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CSE 421

Matching, Connectivity, Image Segmentation

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Perfect Bipartite Matching

Perfect Bipartite Matching

Def. A matching $M \subseteq E$ is **perfect** if each node appears in exactly one edge in M .

Q. When does a bipartite graph have a perfect matching?

Structure of bipartite graphs with perfect matchings:

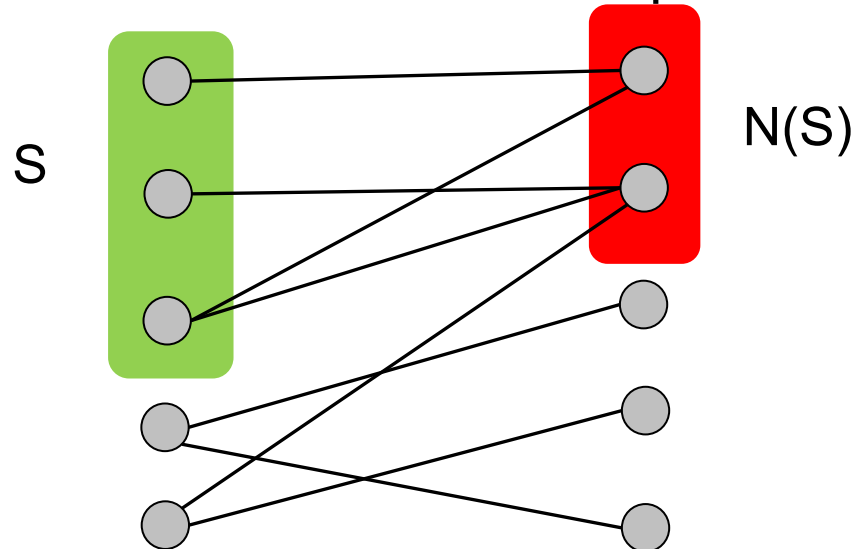
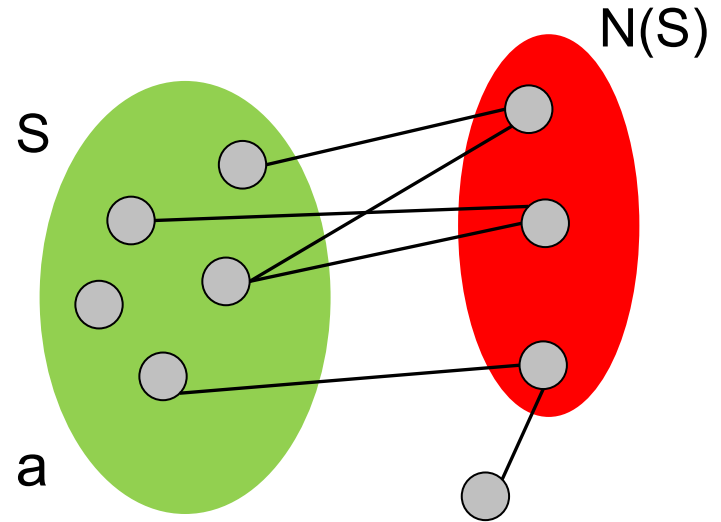
- Clearly we must have $|X| = |Y|$.
- What other conditions are necessary?
- What conditions are sufficient?

Perfect Bipartite Matching: $N(S)$

Def. Let S be a subset of nodes, and let $N(S)$ be the set of nodes adjacent to nodes in S .

Observation. If a bipartite graph G has a perfect matching, then $|N(S)| \geq |S|$ for all subsets $S \subseteq X$.

Pf. Each $v \in S$ has to be matched to a unique node in $N(S)$.



Marriage Theorem

Thm: [Frobenius 1917, Hall 1935] Let $G = (X \cup Y, E)$ be a bipartite graph with $|X| = |Y|$.

Then, G has a perfect matching iff $|N(S)| \geq |S|$ for all subsets $S \subseteq X$.

Pf. \Rightarrow

This was the previous observation.

If $|N(S)| < |S|$ for some S , then there is no perfect matching.

Marriage Theorem

Pf. $\exists S \subseteq X$ s.t., $|N(S)| < |S| \iff G$ does not have a perfect matching

Formulate as a max-flow and let (A, B) be the min s-t cut

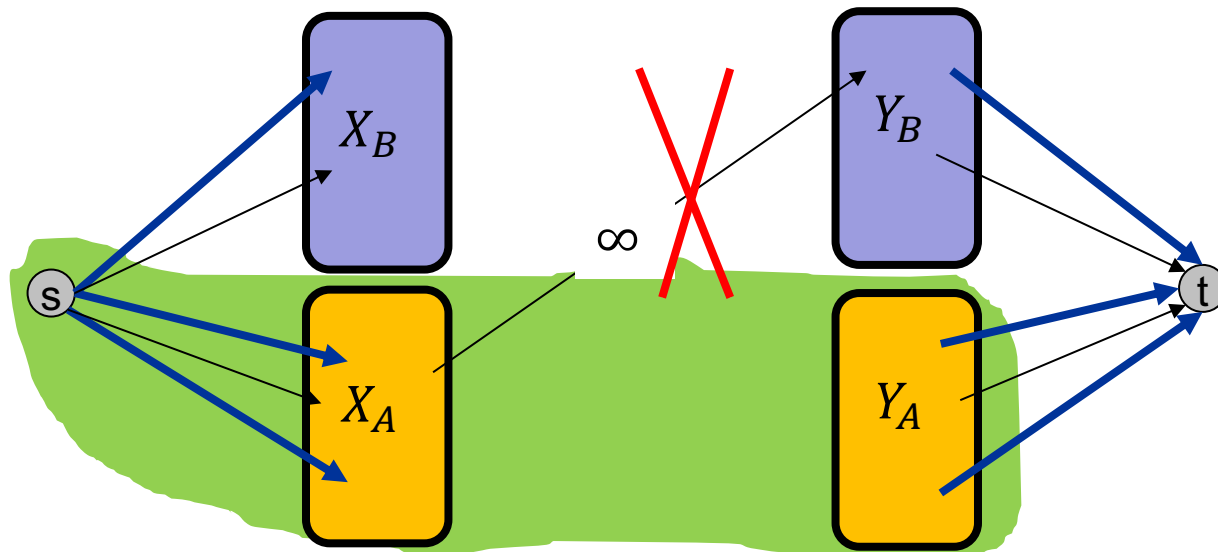
G has no perfect matching $\Rightarrow v(f^*) < |X|$. So, $cap(A, B) < |X|$

Define $X_A = X \cap A, X_B = X \cap B, Y_A = Y \cap A$

Then, $cap(A, B) = |X_B| + |Y_A|$

Since min-cut does not use ∞ edges, $N(X_A) \subseteq Y_A$

$|N(X_A)| \leq |Y_A| = cap(A, B) - |X_B| = cap(A, B) - |X| + |X_A| < |X_A|$



Bipartite Matching Running Time

Which max flow algorithm to use for bipartite matching?

Generic augmenting path: $O(m \text{ val}(f^*)) = O(mn)$.

Capacity scaling: $O(m^2 \log C) = O(m^2)$.

Shortest augmenting path: $O(m n^{1/2})$.

Non-bipartite matching.

Structure of non-bipartite graphs is more complicated, but well-understood. [Tutte-Berge, Edmonds-Galai]

Blossom algorithm: $O(n^4)$. [Edmonds 1965]

Best known: $O(m n^{1/2})$. [Micali-Vazirani 1980]

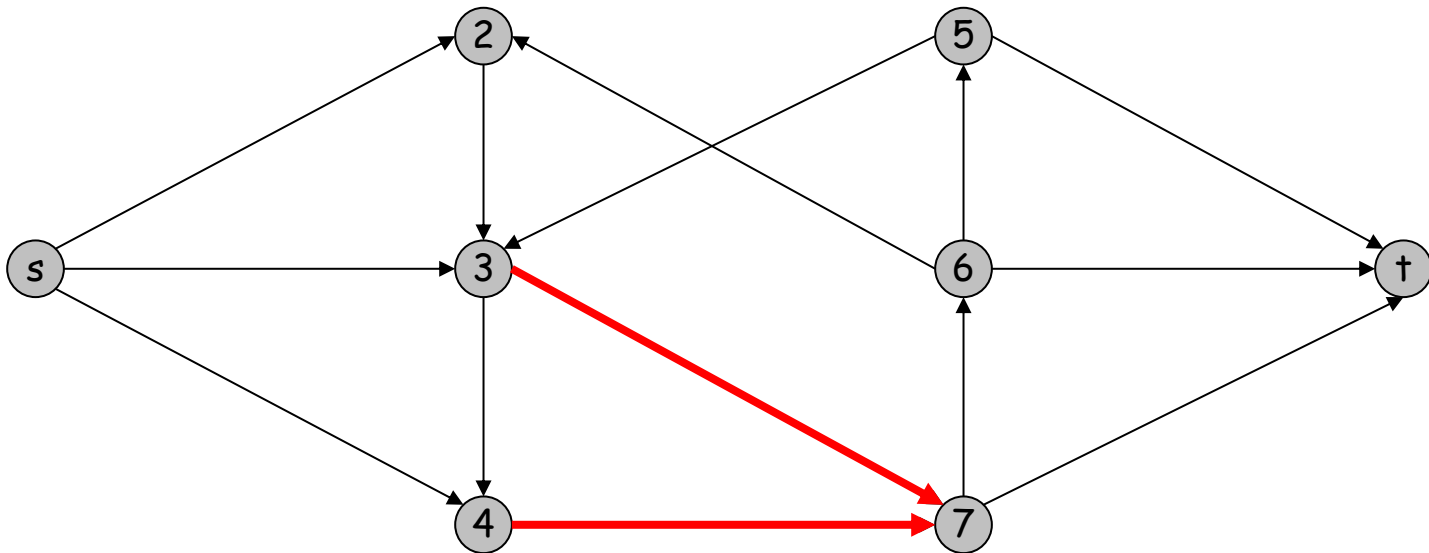
Network Connectivity

Network Connectivity

Given a digraph $G = (V, E)$ and two nodes s and t , find min number of edges whose removal disconnects t from s .

Def. A set of edges $F \subseteq E$ **disconnects t from s** if all s - t paths uses at least one edge in F .

Ex: In testing network reliability



Network Connectivity using Min Cut

Thm. [Menger 1927] The max number of edge-disjoint s-t paths is equal to the min number of edges whose removal disconnects t from s.

Pf.

- i) We showed that max number edge disjoint s-t paths = max flow.
- ii) Max-flow Min-cut theorem \Rightarrow min s-t cut = max-flow
- iii) For a s-t cut (A,B) , $\text{cap}(A,B)$ is equal to the number of edges out of A. In other words, every s-t cut (A,B) corresponds to $\text{cap}(A,B)$ edges whose removal disconnects s from t.

So, max number of edge disjoint s-t paths
= min number of edges to disconnect s from t.

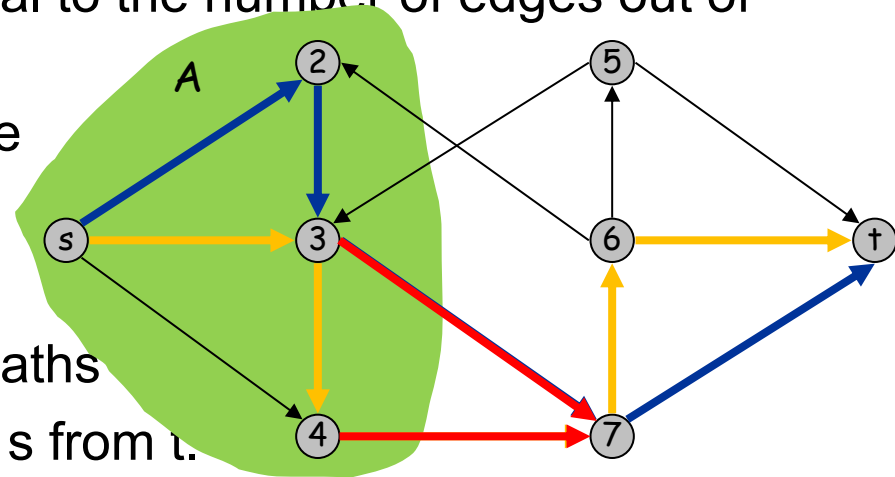


Image Segmentation

Given an image we want to separate foreground from background

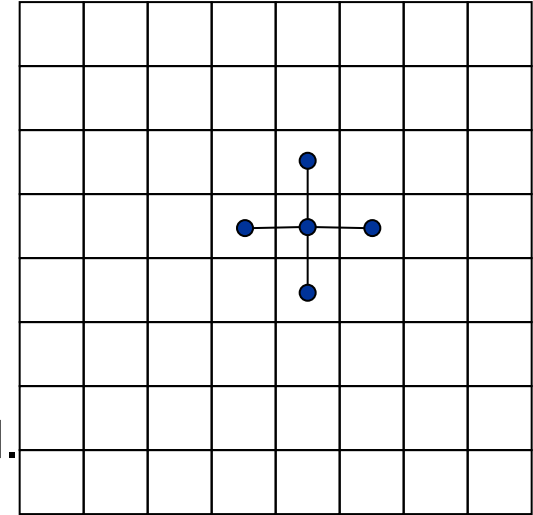
- Central problem in image processing.
- Divide image into coherent regions.



Foreground / background segmentation

Label each pixel as foreground/background.

- V = set of pixels, E = pairs of neighboring pixels.
- $a_i \geq 0$ is likelihood pixel i in foreground.
- $b_i \geq 0$ is likelihood pixel i in background.
- $p_{i,j} \geq 0$ is separation penalty for labeling one of i and j as foreground, and the other as background.



Goals.

Accuracy: if $a_i > b_i$ in isolation, prefer to label i in foreground.

Smoothness: if many neighbors of i are labeled foreground, we should be inclined to label i as foreground.

Find partition (A, B) that **maximizes**:

$$\sum_{i \in A} a_i + \sum_{j \in B} b_j - \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

An arrow points from the word "Foreground" to the set A in the equation above. Another arrow points from the word "Background" to the set B in the equation above.

Image Seg: Min Cut Formulation

Difficulties:

- Maximization (as opposed to minimization)
- No source or sink
- Undirected graph

Step 1: Turn into Minimization

Maximizing
$$\sum_{i \in A} a_i + \sum_{j \in B} b_j - \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

Equivalent to minimizing
$$+ \sum_{i \in V} a_i + \sum_{j \in V} b_j - \sum_{i \in A} a_i - \sum_{j \in B} b_j + \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

Equivalent to minimizing
$$+ \sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

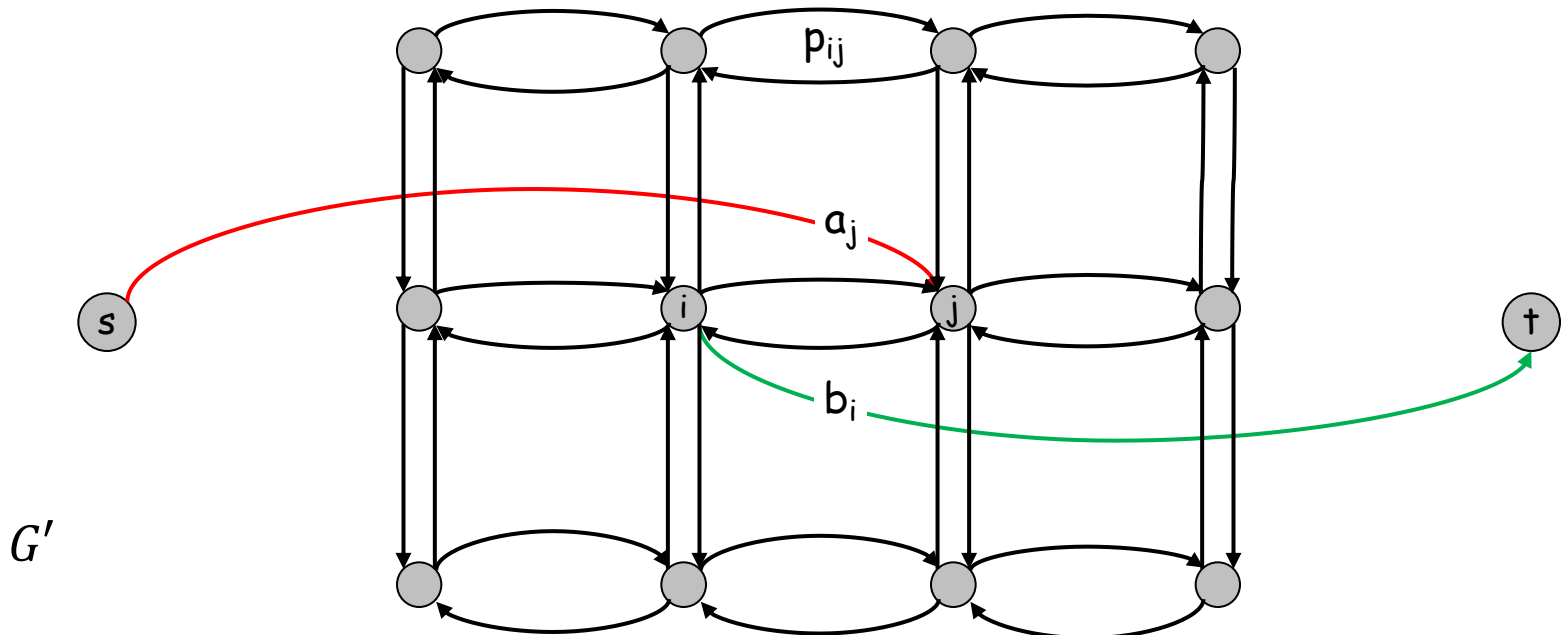
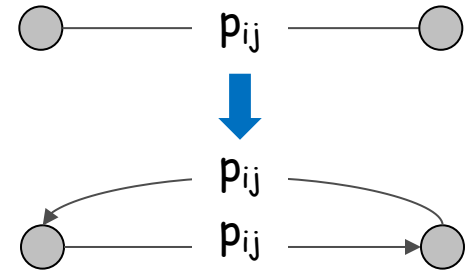
Min cut Formulation (cont'd)

$G' = (V', E')$.

Add s to correspond to foreground;

Add t to correspond to background

Use two anti-parallel edges
instead of undirected edge.



Min cut Formulation (cont'd)

Consider min cut (A, B) in G' . (A = foreground.)

$$cap(A, B) = \sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

Precisely the quantity we want to minimize.

