Introduction to Database Systems CSE 444

Lecture 20: Overview of Query Optimization

Announcements

- Project 3 is due tonight
 - How is it going?
- HW3 is out and is due on next Wednesday
 - Rather short assignment
 - But start early in case you have questions
- Project 4 will be out shortly (last assignment)
 - Group assignment: 2 to 4 students (but 1 ok too)

Where We Are

- We are learning how a DBMS executes a query
- What we learned so far
 - How data is stored and indexed (lectures 15 and 16)
 - Logical query plans: relational algebra (lecture 17)
 - Steps involved in processing a query (lecture 18)
 - Operator algorithms (lecture 19)
- Today
 - How to select logical & physical query plans
 - Chapter 16 in the book (recommended, not required)

Query Optimization Goal

- For a query
 - There exists many logical and physical query plans
 - Query optimizer needs to pick a good one

Query Optimization Algorithm

- Enumerate alternative plans
- Compute estimated cost of each plan
 - Compute number of I/Os
 - Compute CPU cost
- Choose plan with lowest cost
 - This is called cost-based optimization

Outline

- Search space
- Algorithm for enumerating query plans
- Estimating the cost of a query plan

Relational Algebra Equivalences

Selections

- Commutative: $\sigma_{c1}(\sigma_{c2}(R))$ same as $\sigma_{c2}(\sigma_{c1}(R))$
- Cascading: $\sigma_{c1 \wedge c2}(R)$ same as $\sigma_{c2}(\sigma_{c1}(R))$

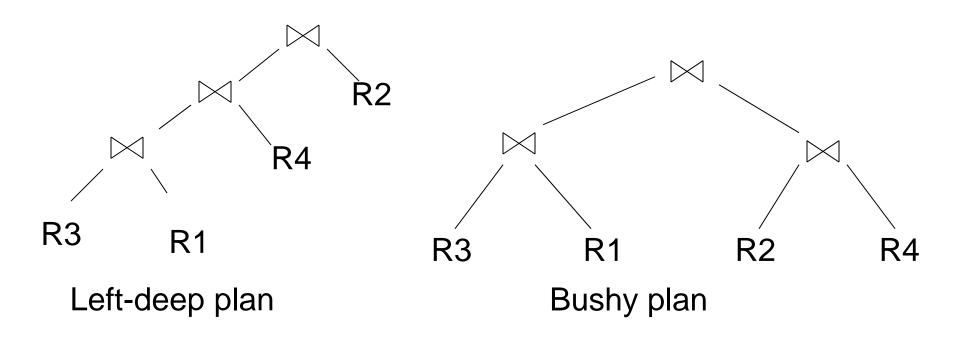
Projections

- Cascading

Joins

- Commutative : R ⋈ S same as S ⋈ R
- Associative: R ⋈ (S ⋈ T) same as (R ⋈ S) ⋈ T

Left-Deep Plans and Bushy Plans



Relational Algebra Equivalences

- Selects, projects, and joins
 - We can commute and combine all three types of operators
 - We just have to be careful that the fields we need are available when we apply the operator
 - Relatively straightforward. See book 16.2

Search Space Challenges

- Search space is huge!
 - Many possible equivalent trees
 - Many implementations for each operator
 - Many access paths for each relation
 - File scan or index + matching selection condition
- Cannot consider ALL plans
- Want search space that includes low-cost plans

Outline

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- Estimating the cost of a query plan

Key Decisions

- When selecting a plan, some of the most important decisions include:
 - Logical plan
 - Can we push selections down?
 - Can we push projections or aggregations down?
 - What order to use for joins?
 - Physical plan
 - What join algorithms to use?
 - What access paths to use (file scan or index)?

Plan Enumeration Algorithms

- Rule-based vs cost-based algorithms
- Logical plans
 - Heuristic-based algorithms
 - Use size of intermediate results as cost measure
- Physical plans
 - Top-down algorithms or
 - Bottom-up: dynamic programming approaches
 - Also called "Selinger-style" optimizers
 - Use heuristics to limit search space

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Computing the Cost of a Plan

- Collect statistical summaries of stored data
- Compute cost in a bottom-up fashion
- For each operator compute
 - Estimate cost of executing the operation
 - Estimate statistical summary of the output data

Statistics on Base Data

- Collected information for each relation
 - Number of tuples (cardinality)
 - Indexes, number of keys in the index
 - Number of physical pages, clustering info
 - Statistical information on attributes
 - Min value, max value, number distinct values
 - Histograms
 - Correlations between columns (hard)
- Collection approach: periodic, using sampling

Retrieving data from Storage

- Access path: a way to retrieve tuples from a table
 - A file scan
 - An index plus a matching selection condition
- Index matches selection condition if it can be used to retrieve just tuples that satisfy the condition
 - Example: Supplier(sid,sname,scity,sstate)
 - B+-tree index on (scity,sstate)
 - matches scity='Seattle'
 - does not match sid=3, does not match sstate='WA'

Access Path Selection

- Supplier(sid,sname,scity,sstate)
- Selection condition: sid > 300 \(\sigma \) scity='Seattle'
- Indexes: B+-tree on sid and B+-tree on scity
- Which access path should we use?
- We should pick the most selective access path

Access Path Selectivity

- Access path selectivity is the number of pages retrieved if we use this access path
 - Most selective retrieves fewest pages
- As we saw earlier, for equality predicates
 - Selection on equality: $\sigma_{a=v}(R)$
 - V(R, a) = # of distinct values of attribute a
 - 1/V(R,a) is thus the reduction factor
 - Clustered index on a: cost B(R)/V(R,a)
 - Unclustered index on a: cost T(R)/V(R,a)
 - (we are ignoring I/O cost of index pages for simplicity)

Selectivity for Range Predicates

- Selection on range: $\sigma_{a>v}(R)$
- How to compute the selectivity?
- Assume values are uniformly distributed
- Reduction factor X
- X = (Max(R,a) v) / (Max(R,a) Min(R,a))
- Clustered index on a, cost is B(R)*X
- Unclustered index on a, cost is T(R)*X

Back to Our Example

- Selection condition: sid > 300 ∧ scity='Seattle'
 - Index I1: B+-tree on sid clustered
 - Index I2: B+-tree on scity unclustered
- Let's assume
 - V(Supplier,scity) = 20
 - Max(Supplier, sid) = 1000, Min(Supplier, sid)=1
 - B(Supplier) = 100, T(Supplier) = 1000
- Cost I1: B(R) * (Max-v)/(Max-Min) = $100*700/999 \approx 70$
- Cost I2: T(R) * 1/V(Supplier,scity) = 1000/20 = 50

Selectivity with Multiple Conditions

What if we have an index on multiple attributes?

• Example selection $\sigma_{a=v1 \land b=v2}(R)$ and index on <a,b>

How to compute the selectivity?

- Assume attributes are independent
- X = 1 / (V(R,a) * V(R,b))
- Clustered index on <a,b>: cost B(R)*X
- Unclustered index on <a,b>: cost T(R)*X

Computing Cost of an Operator

- The cost of executing an operator depends
 - On the operator implementation
 - On the input data
- We learned how to compute this in the previous lecture, so we do not repeat it here

Statistics on the Output Data

- Most important piece of information
 - Size of operator result
 - I.e., the number of output tuples

- Projection: output size same as input size
- Selection: multiply input size by reduction factor
 - Similar to what we did for estimating access path selectivity
 - Assume independence between conditions in the predicate
 - (use product of the reduction factors for the terms)

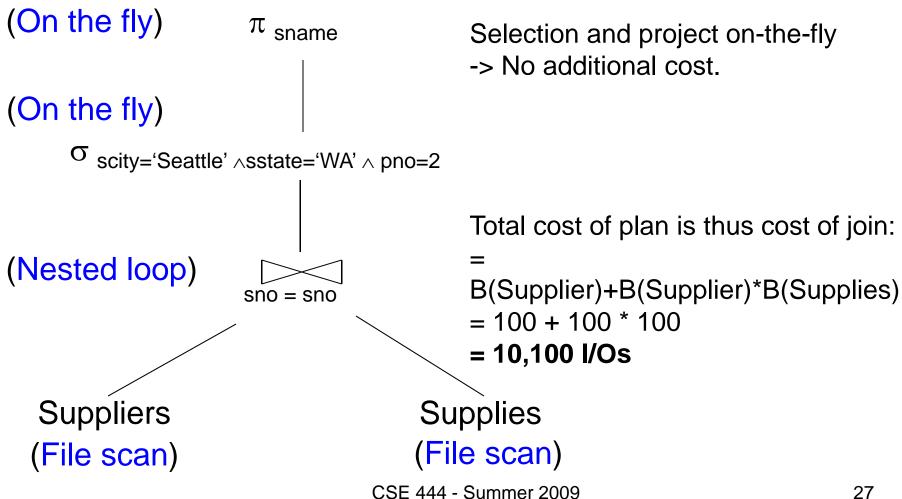
Estimating Result Sizes

- For joins R ⋈ S
 - Take product of cardinalities of relations R and S
 - Apply reduction factors for each term in join condition
 - Terms are of the form: column1 = column2
 - Reduction: 1/ (MAX(V(R,column1), V(S,column2))
 - Assumes each value in smaller set has a matching value in the larger set

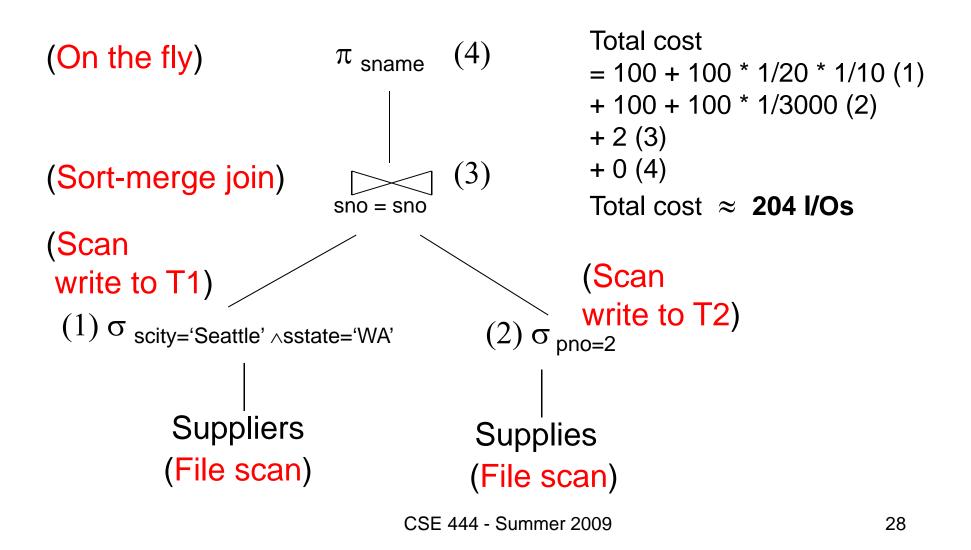
Our Example

- Suppliers(sid,sname,scity,sstate)
- Supplies(pno,sid,quantity)
- Some statistics
 - T(Supplier) = 1000 records
 - B(Supplier) = 100 pages
 - T(Supplies) = 10,000 records
 - B(Supplies) = 100 pages
 - V(Supplier,scity) = 20, V(Supplier,state) = 10
 - V(Supplies,pno) = 3,000
 - Both relations are clustered

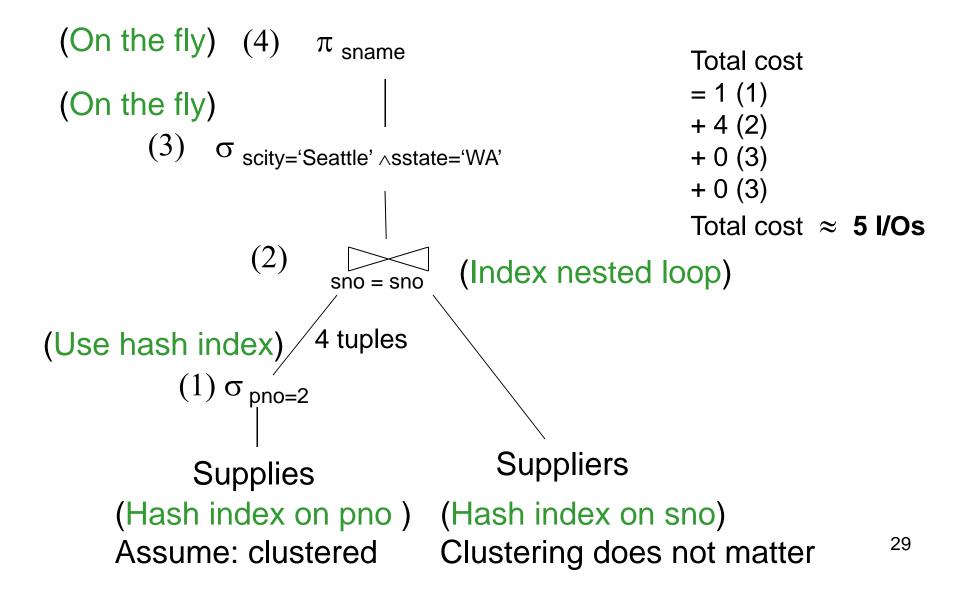
Physical Query Plan 1



Physical Query Plan 2



Physical Query Plan 3



Simplifications

- In the previous examples, we assumed that all index pages were in memory
 - When this is not the case, we need to add the cost of fetching index pages from disk
- We also assumed that CPU time is irrelevant
 - Not the entire story in production systems