Disjoint Sets and Dynamic Equivalence Relations

CSE 373 Data Structures and Algorithms

10/22/2012

Today's Outline

- Announcements – Assignment #3 due Thurs 10/25 at 11pm.
- Today's Topics: – Disjoint Sets & Dynamic Equivalence

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Motivation

Some kinds of data analysis require keeping track of transitive relations.

Equivalence relations are one family of transitive relations.

Grouping pixels of an image into colored regions is one form of data analysis that uses "dynamic equivalence relations".

Creating mazes without cycles is another application.

Later we'll learn about "minimum spanning trees" for networks, and how the dynamic equivalence relations help out in computing spanning trees.

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Disjoint Sets

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- Two sets S₁ and S₂ are disjoint if and only if they have no elements in common.
- S_1 and S_2 are disjoint iff $S_1 \cap S_2 = \emptyset$ (the intersection of the two sets is the empty set)

For example {a, b, c} and {d, e} are disjoint.

But $\{x, y, z\}$ and $\{t, u, x\}$ are not disjoint.

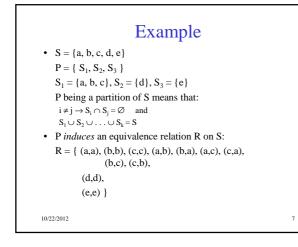
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Equivalence Relations

- A binary relation R on a set S is an equivalence relation provided it is reflexive, symmetric, and transitive:
- Reflexive R(a,a) for all a in S.
- Symmetric $R(a,b) \rightarrow R(b,a)$
- Transitive $R(a,b) \wedge R(b,c) \rightarrow R(a,c)$
- Is \leq an equivalence relation on integers?
- Is "is connected by roads" an equivalence relation on cities?

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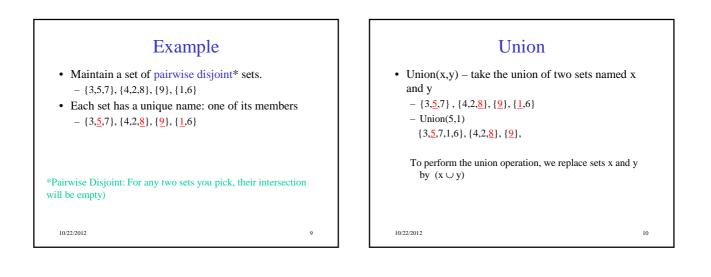
Induced Equivalence Relations • Let S be a set, and let P be a partition of S. $P = \{S_1, S_2, \dots, S_k\}$ P being a partition of S means that: $i \neq j \rightarrow S_i \cap S_j = \emptyset$ and $S_1 \cup S_2 \cup \dots \cup S_k = S$ • P *induces* an equivalence relation R on S: R(a,b) provided a and b are in the same subset (same element of P). So given any partition P of a set S, there is a corresponding equivalence relation R on S.

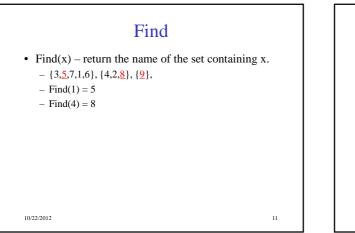


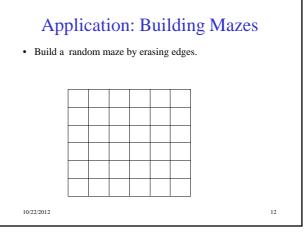
Introducing the UNION-FIND ADT

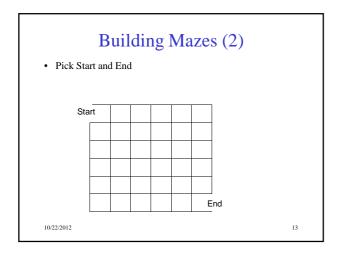
- Also known as the Disjoint Sets ADT or the Dynamic Equivalence ADT.
- There will be a set S of elements that does not change.
- We will start with a partition P₀, but we will modify it over time by combining sets.
- The combining operation is called "UNION"
- Determining which set (of the current partition) an element of S belongs to is called the "FIND" operation.

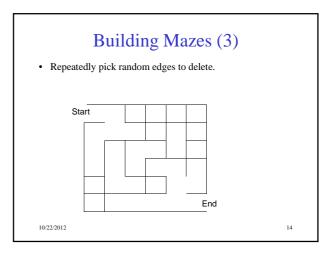
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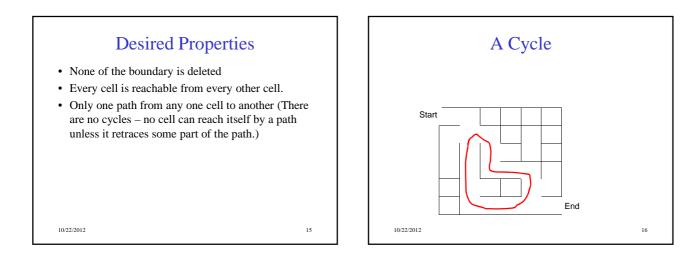


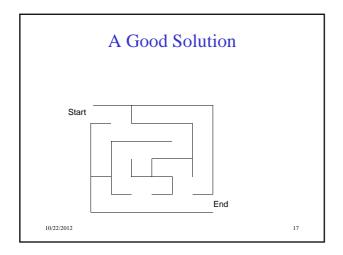


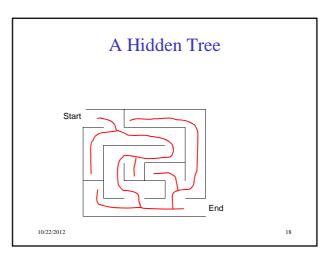


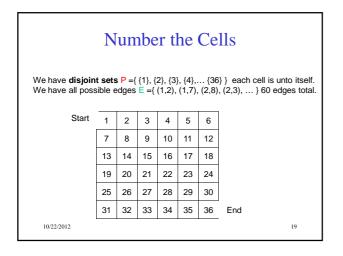


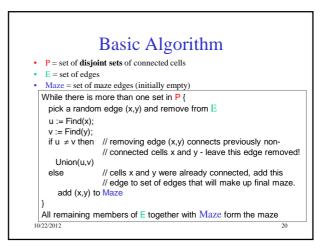


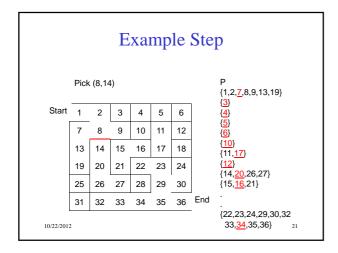


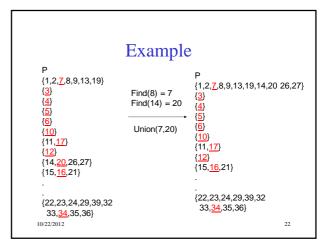


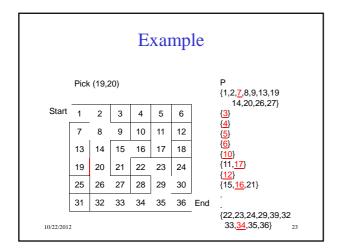


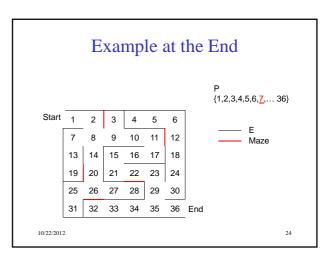


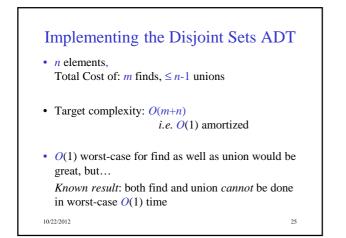


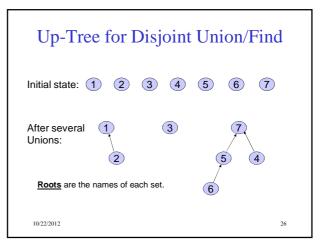


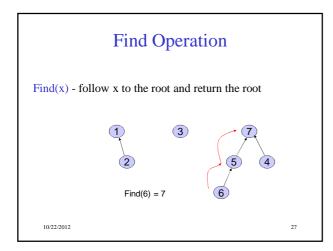


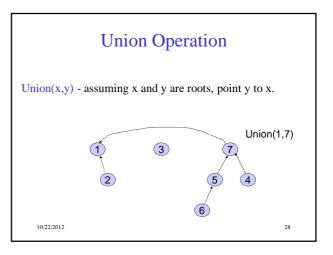


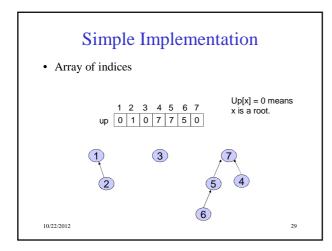


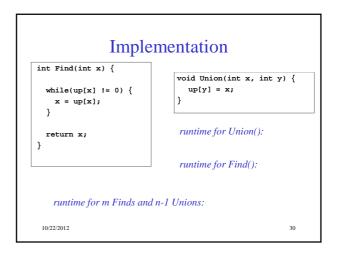


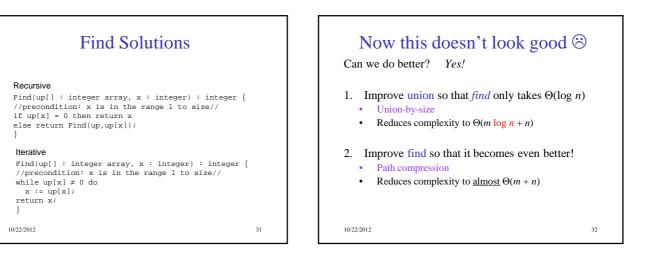


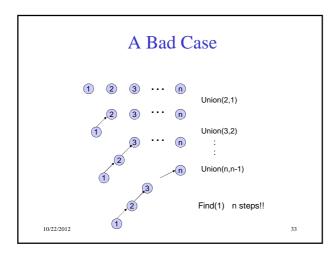


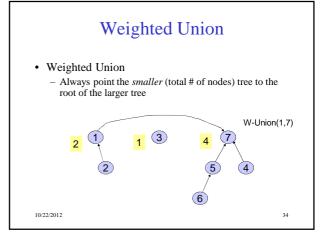


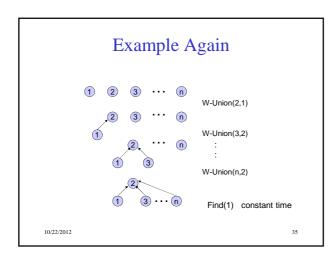


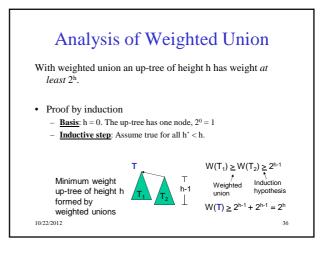


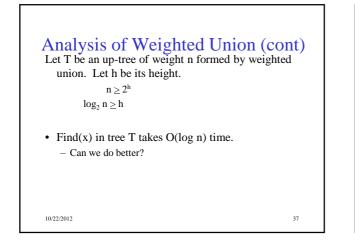


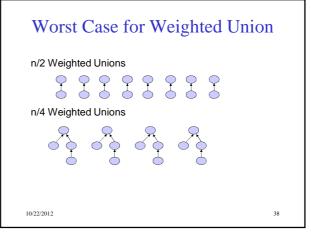


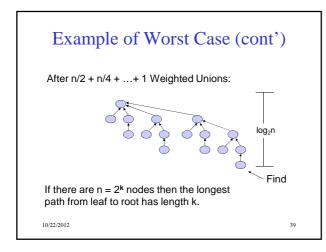


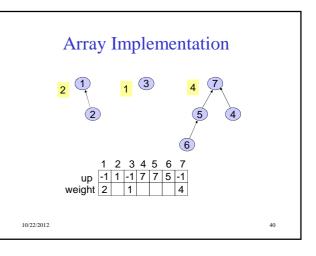


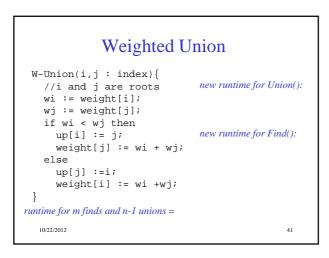


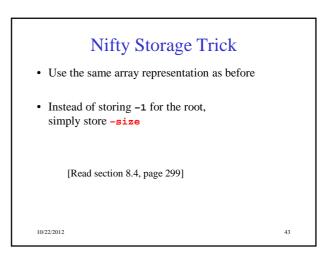


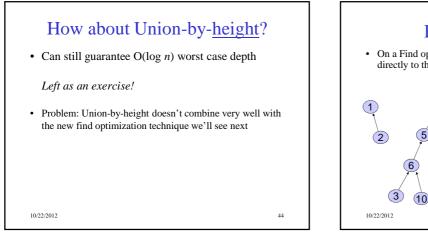


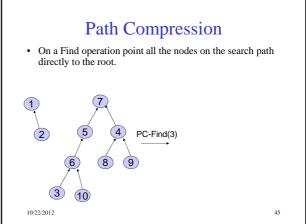


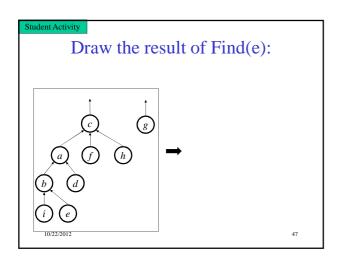


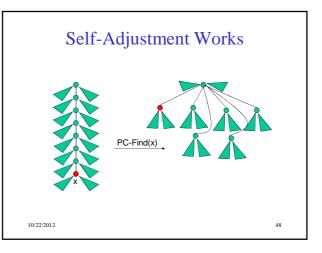


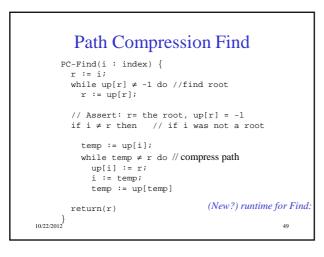


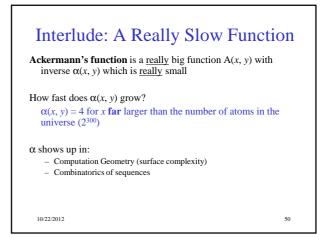


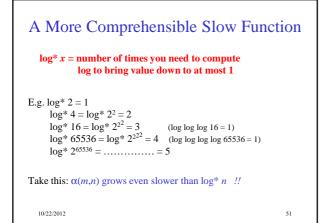


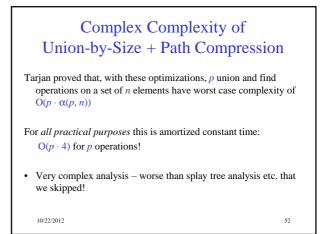












Disjoint Union / Find with Weighted Union and PC • Worst case time complexity for a W-Union is O(1) and for a PC-Find is O(log n).

- Time complexity for m ≥ n operations on n elements is O(m log* n) where log* n is a very slow growing function.
 - Log * n < 7 for all reasonable n. Essentially constant time per operation!

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Amortized Complexity
For disjoint union / find with weighted union and path compression.

average time per operation is essentially a constant.
worst case time for a PC-Find is O(log n).

An individual operation can be costly, but over time the average cost per operation is not.