

Comparison Sorting

CSE 373
Data Structures & Algorithms
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Today's Outline

- **Admin:**
 - HW #5 – Graphs, due Thurs Nov 29 at 11pm
 - HW #6 – last homework, on sorting, individual project, no Java programming, due Thurs Dec 6.
- **Sorting**
 - Comparison Sorting

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Why Sort?

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Introduction to sorting

- Stacks, queues, priority queues, and dictionaries all focused on providing one element at a time
- But often we know we want “all the data items” in some order
 - Anyone can sort, but a computer can sort faster
 - Very common to need data sorted somehow
 - Alphabetical list of people
 - Population list of countries
 - Search engine results by relevance
 - ...
- Different algorithms have different asymptotic and constant-factor trade-offs
 - No single ‘best’ sort for all scenarios
 - Knowing one way to sort just isn’t enough

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More reasons to sort

General technique in computing:
Preprocess (e.g. sort) data to make subsequent operations faster

- Example: Sort the data so that you can
- Find the k^{th} largest in constant time for any k
 - Perform binary search to find an element in logarithmic time

- Whether the performance of the preprocessing matters depends on
- How often the data will change
 - How much data there is

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The main problem, stated carefully

For now we will assume we have n comparable elements in an array and we want to rearrange them to be in increasing order

Input:

- An array A of data records
- A key value in each data record
- A comparison function (consistent and total)
 - Given keys a & b , what is their relative ordering? $<$, $=$, $>$?
 - Ex: keys that implement Comparable or have a Comparator that can handle them

Effect:

- Reorganize the elements of A such that for any i and j ,
 if $i < j$ then $A[i] \leq A[j]$
- Usually unspoken assumption: A must have all the same data it started with
- Could also sort in reverse order, of course

An algorithm doing this is a **comparison sort**

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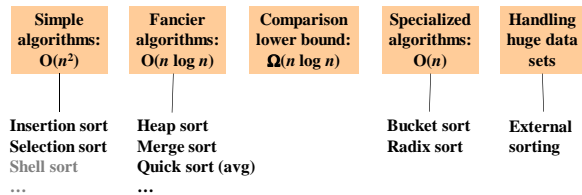
Variations on the basic problem

1. Maybe elements are in a linked list (could convert to array and back in linear time, but some algorithms needn't do so)
2. Maybe in the case of ties we should preserve the original ordering
 - Sorts that do this naturally are called **stable sorts**
 - One way to sort twice, Ex: Sort movies by year, then for ties, alphabetically
3. Maybe we must not use more than $O(1)$ "auxiliary space"
 - Sorts meeting this requirement are called **'in-place' sorts**
 - Not allowed to allocate extra array (at least not with size $O(n)$), but can allocate $O(1)$ # of variables
 - All work done by swapping around in the array
4. Maybe we can do more with elements than just compare
 - Comparison sorts assume we work using a binary 'compare' operator
 - In special cases we can sometimes get faster algorithms
5. Maybe we have too much data to fit in memory
 - Use an **"external sorting"** algorithm

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Sorting: The Big Picture



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Insertion Sort

- Idea: At the k^{th} step put the k^{th} input element in the correct place among the first k elements
- "Loop invariant": when loop index is i , first i elements are sorted
- Alternate way of saying this:
 - Sort first two elements
 - Now insert 3rd element in order
 - Now insert 4th element in order
 - ...
- Time?
 - Best-case _____ Worst-case _____ "Average" case _____

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Insertion Sort

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 - Sort first two elements
 - Now insert 3rd element in order
 - Now insert 4th element in order
 - ...
- Time?

Best-case	$O(n)$	Worst-case	$O(n^2)$	"Average" case	$O(n^2)$
	start sorted		start reverse sorted		(see text)

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Selection sort

- Idea: At the k^{th} step, find the smallest element among the not-yet-sorted elements and put it at position k
- "Loop invariant": when loop index is i , first i elements are the i smallest elements in sorted order
- Alternate way of saying this:
 - Find smallest element, put it 1st
 - Find next smallest element, put it 2nd
 - Find next smallest element, put it 3rd
 - ...
- Time?

Best-case	_____	Worst-case	_____	"Average" case	_____
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Selection sort

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- Alternate way of saying this:
 - Find smallest element, put it 1st
 - Find next smallest element, put it 2nd
 - Find next smallest element, put it 3rd
 - ...
- Time?

Best-case	$O(n^2)$	Worst-case	$O(n^2)$	"Average" case	$O(n^2)$
	<i>Always $T(1) = 1$ and $T(n) = n + T(n-1)$</i>				

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Insertion Sort vs. Selection Sort

- They are different algorithms
- They solve the same problem
- They have the same worst-case and average-case asymptotic complexity
 - Insertion sort has better best-case complexity; preferable when input is “mostly sorted”
- Other algorithms are more efficient for larger arrays that are not already almost sorted
 - Small arrays may do well with Insertion sort

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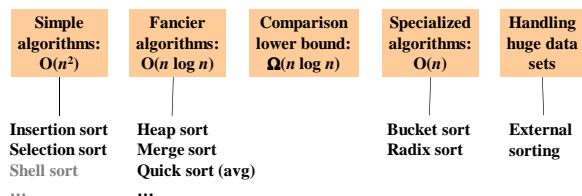
Aside: We won't cover Bubble Sort

- It doesn't have good asymptotic complexity: $O(n^2)$
- It's not particularly efficient with respect to common factors
- Basically, almost everything it is good at, some other algorithm is at least as good at
- Some people seem to teach it just because someone taught it to them
- For fun see: “Bubble Sort: An Archaeological Algorithmic Analysis”, Owen Astrachan, SIGCSE 2003

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Sorting: The Big Picture



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Heap sort

- Sorting with a heap is easy:
 - insert each `arr[i]`, better yet `buildHeap`
 - `for(i=0; i < arr.length; i++)`
`arr[i] = deleteMin();`
- Worst-case running time:
- We have the array-to-sort and the heap
 - So this is not an in-place sort
 - There's a trick to make it in-place...

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Heap sort

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 - insert each `arr[i]`, better yet `buildHeap`
 - `for(i=0; i < arr.length; i++)`
`arr[i] = deleteMin();`
- Worst-case running time: $O(n \log n)$ why?
- We have the array-to-sort and the heap
 - So this is not an in-place sort
 - There's a trick to make it in-place...

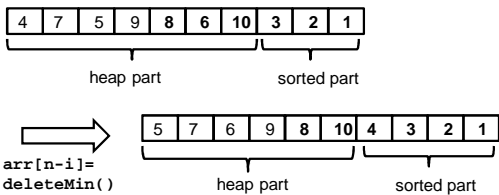
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In-place heap sort

But this reverse sorts – how would you fix that?

- Treat the initial array as a heap (via `buildHeap`)
- When you delete the i^{th} element, put it at `arr[n-i]`
 - It's not part of the heap anymore!



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“AVL sort”

- How?

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“AVL sort”

- We can also use a balanced tree to:
 - **insert** each element: total time $O(n \log n)$
 - Repeatedly **delete** the min value: total time $O(n \log n)$
 - OR: Do an inorder traversal $O(n)$
- But this cannot be made in-place and has worse constant factors than heap sort
 - heap sort is better
 - both are $O(n \log n)$ in worst, best, and average case
 - neither parallelizes well
- Don't even think about trying to sort with a hash table...

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Divide and conquer

Very important technique in algorithm design

1. Divide problem into smaller parts
2. Solve the parts independently
 - Think recursion
 - Or potential parallelism
3. Combine solution of parts to produce overall solution

Ex: Sort each half of the array, combine together; to sort each half, split into halves...

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Divide-and-conquer sorting

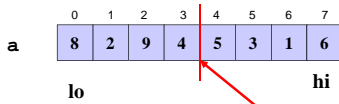
Two great sorting methods are fundamentally divide-and-conquer

1. Mergesort: Sort the left half of the elements (recursively)
Sort the right half of the elements (recursively)
Merge the two sorted halves into a sorted whole
2. Quicksort: Pick a "pivot" element
Divide elements into less-than pivot
and greater-than pivot
Sort the two divisions (recursively on each)
Answer is [sorted-less-than then pivot then sorted-greater-than]

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Mergesort

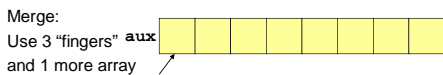
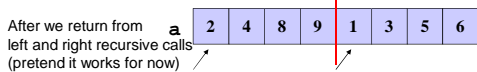


- To sort array from position `lo` to position `hi`:
 - If range is 1 element long, it's sorted! (Base case)
 - Else, split into two halves:
 - Sort from `lo` to $(hi+lo)/2$
 - Sort from $(hi+lo)/2$ to `hi`
 - Merge the two halves together
- Merging takes two sorted parts and sorts everything
 - $O(n)$ but requires auxiliary space...

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Example, focus on merging



(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge:
Use 3 "fingers" and 1 more array

1							
---	--	--	--	--	--	--	--

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge:
Use 3 "fingers" and 1 more array

1	2						
---	---	--	--	--	--	--	--

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge:
Use 3 "fingers" and 1 more array

1	2	3					
---	---	---	--	--	--	--	--

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge:
 Use 3 "fingers" and 1 more array

1	2	3	4				
---	---	---	---	--	--	--	--

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge:
 Use 3 "fingers" and 1 more array

1	2	3	4	5			
---	---	---	---	---	--	--	--

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge:
 Use 3 "fingers" and 1 more array

1	2	3	4	5	6		
---	---	---	---	---	---	--	--

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge: Use 3 "fingers" and 1 more array

1	2	3	4	5	6	8	
---	---	---	---	---	---	---	--

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

Merge: Use 3 "fingers" and 1 more array

1	2	3	4	5	6	8	9
---	---	---	---	---	---	---	---

(After merge, copy back to original array)

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Example, focus on merging

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion: (not magic ☺)

2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---

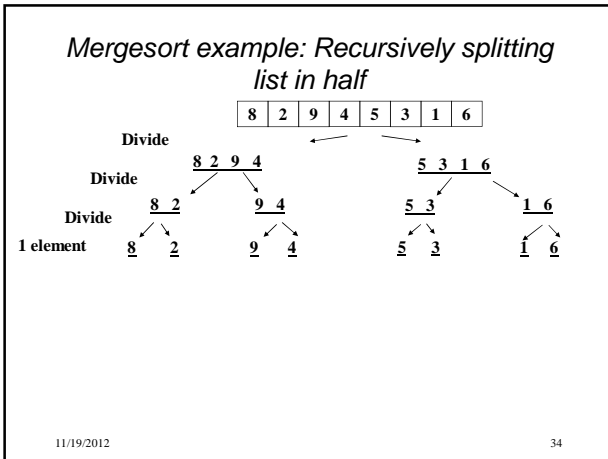
Merge: Use 3 "fingers" and 1 more array

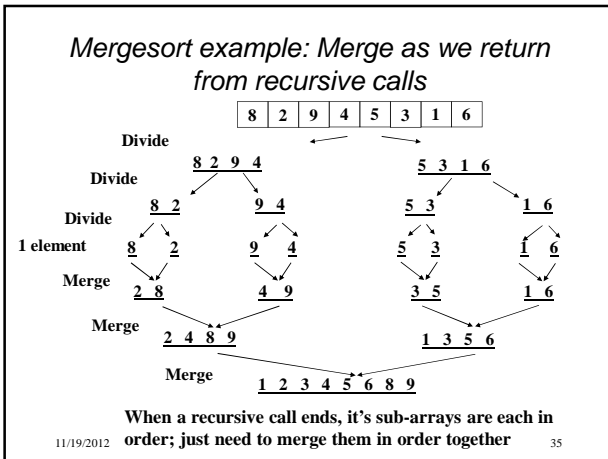
1	2	3	4	5	6	8	9
---	---	---	---	---	---	---	---

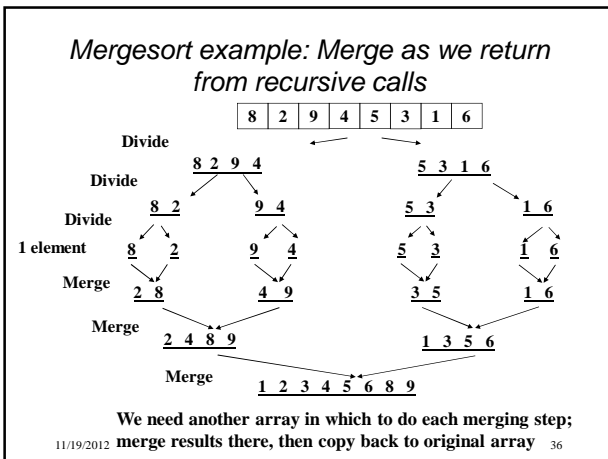
(After merge, copy back to original array)

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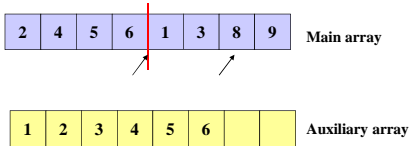






Mergesort, some details: saving a little time

- What if the final steps of our merging looked like the following:



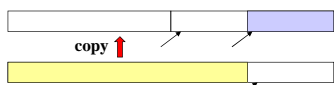
- Seems kind of wasteful to copy 8 & 9 to the auxiliary array just to copy them immediately back...

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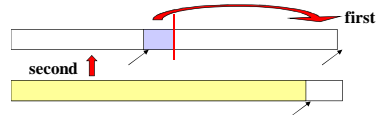
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Mergesort, some details: saving a little time

- Unnecessary to copy 'dregs' over to auxiliary array
 - If left-side finishes first, just stop the merge & copy the auxiliary array:



- If right-side finishes first, copy dregs directly into right side, then copy auxiliary array



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Some details: saving space / copying

Simplest / worst approach:

Use a new auxiliary array of size $(hi-lo)$ for every merge
 Returning from a recursive call? Allocate a new array!

Better:

Reuse same auxiliary array of size n for every merging stage
 Allocate auxiliary array at beginning, use throughout

Best (but a little tricky):

Don't copy back - at 2nd, 4th, 6th, ... merging stages, use the original array as the auxiliary array and vice-versa
 - Need one copy at end if number of stages is odd

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Picture of the "best" from previous slide: Allocate one auxiliary array, switch each step

First recurse down to lists of size 1
As we return from the recursion, switch off arrays

Arguably easier to code up without recursion at all
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Linked lists and big data

We defined the sorting problem as over an array, but sometimes you want to sort linked lists

One approach:

- Convert to array: $O(n)$
- Sort: $O(n \log n)$
- Convert back to list: $O(n)$

Or: mergesort works very nicely on linked lists directly

- Heapsort and Quicksort do not
- Insertion sort and selection sort do but they're slower

Mergesort is also the sort of choice for external sorting

- Linear merges minimize disk accesses

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Mergesort Analysis

Having defined an algorithm and argued it is correct, we should analyze its running time (and space):

To sort n elements, we:

- Return immediately if $n=1$
- Else do 2 subproblems of size $n/2$ and then an $O(n)$ merge

Recurrence relation?

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Mergesort Analysis

Having defined an algorithm and argued it is correct, we should analyze its running time (and space):

To sort n elements, we:

- Return immediately if $n=1$
- Else do 2 subproblems of size $n/2$ and then an $O(n)$ merge

Recurrence relation:

$$T(1) = c_1$$

$$T(n) = 2T(n/2) + c_2n$$

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MergeSort Recurrence

(For simplicity let constants be 1 – no effect on asymptotic answer)

$$T(1) = 1$$

$$T(n) = 2T(n/2) + n$$

$$= 2(2T(n/4) + n/2) + n$$

$$= 4T(n/4) + 2n$$

$$= 4(2T(n/8) + n/4) + 2n$$

$$= 8T(n/8) + 3n$$

.... (after k expansions)

$$= 2^k T(n/2^k) + kn$$

So total is $2^k T(n/2^k) + kn$ where

$$n/2^k = 1, \text{ i.e., } \log n = k$$

That is, $2^{\log n} T(1) + n \log n$

$$= n + n \log n$$

$$= O(n \log n)$$

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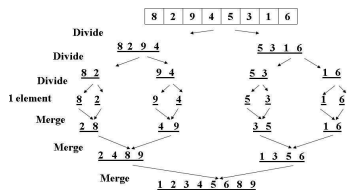
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Or more intuitively...

This recurrence comes up often enough you should just "know" it's $O(n \log n)$

Merge sort is relatively easy to intuit (best, worst, and average):

- The recursion "tree" will have $\log n$ height
- At each level we do a *total* amount of merging equal to n



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Quicksort

- Also uses divide-and-conquer
 - Recursively chop into two pieces
 - But, instead of doing all the work as we merge together, we'll do all the work as we recursively split into two pieces
 - Also unlike MergeSort, does not need auxiliary space
- $O(n \log n)$ on average ☺, but $O(n^2)$ worst-case ☹
 - MergeSort is always $O(n \log n)$
 - So why use QuickSort?
- Can be faster than mergesort
 - Often believed to be faster
 - Does fewer copies and more comparisons, so it depends on the relative cost of these two operations!

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Quicksort overview

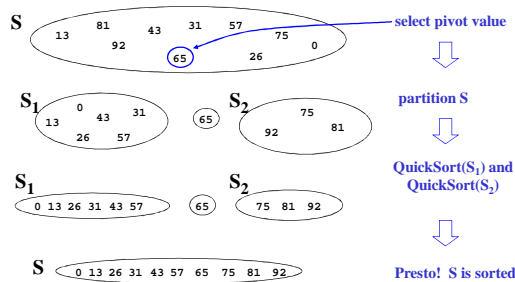
1. Pick a pivot element
 - Hopefully an element ~median
 - Good QuickSort performance depends on good choice of pivot; we'll see why later, and talk about good pivot selection later
2. Partition all the data into:
 - A. The elements less than the pivot
 - B. The pivot
 - C. The elements greater than the pivot
3. Recursively sort A and C
4. The answer is, "as simple as A, B, C"

(Alas, there are some details lurking in this algorithm)

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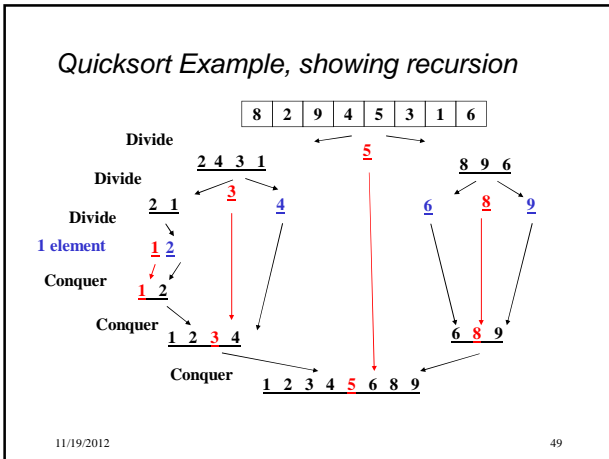
Quicksort: Think in terms of sets

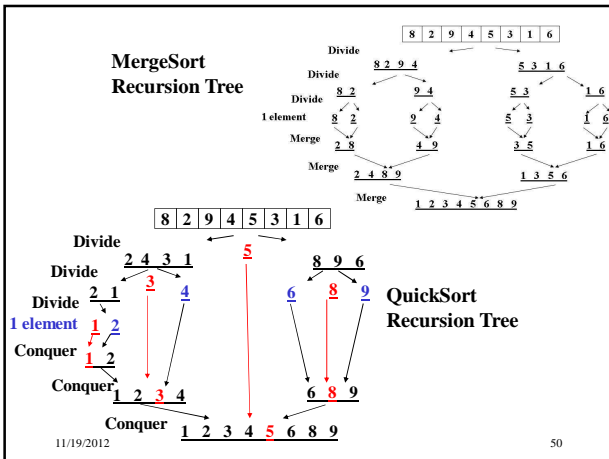


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Quicksort Details

We haven't explained:

- How to pick the pivot element
 - Any choice is correct: data will end up sorted
 - But as analysis will show, want the two partitions to be about equal in size
- How to implement partitioning
 - In linear time
 - In place

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Pivots

- Best pivot?
 - Median
 - Halve each time
- Worst pivot?
 - Greatest/least element
 - Reduce to problem of size 1 smaller
 - $O(n^2)$

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Quicksort: Potential pivot rules

While sorting `arr` from `lo` (inclusive) to `hi` (exclusive)...

- Pick `arr[lo]` or `arr[hi-1]`
 - Fast, but worst-case is (mostly) sorted input
- Pick random element in the range
 - Does as well as any technique, but (pseudo)random number generation can be slow
 - (Still probably the most elegant approach)
- Median of 3, e.g., `arr[lo]`, `arr[hi-1]`, `arr[(hi+lo)/2]`
 - Common heuristic that tends to work well

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Partitioning

- That is, given 8, 4, 2, 9, 3, 5, 7 and pivot 5
 - Getting into left half & right half (based on pivot)
- Conceptually simple, but hardest part to code up correctly
 - After picking pivot, need to partition
 - Ideally in linear time
 - Ideally in place
- Ideas?

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Partitioning

- One approach (there are slightly fancier ones):
 - Swap pivot with `arr[l0]`; move it 'out of the way'
 - Use two fingers `i` and `j`, starting at `l0+1` and `hi-1` (start & end of range, apart from pivot)
 - Move from right until we hit something less than the pivot; belongs on left side
Move from left until we hit something greater than the pivot; belongs on right side
Swap these two; keep moving inward

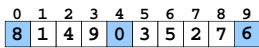
```
while (i < j)
    if (arr[j] > pivot) j--
    else if (arr[i] < pivot) i++
    else swap arr[i] with arr[j]
```
 - Put pivot back in middle (Swap with `arr[i]`)

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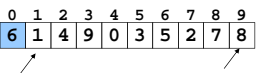
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Quicksort Example

- Step one: pick pivot as median of 3
- `l0 = 0, hi = 10`



- Step two: move pivot to the `l0` position

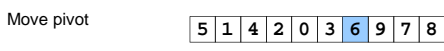
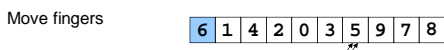
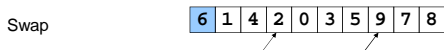
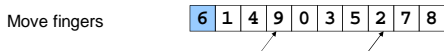
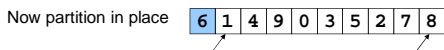


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Quicksort Example

Often have more than one swap during partition – this is a short example



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Quicksort Analysis

- Best-case?

- Worst-case?

- Average-case?

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Quicksort Analysis

- Best-case: Pivot is always the median
 $T(0)=T(1)=1$
 $T(n)=2T(n/2) + n$ -- linear-time partition
 Same recurrence as mergesort: $O(n \log n)$

- Worst-case: Pivot is always smallest or largest element
 $T(0)=T(1)=1$
 $T(n) = 1T(n-1) + n$
 Basically same recurrence as selection sort: $O(n^2)$

- Average-case (e.g., with random pivot)
 – $O(n \log n)$, not responsible for proof (in text)

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Quicksort Cutoffs

- For small n , all that recursion tends to cost more than doing a quadratic sort
 - Remember asymptotic complexity is for large n
 - Also, recursive calls add a lot of overhead for small n
- Common engineering technique: switch to a different algorithm for subproblems below a [cutoff](#)
 - Reasonable rule of thumb: use insertion sort for $n < 10$
- Notes:
 - Could also use a cutoff for merge sort
 - Cutoffs are also the norm with parallel algorithms
 - switch to sequential algorithm
 - None of this affects asymptotic complexity

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Quicksort Cutoff skeleton

```
void quicksort(int[] arr, int lo, int hi) {  
    if(hi - lo < CUTOFF)  
        insertionSort(arr,lo,hi);  
    else  
        ...  
}
```

- Notice how this cuts out the vast majority of the recursive calls
- Think of the recursive calls to quicksort as a tree
 - Trims out the bottom layers of the tree

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