



CSE373: Data Structures & Algorithms

Lecture 20: Minimum Spanning Trees

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Announcements

Minimum Spanning Trees

The minimum-spanning-tree problem

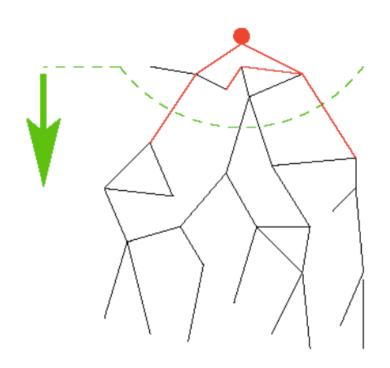
 Given a weighted undirected graph, compute a spanning tree of minimum weight

Given an undirected graph G=(V,E), find a graph G'=(V, E') such that:

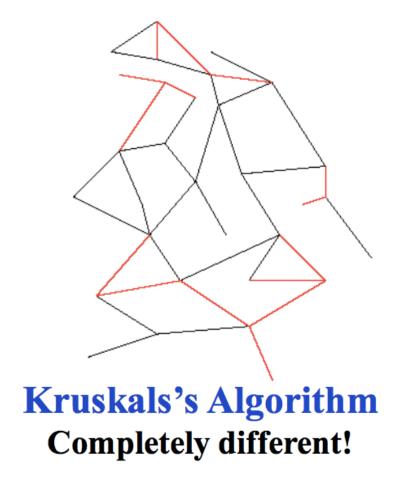
- E' is a subset of E
- |E'| = |V| 1
- G' is connected

G' is a minimum spanning tree.

Two different approaches



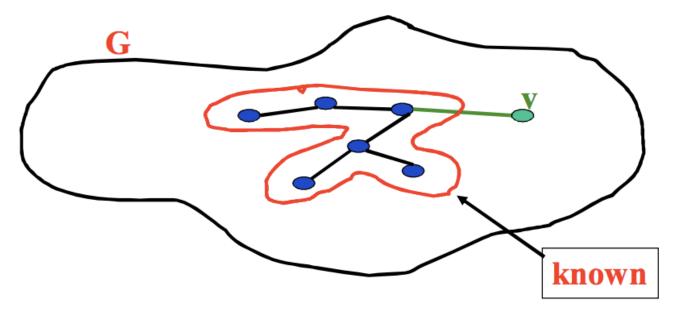
Prim's Algorithm
Almost identical to Dijkstra's



Prim's Algorithm Idea

Idea: Grow a tree by picking a vertex from the unknown set that has the smallest cost. Here cost = cost of the edge that connects that vertex to the known set. Pick the vertex with the smallest cost that connects "known" to "unknown."

A *node-based* greedy algorithm Builds MST by greedily adding nodes



Prim's vs. Dijkstra's

Recall:

Dijkstra picked the unknown vertex with smallest cost where cost = distance to the source.

Prim's pick the unknown vertex with smallest cost where

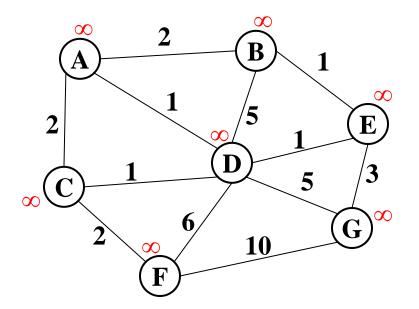
cost = distance from this vertex to the known set

(in other words, the cost of the smallest edge connecting this vertex to the known set)

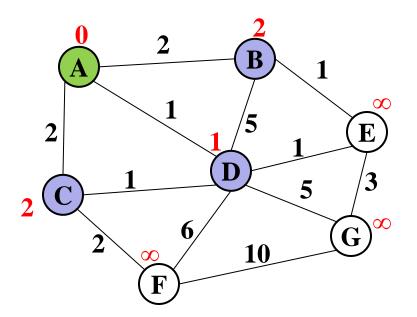
Otherwise identical ©

- 1. For each node v, set v.cost = ∞ and v.known = false
- 2. Choose any node v
 - a) Mark v as known
 - b) For each edge (v,u) with weight w, set u.cost=w and u.prev=v
- 3. While there are unknown nodes in the graph
 - a) Select the unknown node **v** with lowest cost
 - b) Mark v as known and add (v, v.prev) to output
 - c) For each edge (v,u) with weight w,

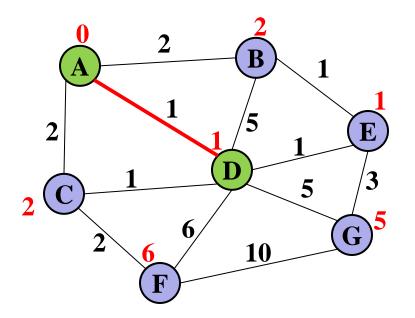
```
if(w < u.cost) {
   u.cost = w;
   u.prev = v;
}</pre>
```



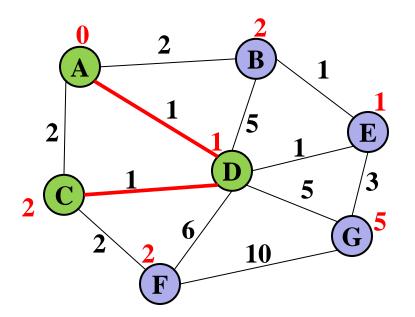
vertex	known?	cost	prev
А		??	
В		??	
С		??	
D		??	
Е		??	
F		??	
G		??	



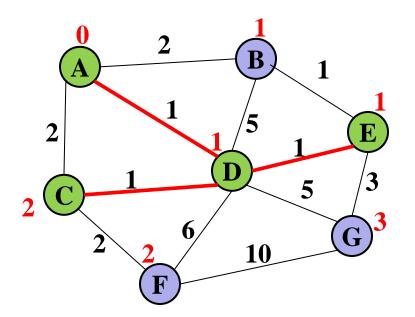
vertex	known?	cost	prev
А	Υ	0	
В		2	Α
С		2	Α
D		1	Α
Е		??	
F		??	
G		??	



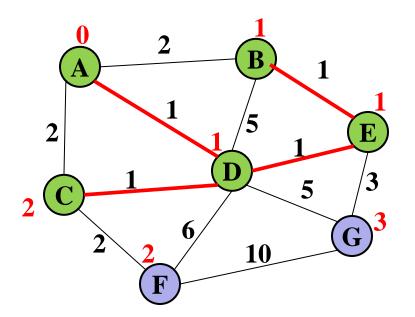
vertex	known?	cost	prev
А	Υ	0	
В		2	Α
С		1	D
D	Υ	1	Α
Е		1	D
F		6	D
G		5	D



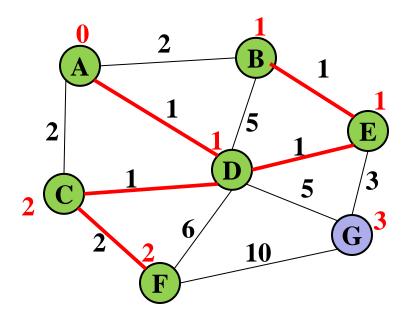
vertex	known?	cost	prev
А	Υ	0	
В		2	А
С	Υ	1	D
D	Υ	1	Α
Е		1	D
F		2	С
G		5	D



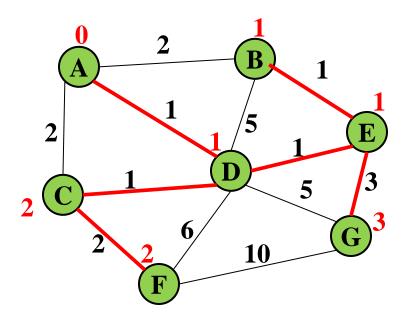
vertex	known?	cost	prev
А	Υ	0	
В		1	Ш
С	Υ	1	D
D	Υ	1	Α
Е	Υ	1	D
F		2	С
G		3	Е



vertex	known?	cost	prev
А	Υ	0	
В	Υ	1	E
С	Υ	1	D
D	Υ	1	Α
Е	Y	1	D
F		2	С
G		3	E



vertex	known?	cost	prev
А	Y	0	
В	Υ	1	Е
С	Υ	1	D
D	Υ	1	А
Е	Υ	1	D
F	Y	2	С
G		3	Е



vertex	known?	cost	prev
А	Υ	0	
В	Y	1	Е
С	Y	1	D
D	Υ	1	А
Е	Υ	1	D
F	Y	2	С
G	Y	3	Е

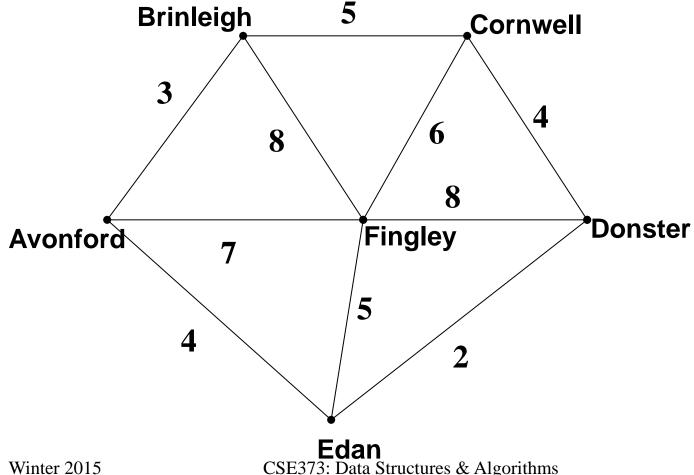
Analysis

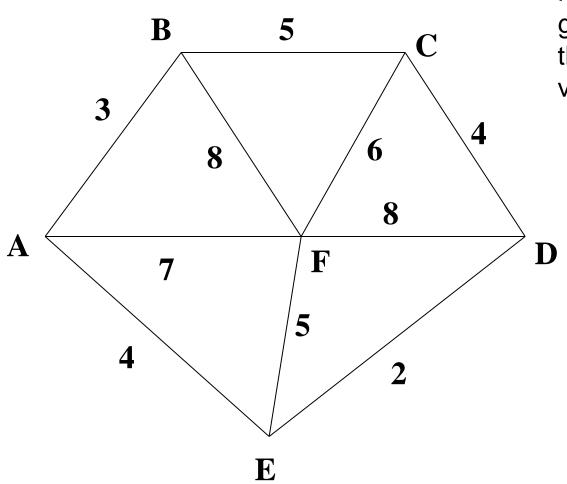
- Correctness
 - A bit tricky
 - Intuitively similar to Dijkstra

- Run-time
 - Same as Dijkstra
 - O(|E|log|V|) using a priority queue
 - Costs/priorities are just edge-costs, not path-costs

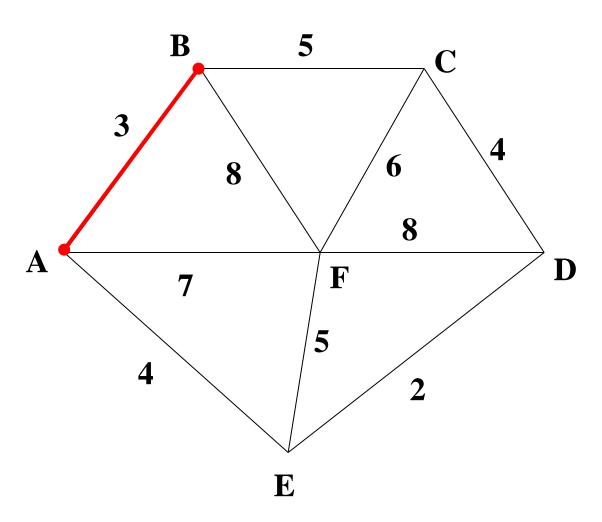
Another Example

A cable company wants to connect five villages to their network which currently extends to the town of Avonford. What is the minimum length of cable needed?





Model the situation as a graph and find the MST that connects all the villages (nodes).

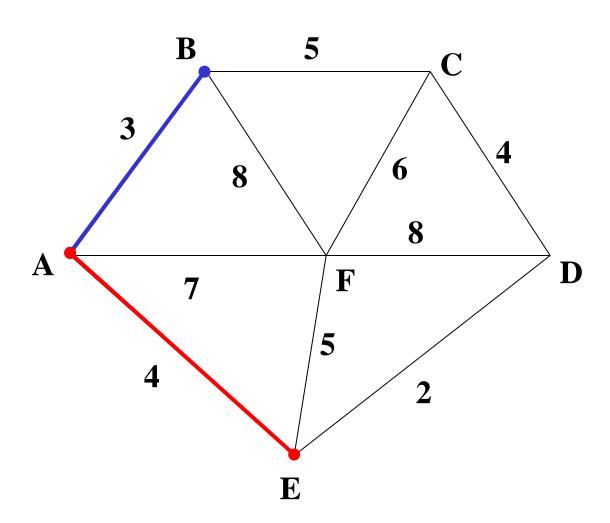


Select any vertex

Α

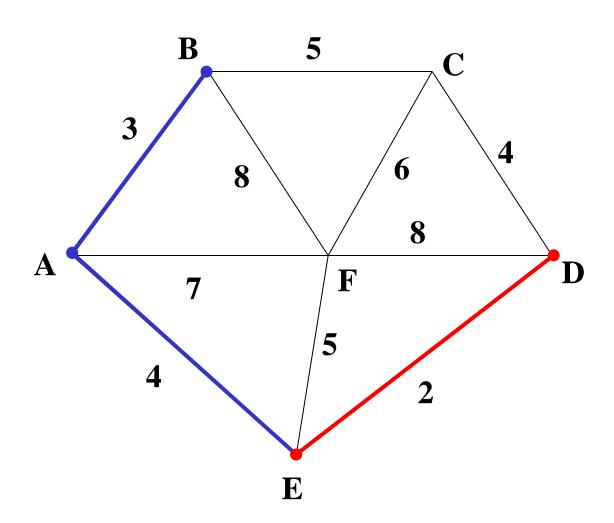
Select the shortest edge connected to that vertex

AB 3



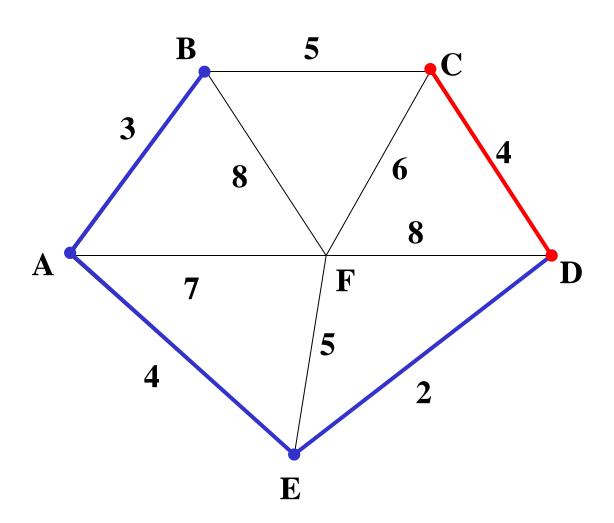
Select the shortest edge that connects an unknown vertex to any known vertex.

AE 4



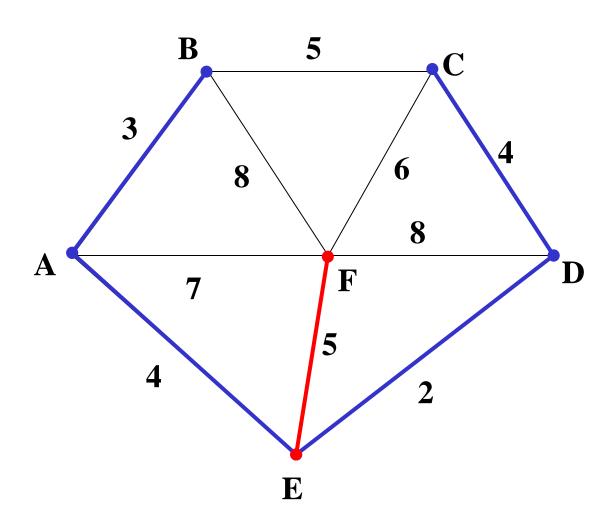
Select the shortest edge that connects an unknown vertex to any known vertex.

ED 2



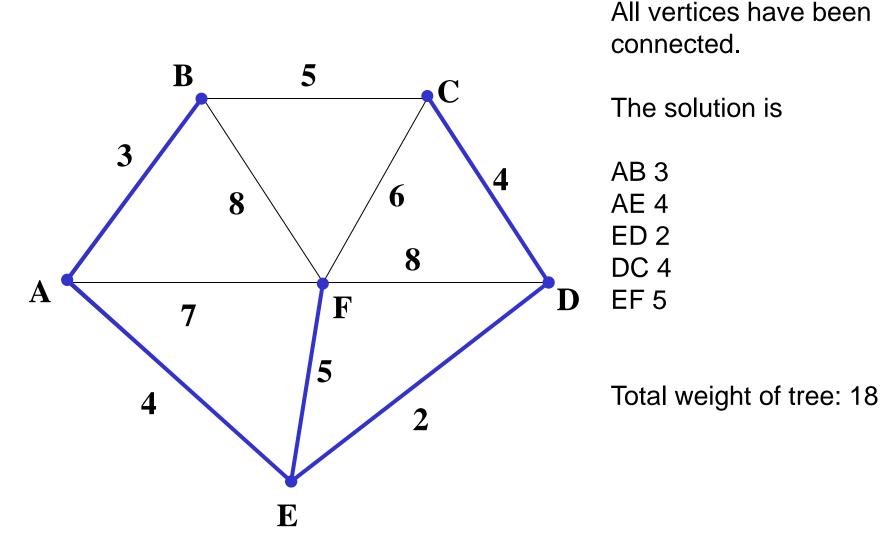
Select the shortest edge that connects an unknown vertex to any known vertex.

DC 4



Select the shortest edge that connects an unknown vertex to any known vertex.

EF 5

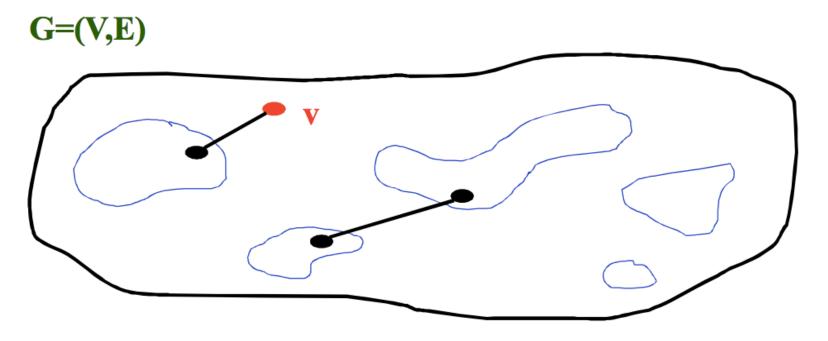


Minimum Spanning Tree Algorithms

- Prim's Algorithm for Minimum Spanning Tree
 - Similar idea to Dijkstra's Algorithm but for MSTs.
 - Both based on expanding cloud of known vertices
 (basically using a priority queue instead of a DFS stack)
- Kruskal's Algorithm for Minimum Spanning Tree
 - Another, but different, greedy MST algorithm.
 - Uses the Union-Find data structure.

Idea: Grow a forest out of edges that do not create a cycle. Pick an edge with the smallest weight.

An edge-based greedy algorithm Builds MST by greedily adding edges

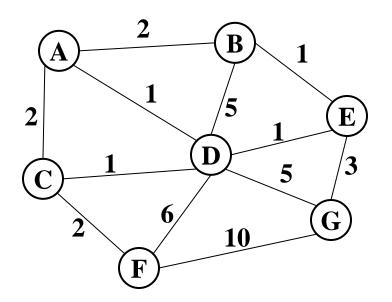


Kruskal's Algorithm Pseudocode

- 1. Sort **edges** by weight (min-heap)
- 2. Each **node** in its own set (up-trees)
- 3. While output size < |V|-1
 - Consider next smallest edge (u,v)
 - if find(u) and find(v) indicate u and v are in different sets
 - output (u,v)
 - union(find(u),find(v))

Recall invariant:

u and **v** in same set if and only if connected in output-so-far



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

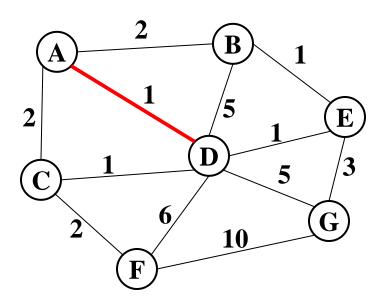
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output:



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

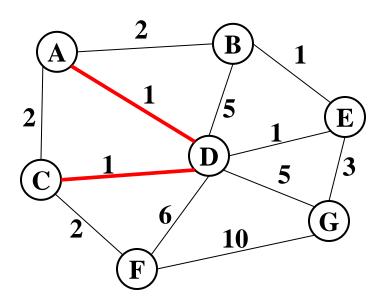
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

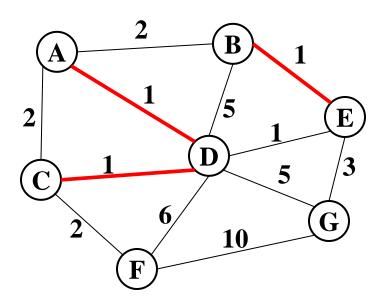
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

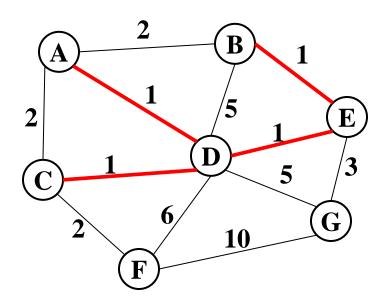
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

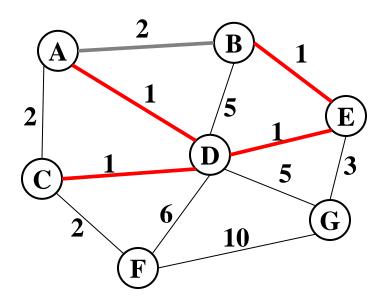
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

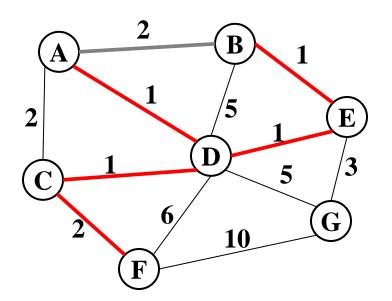
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

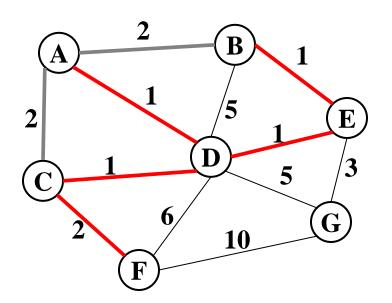
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

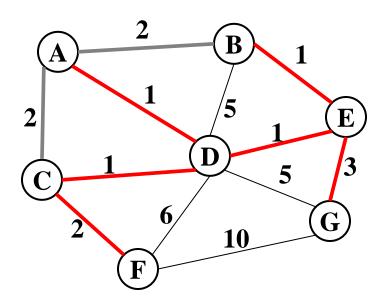
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F), (E,G)

Kruskal's Algorithm Analysis

Idea: Grow a forest out of edges that do not grow a cycle, just like for the spanning tree problem.

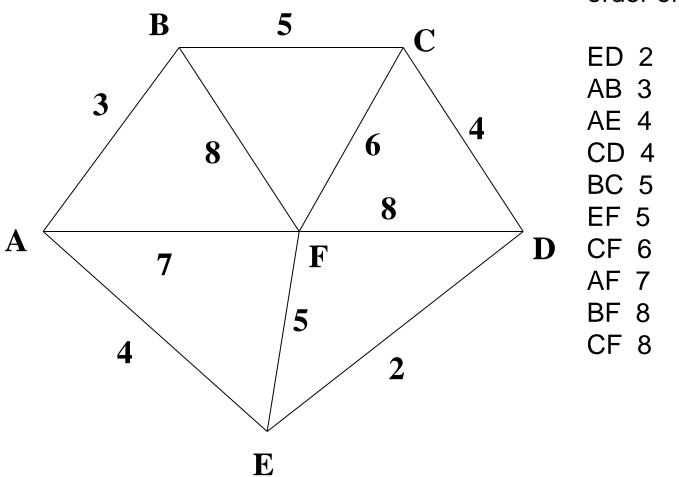
But now consider the edges in order by weight

So:

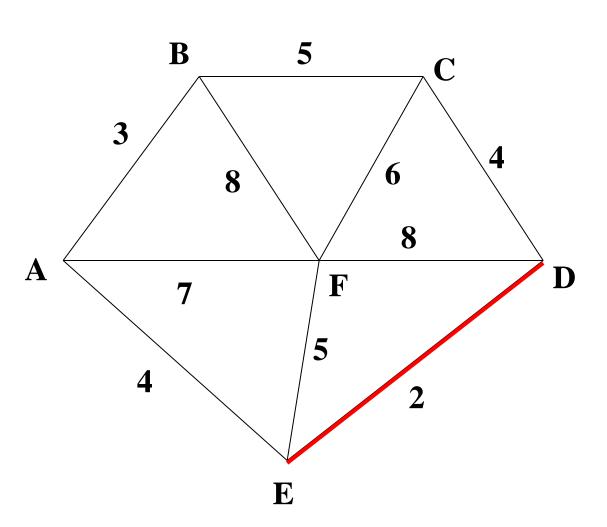
- Sort edges: O(|E|log |E|) (next course topic)
- Iterate through edges using union-find for cycle detection almost O(|E|)

Somewhat better:

- Floyd's algorithm to build min-heap with edges O(|E|)
- Iterate through edges using union-find for cycle detection and deleteMin to get next edge O(|E|log|E|)
- Not better worst-case asymptotically, but often stop long before considering all edges.

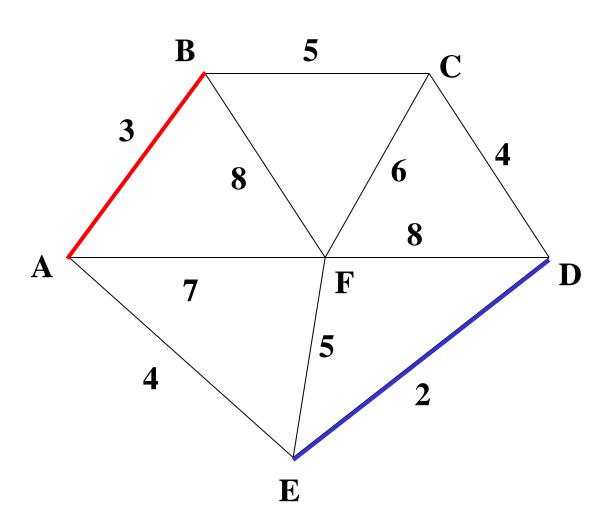


List the edges in order of size:



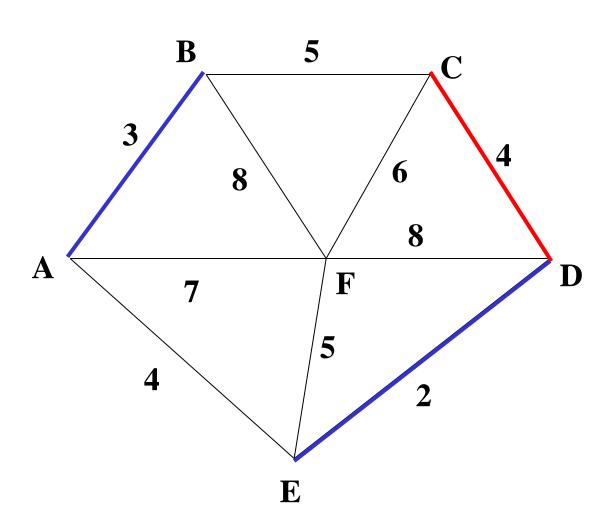
Select the edge with min cost

ED 2



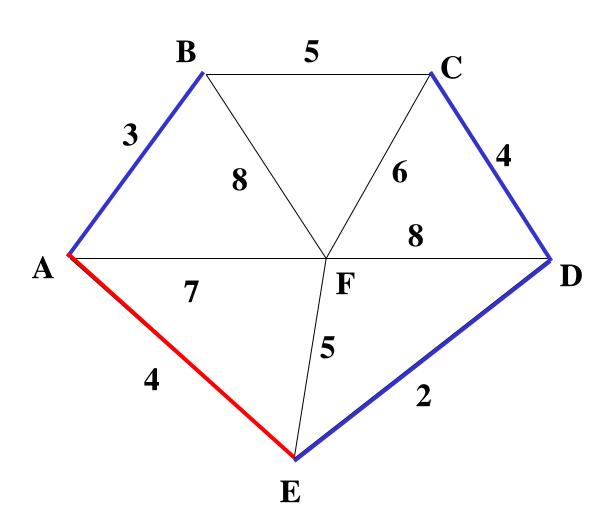
Select the next minimum cost edge that does not create a cycle

ED 2 AB 3



Select the next minimum cost edge that does not create a cycle

ED 2 AB 3 CD 4 (or AE 4)



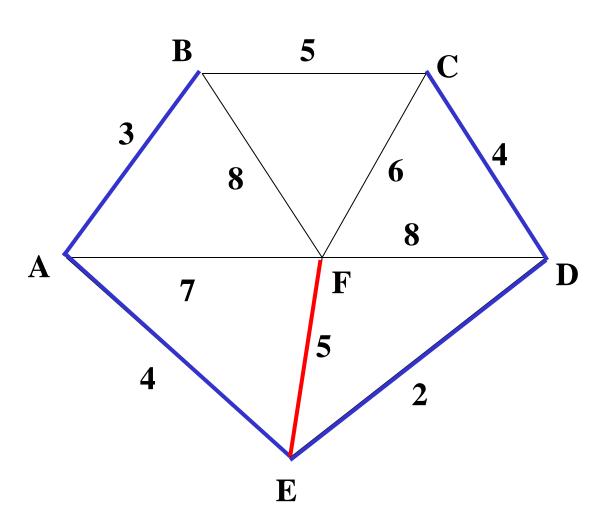
Select the next minimum cost edge that does not create a cycle

ED 2

AB 3

CD 4

AE 4



Select the next minimum cost edge that does not create a cycle

ED 2

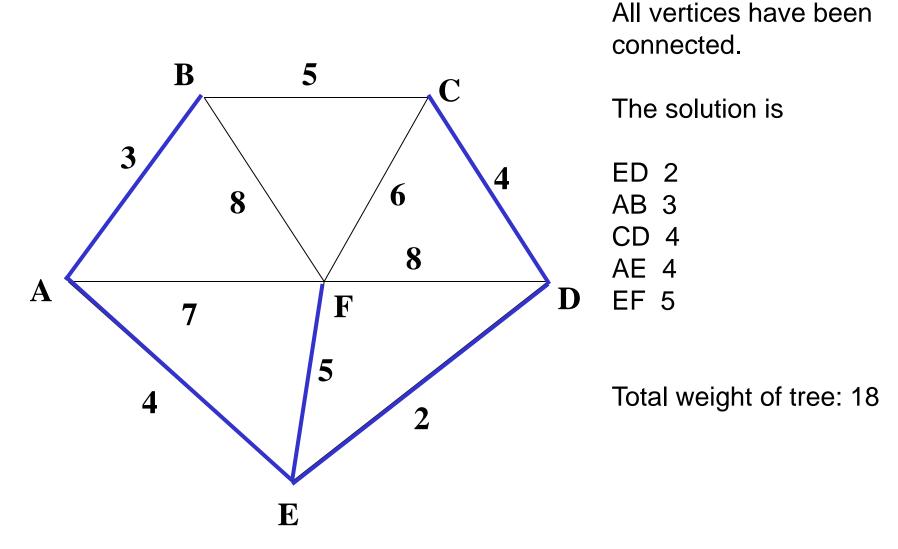
AB 3

CD 4

AE 4

BC 5 – forms a cycle

EF 5



Done with graph algorithms!

Next lecture...

Sorting