

# CSE 333

## Lecture 21 -- fork, pthread\_create

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# Administrivia

HW4 is due Thursday night

- **<panic>** if you haven't started yet **</panic>**
- Usual late days apply *if* you have any left

Final exam Wednesday, June 10, **8:30 am** here

- Overview/review in sections this week
- Last minute Q&A Tuesday, June 9, 4:30 pm, EEB 045



# Some common HW4 bugs

Your server works, but is really really slow

- check the 2nd argument to the QueryProcessor constructor

Funny things happen after the first request

- make sure you're not destroying the HTTPConnection object too early (e.g., falling out of scope in a while loop)

Server crashes on blank request

- make sure you handle the case that read() [or WrappedRead] returns 0



# Previously

We implemented hw3 searchserver, but it was sequential

- it processed requests one at a time, in spite of client interactions blocking for arbitrarily long periods of time
  - ▶ this led to terrible performance

Servers should be concurrent

- process multiple requests simultaneously
  - ▶ issue multiple I/O requests simultaneously
  - ▶ overlap the I/O of one request with computation of another
  - ▶ utilize multiple CPUs / cores



# Today

We'll go over three versions of searchserver

- sequential
- concurrent
  - processes [ **fork()** ]
  - threads [ **pthread\_create()** ]

Alternative (which we won't get to): non-blocking, event driven version

- non-blocking I/O [ **select()** ]

Reference: *Computer Systems: A Programmer's Perspective*

- 351 textbook, good source for process/thread/OS ideas



# Sequential

pseudocode:

```
listen_fd = Listen(port);  
  
while(1) {  
    client_fd = accept(listen_fd);  
    buf = read(client_fd);  
    resp = ProcessQuery(buf);  
    write(client_fd, resp);  
    close(client_fd);  
}
```

*look at **searchserver\_sequential***



# Whither sequential?

## Benefits

- super simple to build

## Disadvantages

- incredibly poorly performing
  - ▶ one slow client causes **all** others to block
  - ▶ poor utilization of network, CPU



# fork()

```
pid_t fork(void);
```

Fork is used to create a new process (the “child”) that is an exact clone of the current process (the “parent”)

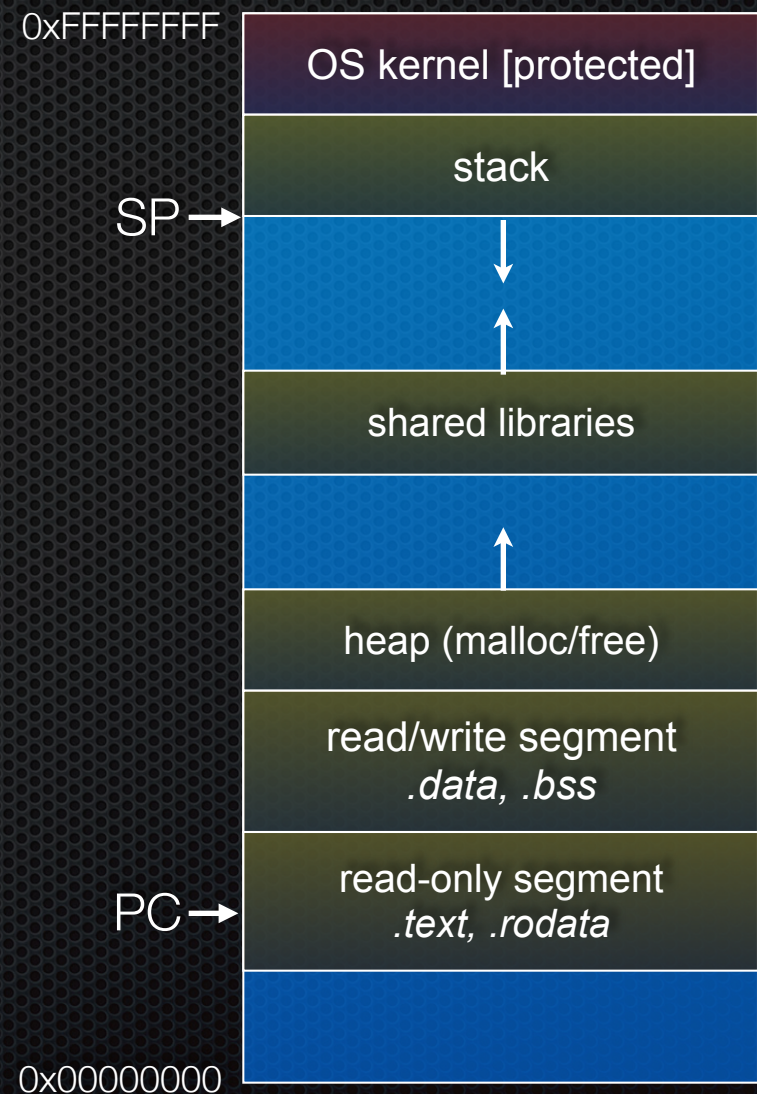
- everything is cloned (except threads)
  - ▶ all variables, file descriptors, open sockets, etc.
  - ▶ the heap, the stack, etc.
- primarily used in two patterns
  - ▶ servers: fork a child to handle a connection
  - ▶ shells: fork a child, which then exec’s a new program



# fork() and address spaces

Remember this picture...?

- a process executes within an **address space**
- the address space includes:
  - ▶ a stack (for stack frames)
  - ▶ heap (for dynamically allocated data)
  - ▶ text segment (containing code)
  - ▶ etc.

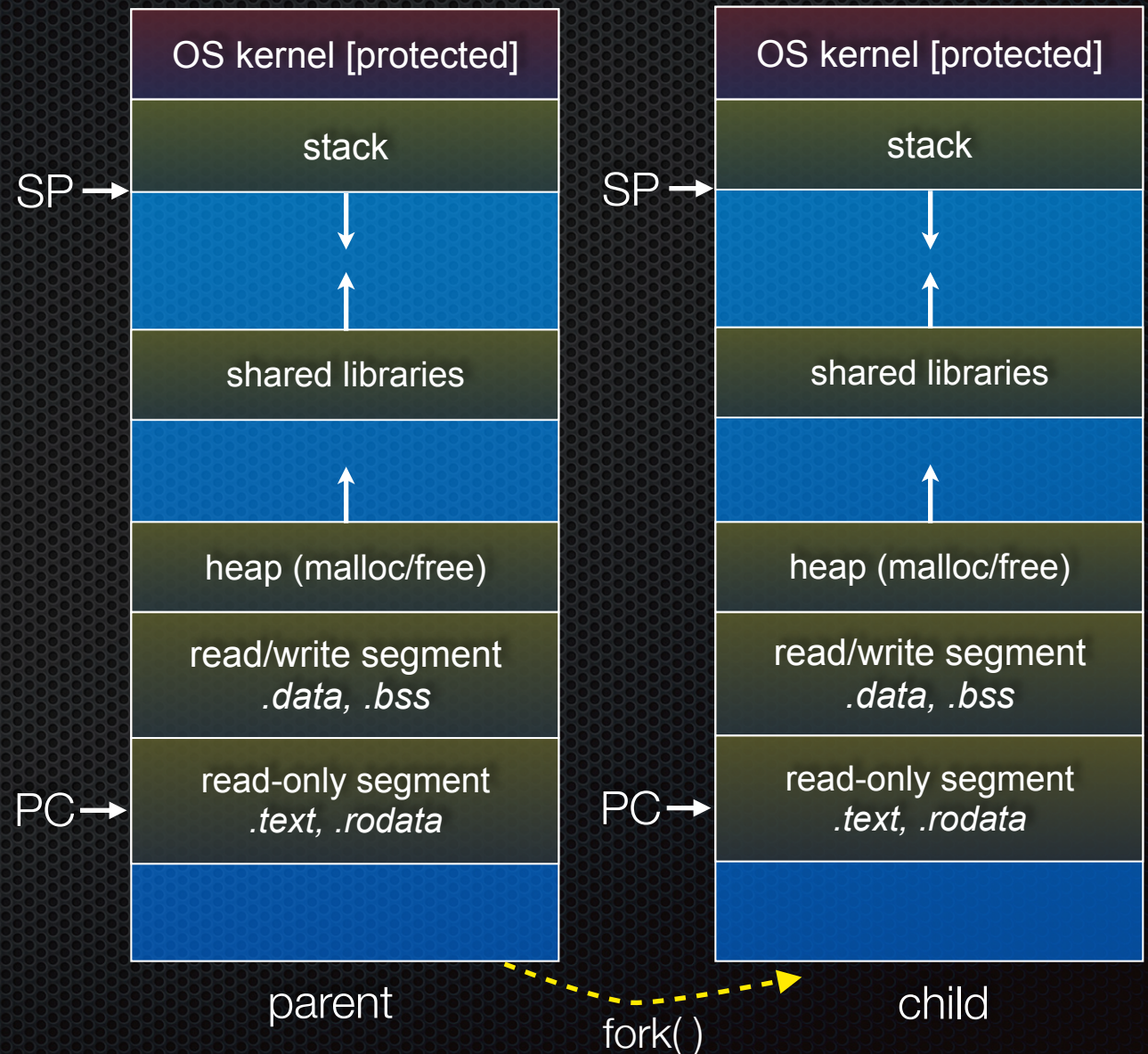




# fork() and address spaces

Fork causes the OS to clone the address space, creating a brand new process

- the new process starts life as a **copy** the old process in (nearly) every way
- the **copies** of the heap, stack, text segment, etc. are (nearly) identical
- the new process has **copies** of the parent's data structures, stack-allocated variables, open file descriptors, and so on

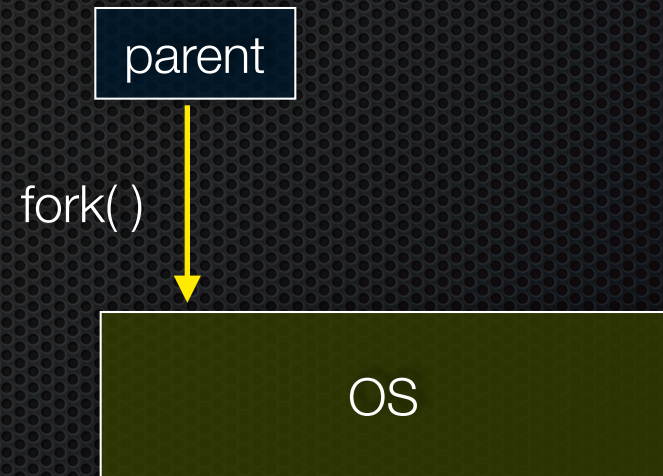




# fork()

## fork() has peculiar semantics

- the parent invokes fork()
- the operating system clones the parent
- **both** the parent and the child return from fork
  - ▶ parent receives child's pid
  - ▶ child receives a "0" as pid

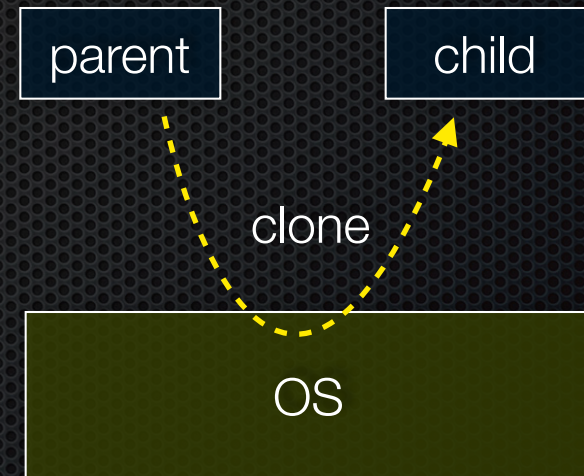




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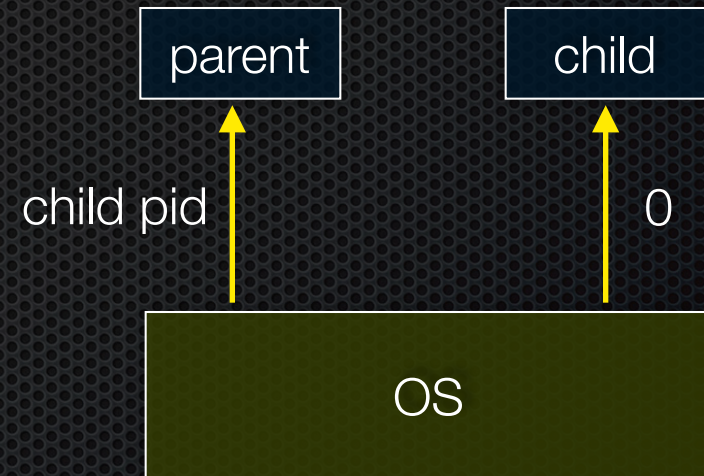




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# fork()

*fork\_example.cc*



# Concurrency with processes

The **parent** process blocks on **accept()**, waiting for a new client to connect

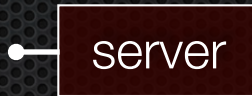
- when a new connection arrives, the parent calls **fork()** to create a **child** process
- the child process handles that new connection, and **exit()**'s when the connection terminates

Remember that children become “zombies” after death

- option a) parent calls **wait()** to “reap” children
- option b) use the double-fork trick



# Graphically



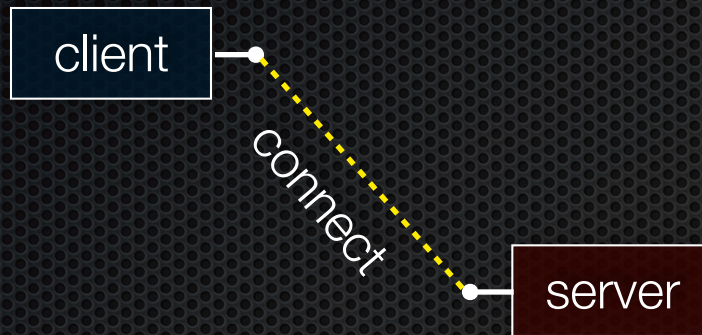


# Graphically



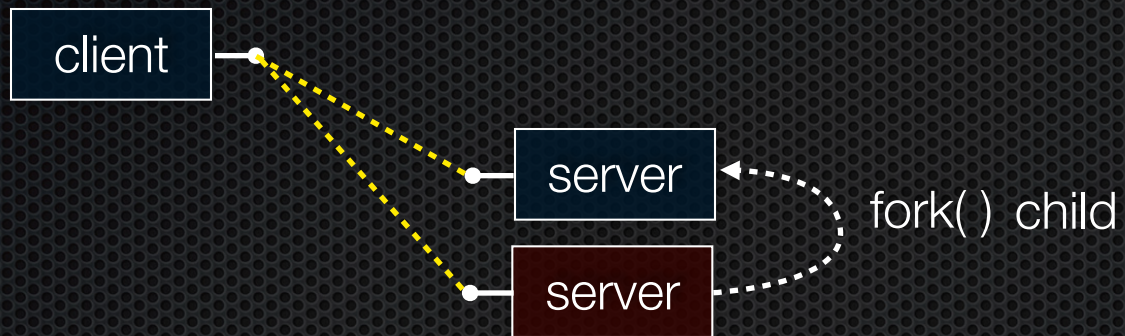


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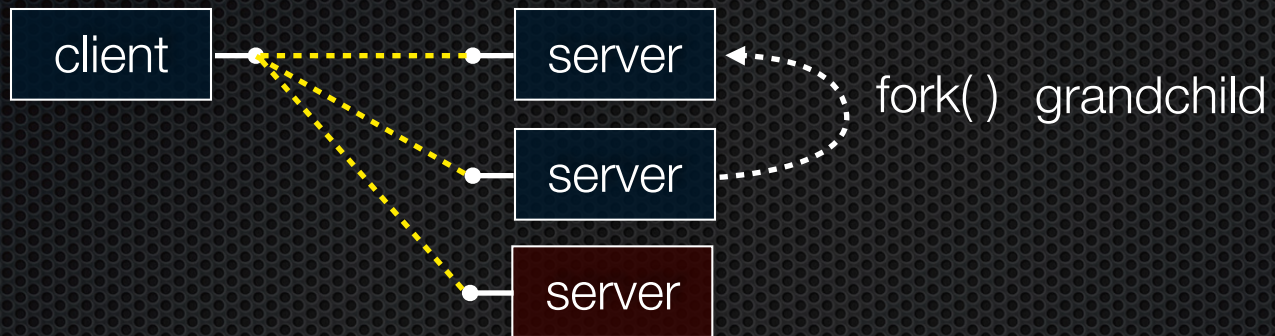


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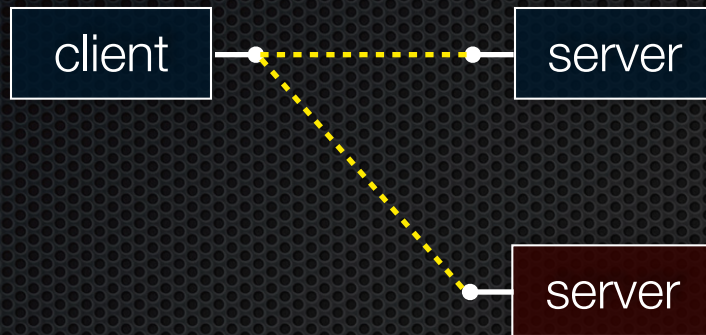


# Graphically





# Graphically



child `exit()`'s / parent `wait()`'s

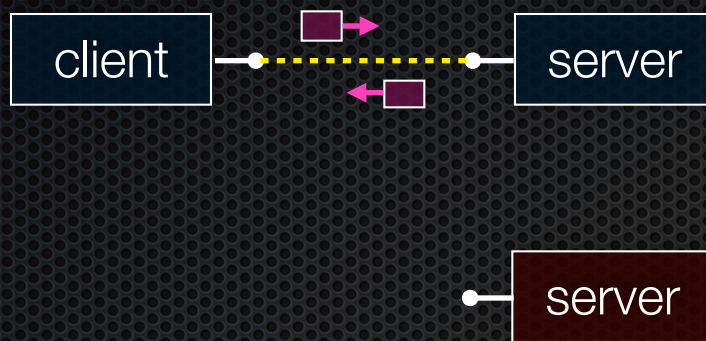


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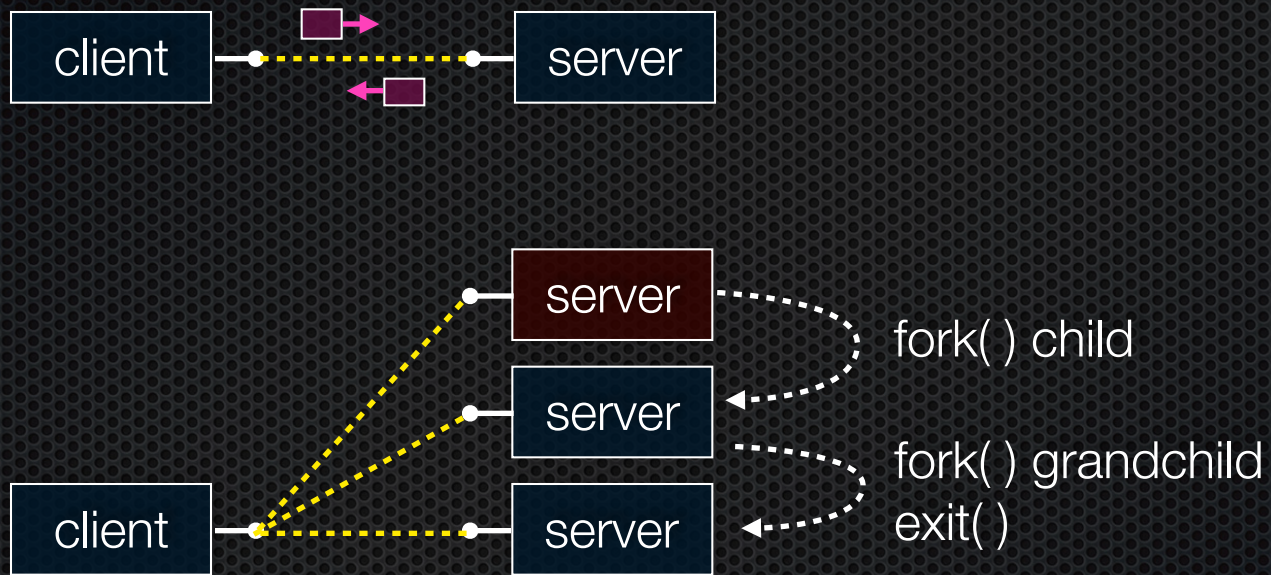


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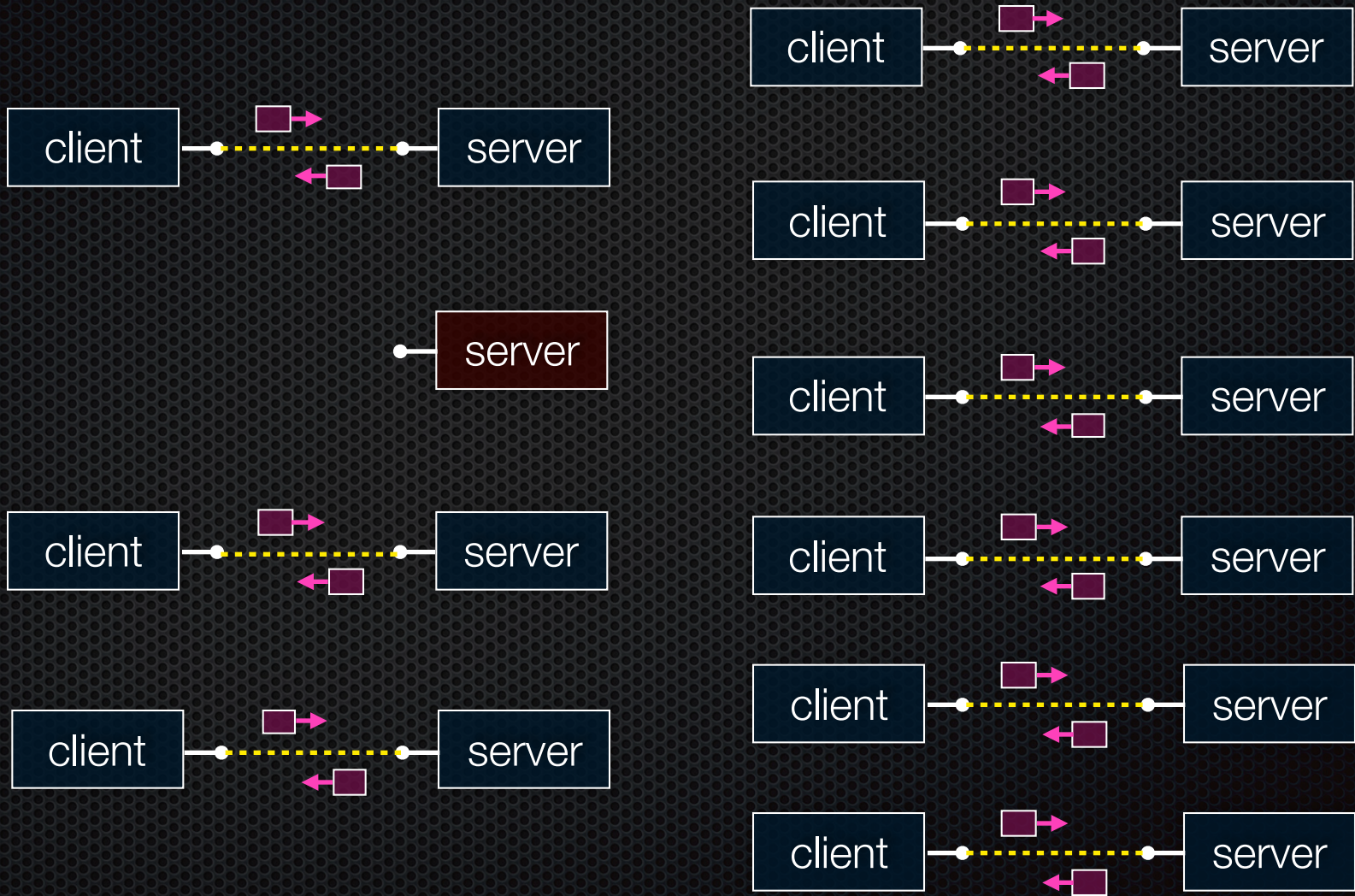


# Graphically





# Graphically





# Concurrent with processes

*look at **searchserver\_processes***



# Whither concurrent processes?

## Benefits

- almost as simple as sequential
  - ▶ in fact, most of the code is identical!
- parallel execution; good CPU, network utilization

## Disadvantages

- processes are heavyweight
  - ▶ relatively slow to fork
  - ▶ context switching latency is high
- communication between processes is complicated



# How slow is fork?

*run **forklatency.cc***



# Implications?

## 0.25 ms per fork

- maximum of  $(1000 / 0.25) = 4,000$  connections per second per core
- ~0.5 billion connections per day per core
  - ▶ fine for most servers
  - ▶ too slow for a few super-high-traffic front-line web services
    - Facebook serves  $O(750 \text{ billion})$  page views per day
    - would need 3,000 -- 6,000 cores just to handle `fork()`, i.e., without doing any work for each connection!



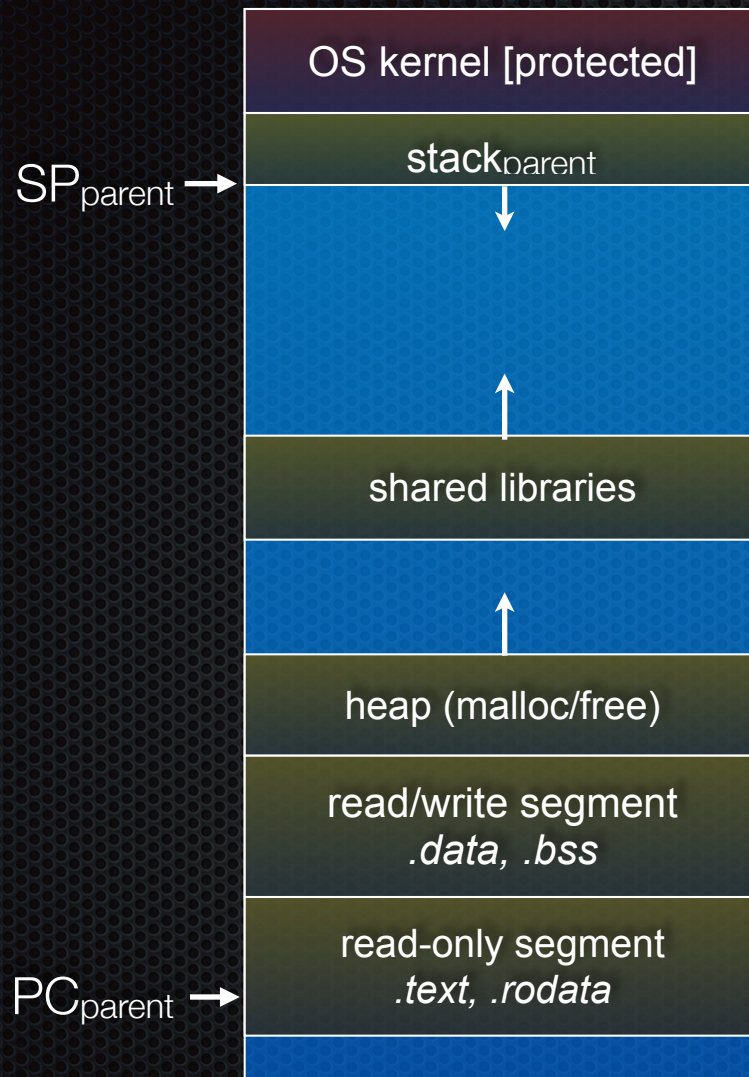
# threads

## Threads are like lightweight processes

- like processes, they execute concurrently
  - ▶ multiple threads can run simultaneously on multiple cores/CPU's
- unlike processes, threads cohabit the same address space
  - ▶ the threads within a process see the same heap and globals
    - threads can communicate with each other through variables
    - but, threads can interfere with each other: need synchronization
  - ▶ each thread has its own stack



# threads and the address space

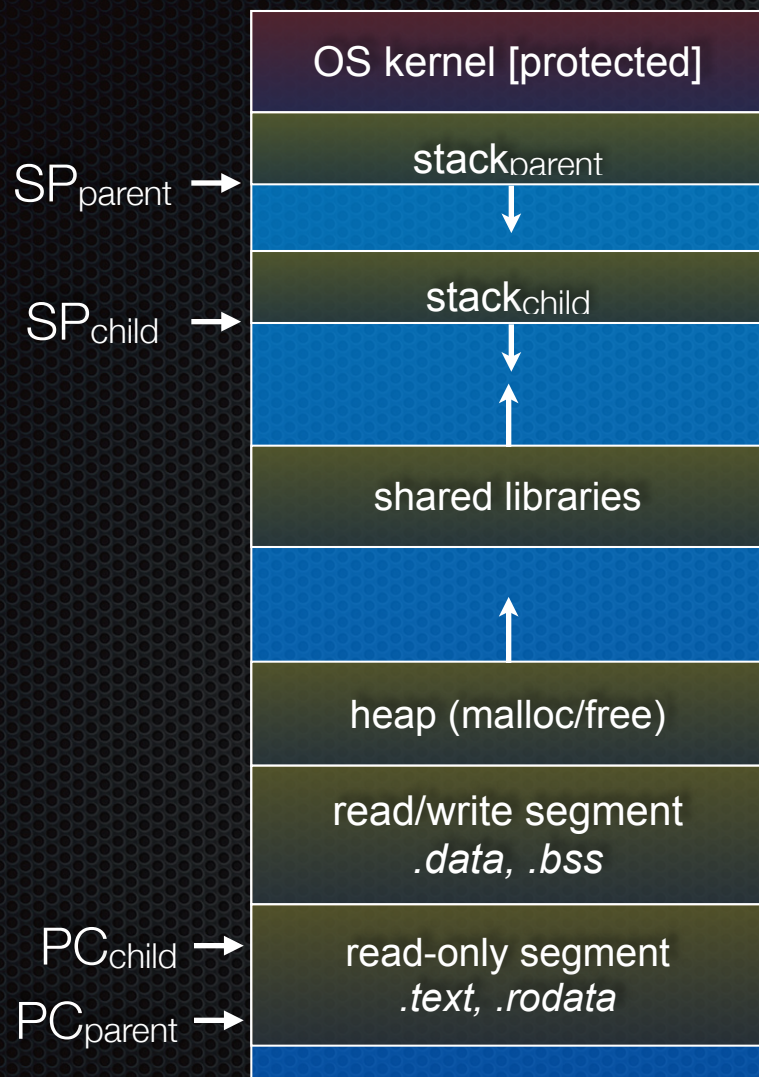


## Pre- thread create

- one thread of execution running in the address space
  - ▶ the “main” thread
  - ▶ therefore, one stack, SP, PC
- that main thread invokes a function to create a new thread
  - ▶ typically “pthread\_create( )”



# threads and the address space



## Post- thread create

- two threads of execution running in the address space
  - ▶ the “main” thread (parent)
  - ▶ the child thread
  - ▶ thus, two stacks, SPs, PCs
- both threads share the heap and text segment (globals)
  - ▶ they can cooperatively modify shared data



# threads

*see `thread_example.cc`*



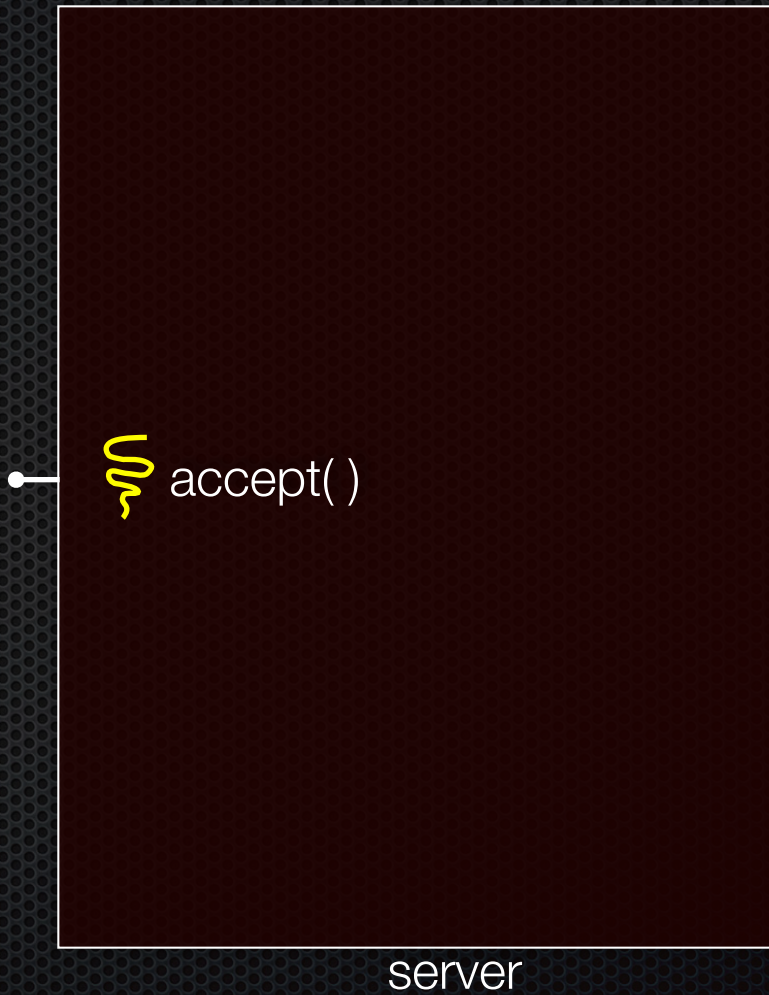
# Concurrent server with threads

A single **process** handles all of the connections

- but, a parent **thread** forks (or dispatches) a new thread to handle each connection
- the child thread:
  - ▶ handles the new connection
  - ▶ exits when the connection terminates

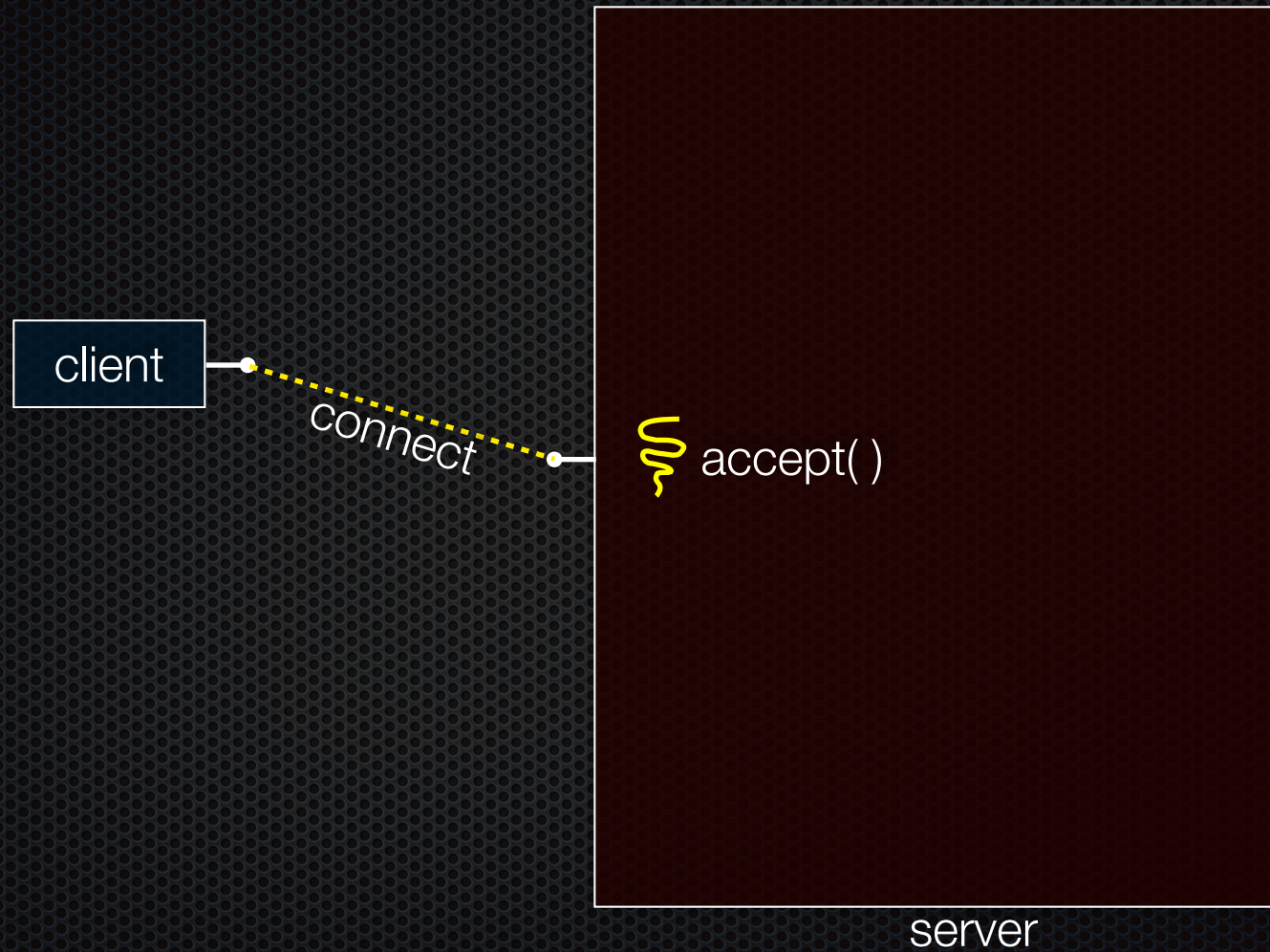


# Graphically



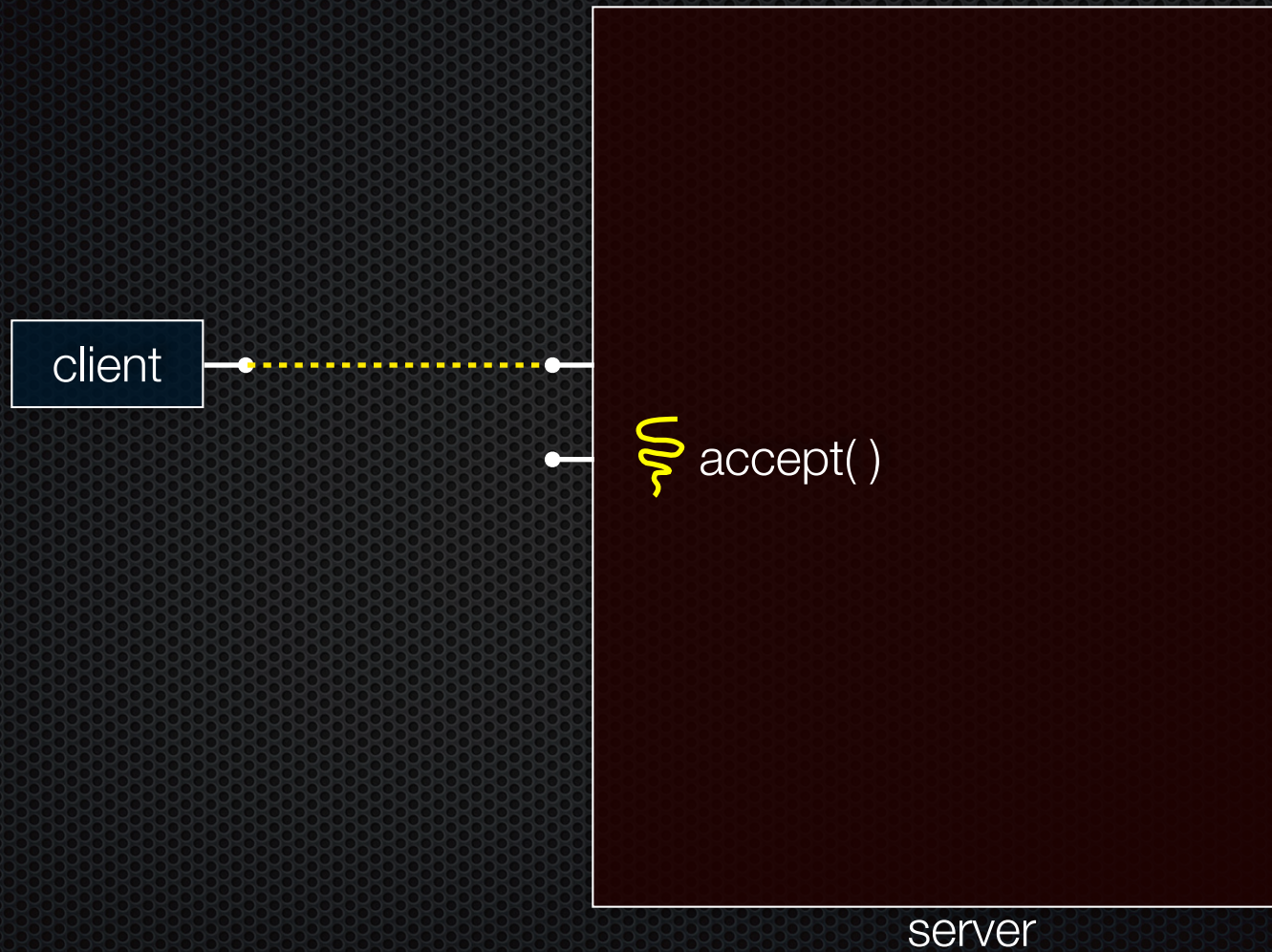


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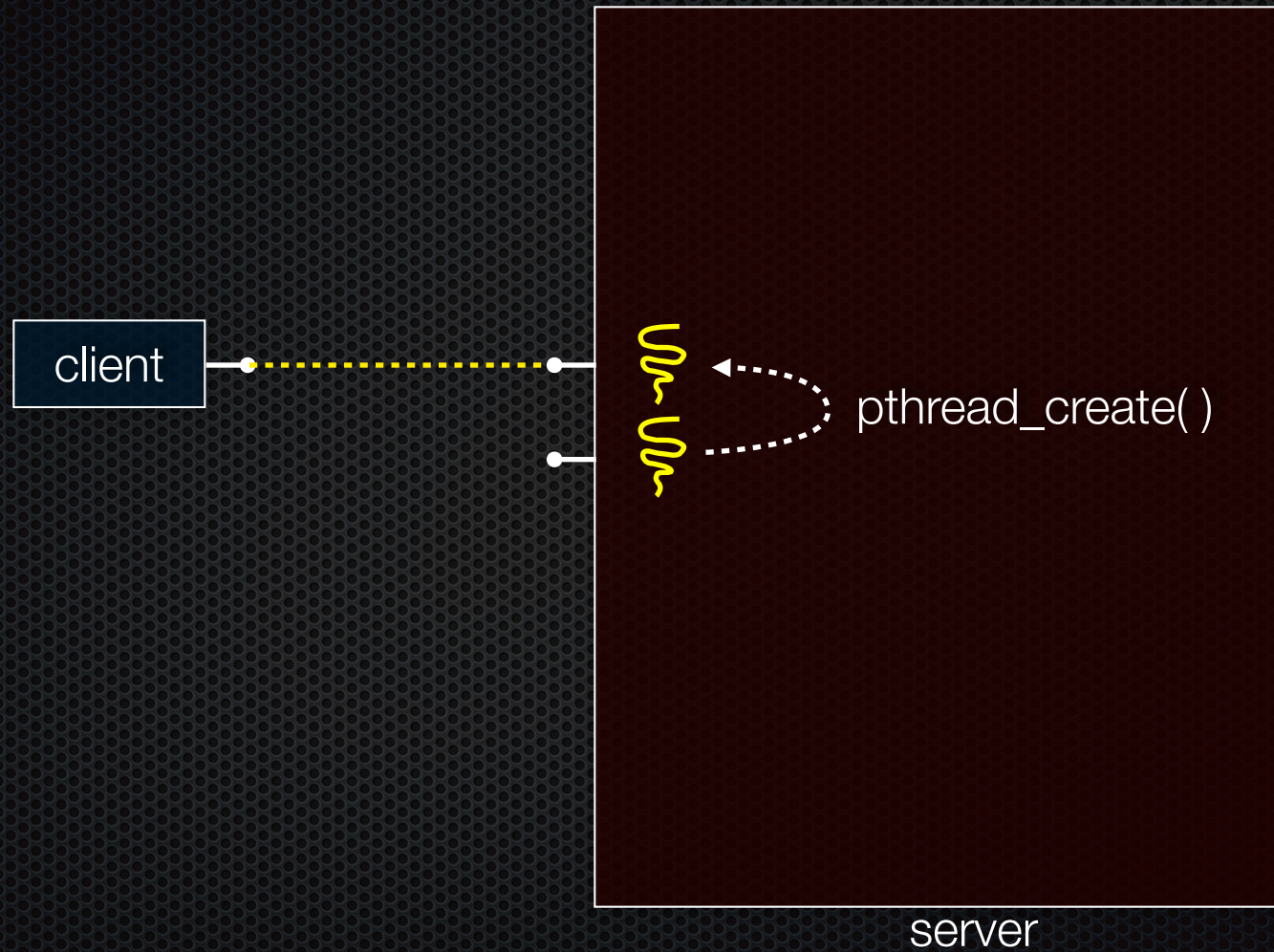


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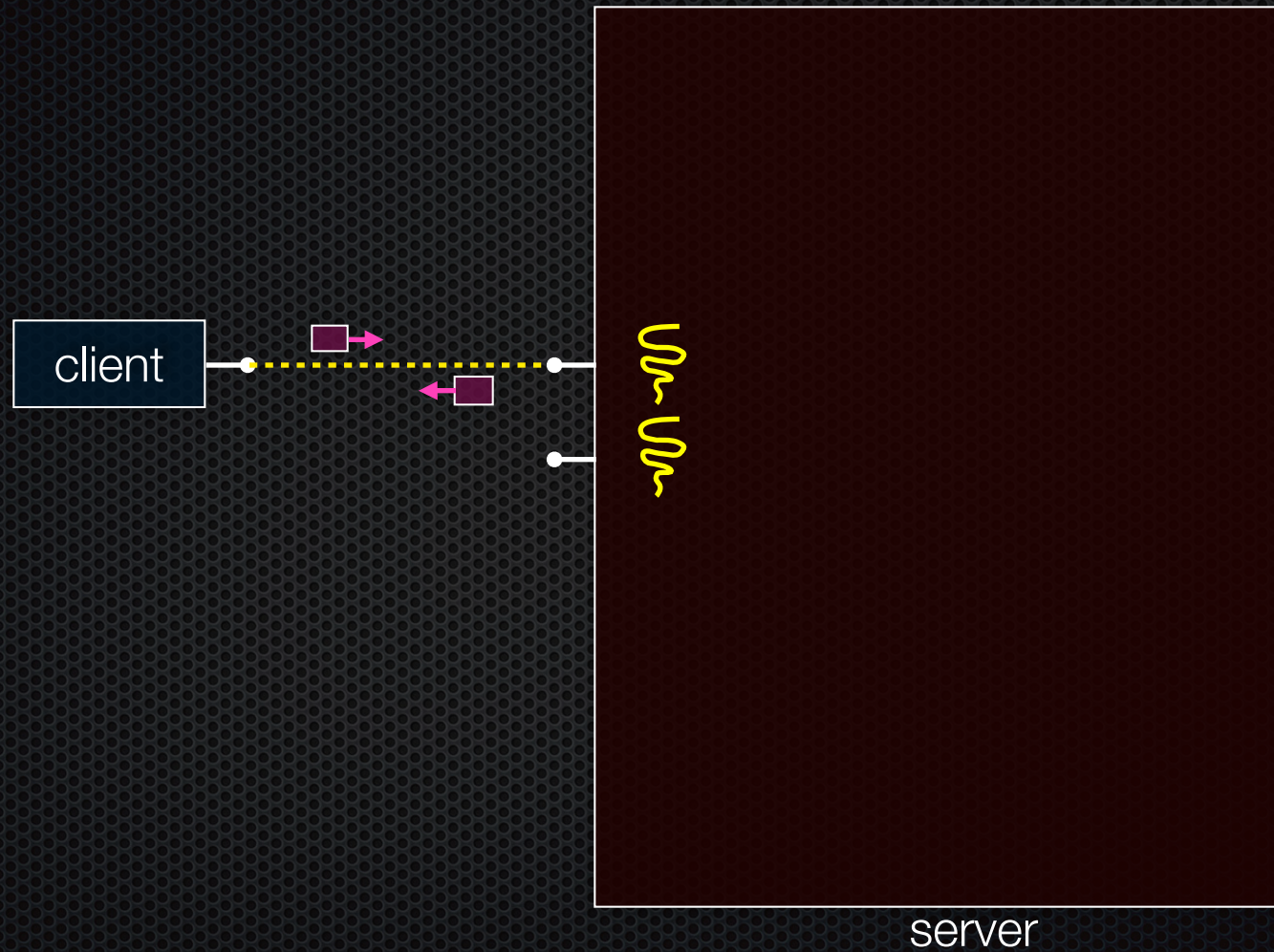


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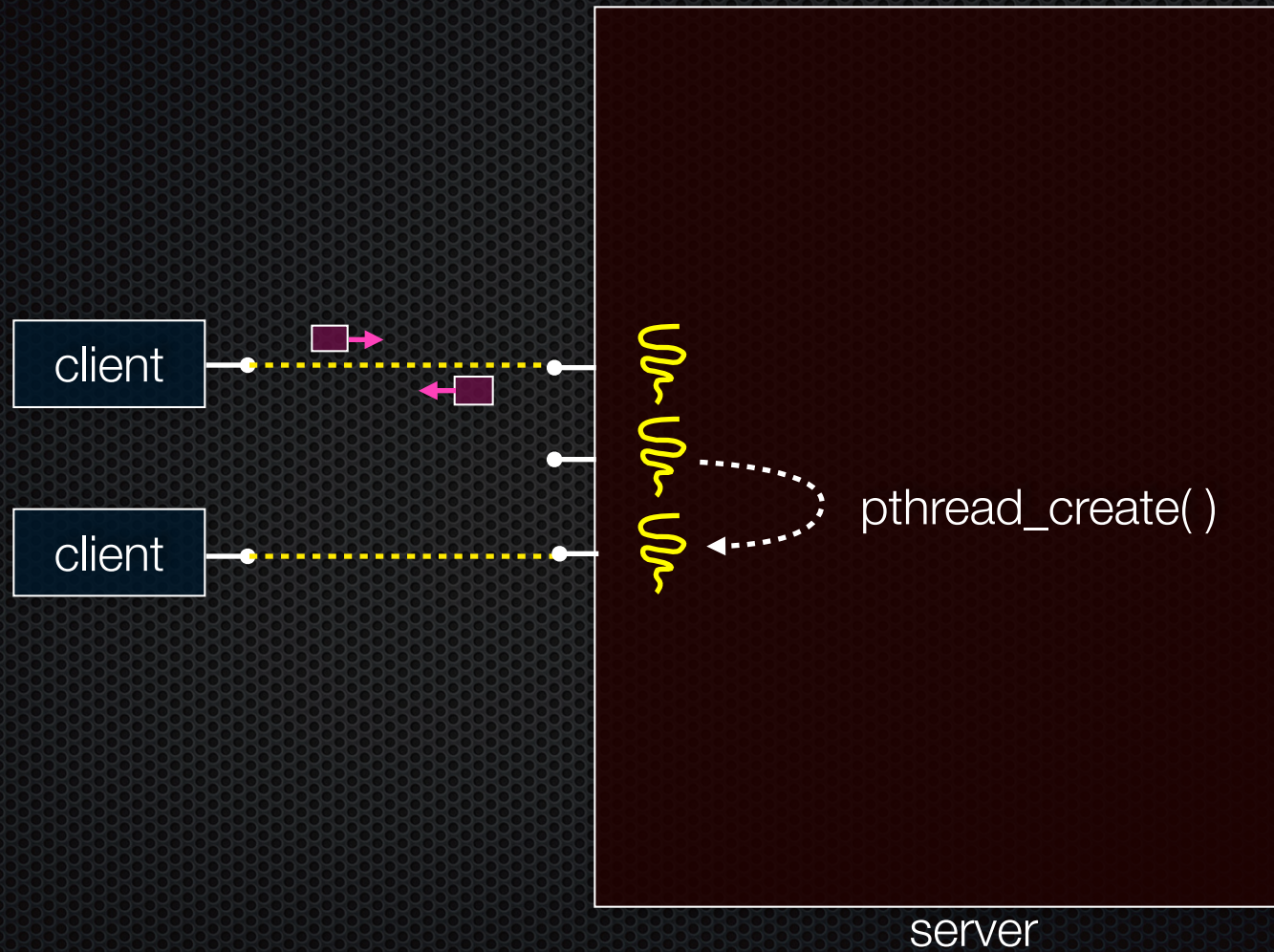


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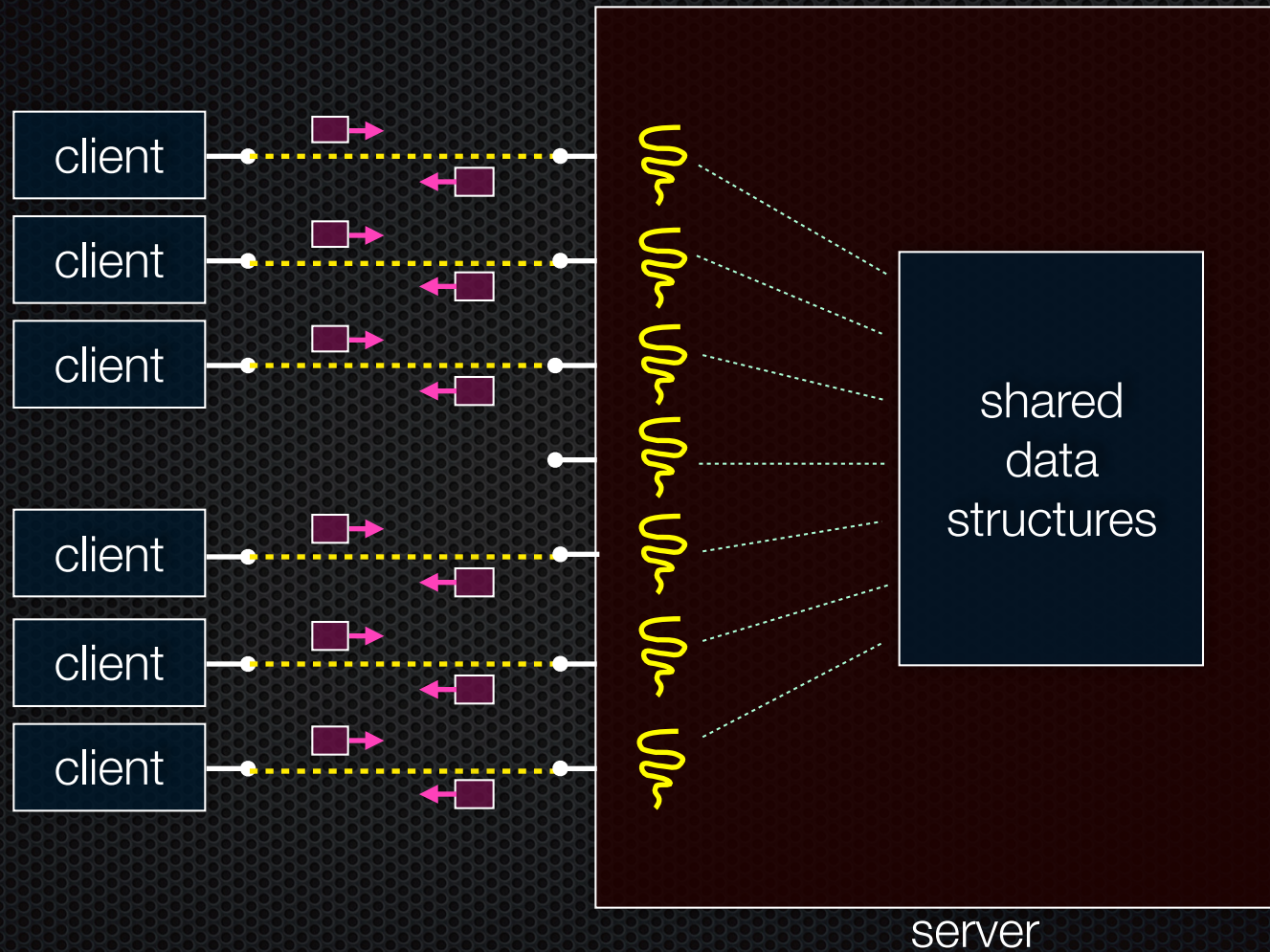


# Graphically





# Graphically





# Concurrent with threads

*look at **searchserver\_threads/***



# Whither concurrent threads?

## Benefits

- straight-line code
  - ▶ still the case that much of the code is identical to sequential!
- parallel execution; good CPU, network utilization
  - ▶ lower overhead than processes
- shared-memory communication is possible

## Disadvantages

- **synchronization** is complicated
- shared fate within a process; one rogue thread can hurt you badly



# How fast is `pthread_create`?

*run **threadlatency.cc***



# Implications?

**0.036 ms** per thread create; ~10x faster than process forking

- maximum of  $(1000 / 0.018) = \sim 60,000$  connections per second
- ~10 billion connections per day per core
  - ▶ much better

But, writing safe multithreaded code can be serious voodoo



# Thread Pools

In real servers we'd like to avoid overhead needed to create a new thread or process for every request

Idea: thread pools

- Create a set of worker threads or processes on server startup, put them in a queue
- When a request arrives, remove the first worker thread from the queue and assign it to handle the request
- When a worker is done it places itself back on the queue and then sleeps until dequeued and handed a new request



# Threads and races

What happens if two threads try to mutate the same data structure?

- they might interfere in painful, non-obvious ways, depending on the specifics of the data structure
  - ▶ imagine if two threads try to push an item onto the head of the linked list at the same time
  - ▶ depending on how the threads interleave, you might end up with a correct answer, or you might break the data structure altogether



# Simple “race” example

If no milk, buy some more

- liveness: if out, somebody buys
- safety: at most one person buys

What happens with multiple threads?

```
if (!milk) {  
    buy milk  
}
```



# Simple “race” example

Does this fix the problem?

```
if (!note) {  
    if (!milk) {  
        leave note  
        buy milk  
        remove note  
    }  
}
```



# Synchronization

Synchronization is the act of preventing two (or more) concurrently running threads from interfering with each other when operating on shared data

- need some mechanism to coordinate the threads
  - ▶ “let me go first, then you go”
- many different coordination mechanisms have been invented
  - ▶ take cse451 for details



# Locks

## lock acquire

- wait until the lock is free, then take it

## lock release

- release the lock
- if other threads are waiting for it
  - ▶ wake up exactly one of them
  - ▶ give it the lock

## simplifies concurrent code

- prevents more than one thread from entering a *critical section*

```
... non-critical code ...  
lock.acquire() ;  
    critical section  
lock.release() ;  
... non-critical code ...
```



# Simple “race” solution

What is the critical section?

- checking for milk
- buying more milk if out

These two steps must be uninterrupted, i.e., **atomic**

- solution: protect the critical section with a lock

```
milk_lock.lock()

if (!milk) {
    buy milk
}

milk_lock.unlock()
```



# pthread and locks

`pthread_mutex_init()`

- creates a mutex (a.k.a. a lock)

`pthread_mutex_lock()`

- grabs the lock

`pthread_mutex_unlock()`

- releases the lock

see ***lock\_example.cc***



# C++ 11 Threads

C++ 11 added threads and concurrency to the libraries

- `<thread>` - thread objects
- `<mutex>` - locks to handle critical sections
- `<condition_variable>` - used to block objects until notified to resume
- `<atomic>` - indivisible, atomic operations
- `<future>` - asynchronous access to data

Might be built on top of `<pthread.h>`, maybe not

Definitely use in C++ 11 code, but `pthread` will still be around for a long, long time



# Exercise 1

Write a simple “proxy” server

- forks a process for each connection
- reads an HTTP request from the client
  - ▶ relays that request to `www.cs.washington.edu`
- reads the response from `www.cs.washington.edu`
  - ▶ relays the response to the client, closes the connection

Try visiting your proxy using a web browser :)



# Exercise 2

Write a client program that:

- loops, doing “requests” in a loop. Each request must:
  - ▶ connect to one of the echo servers from the lecture
  - ▶ do a network exchange with the server
  - ▶ close the connection
- keeps track of the latency (time to do a request) distribution
- keeps track of the throughput (requests / s)
- prints these out



See you on Friday !