - Take a node that may be larger than one of its children, repeatedly swap with smallest child until both children are larger
- Worst case running time of each:
  - $\Theta(\log n)$

## Percolate Up

L. INdex

percolateUp(int i){

int parent = i/2; \\ index of parent

```
Item val = arr[i]; \\ value at current location
```

```
while(i > 1 && arr[i].priority < arr[parent].priority){ \\ until location is root or heap property holds
arr[i] = arr[parent]; \\ move parent value to this location
arr[parent] = val; \\ put current value into parent's location
i = parent; \\ make current location the parent
parent = i/2; \\ update new parent</pre>
```

#### DeleteMin Psuedocode

```
deleteMin(){
  theMin = arr[1];
  arr[1] = arr[size];
  size--;
  percolateDown(1);
  return theMin;
}
```

#### Percolate Down

```
percolateDown(int i){
  int left = i*2; \\ index of left child
  int right = i*2+1; \\ index of right child
  Item val = arr[i]; \\ value at location
  while(left <= size){ \\ until location is leaf</pre>
    int toSwap = right;
    if(right > size || arr[left].priority < arr[right] .priority){ \\ if there is no right child or if left child is smaller
       toSwap = left; \\ swap with left
    } \\ now toSwap has the smaller of left/right, or left if right does not exist
    if (arr[toSwap] .priority < val.priority) { \\ if the smaller child is less than the current value
       arr[i] = arr[toSwap];
       arr[toSwap] = val; \\ swap parent with smaller child
       i = toSwap; \\ update current node to be smaller child
       left = i^2;
       right = i^{*}2+1;
```

else{ return;} \\ if we don't swap, then heap property holds

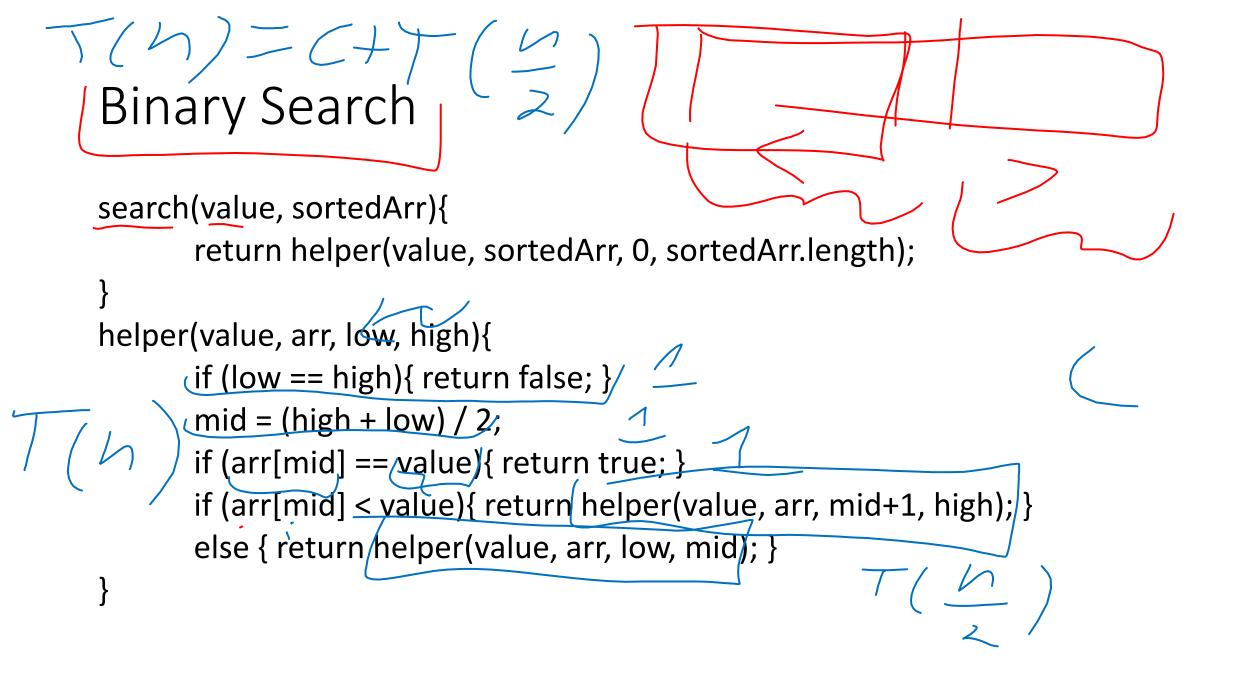
}

#### Other Operations



- Increase Key
  - Given the index of an item in the PQ, make its priority value larger
    - Min Heap: Then percolate down
    - Max Heap: Then percolate up
- Decrease Key
  - Given the index of an item in the PQ, make its priority value smaller
    - Min Heap: Then percolate up
    - Max Heap: Then percolate down
- Remove
  - Given the item at the given index from the PQ

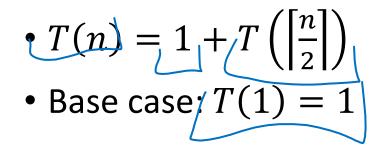




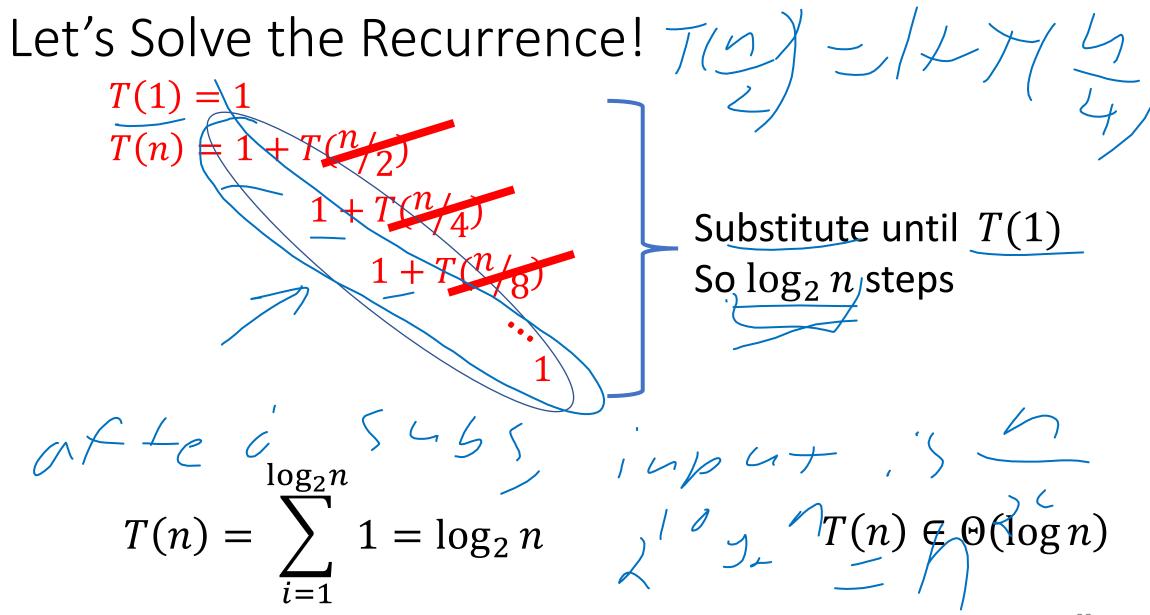
#### Analysis of Recursive Algorithms

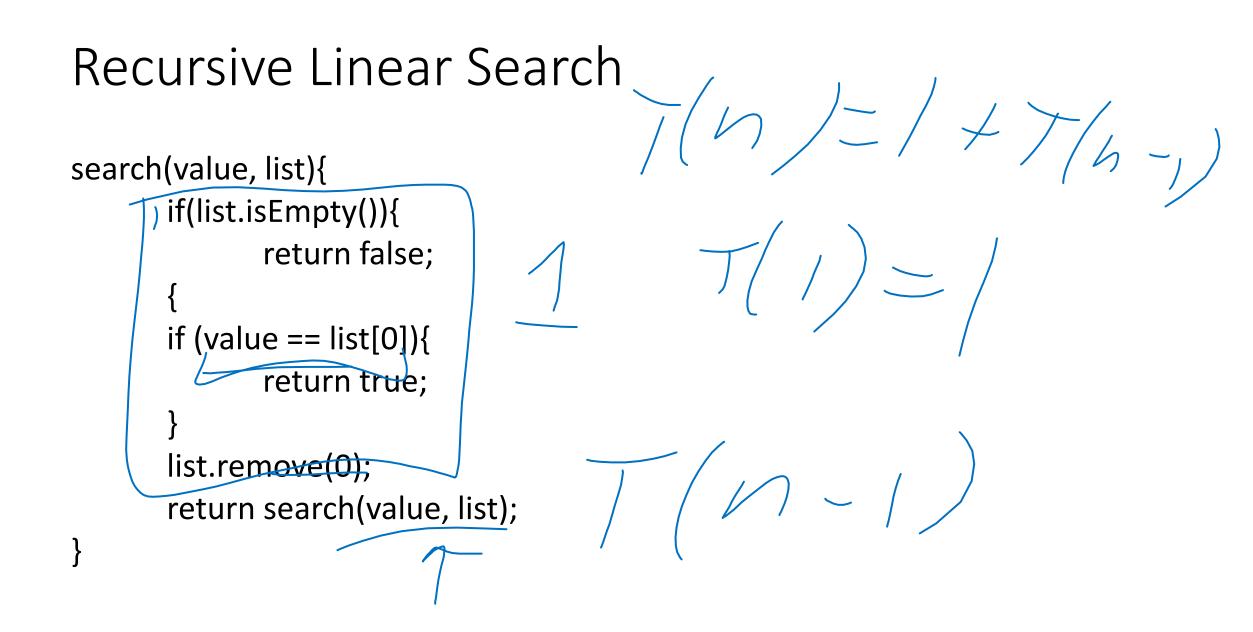
- Overall structure of recursion:
  - Do some non-recursive "work" 🥧
  - Do one or more recursive calls on some portion of your input
  - Do some more non-recursive "work"
  - Repeat until you reach a base case
- Running time:  $T(n) = T(p_1) + T(p_2) + \dots + T(p_x) + f(n)$ 
  - The time it takes to run the algorithm on an input of size *n* is:
  - The sum of how long it takes to run the same algorithm on each smaller input
  - Plus the total amount of non-recursive work done at that step
- Usually:
  - $T(n) = a \cdot T\left(\frac{n}{b}\right) + f(n)$ 
    - Called "divide and conquer"
  - T(n) = T(n-c) + f(n)
    - Called "chip and conquer"

How Efficient Is It?



T(n) = "cost" of running the entire algorithm on an array of length n

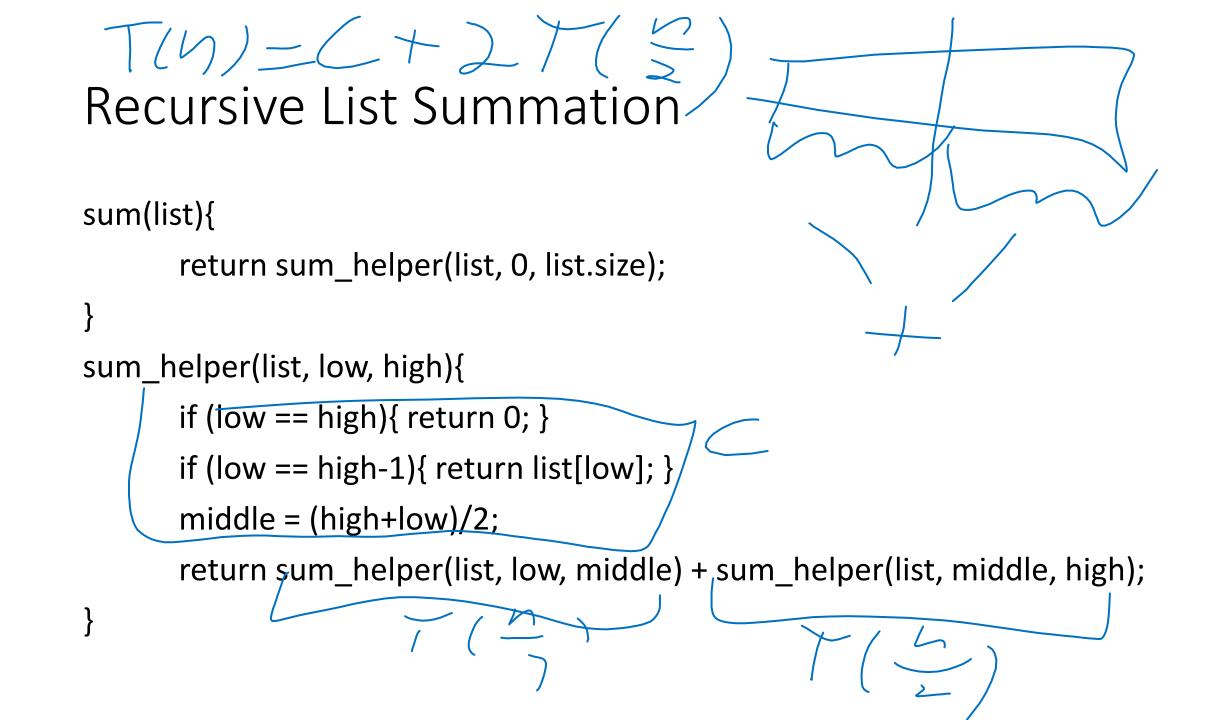




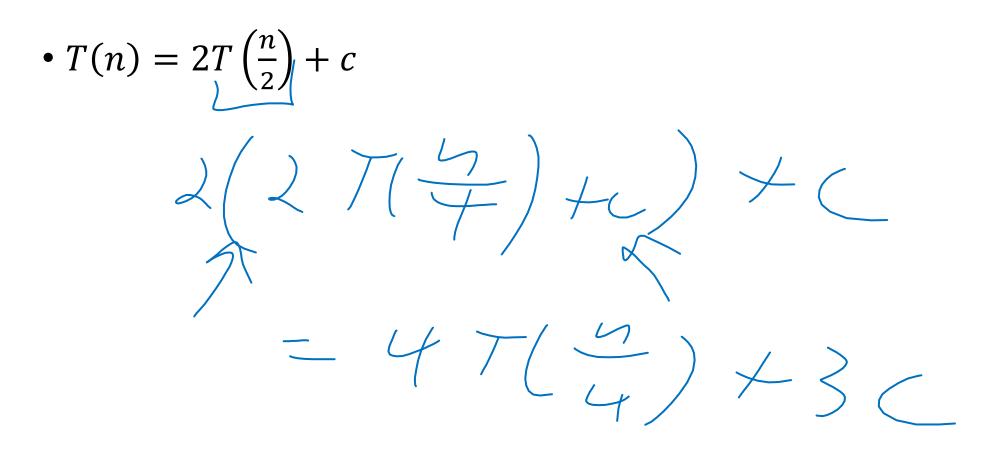
#### Unrolling Method

- Repeatedly substitute the recursive part of the recurrence
- T(n) = T(n-1) + c• T(n) = T(n-2) + c + c
- T(n) = T(n-3) + c + c + c
- $T(n) = c + c + c + \dots + c$ • How many *c*'s?



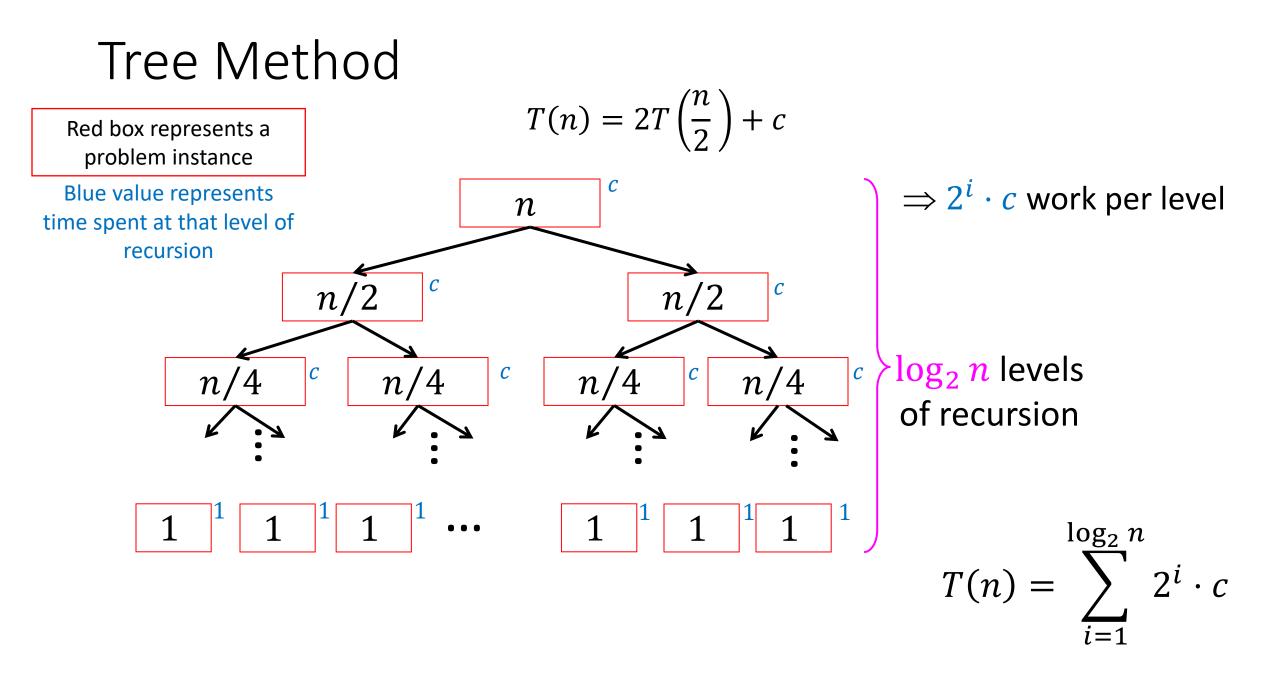


#### Loop Unrolling Method



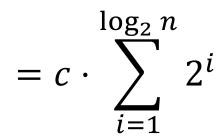
#### Loop Unrolling Method

•  $T(n) = 2T\left(\frac{n}{2}\right) + c$ •  $T(n) = 2\left(2T\left(\frac{n}{4}\right) + c\right) + c = 4T\left(\frac{n}{4}\right) + 3c$ •  $T(n) = 4\left(2T\left(\frac{n}{8}\right) + c\right) + 3c = 8T\left(\frac{n}{8}\right) + \frac{7c}{4}$ • ...after i - 1 substitutions •  $T(n) = 2^{i}T\left(\frac{n}{2^{i}}\right) + (2^{i} - 1)c$ •  $T\left(\frac{n}{2^{i}}\right) = T(1)$  when  $i = \log_{2} n$ •  $T(n) = 2^{\log_2 n} T(1) + (2^{\log_2 n} - 1)c = n \cdot c_0 + cn - c = \Theta(n)$ 



#### **Recursive List Summation**

$$T(n) = \sum_{i=1}^{\log_2 n} 2^i \cdot c$$



$$= c \left( \frac{1 - 2^{\log_2 n}}{1 - 2} \right)$$