



CSE373: Data Structures & Algorithms

Lecture 19: Spanning Trees

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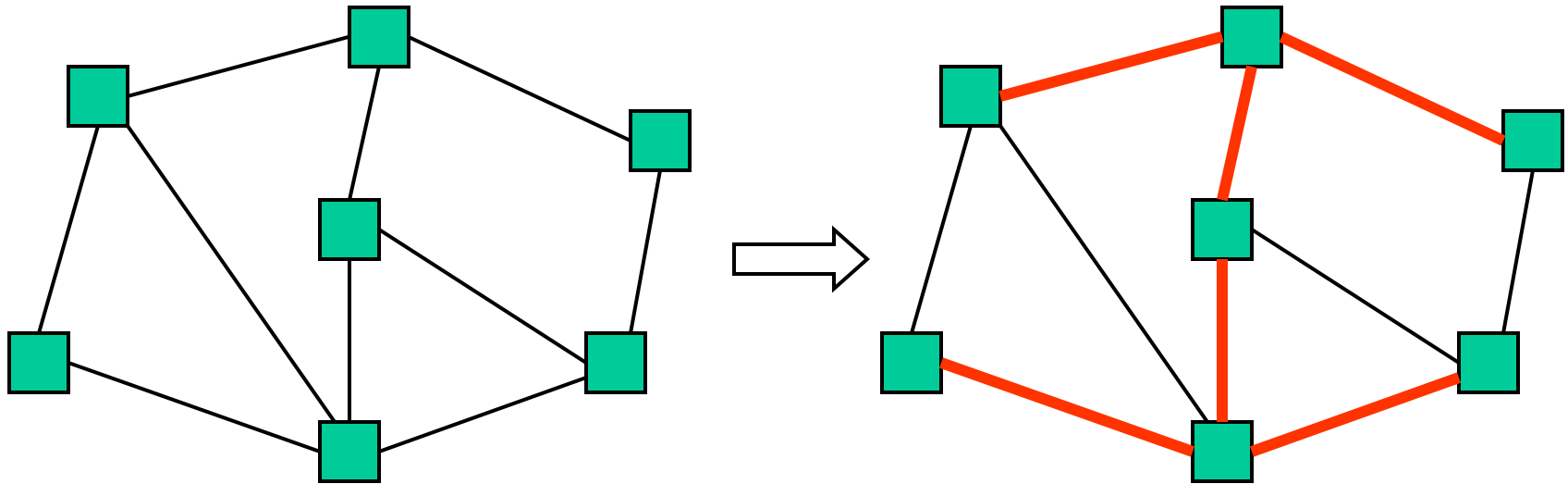
Announcements

Done with Dijkstra

- You will implement Dijkstra's algorithm in homework 6, just as part of the exercises. 😊
- Onward..... Spanning trees!

Spanning Trees

- A simple problem: Given a *connected* undirected graph $\mathbf{G}=(\mathbf{V},\mathbf{E})$, find a *minimal subset* of edges such that \mathbf{G} is still connected
 - A graph $\mathbf{G2}=(\mathbf{V},\mathbf{E2})$ such that $\mathbf{G2}$ is connected and removing any edge from $\mathbf{E2}$ makes $\mathbf{G2}$ disconnected

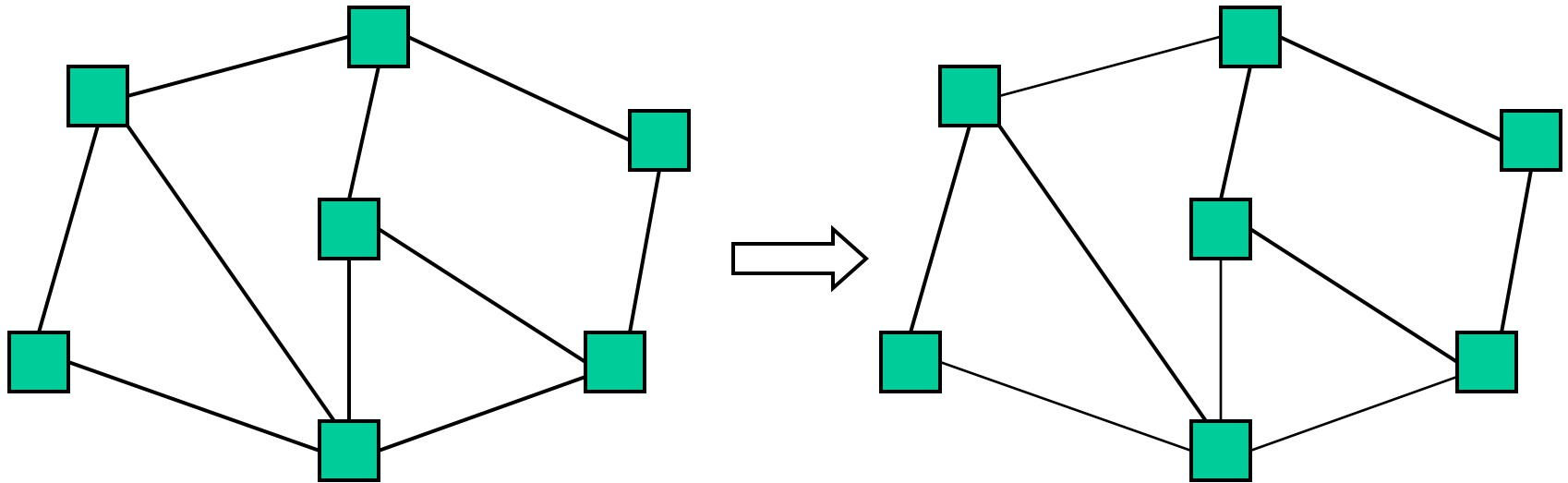


Observations

1. Any solution to this problem is a tree
 - Recall a tree does not need a root; just means acyclic
 - For any cycle, could remove an edge and still be connected
2. Solution not unique unless original graph was already a tree
3. Problem ill-defined if original graph not connected
 - So $|E| \geq |V|-1$
4. A tree with $|V|$ nodes has $|V|-1$ edges
 - So every solution to the spanning tree problem has $|V|-1$ edges

Spanning Trees

- Can we find another spanning tree?
- Pick a start node and think like a tree.



Motivation

A **spanning tree** connects all the nodes with as few edges as possible

- **Example:** A “phone tree” so everybody gets the message and no unnecessary calls get made



In most compelling uses, we have a *weighted* undirected graph and we want a tree of least total cost

- **Example:** Electrical wiring for a house or clock wires on a chip

Two Approaches

Different algorithmic approaches to the spanning-tree problem:

1. Do a **graph traversal** (e.g., depth-first search, but any traversal will do), keeping track of edges that form a tree
2. **Iterate through edges**; add to output any edge that does not create a cycle

Spanning tree via DFS

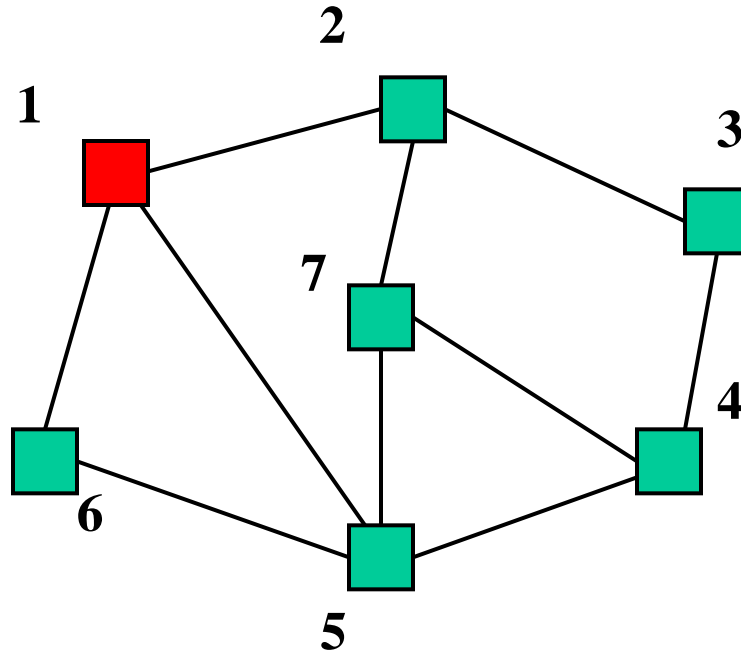
```
spanning_tree(Graph G) {
    for each node i
        i.marked = false
    for some node i: f(i)
}
f(Node i) {
    i.marked = true
    for each j adjacent to i:
        if(!j.marked) {
            add(i,j) to output
            f(j) // DFS
        }
}
```

Correctness: DFS reaches each node. We add one edge to connect it to the already visited nodes. Order affects result, not correctness.

Time: $O(|E|)$

Example

Stack
f(1)



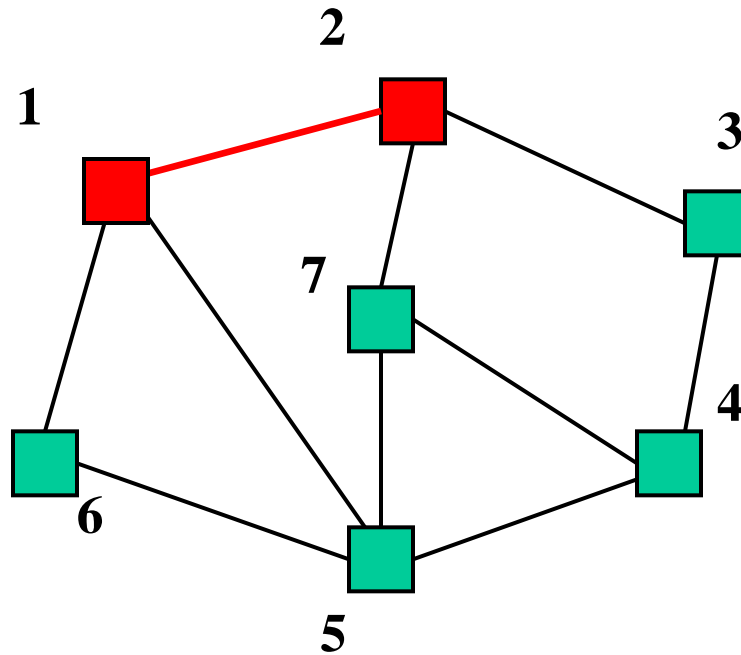
Output:

Example

Stack

f(1)

f(2)



Output: (1,2)

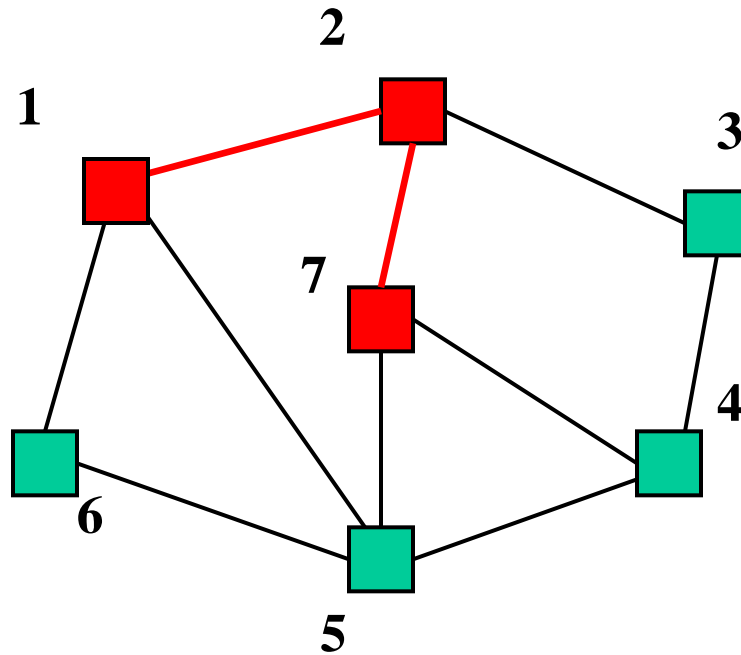
Example

Stack

f(1)

f(2)

f(7)



Output: (1,2), (2,7)

Example

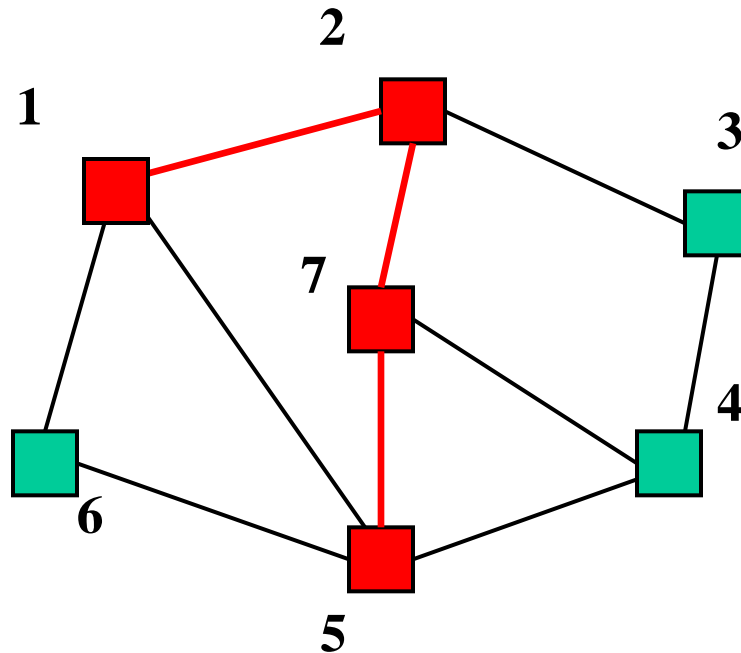
Stack

f(1)

f(2)

f(7)

f(5)



Output: (1,2), (2,7), (7,5)

Example

Stack

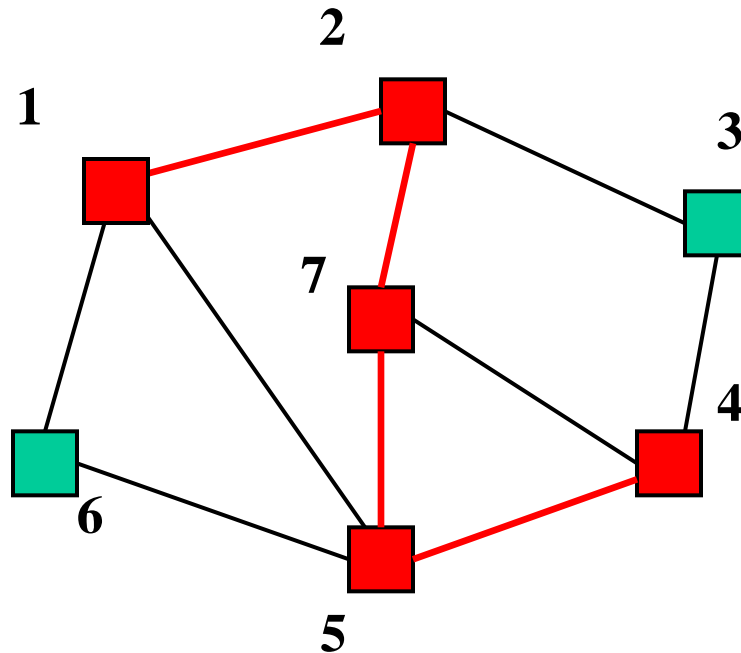
f(1)

f(2)

f(7)

f(5)

f(4)



Output: (1,2), (2,7), (7,5), (5,4)

Example

Stack

f(1)

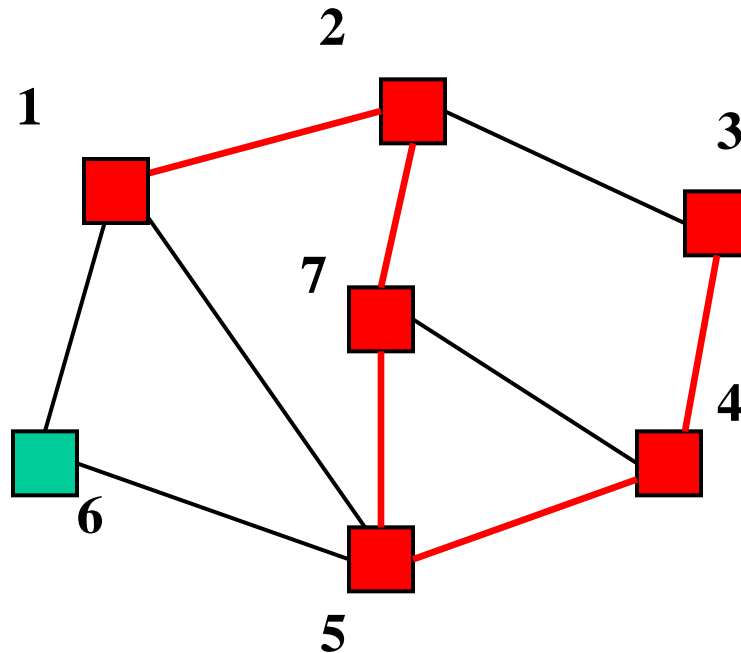
f(2)

f(7)

f(5)

f(4)

f(3)

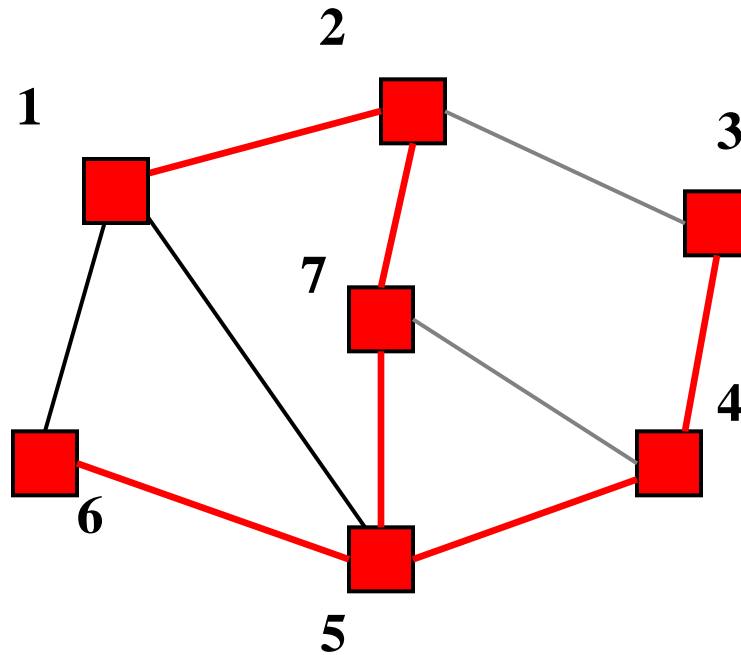


Output: (1,2), (2,7), (7,5), (5,4),(4,3)

Example

Stack

f(1)
f(2)
f(7)
f(5)
f(4) f(6)
f(3)

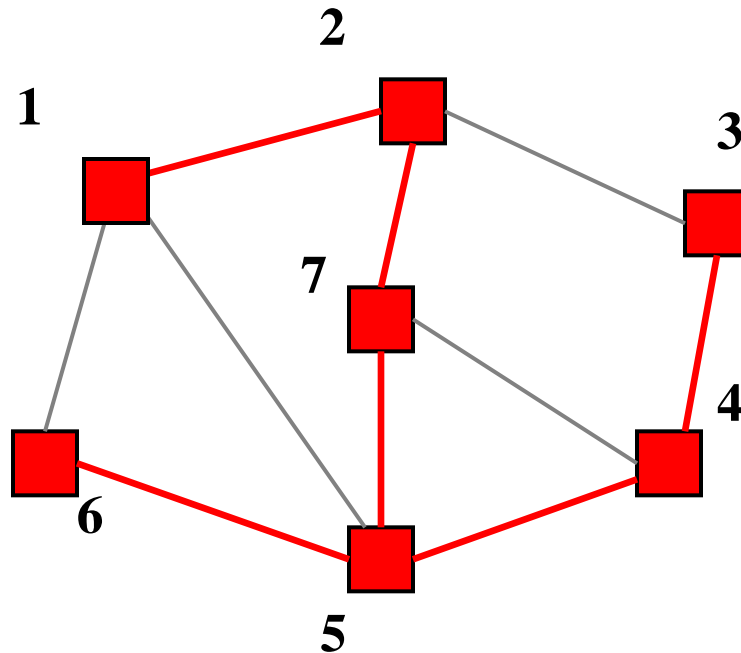


Output: (1,2), (2,7), (7,5), (5,4), (4,3), (5,6)

Example

Stack

f(1)
f(2)
f(7)
f(5)
f(4) f(6)
f(3)



Output: (1,2), (2,7), (7,5), (5,4), (4,3), (5,6)

Second Approach

Iterate through edges; output any edge that does not create a cycle

Correctness (hand-wavy):

- Goal is to build an acyclic connected graph
- When we add an edge, it adds a vertex to the tree
 - Else it would have created a cycle
- The graph is connected, so we reach all vertices

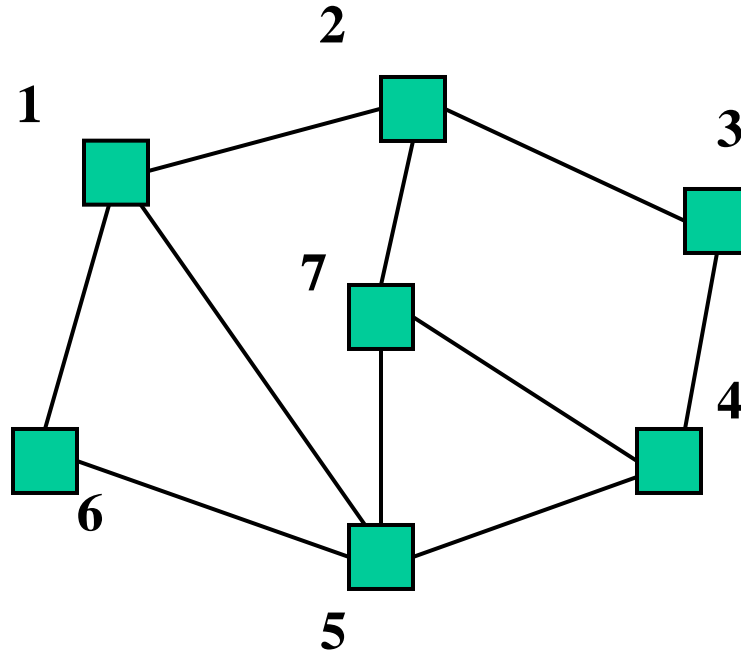
Efficiency:

- Depends on how quickly you can detect cycles
- Reconsider after the example

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

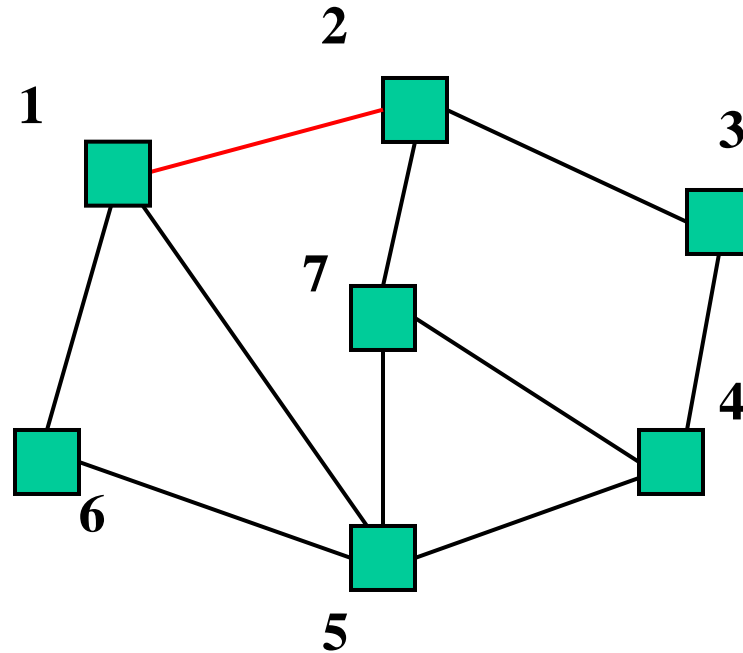


Output:

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

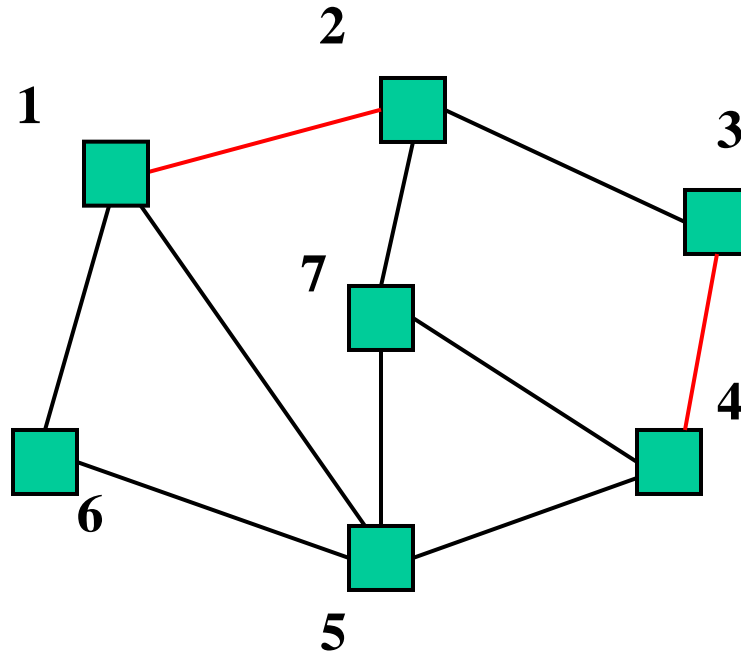


Output: (1,2)

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

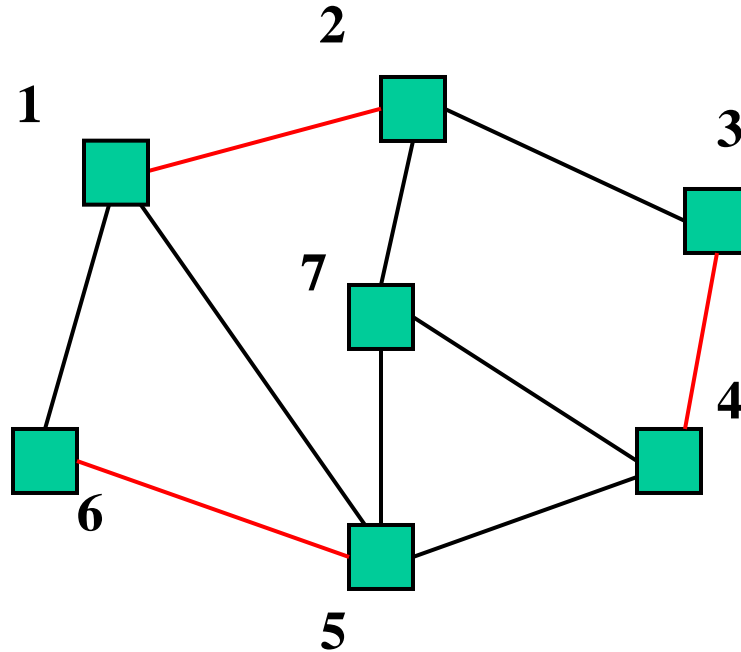


Output: (1,2), (3,4)

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

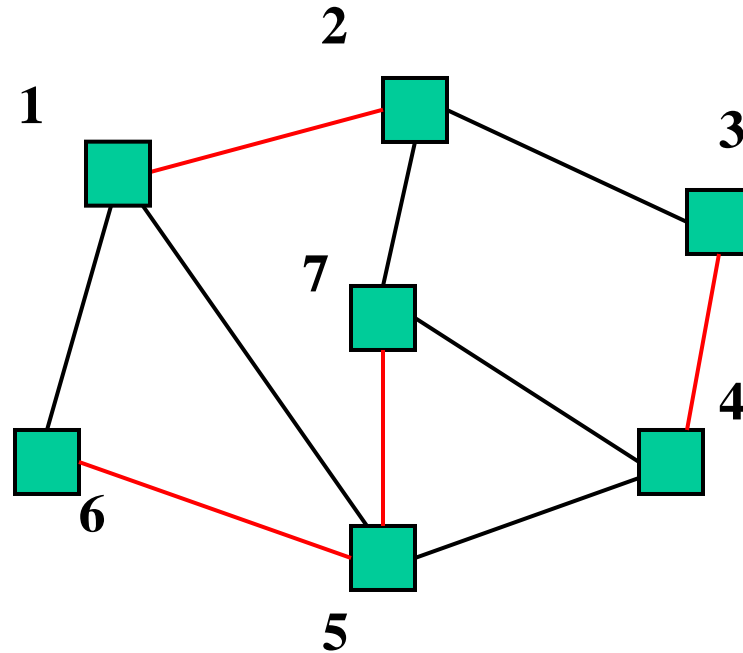


Output: (1,2), (3,4), (5,6),

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

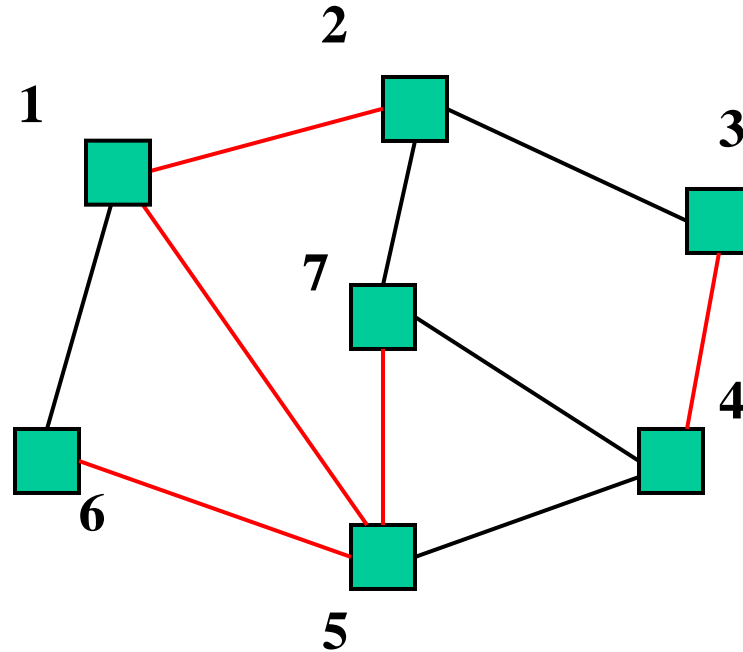


Output: (1,2), (3,4), (5,6), (5,7)

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

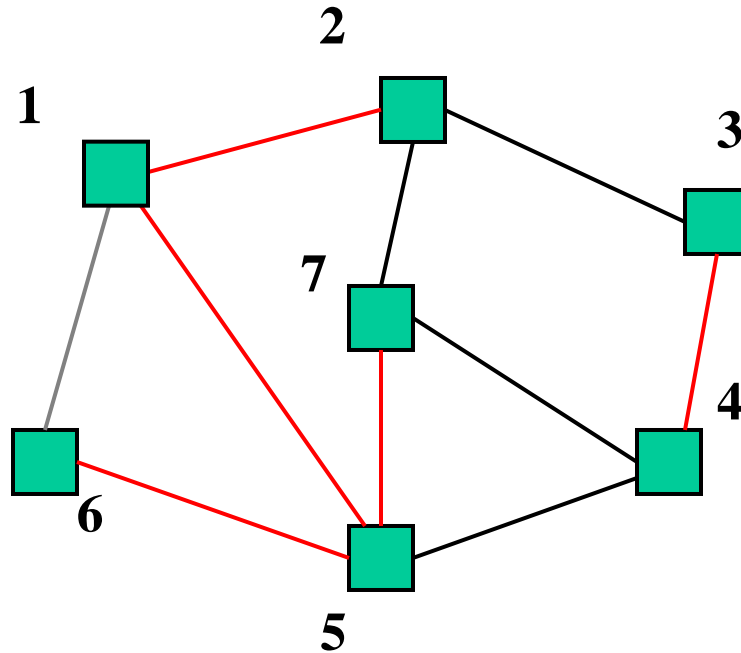


Output: (1,2), (3,4), (5,6), (5,7), (1,5)

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

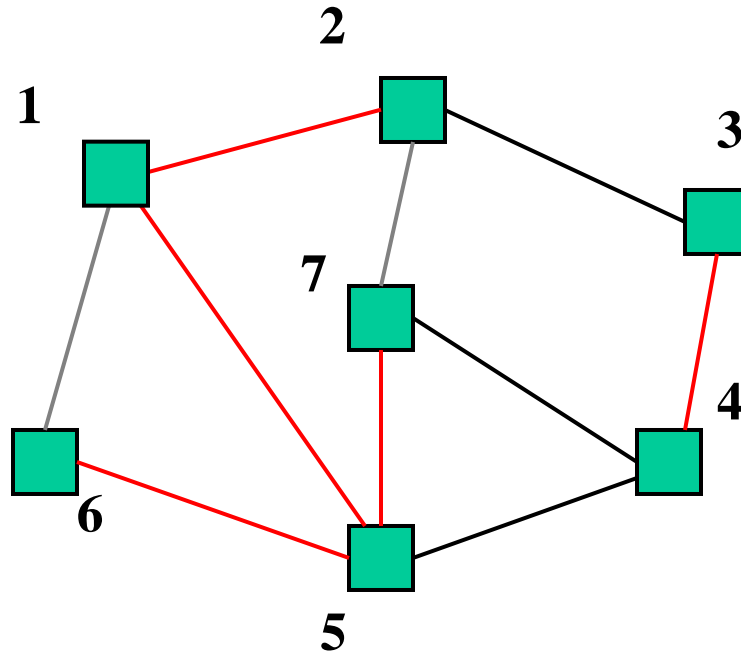


Output: (1,2), (3,4), (5,6), (5,7), (1,5)

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

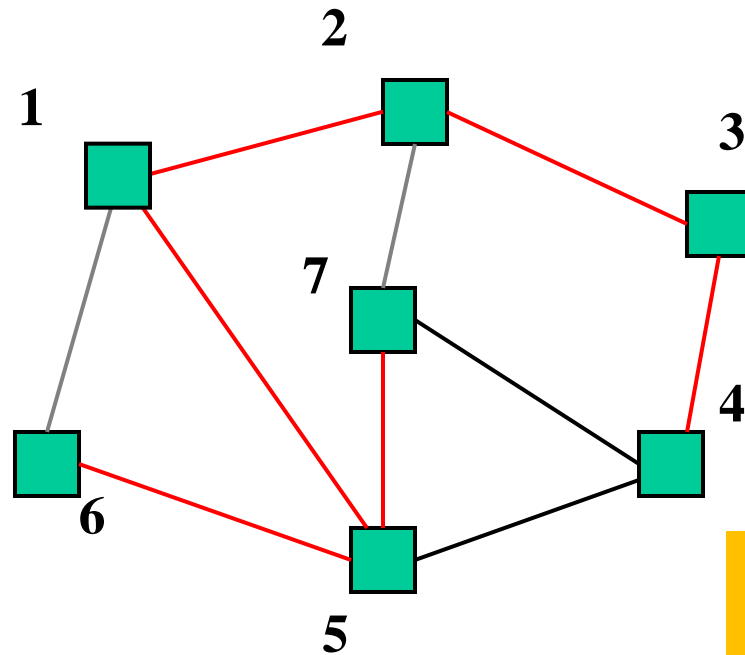


Output: (1,2), (3,4), (5,6), (5,7), (1,5)

Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)



Can stop once we have $|V|-1$ edges

Output: (1,2), (3,4), (5,6), (5,7), (1,5), (2,3)

Cycle Detection

- To decide if an edge could form a cycle is $O(|V|)$ because we may need to traverse all edges already in the output
- So overall algorithm would be $O(|V||E|)$
- But there is a faster way we know
- Use union-find!
 - Initially, each item is in its own 1-element set
 - Union sets when we add an edge that connects them
 - Stop when we have one set

Using Disjoint-Sets

Can use a disjoint-set implementation in our spanning-tree algorithm to detect cycles:

Invariant: u and v are connected in output-so-far
iff
 u and v in the same set

- Initially, each node is in its own set
- When processing edge (u, v) :
 - If $\text{find}(u)$ equals $\text{find}(v)$, then do not add the edge
 - Else add the edge and $\text{union}(\text{find}(u), \text{find}(v))$
 - $O(|E|)$ operations that are almost $O(1)$ amortized

Summary So Far

The **spanning-tree problem**

- Add nodes to partial tree approach is $O(|E|)$
- Add acyclic edges approach is *almost* $O(|E|)$
 - Using union-find “as a black box”

But really want to solve the **minimum-spanning-tree problem**

- Given a weighted undirected graph, give a spanning tree of minimum weight
- Same two approaches will work with minor modifications
- Both will be $O(|E| \log |V|)$

Minimum Spanning Tree Algorithms

Algorithm #1

Shortest-path is to Dijkstra's Algorithm
as

Minimum Spanning Tree is to **Prim's Algorithm**

(Both based on expanding cloud of known vertices, basically using a priority queue instead of a DFS stack)

Algorithm #2

Kruskal's Algorithm for Minimum Spanning Tree
is

Exactly our 2nd approach to spanning tree
but process edges in cost order